

Computational Physics

Lecture 10 – Introduction to Finite Difference Methods

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Slides available from <https://bb.imperial.ac.uk/>

Outline

- 1 Numerical derivatives
- 2 Introduction to solving ODEs
- 3 The Euler method

Goals

By the end of today's lecture, you should

- Be able to calculate the derivative of a function numerically (i.e. from the function's values only, without an analytical expression for the derivative)
- Understand what a finite difference scheme is
- Have a feeling for how to build finite difference schemes from each other
- Be able to identify different ODE problems as either initial value or boundary value
- Be able to implement the simplest finite difference scheme (Euler's method) numerically

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The simplest option: forward difference

The standard definition of the derivative dy/dx or $y'(x)$ is

$$\frac{dy(x)}{dx} \equiv \lim_{h \rightarrow 0} \frac{y(x+h) - y(x)}{h} \equiv \lim_{\Delta x \rightarrow 0} \frac{\Delta y}{\Delta x}. \quad (1)$$

We can implement

$$\tilde{y}'_f(x) \equiv \frac{y(x+h) - y(x)}{h}. \quad (2)$$

directly on a computer, and take h to be pretty small

→ this is a **forward difference scheme (FDS)**

→ example of a **finite difference approximation**

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Note notation: \sim indicates ‘numerical approximation to’

The simplest option: forward difference

$$\tilde{y}'_f(x) \equiv \frac{y(x+h) - y(x)}{h} \quad (3)$$

Problems: we can't take h to zero numerically, for two reasons:

- divide by zero
- finite accuracy of the difference in the numerator

This induces an error in our estimate of $y'(x)$. To see what sort of error, Taylor expand $y(x+h)$ around x :

$$y(x+h) = y(x) + y'(x)h + \frac{y''(x)}{2}h^2 + \dots, \quad (4)$$

Rearrange to get $y'(x)$:

$$y'(x) = \frac{y(x+h) - y(x)}{h} - \frac{y''(x)}{2}h + \dots = \tilde{y}'_f(x) - \mathcal{O}(h). \quad (5)$$

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Rearrange to get $y'(x)$: \Rightarrow **truncation error is $\mathcal{O}(h)$** . Meaning?

$$y'(x) = \frac{y(x+h) - y(x)}{h} - \frac{y''(x)}{2}h + \dots = \tilde{y}'_f(x) - \mathcal{O}(h). \quad (5)$$

Backwards difference scheme

This was the forwards difference scheme:

$$\tilde{y}'_f(x) \equiv \frac{y(x+h) - y(x)}{h}. \quad (6)$$

We can construct an equivalent-order scheme in the opposite (backwards) direction too:

$$\tilde{y}'_b(x) \equiv \frac{y(x) - y(x-h)}{h}. \quad (7)$$

Two different answers with the same order error.

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Two different answers with the same order error. Which to choose?

Central difference scheme

Two answers at the same order...

⇒ we can average them to bootstrap our way up to the next level of accuracy:

$$\tilde{y}'_c(x) \equiv \frac{\tilde{y}'_f(x) + \tilde{y}'_b(x)}{2} = \frac{y(x+h) - y(x-h)}{2h}. \quad (8)$$

This is the **central difference scheme**.

Central difference scheme

$$\tilde{y}'_c(x) \equiv \frac{\tilde{y}'_f(x) + \tilde{y}'_b(x)}{2} = \frac{y(x+h) - y(x-h)}{2h}. \quad (9)$$

To see the order of the error, expand to 3rd order:

$$y(x+h) = y(x) + y'(x)h + \frac{1}{2}y''(x)h^2 + \frac{1}{3!}y'''(x)h^3 + \dots (10)$$

$$y(x-h) = y(x) - y'(x)h + \frac{1}{2}y''(x)h^2 - \frac{1}{3!}y'''(x)h^3 + \dots (11)$$

We can use this to define

$$y(x+h) - y(x-h) = 2y'(x)h + \mathcal{O}(h^3), \quad (12)$$

so

$$y'(x) = \frac{y(x+h) - y(x-h)}{2h} - \mathcal{O}(h^2) \equiv \tilde{y}'_c(x) - \mathcal{O}(h^2), \quad (13)$$

Central difference scheme

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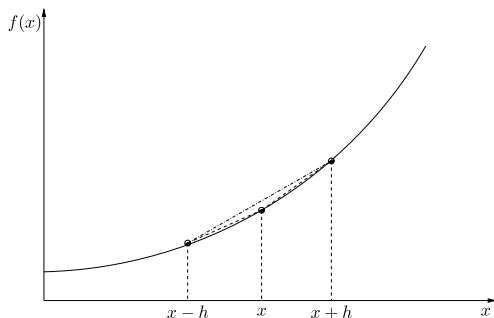
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$$y(x+h) - y(x-h) = 2y'(x)h + \mathcal{O}(h^3), \quad (12)$$

so \implies truncation error is $\mathcal{O}(h^2)$.

