

This Week in Mechanical Team (9/16/17)

Design Work

- Chassis Derick Whited
- Suspension Kai Davis, Jefferson O'Brien
 - Bottom of chassis 10in above ground
- Electrical Box Riley Roche
- Robotic Arm Kyle
- Robotic Arm Base Rotation
 - Planetary Gear Variant Hubert
 - Pinion and Annular Variant Chris

Research/Documentation

- Camera Mounting Scheme Matthew
 - <u>Deliverable</u>: A 1+ page document summarizing your research and result
 - Will be sent to Kyle and we'll review it on the Tuesday meeting
 - Driving, Panorama, Arm Camera:
- o Robotic Arm Base Rotation Hubert, Chris
 - <u>Deliverable:</u> A short report detailing at least three existing solutions, and any analysis on their viability in the a moving rover.
 - Team Analysis:
 - Oil impregnated brass
 - Bushing if low enough friction
 - Dry graphite lubricant (pinewood derby short lifespan)
 - From Here:
 - Planetary Gear Hubert
 - Pinion and Annular Chris
- Finite Element Analysis Kyle
 - <u>Deliverable</u>: A one page document summarizing your research and results (template attached).
- Organization Kyle
 - <u>Deliverables:</u> Naming convention scheme, Mechanical Team Wiki, myfiles engineering MAVRIC folder, CAD documentation

Manufacturing Work

Boyd Training:

I still encourage everybody to get trained on any relevant Boyd lab machines.
You can navigate to training signup from here.

Notices and Orders

- Currently, only raw materials can be ordered. If you have any rough estimates for materials that you will need for your designs, please inform me of them now.
- Weekly Meeting -
- **Attendance** (bold indicates attended)
 - Davis, Stephen K
 - Matejka, Matthew
 - o Ogle, Rebecka L
 - o Ooi, Hubert Y
 - o Roche, Riley P
 - Whited, Derick J
 - Wong, Christopher W