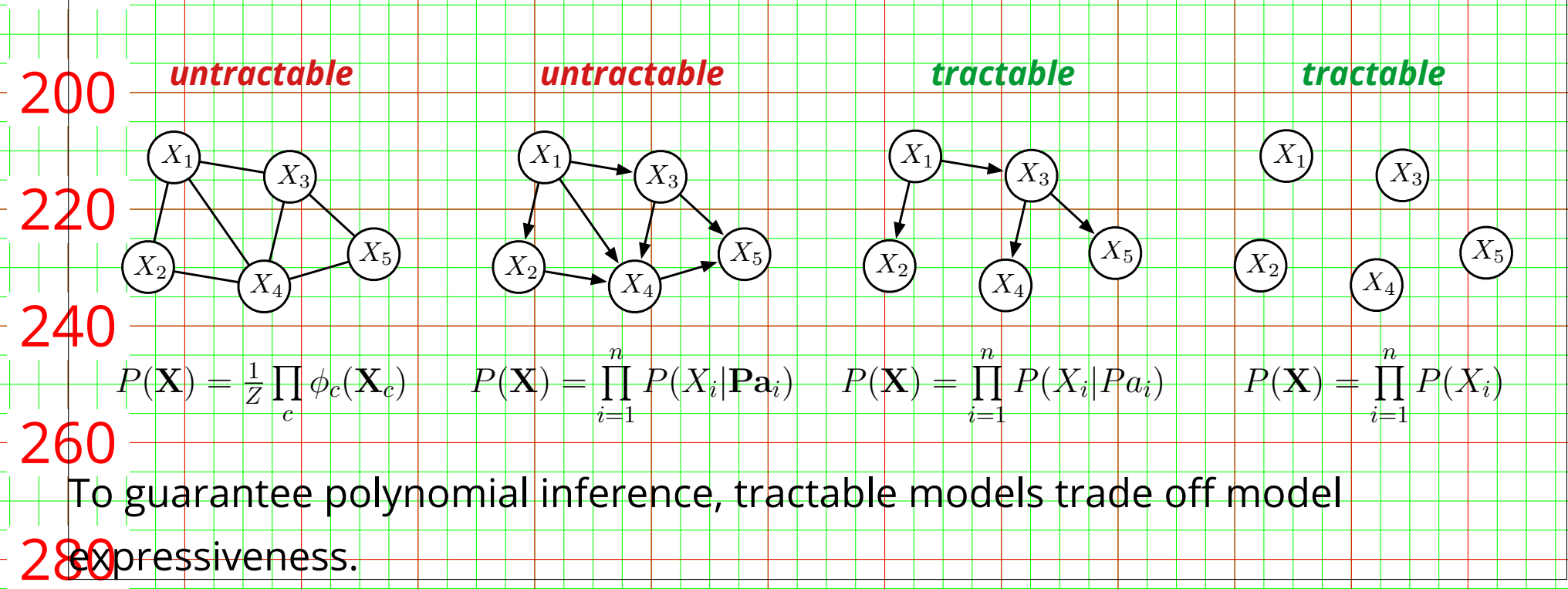


Simplifying, Regularizing and Strengthening Sum-Product Network Structure Learning

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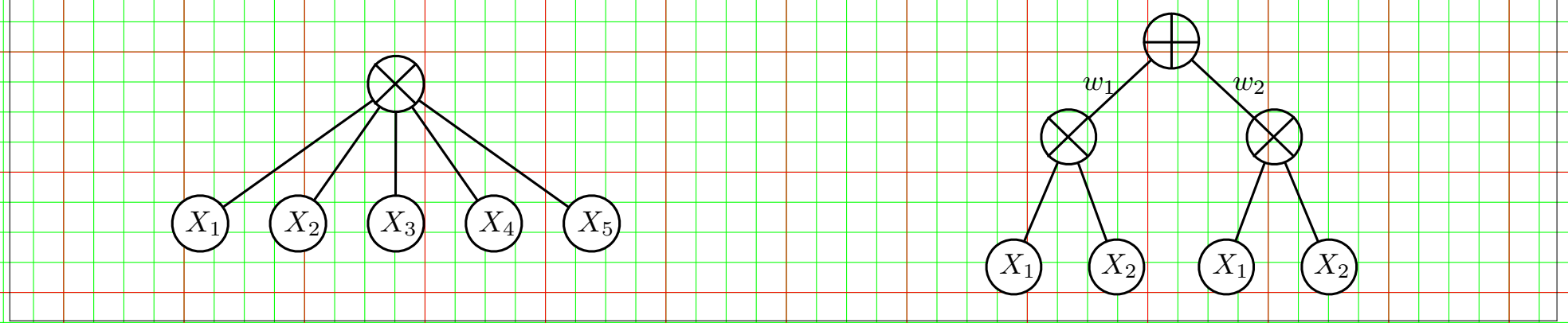
Sum-Product Networks and Tractable Models

