Generic 1 model

Parametrization

The Type 1 generic model implements the following precision matrix

$$\mathbf{Q} = \tau (\mathbf{I} - \frac{\beta}{\lambda_{max}} \mathbf{C})$$

where **C** is the structure matrix. The parameter λ_{max} is the maximum eigenvalue of **C**, which allows β to be in the range $\beta \in [0, 1)$

Hyperparameters

The two parameters of the generic1 model are represented as

$$\theta_1 = \log(\tau)$$
 $\theta_2 = \log t(\beta)$

and priors are assigned to (θ_1, θ_2)

Specification

The generic1 model is specified inside the f() function as

where <Cmat> can be given in two different ways:

- a dense matrix or a sparse-matrix defined be Matrix::sparseMatrix().
- the name of a file giving the structure matrix. The file should have the following format

$$i \quad j \quad \mathbf{C}_{ij}$$

where i and j are the row and column index and C_{ij} is the corresponding element of the precision matrix. Only the non-zero elements of the precision matrix need to be stored in the file.

Example

```
n = 100
## build a structure matrix
Cm = matrix(runif(n^2,min=-1,max=1),n,n)
diag(Cm) = 0
Cm = 0.5*(Cm + t(Cm))
lambda.max = max(eigen(Cm)$values)

## define the precision matrix
beta = 0.9
Q = diag(rep(1,n)) - beta/lambda.max * Cm
Sigma = solve(Q)
```

```
#simulate data
require(mvtnorm)
sd = 0.001
z = rnorm(n)
eta = rmvnorm(n=1, sigma = Sigma)
y = c(eta) + sd*rnorm(n) + z
idx = 1:n
d = list(y=y,idx=idx,z=z)
## Alternative 1
## print the file containing the C matrix
file = "Cmatrix.dat"
cat("",file=file, append = FALSE)
for(i in 1:n)
{
   j = i
   cat(i, j, Cm[i,j], "\n", sep = " ", file=file, append=TRUE)
   if (i < n)
       for(j in (i+1):n)
           cat(i, j, Cm[i,j], "\n", sep = " ", file=file, append=TRUE)
}
formula = y ~ f(idx, model = "generic1", Cmatrix = file,
               initial=c(0,0),fixed=c(F,F)) + z
## Alternative 2
## formula = y ~ f(idx, model = "generic1", Cmatrix = Cm,
##
                  initial=c(0,0), fixed=c(F,F)) + z
## Alternative 3
## formula = y ~ f(idx, model = "generic1", Cmatrix = as(Cm, "dgTMatrix"),
                  initial=c(0,0),fixed=c(F,F)) + z
result = inla(formula, data=d,family="gaussian",
             control.data = list(initial = log(1/sd^2), fixed=TRUE),
             verbose=T, keep=T)
```

Notes

None