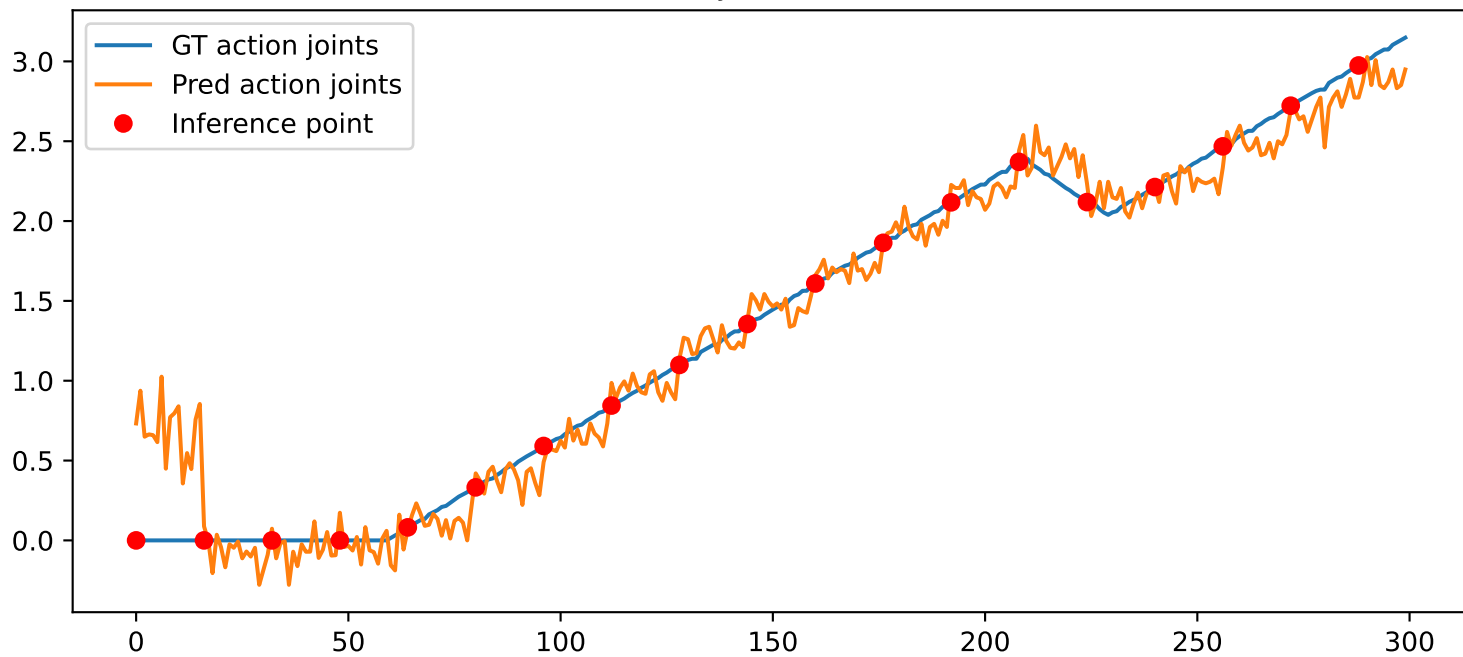


# Trajectory 45 - Evaluation Modalities: left\_wheel, right\_wheel

Joint 0



Joint 1