Probabilistic Graphical Models (PGMs) provide a tool to compactly represent joint probability distributions $P(\mathbf{X})$. However, **inference**, the main task one may want to perform on a PGM, is generally **untractable**.



Sum-Product Networks (SPNs) are DAGs *compiling* a pdf $P(\mathbf{X})$ into a **deep** architecture of **sum** and **product** nodes over univariate distributions X_1, \dots, X_n as leaves. The parameters of the network are the weights w_{ij} associated to sum nodes children edges.

Product nodes define factorizations over independent vars, sum nodes mixtures. Products over nodes with different scopes (*decomposability*) and sums over nodes with same scopes (*completeness*) guarantee modeling a pdf (*validity*).



Bottom-up evaluation of the network:
 $S_{X_i}(x_j) = P(X_i = x_j)$
 $S_{\oplus}(\mathbf{x}) = \sum_{i \in \text{ch}(\oplus)} w_i S_i(\mathbf{x})$ $S_{\times}(\mathbf{x}) = \prod_{i \in \text{ch}(\times)} S_i(\mathbf{x})$

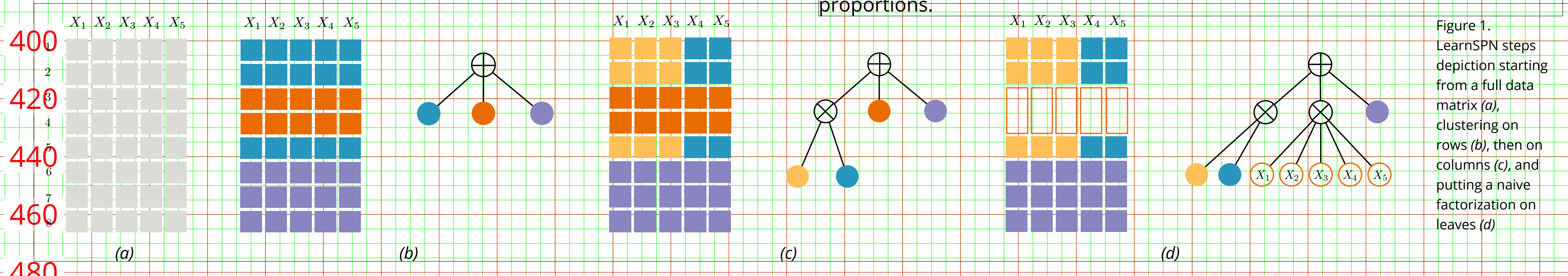
Inferences linear in the **size of the network** (# edges):
 $\oplus Z = S(\ast)$ (all leaves output 1)
 $\oplus P(\mathbf{e}) = S(\mathbf{e})/S(\ast)$
 $\oplus P(\mathbf{q}|\mathbf{e}) = \frac{P(\mathbf{q}, \mathbf{e})}{P(\mathbf{e})} = \frac{S(\mathbf{q}, \mathbf{e})}{S(\mathbf{e})}$
 $\oplus MPE(\mathbf{q}, \mathbf{e}) = \max_{\mathbf{q}} P(\mathbf{q}, \mathbf{e}) = S^{\max}(\mathbf{e})$, turning sum nodes into max nodes

The **depth of the network** (# layers) determines expressive efficiency [5, 9]

How and why to perform structure learning

SPN structure learning is a constraint-based search. Main ideas: to discover hidden variables for sum nodes and independencies for product nodes by applying some form of clustering along matrix axis. Different variations: using K-Means on features [1]; merging features bottom-up with IB heuristics [7]; **LearnSPN** [2] is the first principled top-down greedy algorithm.

