Using optimal transport for trajectory inference

Hugo Lavenant

Bocconi University

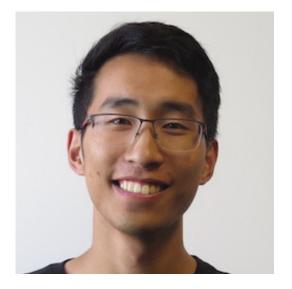


When AI meets Biology: a workshop, Lyon (online), October 1st, 2021

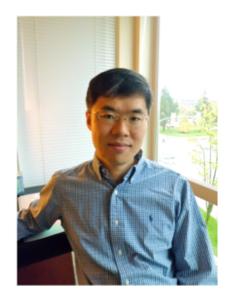
Lavenant*, Zhang*, Kim, Schiebinger (2021). Towards a mathematical theory of trajectory inference. Arxi 2102.09204

Joint work with:





Stephen Zhang



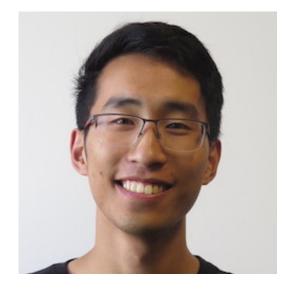
Young-Heon Kim



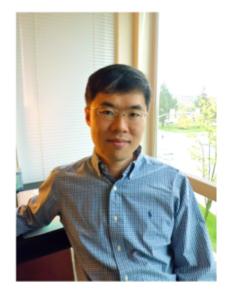
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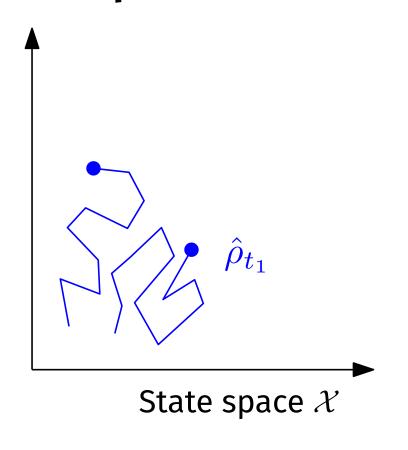
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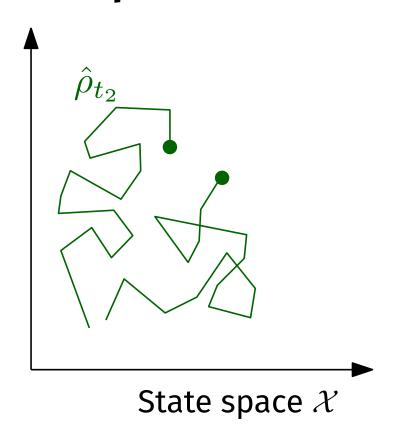
Disclaimer

I am not a biologist, nor a statistican. My background: convex analysis, PDE, Optimal Transport.



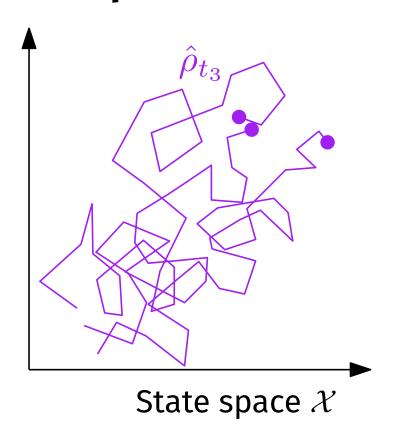
Stochastic process X_t

Samples from law of X_{t_1}



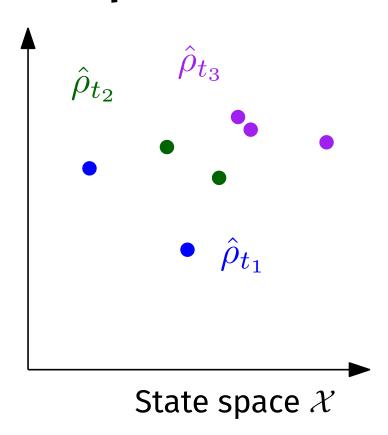
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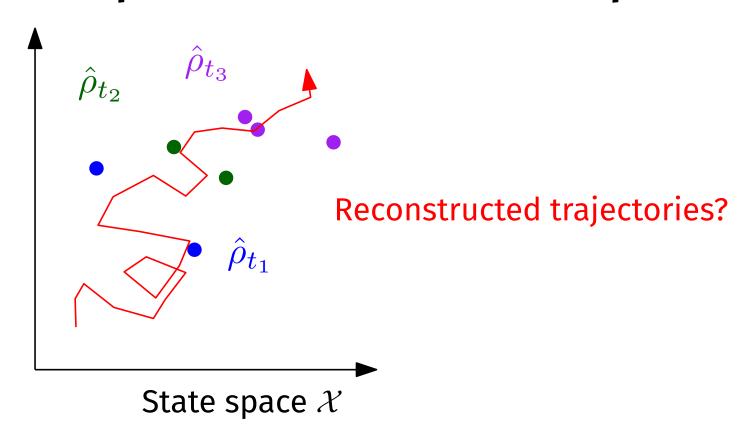
Samples from law of X_{t_2} (independent from the previous samples)



Stochastic process X_t

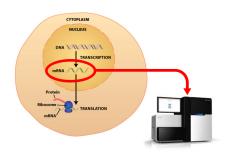
Samples from law of X_{t_3} (independent from the previous samples)

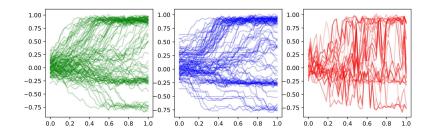




Goal: reconstruct the law of the trajectories X_t from samples of the temporal marginals.

