

UTS SAFE WORK METHOD STATEMENT (SWMS)

1. FACULTY/SUBJECT			
Faculty/Subject title		41013 Industrial Robotics	
Subject supervisor/coordinator		Gavin Paul	
SWMS prepared by		Hugh Radvan, Cristian Corso, Arthur Demasi	
2. WORK ACTIVITY DESCRIPTION			
<p>Describe the work activity E.g. Operating, Handling, Using..</p> <p>Include names of hazardous equipment, substances or materials used, and any quantities and concentrations of substance(s) or reaction products.</p>		<ul style="list-style-type: none"> Testing the operation of the UR3 and Dobot CR5 robot arm Handling of the robot and associated tools (teach pendant) and testing commands/operations. Use UR3 and CR5 to handle objects, including: <ul style="list-style-type: none"> Pints (glass/plastic cups) Taps (beer taps) Glass rinsing equipment (CR5 only) To test incorporation of robots with light barriers and collision detection systems 	
3. HAZARDS: Choose those hazard types that will need to have control measures in Section 4			
Work Environment <ul style="list-style-type: none"> Working in Remote Locations Working Outdoors/fieldwork Clinical/Industrial setting Poor ventilation/Air quality Temperature extremes Working at Height Slip/Trip/Fall hazards 	Plant <ul style="list-style-type: none"> Noise Vibration Working with compressed air Lifts Hoists or Cranes Moving parts (Crushing, friction, cut, stab, shear hazards) Pressure Vessels or Boilers 	Chemical <ul style="list-style-type: none"> Hazardous Chemicals use Skin/eye irritant Sensitiser Mutagen Carcinogen Toxic to reproduction Aquatic toxicity Toxic Corrosive Dangerous when wet 	Ergonomic/Manual Handling <ul style="list-style-type: none"> Repetitive or awkward movements Lifting heavy objects Over reaching Working above shoulder or below knee height Poor workstation set up
Electrical <ul style="list-style-type: none"> Plug in equipment High voltage Exposed wiring Exposed conductors 	Radiation <ul style="list-style-type: none"> Ionising Radiation Non-ionising radiation (Lasers, Microwaves, Ultraviolet light) 	Biological <ul style="list-style-type: none"> Sharps/Needles Cytotoxins Pathogens/infectious materials Infectious materials Communicable diseases Animal/insects Work with fungi/bact/viruses 	Psychosocial <ul style="list-style-type: none"> Aggressive or violent clients/students Working in isolation Working with timeframes Staffing issues
4. CONTROLS MEASURES: Choose those that apply for hazards identified			
Eliminate/Isolate/Substitute / Engineering Controls <ul style="list-style-type: none"> Remove hazard Restrict access Redesign equipment Guarding / Barriers / Fume Cupboard / exhaust Biosafety cabinet Use safer materials/substances Ventilation Regular maintenance of equipment Redesign of workspace / workflow 	Admin specific: Licenses/permits Work Methods <ul style="list-style-type: none"> Training Information or Instruction Licensing or certification of operators Test and tag electrical equipment Restricted access Regular breaks Task rotation Work in pairs Document Chemical risk assessment Ladder / Sling register 	Emergency Response Systems <ul style="list-style-type: none"> First aid kit Chemical spill kit Safety shower Eye wash station Emergency Stop button Remote Communication Mechanism 	
Other controls not listed			

5. PPE REQUIRED (Tick those that apply) ☒



EYE PROTECTION

☐


HEARING PROTECTION

☐


CLOSED-IN FOOTWEAR MUST BE WORN

☒


HAND PROTECTION

☐


FACE SHIELD

☐


PROTECTIVE CLOTHING

☐


RESPIRATORY PROTECTION

☐


LONG HAIR MUST BE CONTAINED

☐


HEAD PROTECTION

☐

6. EMERGENCY EQUIPMENT



EMERGENCY SHOWER

☐


EMERGENCY SPILL KIT INSIDE

☐


EMERGENCY EYEWASH

☐

7. WORK ACTIVITY STEPS

BEFORE YOU START:

- Pre-plan the objectives of the workactivity
- Familiarise myself with UR3 and Dobot CR5 operation
- Construct and verify required code
- Complete nesssasary safety indcutions

STEPS IN WORK ACTIVITY:

1. Connect to UR3/CR5
2. Verify setup is correct with lab supervisor
3. Clear area around the robots and aleart others of impending work with robots
4. Turn on/activate robots
5. Run code to test movement and preform desired action (simulation of the automated beer pouring/serving/cleaning action)
6. Turn off robots and return equipment to desginated sotaage area

EMERGENCY PROCEDURES:

- Press emergency button
- Notify security or dial 6 using the UTS internal phone
- First aid kit incase of glass/laceration injury

TRAINING REQUIRED:

- CB11 mechatronics lab safety induction

8. SIGN OFF

PREPARED BY:

LAB SUPERVISOR

DATE: 13/10/23

NAME: HUGH RADVAN, CRISTIAN CORSO, ARTHUR DEMASI

NAME: MICHAEL LEE

REVIEW DATE: _____