LearnSPN builds a tree-like SPN by recursively split the data matrix. It splits columns in pairs by a greedy **G Test** based procedure with threshold ρ : $G(X_i, X_j) = 2 \sum_{x_i \sim X_i} \sum_{x_j \sim X_j} c(x_i, x_j) \cdot \log \frac{c(x_i, x_j) \cdot |T|}{c(x_i) \cdot c(x_j)}$ (Figure 1.c); it clusters instances in $|C|$ sets with **online Hard-EM** (Figure 1.b) with cluster number penalty λ : $Pr(\mathbf{X}) = \sum_{C_i \in C} \prod_{X_j \in X} Pr(X_j, C_i)$. Weights are the cluster proportions.



If there are less than m instances, it puts a **naive factorization** over leaves (Figure 1.d). For each univariate distribution it gets its **ML estimation** smoothed by α . LearnSPN hyperparameter space is thus: $\{\rho, \lambda, m, \alpha\}$.

The state-of-the-art, in terms of test likelihood, is **ID-SPN**: it turns LearnSPN in log-likelihood guided expansion of sub-networks approximated by Arithmetic Circuits [8]. However it is overparametrized, and slower.

Tractability is guaranteed if the network size is polynomial in # vars. **Structure quality matters** as much as likelihood. comparing network sizes is more solid than comparing inference times.

LearnSPN is too greedy and the resulting SPNs are overcomplex networks that may not generalize well. **Structure quality desiderata**: smaller but accurate, deeper but not wider, SPNs.

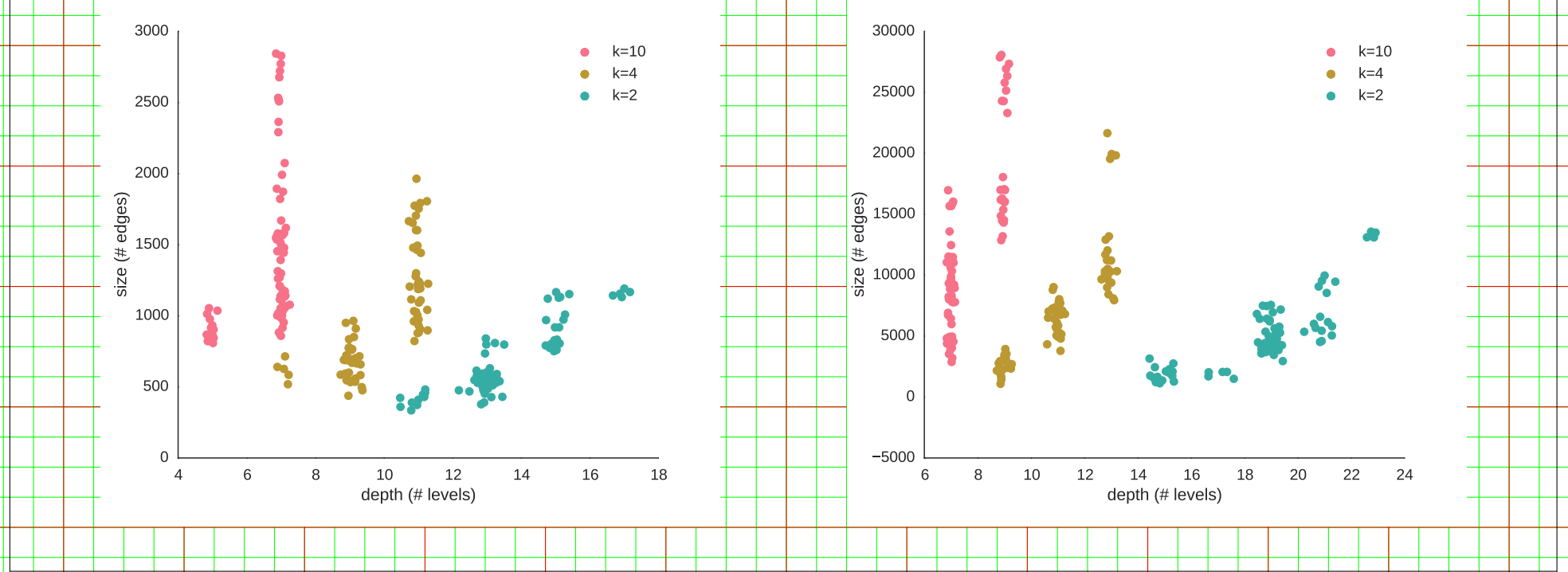
Simplifying by limiting node splits

LearnSPN performs two interleaved **greedy hierarchical** divisive **clustering** processes (co-clustering). Each process benefits from the other one improvements/highly suffers from other's mistakes.

Idea: slowing down the processes by limiting the number of nodes to split into. SPN-B, variant of LearnSPN that uses EM for mixture modeling with $k = 2$ to cluster rows.