1 - Biological Context



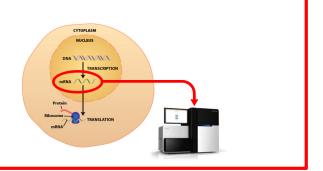


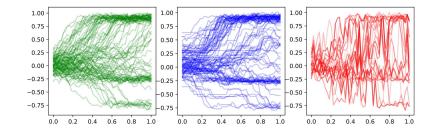
2 - Algorithms and results

3 - Theoretical analysis

$$dX_t = \mathbf{v}(t, X_t)dt + \sigma dB_t$$

1 - Biological Context



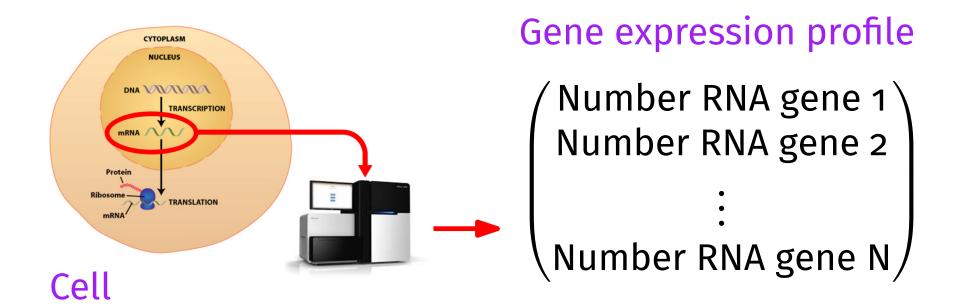


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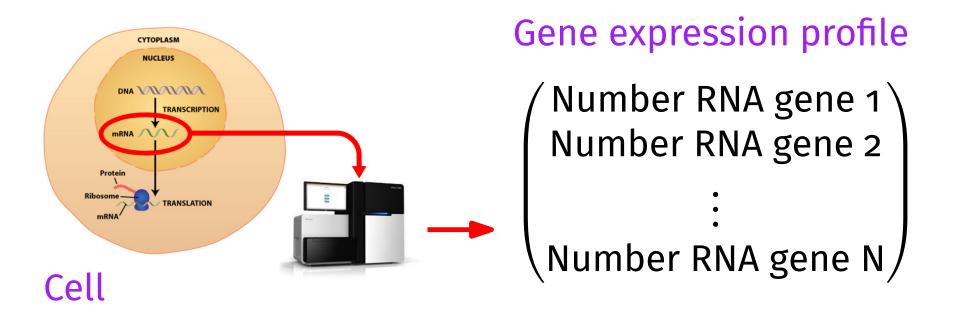
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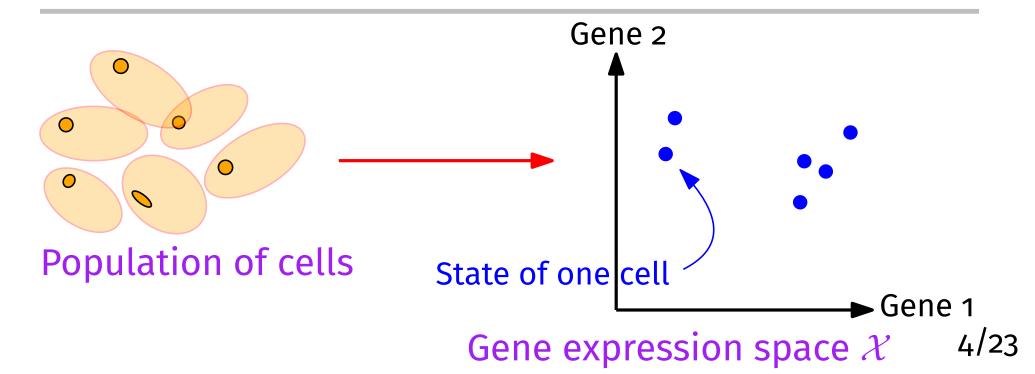
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Single-cell RNA sequencing

