

Cifar10

February 3, 2022

1 Image Classification with CIFAR-10 dataset

In this notebook, I am going to classify images from the [CIFAR-10 dataset](#). The dataset consists of airplanes, dogs, cats, and other objects. You'll preprocess the images, then train a convolutional neural network on all the samples. The images need to be normalized and the labels need to be one-hot encoded.

1.1 Get the Data

Run the following cell to download the [CIFAR-10 dataset for python](#).

1.1.1 List of files

the dataset is broken into batches to **prevent** your machine from running **out of memory**. The CIFAR-10 dataset consists of 5 batches, named `data_batch_1`, `data_batch_2`, etc..

1.1.2 Understanding the original data

In order to feed an image data into a CNN model, the dimension of the tensor representing an image data should be either (width x height x num_channel) or (num_channel x width x height). I am going to use the dimension of the first choice because the default choice in tensorflow's CNN operation is so.

1.1.3 Understanding the original labels

The label data is just a list of 10000 numbers in the range 0-9, which corresponds to each of the 10 classes in CIFAR-10.

- airplane
- automobile
- bird
- cat
- deer
- dog
- frog
- horse
- ship
- truck

```
[1]: from urllib.request import urlretrieve
from os.path import isfile, isdir
from tqdm import tqdm
import tarfile

cifar10_dataset_folder_path = 'cifar-10-batches-py'

class DownloadProgress(tqdm):
    last_block = 0

    def hook(self, block_num=1, block_size=1, total_size=None):
        self.total = total_size
        self.update((block_num - self.last_block) * block_size)
        self.last_block = block_num

    """
        check if the data (zip) file is already downloaded
        if not, download it from "https://www.cs.toronto.edu/~kriz/cifar-10-python.
        →tar.gz" and save as cifar-10-python.tar.gz
    """
    if not isfile('cifar-10-python.tar.gz'):
        with DownloadProgress(unit='B', unit_scale=True, miniters=1, desc='CIFAR-10_
        →Dataset') as pbar:
            urlretrieve(
                'https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz',
                'cifar-10-python.tar.gz',
                pbar.hook)

    if not isdir(cifar10_dataset_folder_path):
        with tarfile.open('cifar-10-python.tar.gz') as tar:
            tar.extractall()
            tar.close()
```

CIFAR-10 Dataset: 171MB [00:02, 68.1MB/s]

```
[3]: def load_cifar10_batch(cifar10_dataset_folder_path, batch_id):
    with open(cifar10_dataset_folder_path + '/data_batch_' + str(batch_id),
    →mode='rb') as file:
        # note the encoding type is 'latin1'
        batch = pickle.load(file, encoding='latin1')

        features = batch['data'].reshape((len(batch['data']), 3, 32, 32)).
        →transpose(0, 2, 3, 1)
        labels = batch['labels']

    return features, labels
```

```

def load_label_names():
    return ['airplane', 'automobile', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck']

def display_stats(cifar10_dataset_folder_path, batch_id, sample_id):
    features, labels = load_cifar10_batch(cifar10_dataset_folder_path, batch_id)

    if not (0 <= sample_id < len(features)):
        print('{} samples in batch {}. {} is out of range.'.format(len(features), batch_id, sample_id))
        return None

    print('\nStats of batch #{}:'.format(batch_id))
    print('# of Samples: {}'.format(len(features)))

    label_names = load_label_names()
    label_counts = dict(zip(*np.unique(labels, return_counts=True)))
    for key, value in label_counts.items():
        print('Label Counts of [{}]({}) : {}'.format(key, label_names[key].upper(), value))

    sample_image = features[sample_id]
    sample_label = labels[sample_id]

    print('\nExample of Image {}'.format(sample_id))
    print('Image - Min Value: {} Max Value: {}'.format(sample_image.min(), sample_image.max()))
    print('Image - Shape: {}'.format(sample_image.shape))
    print('Label - Label Id: {} Name: {}'.format(sample_label, label_names[sample_label]))

    plt.imshow(sample_image)

```

```

[4]: %matplotlib inline
      %config InlineBackend.figure_format = 'retina'

      import numpy as np
      import pickle
      import matplotlib.pyplot as plt
      # Explore the dataset
      batch_id = 3
      sample_id = 7000
      display_stats(cifar10_dataset_folder_path, batch_id, sample_id)

