#### **Dynamic Memory**

# Using new, delete and delete[]

Use new to create an object on the heap and get its address (new evaluates to the address of the newly-created object). Use delete on a heap object's address to deallocate it and free up memory.

- ① Using delete on a nullptr does nothing.

  A dynamic object's lifetime begins when it's created via new, and its lifetime ends (and its dtor is called) only when you use delete on its address.
- Array elements are constructed from left-to-right (and are destroyed in the reverse order). Class members are initialized in the order that they're declared in the class body.

Dynamic arrays are created with new (which yields a pointer to its first element) and deleted by using delete[] on the address of its first element. (Note that you can't delete individual elements.)

struct X {···}; class Y {···};

new int; // does nothing (atomic type)
new Y; // calls default Y ctor

int\* ptr1 = new int(); // \*ptr1 == 0
int\* ptr2 = new int{}; // \*ptr2 == 0
Y\* ptr3 = new Y{}; // calls default ctor

// default initialization

// value initialization

- While dynamic arrays are still fixed-size, they're allowed to have their sizes determined at runtime, unlike non-dynamic arrays (which must have compile-time constant sizes).
- Deleting a dynamic array through a pointer with different static/dynamic types causes U.B.
- A If a non-dynamic class/struct object or array has dynamic sub-objects, the sub-objects can outlive the compound object they're part of.

	Storage Duration	Destructor Runs When:	Managed By:	Grows
Stack Memory	Local (automatic)	Scope {} ends	Compiler	✓ Yes
Heap Memory Dynamic		Manually Deleted	Programmer	✓ Yes
Static Memory	Static	Program terminates	Compiler	× No

#### **Memory Management Errors**

The following mistakes cause undefined behavior:

- 1. *Use-after-free*: dereferencing a pointer after using delete on it (delete doesn't kill the pointer itself).
- Bad delete: Using delete on a dynamic array or nondynamic object, or using delete[] on anything other than the address of a dynamic array's first element.
- 3. *Double free*: Using delete on an address twice. Forgetting to delete a heap object causes a **memory leak**, essentially "wasted" memory. Memory leaks are often caused by losing a dynamic object's address.

### RAII (Resource Aquisition Is Initialization)

**RAII** (or scope-bound resource management) is a strategy to prevent memory leaks by wrapping a dynamic object in a class. To create an RAII class:

- 1. Make the class's ctor allocate a dynamic object
- 2. Keep track of the object via a private pointer.
- 3. Make the class's dtor deallocate the object This ties a dynamic object's lifetime to the scope of the non-dynamic class object that "holds" it.

```
int* func(int x) {
   int *y = new int(x);
   y = new int[x]; // Orphaned mem.
   return y;
} // This function leaks memory
int main() {
   int *a = func(5);
   int *b = a;
   delete b; // Wrong delete
   delete[] a; // double delete
   cout << a[2]; // use-after-free
} // We still have a memory leak...</pre>
```

```
template <typename T>
class UnsortedSet {
private:
    T *arr; // ptr to underlying array
    int cap; // array's size limit
    int N; // current size of array
public:
    UnsortedSet() // ctor allocates arr
    : arr(new T[10]), cap(50), N(0) {
    "UnsortedSet() { deLete[] arr; }
}; // dtor deallocates arr
```

⚠ The destructor for an RAII container only cleans up resources allocated for the container itself, not the memory used by dynamic objects that were stored in the container. If you have nested classes that manage dynamic memory, you need to implement custom destructors for all of them (and if you have a container of heap pointers, you can't expect the container to clean them up).

### Deep Copies and the Big Three

# Shallow and Deep Copies

A *deep copy* of a class-type object is a copy whose data members are separate from the original's. A *shallow copy* is a copy whose data members are "shared" with the original object's. E.g. if you create a shallow copy of an <code>UnsortedSet</code>, both objects will have pointers to the *same* dynamic array. The concept only applies to classes that have "owning" pointers/references.