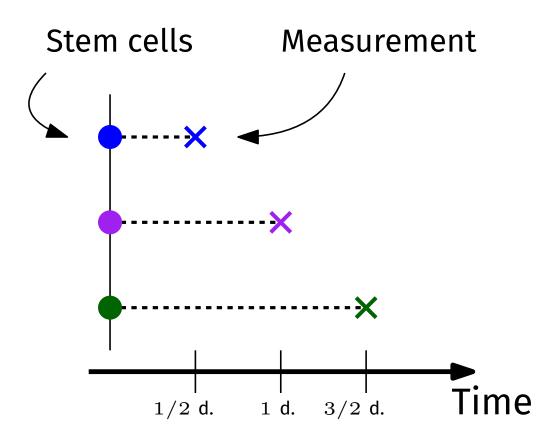


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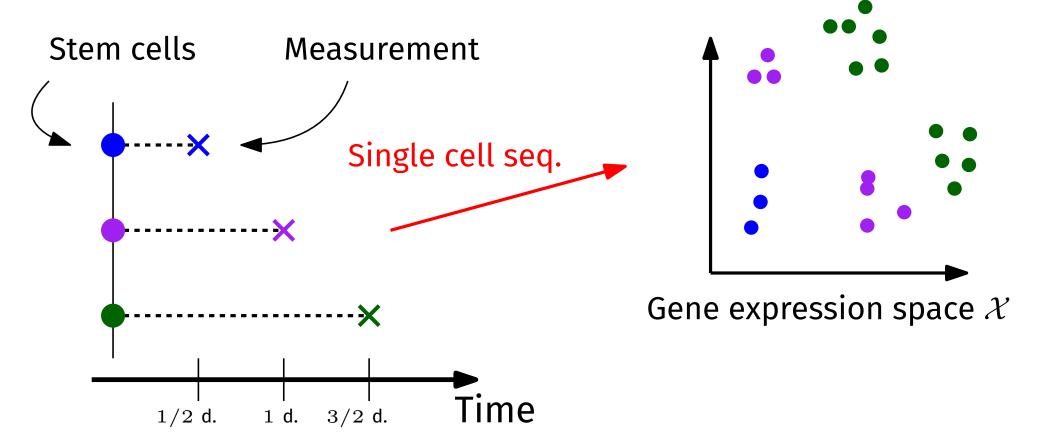




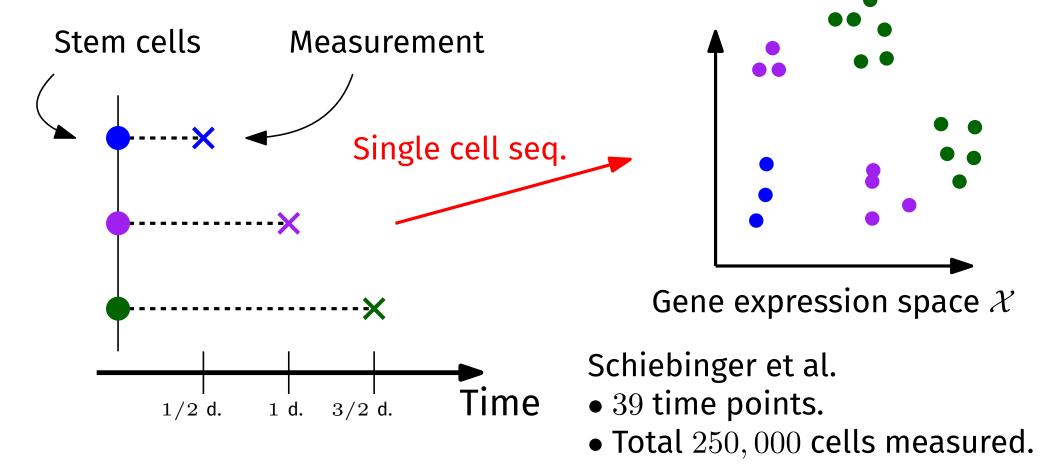
Investing cell differentiation



Investing cell differentiation



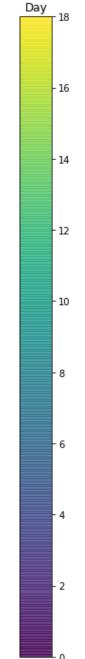
Investing cell differentiation



(Biological) goal: reconstruct fate of cells, unravel the regulatory network.

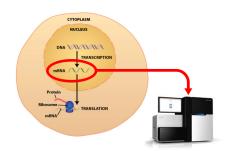
Dataset

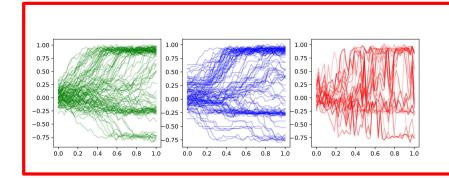




Disclaimer: for the moment, we ignore branching.

1 - Biological Context



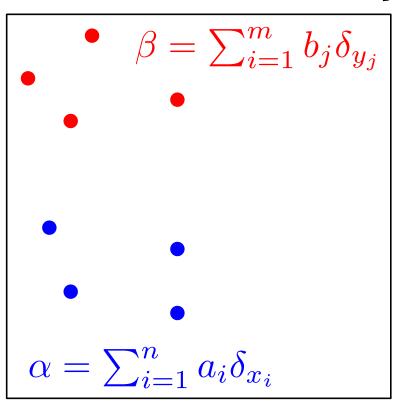


2 - Algorithms and results

3 - Theoretical analysis

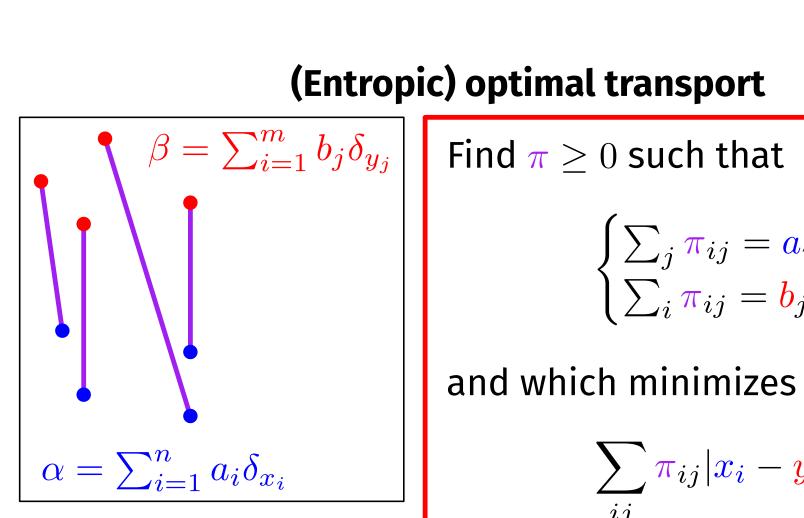
$$dX_t = \mathbf{v}(t, X_t)dt + \sigma dB_t$$