- Pros:
- ⊕ not committing to complex structures too early
 - ⊕ same expressive power: successive splits allow for more node children
 - ⊕ reducing node out fan increases the depth
 - ⊕ same accuracy, smaller networks

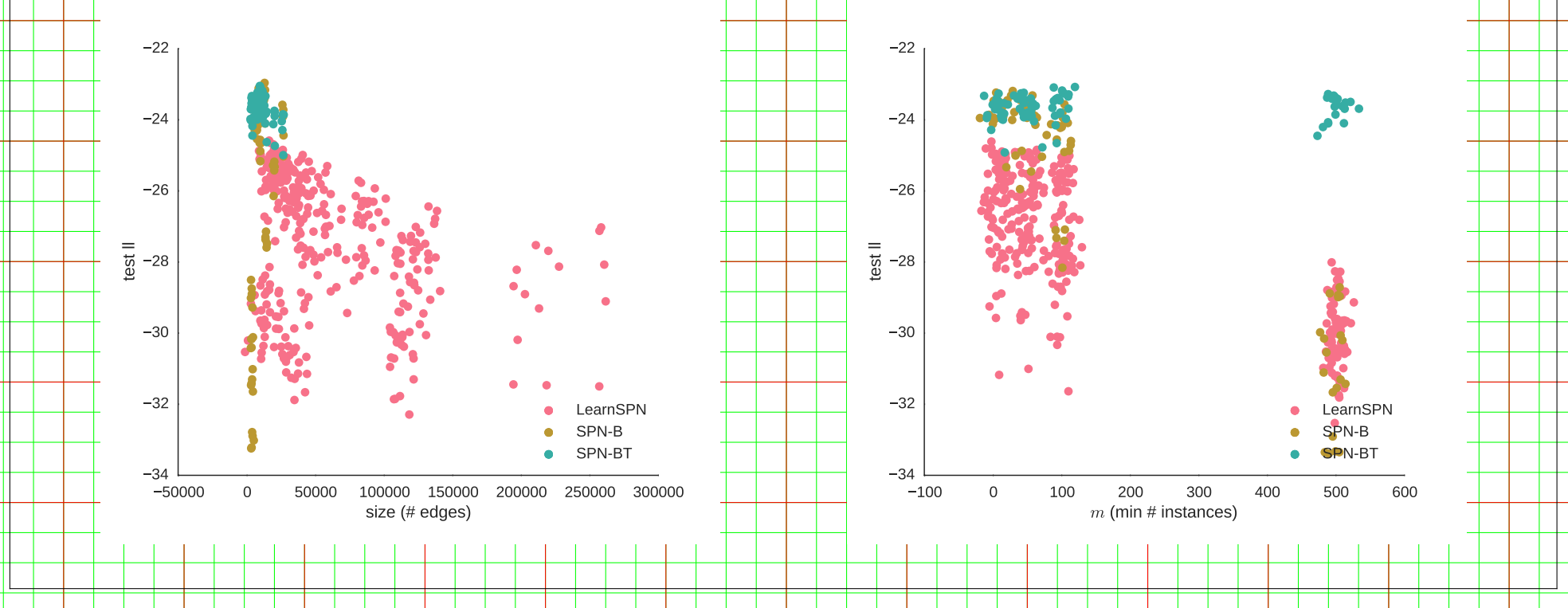
By increasingly limiting the max number of allowed splits the depth of the structures increases. It is also worth noting how the size of the network decreases. Other



Regularizing by introducing tree distributions as leaves

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By increasingly limiting the max number of allowed splits the depth of the structures increases. It is also worth noting how the size of the network decreases. Other



Strengthening by model averaging

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Experiments

Classical setting for **generative** graphical models structure learning [2]:

- ⊕ 19 binary datasets from classification, recommendation, frequent pattern mining...[4] [3]
- ⊕ Training 75% Validation 10% Test 15% splits (no cv)

- Comparing both accuracy and structure quality:
- ⊕ **average log-likelihood** on predicting test instances
 - ⊕ networks sizes (# edges)
 - ⊕ network depth (# alternated type layers)

Comparing the state-of-the-art, LearnSPN, ID-SPN and MT [6], against our variations:

- ⊕ SPN-B using only Binary splits
- ⊕ SPN-BT with Binary splits and Trees as leaves
- ⊕ SPN-BB combining Binary splits and Bagging
- ⊕ SPN-BTB including all variants

Model selection via **grid search** in the same parameter space:

- ⊕ $\lambda \in \{0.2, 0.4, 0.6, 0.8\}$, ⊕ $m \in \{1, 50, 100, 500\}$,
- ⊕ $\rho \in \{5, 10, 15, 20\}$, ⊕ $\alpha \in \{0.1, 0.2, 0.5, 1.0, 2.0\}$.