▲ Compiler-generated copy constructors and assignment = operators create shallow copies, so you must implement custom versions of them for classes that have pointers to dynamic resources.

```
Ex: Copy Ctor Implementation

class IntSet { ...

// 1. Initialize copy's stack members

IntSet(const IntSet& og)

| : cap(og.cap), N(og.size()) {

// 2. Create a new, separate dynamic array

| arr = new int[og.size()];

| for (int i = 0; i < og.size(); ++i) {

| | arr[i] = og.ar[i];

| | } // 3. Copy elements to new array

| }

};
```

```
Ex: Assignment Operator Overload

IntSet& operator=(const IntSet& og) {
    if (this == &og) { return *this; }
    delete[] this=>elts;
    this=>cap = og.cap;
    this=>N = og.size();
    this=>elts = new int[og.size()];
    for (int i = 0; i < og.size(); ++i) {
        | this=>elts[i] = og.elts[i];
    }
    return *this;
}
```

• You can explicitly call a copy constructor by simply passing a pre-existing class object to it. Also, if you initialize a new class object from an existing class object using the assignment operator, that actually makes an implicit call to the class's copy constructor.

# Destructors and Polymorphism (Virtual Destructors)

If you try to delete a derived-class object by calling <code>delete</code> on a base-class pointer to the object, the base class needs to have a <code>virtual</code> destructor defined or else undefined behavior will occur. The compiler-generated default destructor is not <code>virtual</code>, so it's best practice to define a custom virtual destructor for polymorphic classes (i.e., classes that make use of inheritance).

- ⚠ If you call delete on an object whose static type and dynamic type are different, the static type must be a base class of the dynamic type (or U.B. will occur even with a virtual destructor).
- You can prevent derived class objects from being deleted through base-class pointers by declaring the base class destructor protected and non-virtual.

# The Rule of Three

A class's <u>destructor</u>, <u>copy constructor</u>, and <u>assignment operator</u> make up the <u>Big Three</u>. <u>Rule of Three</u>: a class that needs a custom version of one of the Big Three usually needs custom versions of the other two (generally, this describes classes that manage dynamic memory). Not all classes with pointer data members need the Big Three. Ex: Linked List iterators store internal Node\* pointers, but they don't need the Big Three because the List dtor is responsible for managing the nodes. Generally, classes that manage dynamic memory need the Big Three.

#### Linked Lists

### The Linked List Interface (Single and Double)

A *linked list* is a container that stores its elements non-contiguously in memory; its elements are represented as distinct "nodes" that are linked together via pointers. If nodes are linked in one direction, the list is singly-linked, and if nodes are linked in both directions, the list is doubly-linked.

```
12 \longrightarrow 99 \longrightarrow 37 \longrightarrow \times \longrightarrow 12 \longrightarrow 98 \longrightarrow 37 \longrightarrow \times
```

**1** Since there's no need to maintain contiguity, inserting/removing nodes is O(1) at any position in a list, as the only adjustment you need to make is re-pointing the previous node's next pointer (and the following node's prev pointer in a doubly-linked list) instead of shifting every element. This does mean lists have O(n) instead of O(1) indexing, though.

### **Linked List Operations**

#### Recursion

bool SameTree(TreeNode\* p,TreeNode\* q) {
 if (!p || !q) {return (!p == !q);}
 if (p->val != q->val) {return false;}
 return SameTree(p->L, q->L)
 && SameTree(p->R, q->R);
} // check if two trees are identical

void func(int n) {
 for (int i = 0; i < n; ++i) func(i);
} // Yes, this is tree-recursive</pre>

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Inorder Traversal (LPR)

Preorder Traversal (PLR)

Postorder Traversal (LRP)

51 5 1 8 43 87 52 83

1 8 43 5 83 52 87 51

### Properties and Types of Recursion

A *recursive function* is a function that is defined in terms of itself (i.e., that calls itself). Recursive functions break problems down into two types of "cases":

- Base cases, problems that can be solved without recursion (and act as the end condition for a recursive loop). Ex: 0 and 1 for a factorial function.
- Recursive cases, which the function breaks down into simpler sub-problems and then passes to itself (until the problem has been reduced to base cases).

