Generic 0 model

Parametrization

The Type 0 generic model implements the following precision matrix

$$\mathbf{Q} = \tau \mathbf{C}$$

where \mathbf{C} is the structure matrix.

Hyperparameters

The precision parameters of the generic model is represented as

$$\theta = \log(\tau)$$

and prior is assigned to θ

Specification

The generic 0 models is specified inside the f() function as

where <Cmat> can be given in two different ways:

- a list of type Cmatrix = list(i = c(), j = c(), Cij = c()), where i, j and Cij are vectors of the non-zero elements of C. Note that i and j start from 1, and only the upper or lower part of C has to be given.
- the name of a file giving the structure matrix. The file should have the following format

$$i$$
 j \mathbf{C}_{ij}

where i and j are the row and column index and C_{ij} is the corresponding element of the precision matrix. Only the non-zero elements of the precision matrix need to be stored in the file. **NOTE:** the indexes for i and j must start from 0, as this matrix is passed directly into the inla-program.

See the following example for an application

Example

In the example below we define a RW1 model first using the generic0 model and this using the rw1 model.

```
#simulate data
n=50
z=seq(0,6,length.out=n)
y=sin(z)+rnorm(n,mean=0,sd=0.5)
data=data.frame(y=y,z=z)
#specify Cmatrix
```

```
i=c(1:n,1:(n-1))
j=c(1:n,2:n)
Cij=c(1,rep(2,n-2),1,rep(-1,n-1))
#pass the C matrix as a list
#note that for the generic0 model constraints and diagonal have to be defined by the user
formula= y~f(z,model="generic0",Cmatrix=list(i = i, j = j, Cij = Cij),
             rankdef=1,constr=TRUE,diagonal=1e-05)
result=inla(formula,data=data,family="gaussian")
#pass the C matrix as a file
file.name="Cmatrix.dat"
write.table(cbind(i-1,j-1,Cij),file=file.name,col.name=F,row.name=F)
formula1= y~f(z,model="generic0",Cmatrix=file.name,rankdef=1,rankdef=1,constr=TRUE,diagonal=16
result1=inla(formula1,data=data,family="gaussian")
#this is the same model defined using the rw1 model
formula2=y~f(z,model="rw1")
result2=inla(formula2,data=data,family="gaussian")
```

Notes

None