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Comparison of schemes



In general, we can build finite difference combinations to get any higher-order derivative to any accuracy

→ requires using y at more values of x

→ \tilde{y}^n requires $n + 1$ points

→ compare with cubic splines: \tilde{y}'' with 4 points

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- 2 Introduction to solving ODEs**
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The problem

Solve

$$\frac{dy}{dx} = f(x, y) \quad (14)$$

for $y(x)$.

Working with a single first order ODE

What we have:

- 1 The derivative function $\frac{dy}{dx} \equiv f(x, y(x))$
- 2 Some sort of boundary condition

What we really care about

- 1 $y(x)$

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Strategy: use $f(x, y)$ to gradually evolve $y(x)$

- 1 Start with some $y(x_s)$
- 2 Calculate the derivative $f(x_s, y(x_s))$
- 3 Use the derivative to extrapolate y some small distance Δx

$$y(x + \Delta x) \approx y(x_s) + \Delta x f(x_s, y(x_s)) \quad (15)$$

(Schematically; this particular setup is Euler's Method)

The (bigger) problem

Solve

$$\frac{d^N y}{dx^N} = f(x, y, y', y'', \dots, y^{(N-1)}) \quad (16)$$

for $y(x)$.

Any N th order ordinary differential equation can be recast as a coupled set of N first order ODEs

$$\begin{aligned} y'(x) &= y_1(x, y) \\ y_1'(x) &= y_2(x, y, y_1) \\ &\dots \\ y_{N-2}'(x) &= y_{N-1}(x, y, y_1, y_2, \dots, y_{N-2}) \\ y_{N-1}'(x) &= y_N \equiv f(x, y, y_1, y_2, \dots, y_{N-2}, y_{N-1}) \end{aligned} \quad (17)$$

OK, try it! (2 mins)

Write the ODE

$$\frac{d^2y}{dx^2} + x \frac{dy}{dx} = y + 1 \quad (18)$$

as a system of first-order ODEs.

Hint: the general way to start is by defining each lower-order derivative as a new variable, i.e. $u \equiv \frac{dy}{dx}$.

So, we can write any set of N first order ODEs (such as from a higher order ODE) as a single first-order vector equation

$$\frac{dy_i}{dx}(x) = f_i(x, \vec{y}(x)) \quad (19)$$

where $i = 0..N - 1$ and each f_i may individually depend on the full vector $\vec{y} = (y_0, y_1, ..y_{N-1})$

We hence have

- 1 a vector of derivatives $(\frac{dy_i}{dx})$, given by
- 2 a vector-valued function (f_i) that depends on
- 3 x directly, and
- 4 x indirectly, via a vector of auxiliary function values $\vec{y}(x)$

What we have:

- 1 The set of functions f_i for all i
- 2 Some sort of boundary conditions

What we really care about

- 1 $y_0(x)$
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Strategy: use the set of f_i s to gradually evolve $\vec{y}(x)$

- 1 Start with some $\vec{y}(x_s)$
- 2 Calculate the vector of x derivatives $\vec{f}(x_s, \vec{y}(x_s))$
- 3 Use each f_i to extrapolate each component y_i of \vec{y} some small distance Δx

$$\vec{y}(x + \Delta x) \approx \vec{y}(x_s) + \Delta x \vec{f}(x_s, \vec{y}(x_s)) \quad (20)$$

(Just like doing single 1st order ODE evolution, but generalising $f(x, y)$ and y to vectors – example is again Euler's method)

Main types of boundary conditions

- 1 $\vec{y}(x_s) = y_{\text{start}}$
 - Function and all derivatives are defined at some x_s
 - All that remains is to evolve the system forwards and/or backwards from x_s to get $\vec{y}(x)$ for all x of interest
 - This is an **Initial Value Problem**

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 - This is an **Initial Value Problem** – covered in Lecture 12
- 2 Some components of \vec{y} may be specified at one x_s , others at one (or more) other value(s) of x
 - Not all components may be specified
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- 3 Some other more complicated auxiliary condition must be satisfied
 - e.g. $n_{\text{cookies}}(\text{today}) > n_{\text{critical}}$ AND
 $n_{\text{cookies}}(\text{yesterday}) - n_{\text{cookies}}(\text{today}) < \text{MaxDailyConsumption}$

These last two are examples of **Boundary Value Problems**

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Simplest method is just to use the forward difference method directly:

$$y(x + \Delta x) \approx y(x_s) + \Delta x f(x_s, y(x_s)) \quad (21)$$

i.e.

$$y(x + h) \approx y(x) + h f(x, y(x)) \quad (22)$$

or (note that subscripts denote *steps* here, not indices distinguishing N coupled DEs):

$$\tilde{y}_{n+1} = \tilde{y}_n + f(x_n, \tilde{y}_n) h. \quad (23)$$

Some examples of Euler method in action: Jupyter notebook

Housekeeping

- Problem Sheet: combined for Lecs 10–15. Mostly complementary to Project, for extending your understanding, less about preparing you for it (i.e. unlike previous Problem Sheets).
- Reminder: get started on **Assignment** nice and early – due in on **Nov 12**
- Labs continue tomorrow at 9am. Come and ask questions about the Problem Sheets or Assignment.
- Next Tuesday: Evaluating Finite Difference Methods (**bring laptops + install Jupyter!**)