(Entropic) optimal transport



Probability distributions:

$$\sum_{i} a_{i} = \sum_{j} b_{j} = 1$$



$$egin{cases} \sum_j \pi_{ij} = a_i \ \sum_i \pi_{ij} = b_j \end{cases}$$

and which minimizes

$$\sum_{ij} \pi_{ij} |x_i - y_j|^2$$

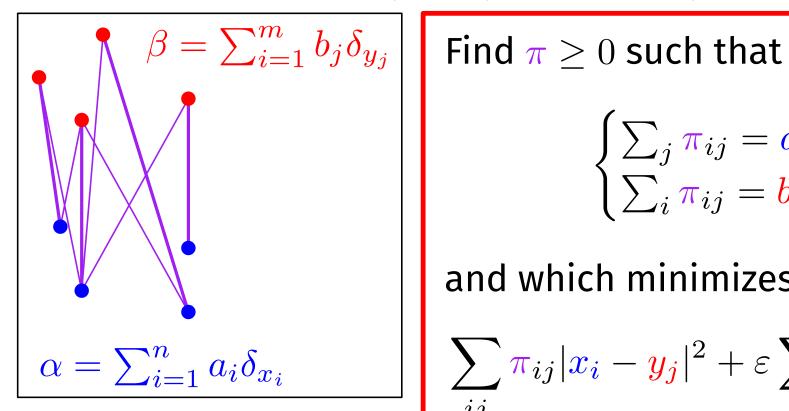
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$$\mathbb{P}(X = x_i, Y = y_j) = \pi_{ij}$$

(Entropic) optimal transport



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$$\sum_{ij} \pi_{ij} |x_i - y_j|^2 + \varepsilon \sum_{ij} \pi_{ij} \log \pi_{ij}$$

Probability distributions:

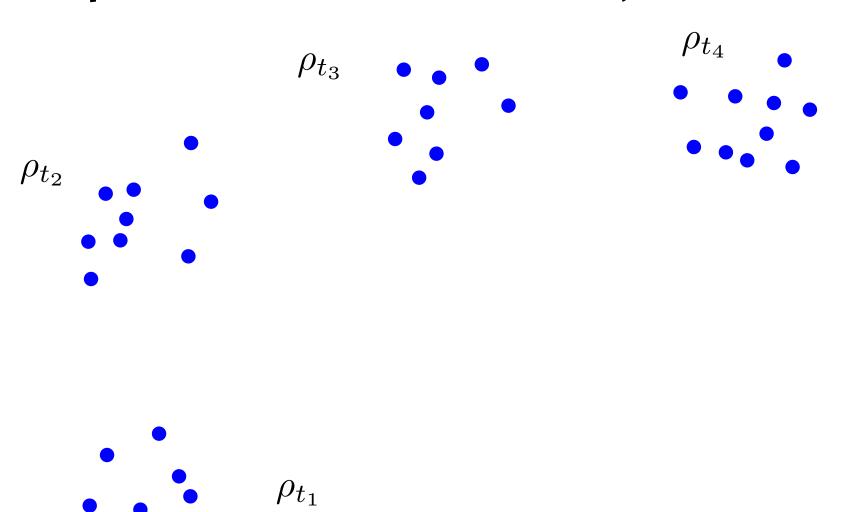
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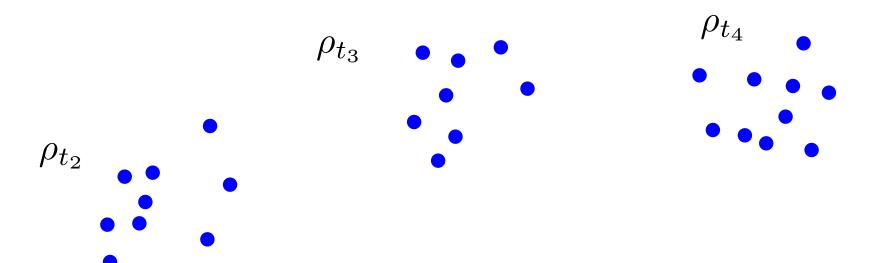
Input: $\rho_{t_1}, \rho_{t_2}, \dots \rho_{t_T}$ probability measures

Ouptut: R law of reconstructed trajectories.

