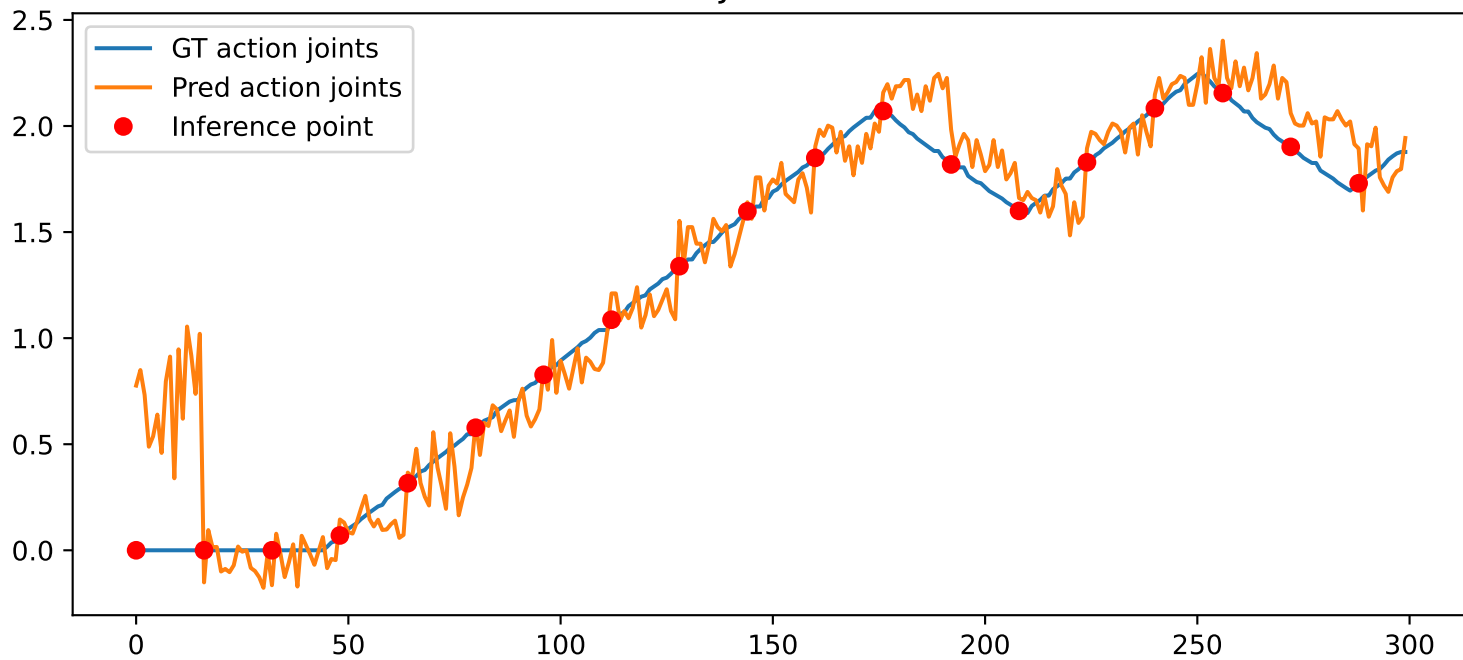


Trajectory 8 - Evaluation Modalities: left_wheel, right_wheel

Joint 0



Joint 1