```

```

Stats of batch #3:
# of Samples: 10000

```

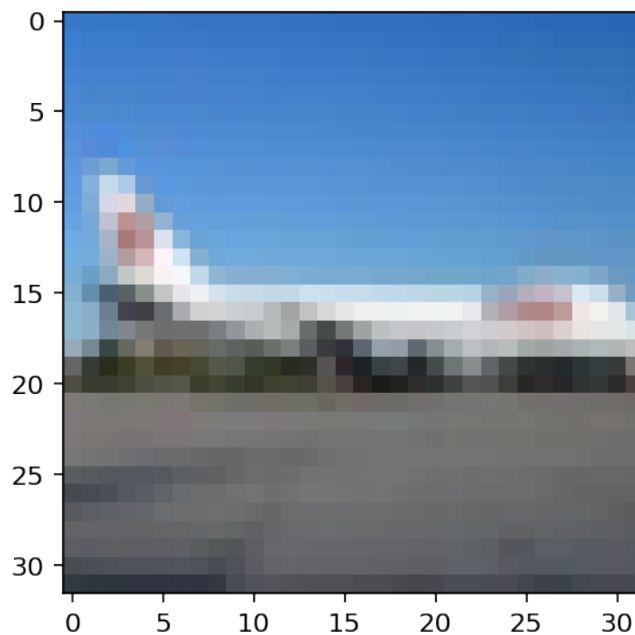
Label Counts of [0](AIRPLANE) : 994
Label Counts of [1](AUTOMOBILE) : 1042
Label Counts of [2](BIRD) : 965
Label Counts of [3](CAT) : 997
Label Counts of [4](DEER) : 990
Label Counts of [5](DOG) : 1029
Label Counts of [6](FROG) : 978
Label Counts of [7](HORSE) : 1015
Label Counts of [8](SHIP) : 961
Label Counts of [9](TRUCK) : 1029

Example of Image 7000:

Image - Min Value: 24 Max Value: 252

Image - Shape: (32, 32, 3)

Label - Label Id: 0 Name: airplane



```
[5]: import numpy
      from tensorflow import keras
      from keras.constraints import maxnorm
      from keras.utils import np_utils
```

```
[6]: seed = 21
```

```
[7]: from keras.datasets import cifar10
```

```
[8]: (X_train, y_train), (X_test, y_test) = cifar10.load_data()
```

Downloading data from <https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz>
170500096/170498071 [=====] - 2s 0us/step
170508288/170498071 [=====] - 2s 0us/step

```
[9]: X_train = X_train.astype('float32')
X_test = X_test.astype('float32')
X_train = X_train / 255.0
X_test = X_test / 255.0
```

```
[10]: y_train = np_utils.to_categorical(y_train)
y_test = np_utils.to_categorical(y_test)
class_num = y_test.shape[1]
```

```
[ ]: model = keras.Sequential()
```

```
[ ]: model.add(keras.layers.Conv2D(32, 3, input_shape=(32, 32, 3),
    ↳activation='relu', padding='same'))
model.add(keras.layers.Dropout(0.2))
model.add(keras.layers.BatchNormalization())

model.add(keras.layers.Conv2D(64, (3, 3), padding='same', activation='relu'))
model.add(keras.layers.MaxPooling2D(2))
model.add(keras.layers.Dropout(0.2))
model.add(keras.layers.BatchNormalization())

model.add(keras.layers.Conv2D(64, 3, padding='same', activation='relu'))
model.add(keras.layers.MaxPooling2D(2))
model.add(keras.layers.Dropout(0.2))
model.add(keras.layers.BatchNormalization())

model.add(keras.layers.Conv2D(128, (3, 3), padding='same', activation='relu'))
model.add(keras.layers.Dropout(0.2))
model.add(keras.layers.BatchNormalization())

model.add(keras.layers.Flatten())
model.add(keras.layers.Dropout(0.2))
model.add(keras.layers.Dense(32, activation='relu'))
model.add(keras.layers.Dropout(0.3))
model.add(keras.layers.BatchNormalization())

model.add(keras.layers.Dense(class_num, activation='softmax'))

model.compile(loss='categorical_crossentropy', optimizer='adam',
    ↳metrics=['accuracy'])

print(model.summary())
```