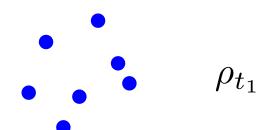


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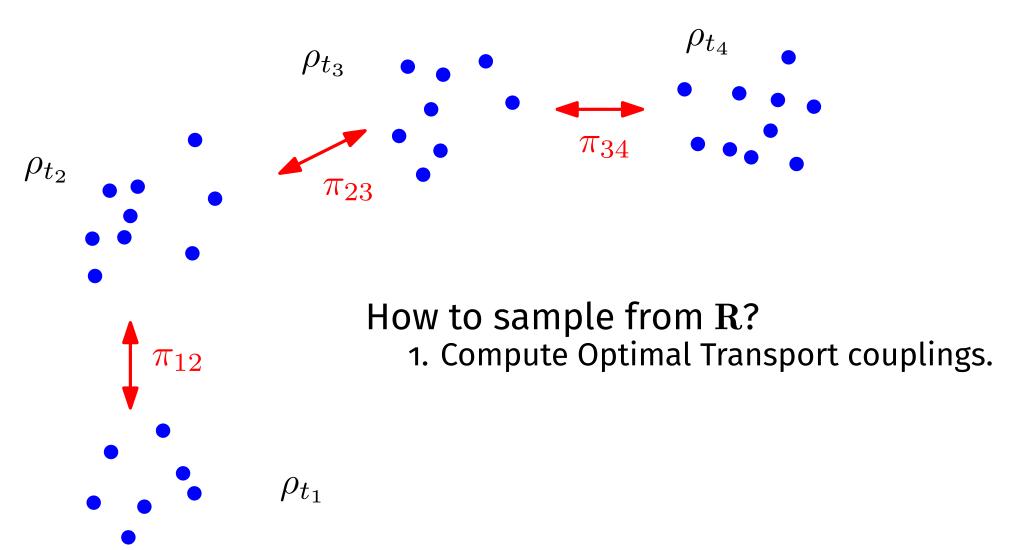


How to sample from R?



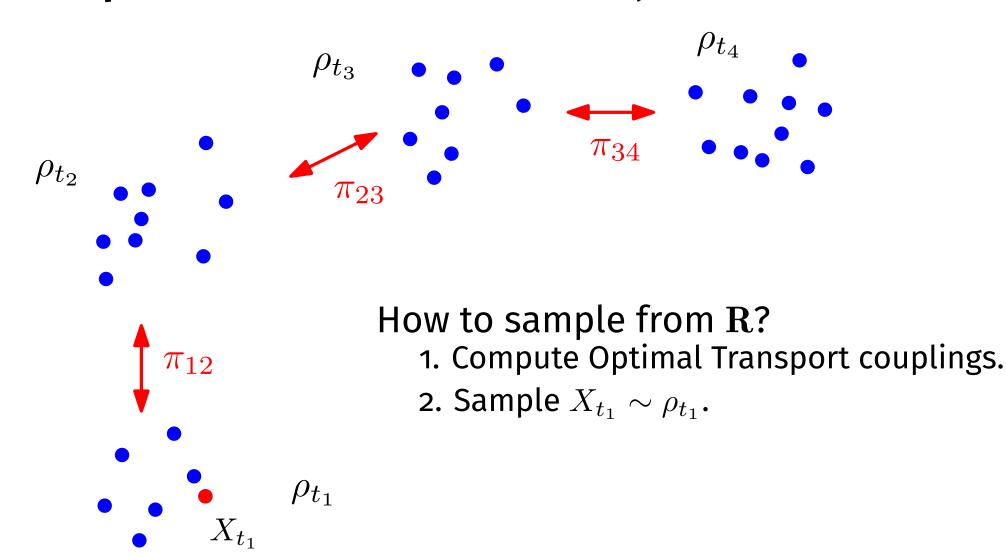
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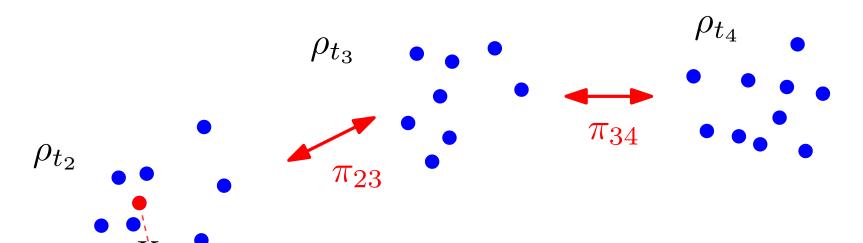
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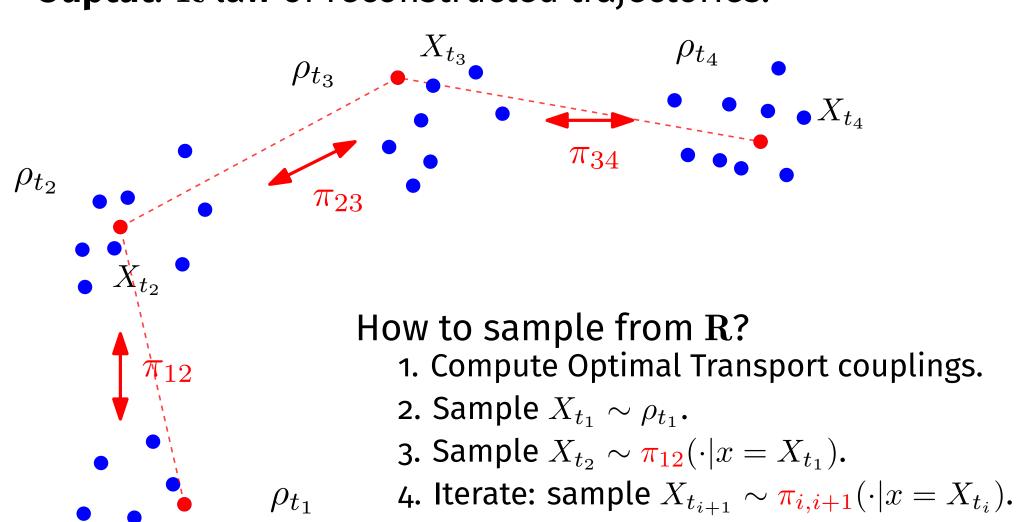
 ho_{t_1}

How to sample from R?

