# Besag2 model for weighted spatial effects

#### Parametrization

The besag2 model is an extention to the besag model. Let the random vector  $\mathbf{z} = (x_1, \dots, x_n)$  be the besag model, then the besag2 is the following extentions

$$\mathbf{x} = (a\mathbf{z}, \mathbf{z}/a)$$

where a > 0 is an additional hyperparameter and  $\dim(\mathbf{x}) = 2n$ , and  $\mathbf{z}$  is the *same* (up to tiny additive noise) random vector.

## Hyperparameters

This model has two hyperparameters  $\theta = (\theta_1, \theta_2)$ . The precision parameter  $\tau$  is represented as

$$\theta_1 = \log \tau$$

and the prior is defined on  $\theta_1$ .

The weight-parameter a is represented as

$$\theta_2 = \log a$$

and the prior is defined on  $\theta_2$ .

# Specification

The besag2 model is specified inside the f() function as

The precision is the precision defining how equal the two copies of z is. The neighbourhood structure of x is passed to the program through the graph.file argument. The structure of this file is described below.

Note that the besag2 model has dimension 2n, where n is the size of the graph.

### Hyperparameter spesification and default values

#### hyper

```
theta1
```

```
name log precision
short.name prec
prior loggamma
param 1 5e-05
initial 4
fixed FALSE
to.theta function(x) log(x)
from.theta function(x) exp(x)
theta2
name scaling parameter
```

```
short.name a
        prior loggamma
        param 10 10
        initial 0
        fixed FALSE
        to.theta function(x) log(x)
        from.theta function(x) exp(x)
constr FALSE
nrow.ncol FALSE
augmented FALSE
aug.factor 1
aug.constr 12
n.div.by 2
n.required TRUE
set.default.values TRUE
pdf besag2
```

#### Structure of the graph file

We describe the required format for the graph file using a small example. Let the file gra.dat, relative to a small graph of only 5 elements, be

```
5
1 1 2
2 2 1 3
3 3 2 4 5
4 1 3
5 1 3
```

Line 1 declares the total number of nodes in the graph (5), then, in lines 2-6 each node is described. For example, line 4 states that node 3 has 4 neighbours and these are nodes 2, 4 and 5.

The graph file can either have nodes indexed from 1 to n, or from 0 to n-1. Note that in the latter case, node i seen from R corresponds to node i-1 in the 0-indexed graph.

#### Example

This is a simulated example.

```
data(Oral)
g = system.file("demodata/germany.graph", package="INLA")
## use data Oral to estimate a spatial field in order to simulate a
## 'realistic' dataset.
formula = Y ~ f(region, model="bym", graph.file=g)
result = inla(formula, data = Oral, family = "poisson", E = E)
x = result$summary.random$region$mean
```

```
m = length(x)/2

## simulate two new datasets. 'a' is the weighting between the

## log.rel.risk:
a = 2

xx = x[1:n]+1

x = c(a*xx, xx/a)

E = c(Oral$E, Oral$E)

N = 2*n

y = rpois(N, lambda = E*exp(x))

## model='besag2' defines a model with length N = 2*graph->n, the

## first half is weighted with 'a' the other half is weighted with

## 1/a. here there is no unstructed terms.
i = 1:N

formula = y ~ f(i, model="besag2", graph.file=g) -1

r = inla(formula, family = "poisson", data = data.frame(E,y,i), E=E, verbose=TRUE)
```

#### Notes

The besag2 model has default constr=FALSE, and constr=TRUE does not make sense.

The model is modified accordingly is the graph has more than one connected components.