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 32, 32, 32)	896
dropout (Dropout)	(None, 32, 32, 32)	0
batch_normalization (Batch Normalization)	(None, 32, 32, 32)	128
conv2d_1 (Conv2D)	(None, 32, 32, 64)	18496
max_pooling2d (MaxPooling2D)	(None, 16, 16, 64)	0
dropout_1 (Dropout)	(None, 16, 16, 64)	0
batch_normalization_1 (Batch Normalization)	(None, 16, 16, 64)	256
conv2d_2 (Conv2D)	(None, 16, 16, 64)	36928
max_pooling2d_1 (MaxPooling2D)	(None, 8, 8, 64)	0
dropout_2 (Dropout)	(None, 8, 8, 64)	0
batch_normalization_2 (Batch Normalization)	(None, 8, 8, 64)	256
conv2d_3 (Conv2D)	(None, 8, 8, 128)	73856
dropout_3 (Dropout)	(None, 8, 8, 128)	0
batch_normalization_3 (Batch Normalization)	(None, 8, 8, 128)	512
flatten (Flatten)	(None, 8192)	0
dropout_4 (Dropout)	(None, 8192)	0
dense (Dense)	(None, 32)	262176
dropout_5 (Dropout)	(None, 32)	0
batch_normalization_4 (Batch Normalization)	(None, 32)	128
dense_1 (Dense)	(None, 10)	330

```

=====
Total params: 393,962
Trainable params: 393,322
Non-trainable params: 640
-----
None

```

```

[ ]: numpy.random.seed(seed)
     history = model.fit(X_train, y_train, validation_data=(X_test, y_test),
     ↪ epochs=25, batch_size=64)

```

```

Epoch 1/25
782/782 [=====] - 358s 455ms/step - loss: 1.5580 -
accuracy: 0.4473 - val_loss: 1.1479 - val_accuracy: 0.5896
Epoch 2/25
782/782 [=====] - 347s 443ms/step - loss: 1.1149 -
accuracy: 0.6097 - val_loss: 0.9357 - val_accuracy: 0.6611
Epoch 3/25
782/782 [=====] - 351s 449ms/step - loss: 0.9590 -
accuracy: 0.6679 - val_loss: 0.8060 - val_accuracy: 0.7178
Epoch 4/25
782/782 [=====] - 353s 452ms/step - loss: 0.8740 -
accuracy: 0.6980 - val_loss: 0.8086 - val_accuracy: 0.7138
Epoch 5/25
782/782 [=====] - 376s 480ms/step - loss: 0.8149 -
accuracy: 0.7201 - val_loss: 0.6927 - val_accuracy: 0.7545
Epoch 6/25
782/782 [=====] - 405s 518ms/step - loss: 0.7618 -
accuracy: 0.7378 - val_loss: 0.7311 - val_accuracy: 0.7489
Epoch 7/25
782/782 [=====] - 413s 528ms/step - loss: 0.7284 -
accuracy: 0.7493 - val_loss: 0.6366 - val_accuracy: 0.7758
Epoch 8/25
782/782 [=====] - 415s 531ms/step - loss: 0.6960 -
accuracy: 0.7587 - val_loss: 0.6262 - val_accuracy: 0.7848
Epoch 9/25
782/782 [=====] - 418s 534ms/step - loss: 0.6628 -
accuracy: 0.7699 - val_loss: 0.5936 - val_accuracy: 0.7958
Epoch 10/25
782/782 [=====] - 413s 528ms/step - loss: 0.6377 -
accuracy: 0.7791 - val_loss: 0.6802 - val_accuracy: 0.7730
Epoch 11/25
782/782 [=====] - 411s 525ms/step - loss: 0.6248 -
accuracy: 0.7849 - val_loss: 0.6025 - val_accuracy: 0.7940
Epoch 12/25
782/782 [=====] - 405s 518ms/step - loss: 0.6003 -