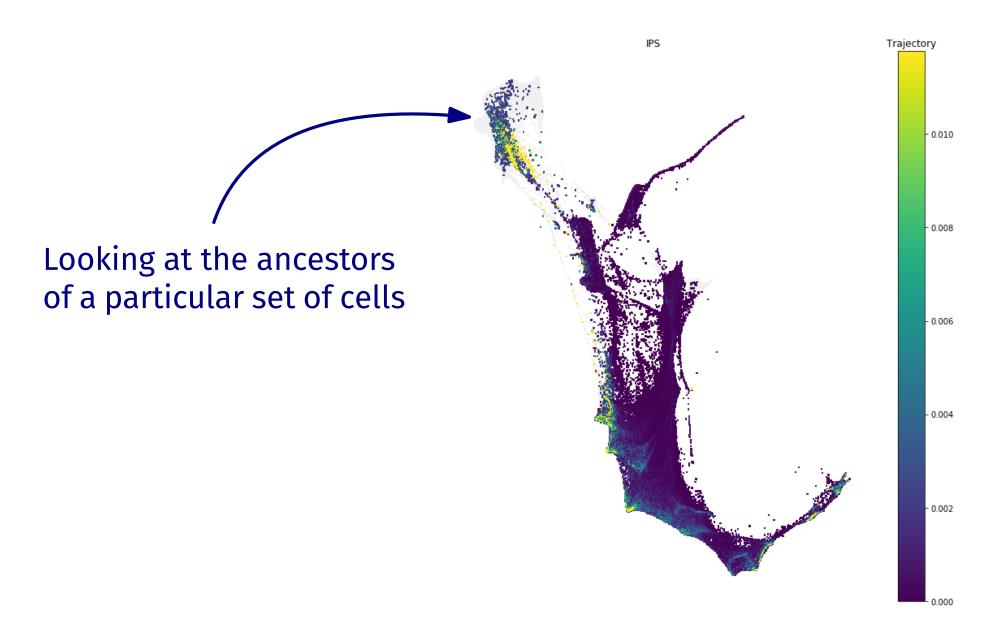
- 1. Compute Optimal Transport couplings.
- 2. Sample $X_{t_1} \sim \rho_{t_1}$.
- 3. Sample $X_{t_2} \sim \pi_{12}(\cdot|x=X_{t_1})$.

Input: $\rho_{t_1}, \rho_{t_2}, \dots \rho_{t_T}$ probability measures

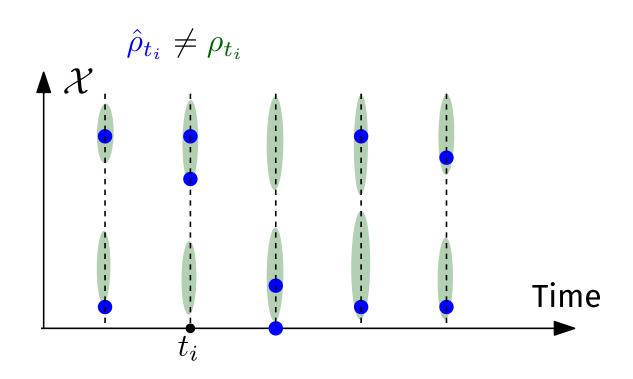
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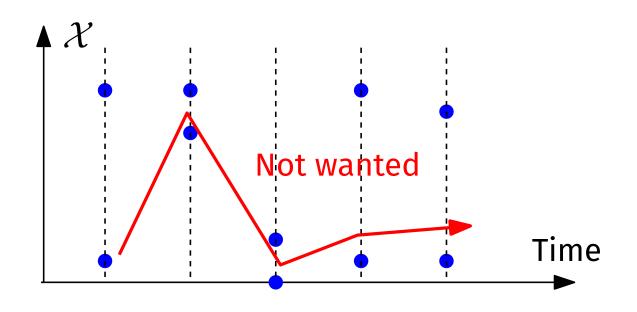
Example on the dataset of Schiebinger et al.



"Sparse data" framework

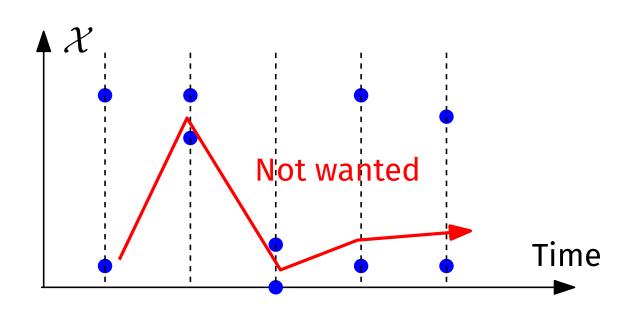


"Sparse data" framework



Few samples per time point, need to share information across time points.