the problem has been reduced to base car. There are three types of recursive functions:

- Linear recursive: functions that make no more than one call to themselves for each invocation.
- 2. *Tail recursive*: a type of linear recursive function whose final instruction is the recursive call.
- Tree recursive: functions that can make multiple recursive calls to themselves in one stack frame (note: they're not limited to tree data structures).
- ▲ A recursive call being on the last line of a function does NOT guarantee that the function is tail recursive—the recursive call must be the last *instruction* executed by the function.

```
int factorial(int n) {
  return (n <= 1) ? 1 : n * factorial(n - 1);
} /* This is NOT tail-recursive because the last instruction the function executes is
  multiplying the recursive result by n, not the recursive call itself. */</pre>
```

### **Memory Usage of Recursive Functions**

*Non-tail* linear recursive functions allocate an additional stack frame with each recursive call. However, the compiler can optimize a tail recursive function to reuse the same stack frame, which means that tail-recursive functions can be optimized to use a constant number of stack frames.

⚠ The total number of recursive calls a function makes to itself does not indicate its space complexity, since not all stack frames have to exist at the same time. Instead, look at the number of return statements until the base case. For example, a recursive algorithm to traverse a balanced BST of height h uses a maximum of O(h) space—not O(2h) space—at any given time.

### Structural Recursion

Structural recursion is when an abstract data type is defined in terms of itself. The Node structs of a linked list are one example: each Node contains a pointer to another Node. Recursive structures have base cases and recursive cases just like recursive functions do: for a linked list, the "base case" is an empty list, and the recursive cases are non-empty lists.

Recursion vs Iteration (and Converting Between Them)

# Binary Search Trees and Maps

### **Binary Search Trees**

A *binary tree* is a tree data structure where each *node* points to at most 2 children. A *binary search tree* is a binary tree where, for *any* node, every node in the left subtree has a lower value and every node in the right subtree has a greater value. (An empty tree is also a BST.)

A BST is *balanced* if the heights of the left and right subtrees at any node differ by no more than 1, so the height of a balanced BST with n nodes is roughly  $\log_2(n)$ . A *leaf* of a BST is a childless node.

# **BST Traversal**

There are multiple ways to traverse a binary tree:

- Inorder traversal: recursively process the left subtree → process the head (current) node → recursively process the right subtree.
   1 | 5 | 8 | 43 | 51 | 52 | 83 | 87
- Preorder traversal: process the head (current) node → recursively process the left subtree → recursively process the right subtree.
- 3. *Postorder traversal*: recursively process the *left* subtree → recursively process the *right* subtree. → process the *head*.
- 1 Inorder traversal of a BST visits nodes by ascending value.

```
void preOrder(Node* p) {
   if (!p) return;
   process(p->val);
   preOrder(p->left);
   preOrder(p->left);
   preOrder(p->left);
   preOrder(p->left);
   preOrder(p->right);
} // preorder traversal
} // inorder traversal

void postOrder(Node* p) {
   if (!p) return;
   postOrder(p->left);
   postOrder(p->left);
   process(p->val);
   process(p->val);
   process(p->val);
} // preorder traversal
} // inorder traversal
} // postOrder traversal
```

### Recursive Big Three

### Operations on BSTs vs Sorted/Unsorted Sets

**Search**: due to the sorting invariant, searching a balanced BST for a value takes  $O(\log n)$  time.

### Recursive Binary Search

```
template <typename Iter, typename T>
int binarySearch(Iter left, Iter right, const T& val) {
  int size = (right - left);
  if (size <= 0) return -1;
  Iter mid = left + (size / 2);
  if (*mid == val) return (mid - left);
  if (*mid > val) return binarySearch(left, mid, val);
  return binarySearch(mid + 1, right, val);
} // eliminates half the search space each loop
```

std::map and std::set are implemented using self-balancing binary search trees, which is how
they maintain Θ(log n) insertion, removal, and searching even in the worst case.

\*Where n = number of nodes in the tree

Best case:  $\Omega(n)$ Worst case: O(n)Average case:  $\Theta(n)$ 

#### Iterators and Functors

*Functors (function objects): first-class* entities that provide the same interface as a function. They can be created from classes that overload the function-call operator, i.e., <code>operator()</code>.