```

```

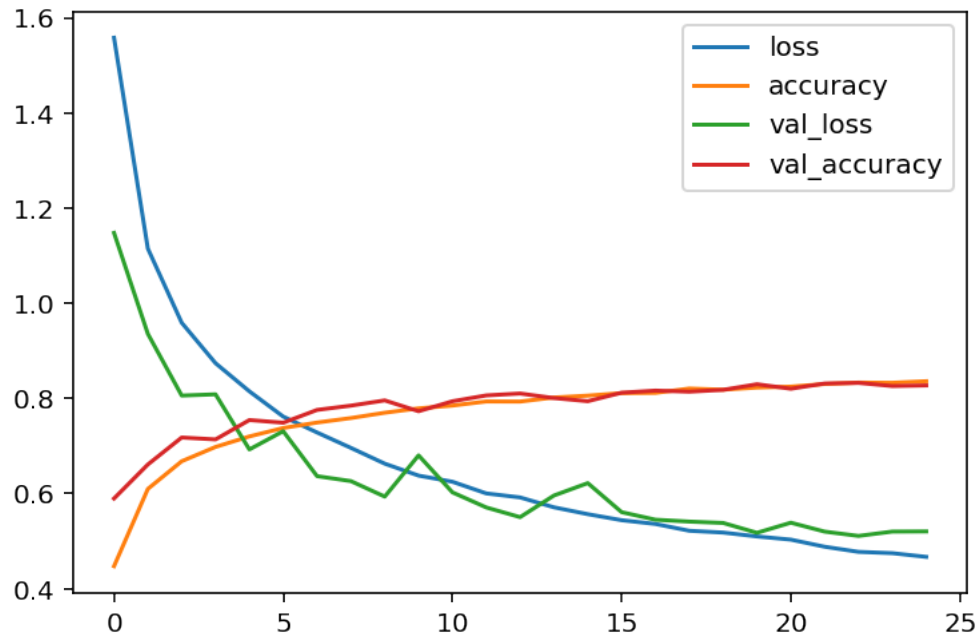
accuracy: 0.7936 - val_loss: 0.5708 - val_accuracy: 0.8063
Epoch 13/25
782/782 [=====] - 408s 522ms/step - loss: 0.5918 -
accuracy: 0.7934 - val_loss: 0.5504 - val_accuracy: 0.8103
Epoch 14/25
782/782 [=====] - 407s 520ms/step - loss: 0.5711 -
accuracy: 0.8019 - val_loss: 0.5959 - val_accuracy: 0.8007
Epoch 15/25
782/782 [=====] - 407s 521ms/step - loss: 0.5567 -
accuracy: 0.8059 - val_loss: 0.6220 - val_accuracy: 0.7941
Epoch 16/25
782/782 [=====] - 408s 522ms/step - loss: 0.5440 -
accuracy: 0.8111 - val_loss: 0.5609 - val_accuracy: 0.8120
Epoch 17/25
782/782 [=====] - 408s 521ms/step - loss: 0.5361 -
accuracy: 0.8115 - val_loss: 0.5451 - val_accuracy: 0.8164
Epoch 18/25
782/782 [=====] - 410s 524ms/step - loss: 0.5218 -
accuracy: 0.8208 - val_loss: 0.5411 - val_accuracy: 0.8141
Epoch 19/25
782/782 [=====] - 401s 512ms/step - loss: 0.5180 -
accuracy: 0.8183 - val_loss: 0.5382 - val_accuracy: 0.8180
Epoch 20/25
782/782 [=====] - 398s 509ms/step - loss: 0.5098 -
accuracy: 0.8227 - val_loss: 0.5175 - val_accuracy: 0.8298
Epoch 21/25
782/782 [=====] - 403s 516ms/step - loss: 0.5032 -
accuracy: 0.8247 - val_loss: 0.5388 - val_accuracy: 0.8203
Epoch 22/25
782/782 [=====] - 408s 521ms/step - loss: 0.4882 -
accuracy: 0.8303 - val_loss: 0.5200 - val_accuracy: 0.8313
Epoch 23/25
782/782 [=====] - 412s 527ms/step - loss: 0.4775 -
accuracy: 0.8333 - val_loss: 0.5109 - val_accuracy: 0.8326
Epoch 24/25
782/782 [=====] - 412s 527ms/step - loss: 0.4747 -
accuracy: 0.8329 - val_loss: 0.5201 - val_accuracy: 0.8260
Epoch 25/25
782/782 [=====] - 419s 536ms/step - loss: 0.4669 -
accuracy: 0.8361 - val_loss: 0.5204 - val_accuracy: 0.8273

```

```
[ ]: model.evaluate(X_test, y_test, verbose=0)
```

```
[ ]: import pandas as pd
import matplotlib.pyplot as plt

pd.DataFrame(history.history).plot()
plt.show()
```

```
[ ]: model.save("model.h5")
print("Saved model to disk")
```

1.2 Results of the Model

Model scored 82.73% accuracy in recognizing pictures from CIFAR-10 data-set.

```
[12]: # load and evaluate a saved model
from numpy import loadtxt
from keras.models import load_model

# load model
model = load_model('model.h5')
# summarize model.
model.summary()
# evaluate the model
score = model.evaluate(X_test, y_test, verbose=0)
print("%s: %.2f%%" % (model.metrics_names[1], score[1]*100))
```

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```
=====
Total params: 393,962
Trainable params: 393,322
Non-trainable params: 640
```

accuracy: 82.73%

2 Generate Documentation

```
[ ]: !wget -nc https://raw.githubusercontent.com/brpy/colab-pdf/master/colab_pdf.py  
from colab_pdf import colab_pdf  
colab_pdf('Cifar10.ipynb')
```

```
[ ]:
```

```
[ ]:
```