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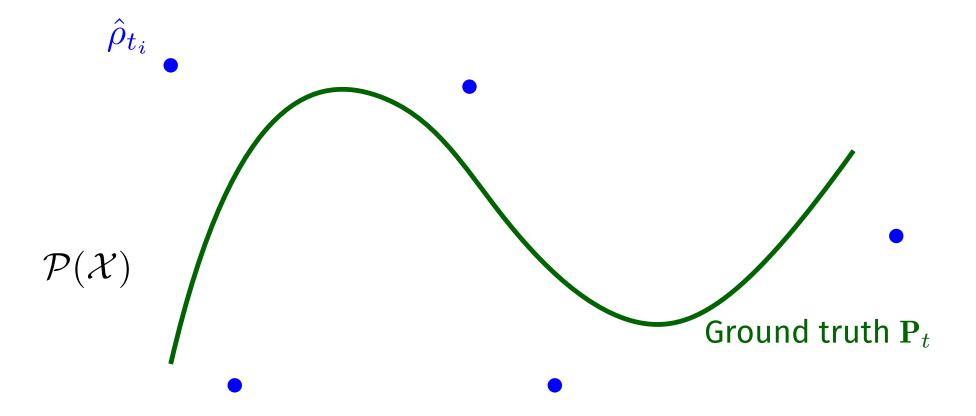
Idea: data fitting + regularization

Cross entropy $H(\hat{\rho}_{t_i}|\mathbf{R}_{t_i})$ between data $\hat{\rho}_{t_i}$ and reconstructed marginal \mathbf{R}_{t_i}

Sum of optimal transport distances

Global Waddington OT

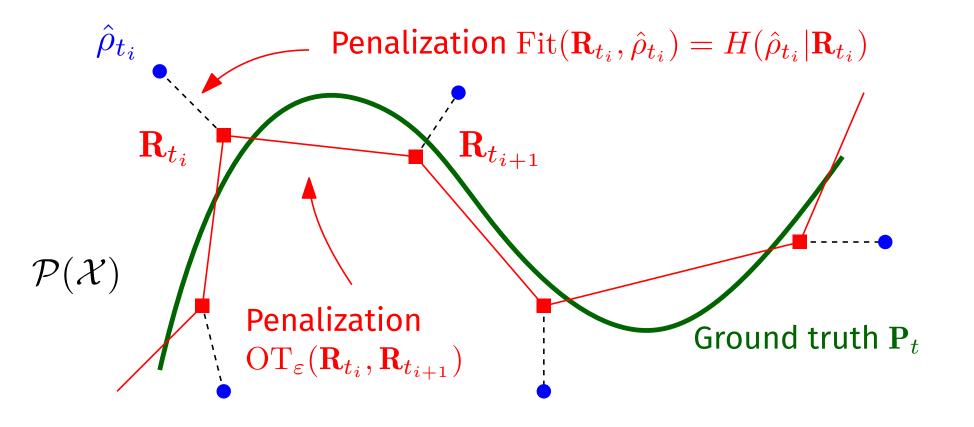
Unknowns: marginals \mathbf{R}_{t_i} , $\operatorname{Reg}((\mathbf{R}_{t_i})_i) \sim \sum_{i=1}^{T-1} \operatorname{OT}_{\varepsilon}(\mathbf{R}_{t_i}, \mathbf{R}_{t_{i+1}})$



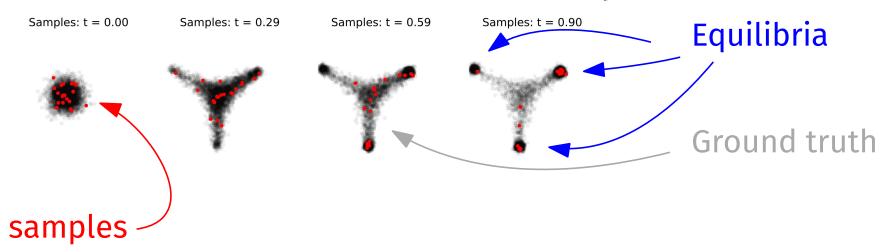
Global Waddington OT

Unknowns: marginals \mathbf{R}_{t_i} , Optimal transport cost

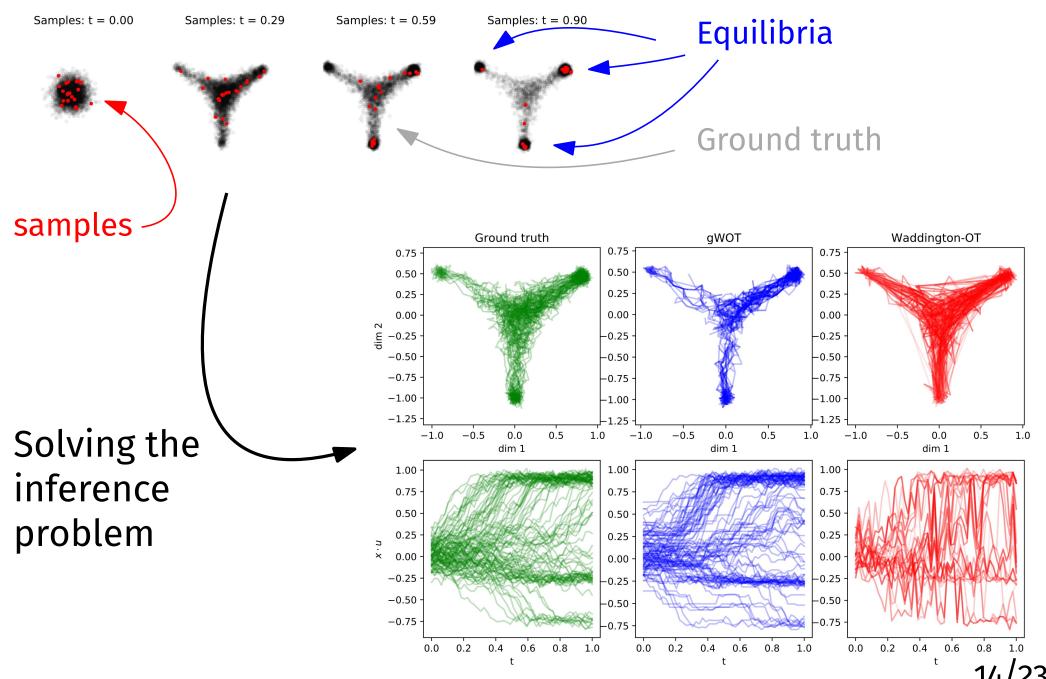
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, $T-1$ $\operatorname{Reg}((\mathbf{R}_{t_i})_i) \sim \sum_{i=1}^{T-1} \operatorname{OT}_{arepsilon}(\mathbf{R}_{t_i}, \mathbf{R}_{t_{i+1}})$