- first-class entities can store state (store and access information), be created at runtime, and be passed as an argument to/returned by a function.
- operator() can only be overloaded from within a class body. It and operator[] are also the only operators that can be overloaded as static member functions.

#### **Function Pointers**

*Iterators* are a type of object that are designed to emulate the interface of a pointer.

	std::sort(it1,it2)	it2 - it1	it[n]	it +=	n it1 < it2	it	++it	it1 == it2	*it
Random Access	✓ Yes	Yes	✓ Yes	✓ Ye	s 🗸 Yes	✓ Yes	✓ Yes	✓ Yes	Yes
Bidirectional	× No	× No	× No	× No	× No	✓ Yes	✓ Yes	✓ Yes	✓ Yes
Forward	× No	× No	× No	× No	× No	× No	✓ Yes	✓ Yes	✓ Yes
Iterator	array <t,n>::iterator</t,n>	vector	<t>::iterat</t>	or	list <t>::iterato</t>	or map <ke< td=""><td>y,T&gt;::itera</td><td>tor set<key>:</key></td><td>::iterator</td></ke<>	y,T>::itera	tor set <key>:</key>	::iterator
Itorotor Class	Bondom Aggoss	Done	lam Asses		Didirectional	Die	livostional	Didino	otional

Iterator	array <t,n>::iterator</t,n>	vector <t>::iterator</t>	list <t>::iterator</t>	map <key,t>::iterator</key,t>	set <key>::iterator</key>	
Iterator Class	Random Access	Random Access	Bidirectional	Bidirectional	Bidirectional	
Container Resizing	N/A	All iterators invalidated	Dynamic	Empty container	Linked	
Insertion	Sequential	Iterators at/above point of insertion are invalididated	Unaffected	Unaffected	Unaffected	
Erasure	Sequential	Iterators at/above point of erasure are invalididated	Dynamic	Empty container	Linked	

#### Friend Classes

Declaring a class S as a friend of class T makes the private data members of S accessible in the scope of T (but not vice versa—T's private members don't become accessible to S).

```
friend class F;
friend F;
{
```

#### **Error Handling and Exceptions**

1 A try block can have multiple catch blocks associated with it.

Uncaught exceptions will make the program terminate.

### C++ Stuff and Impostor Syndrome

*Impostor syndrome* is characterized by doubt in one's abilities that aren't backed up by evidence and an inability to recognize/take credit for one's achievements. These feelings are common and can affect anyone (although people from underrepresented groups may be more susceptible to it).

A *static member function* does *not* have access to the this pointer and also can't access non-static data members (reminder: static members are "shared" between all instances of a class).

Templates and function overloading are forms of *compile-time polymorphism*, while subtype polymorphism is a form of *runtime polymorphism*.

# Container ADTs

static keyword: used to make one copy of a class data member "shared" between all instances of that class. A static data member has static storage duration but exists only within the scope of a class.

stack: a container that's designed to

operate in a LIFO order.

**queue**: a container designed to operate in a first-in/first-out (FIFO) order.

Container	Interface Operations - Optimal Implementations are All O(1)							
Stack	empty	size	top (next	t to pop) push_b		pop_back		
Queue	empty	size	front (next)	back (last)	push_back	pop_front		

1 An efficient way to implement a queue is to create a vector with free space at both ends (a ring/cir-cular buffer). This requires keeping track of the data's "head" (inclusive) and "tail" (exclusive).

Useful std::vector Functions and Constructors							
.size()	v[i]/.at(i)	.pop_back()	.resize(n)				
.front()	.back()	.erase(iterator)	.empty()	.clear()			
vector	<t> v2(v1.begi</t>	vector <t:< td=""><td>&gt; v2(v1)</td></t:<>	> v2(v1)				

\* These refer to the array-based sets we saw in class, not STL sets.

### C++ Standard Library Containers

std::array: Containers with compile-time constant sizes that store elements in contiguous memory.
std::vector: resizable containers that store elements at the front and free space at the back.