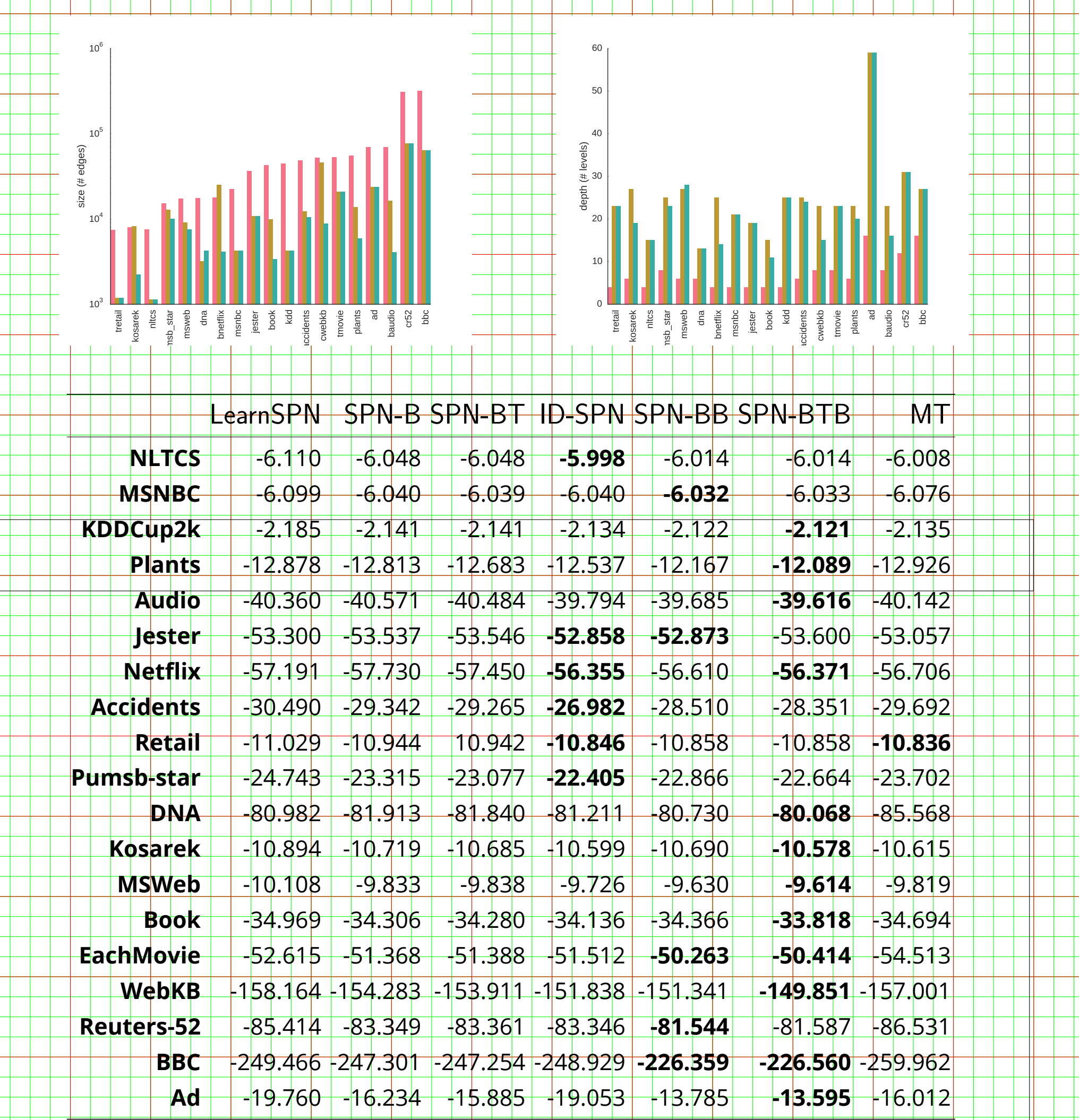


Table : Average test log likelihoods for all algorithms. In bold the best values after a Wilcoxon signed rank test with p -value of 0.05.

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