▲ Element insertions/deletions will invalidate std::vector iterators at and after the modified index. Also, any operation that changes the maximum capacity of a vector invalidates all existing iterators.

**std::list**: a container whose elements are linked via pointers (i.e., in non-contiguous memory).

std::map: an associative array that maps unique keys to values. Keys act like indexes for a map.

**std::set**: an associative sorted container that only stores unique keys.

nemoving an element from a std::list, std::set, or std::map only invalidates iterators to the removed element. Also, inserting an element doesn't ever invalidate iterators for those containers.

```
Useful std::map functions
     C++ Standard Library Containers
                                                        // Returns iterator to the pair with Kev == k
std::array<int, 4> arr = {-4,0,3,6};
std::array arr2{1, 2}; // Only way to omit
                                                        // Returns .end() iterator if no such pair
                                                                exists
       size
                                                        iterator find(const Key_type& k) const;
std::List<int> doubly_linked = {1,2,3};
std::forward_list<int> singly_linked = {4,5,6
                                                        // Inserts a <key, value> std::pair into a map
                                                        // Returns <iterator, false> if Key already in
std::set<int> nums = {3,2,2,1}; // {1,2,3}
                                                                 use
                                                        pair<iterator, bool > insert(const Pair_type&
std::map<string, int> EECS = { {"Bill", 183}
                                                               pair);
cout << EECS["Bill"] << endl: // prints 183
                                                        /* Finds or enters a value for a given key
// Two ways to insert into a map:
EECS["Emily"] = 203;
                                                                then
                                                        returns a reference to the associated value */
EECS.insert(pair<string, int>("James", 280));
                                                        Value_type& operator[](const Key_type& key);
```

#### Templates (Parametric Polymorphism)

**Templates:** special functions that take a data type as a parameter at compile time and instantiate an object or function compatible with that type. They help reduce code duplication in container interfaces

```
Class Template Syntax

template <typename T>
class UnsortedSet {
    public:
    | void insert(T my_val);
    | bool contains(T my_val) const;
    int size() const;
    private:
    | T elts[ELTS_CAPACITY];
    int elts_size;
    | ...
}; // Syntax: UnsortedSet<type> s;

Function Template Syntax

// Note: "class" also works in place of "typename"
template <typename T> // "T" is also an arbitrary name
TaxValue(const I &valA, const I &valA) {
    | return (valB > valA) ? valB : valA;
} // This function returns the greater of valA and valB
// Syntax to call it: maxValue<int/double/etc>(...);

Templated Class Member Function Syntax

template <typename T> // Necessary if outside class body
void UnsortedSet<T>::insert(T my_val) {...}
```

### Iterators, Traversal by Iterator and Range-Based Loops

**Iterators:** objects that have the same interface as pointers; they provide a general interface for traversing and accessing the elements of different types of containers. Note that each container's iterator has its own invalidation conditions (and that using an invalidated iterator causes undefined behavior).

• std::begin() returns an iterator to the start of an STL container. std::end() returns an iterator that's 1 past the end of an STL container (the iterator returned by std::end() should not be dereferenced).

	std::sort(it1,it2)	it2 - it1	it[n]	it += n	<,<=		++	==, !=	*it
Random Access Iterators	✓ Yes	✓ Yes	✓ Yes	✓ Yes	✓ Yes	✓ Yes	✓ Yes	✓ Yes	✓ Yes
Bidirectional Iterators	× No	× No	× No	× No	× No	✓ Yes	✓ Yes	✓ Yes	✓ Yes
Forward Iterators	× No	× No	× No	× No	× No	× No	✓ Yes	✓ Yes	✓ Yes

**Traversal by iterator**: a more general form of traversing a container data type by pointer.

```
vector<int> v(3, -1); // this syntax initializes v to
{-1,-1,-1}
for (vector<int>::iterator it = v.begin(); it != v.end(); ++it)
| { cout << *it << endl; } // ::const_iterator if const vector</pre>
```

### Range-Based For Loop (Works on Any Sequence Traversible by Iterator)