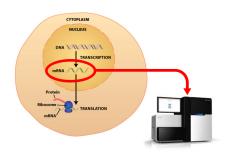
Numerical results (synthetic)

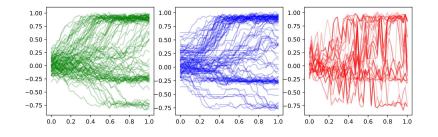


Numerical results (synthetic)



1 - Biological Context





2 - Algorithms and results

3 - Theoretical analysis

$$dX_t = \mathbf{v}(t, X_t)dt + \sigma dB_t$$

In short: temporal couplings are given by optimal transport.

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- 3. Does it converge with more and more marginals?

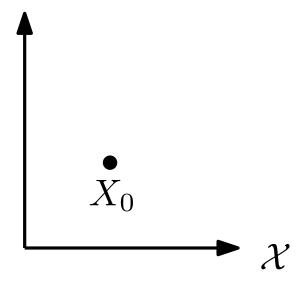
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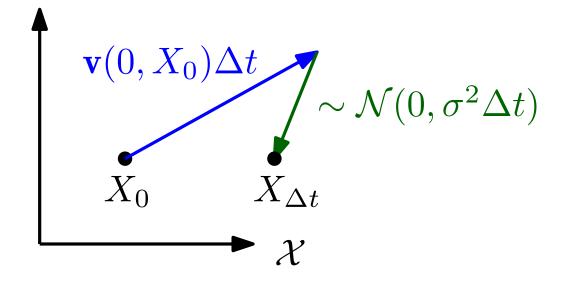
Short answer:

- Works if data is generated by a **potential** Stochastic Differential Equation.
- Choose $\varepsilon = \sigma^2 \Delta t$ with σ noise level in the SDE.

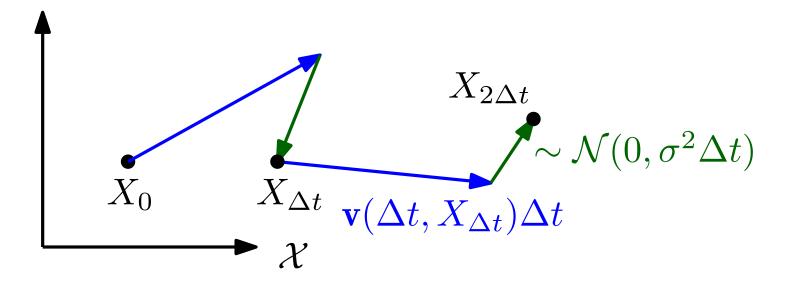
$$dX_t = \mathbf{v}(t, X_t)dt + \sigma dB_t.$$

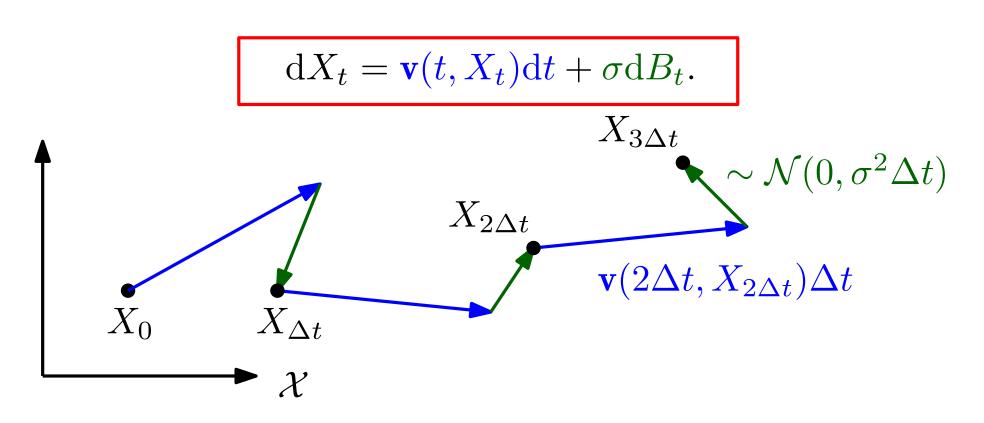


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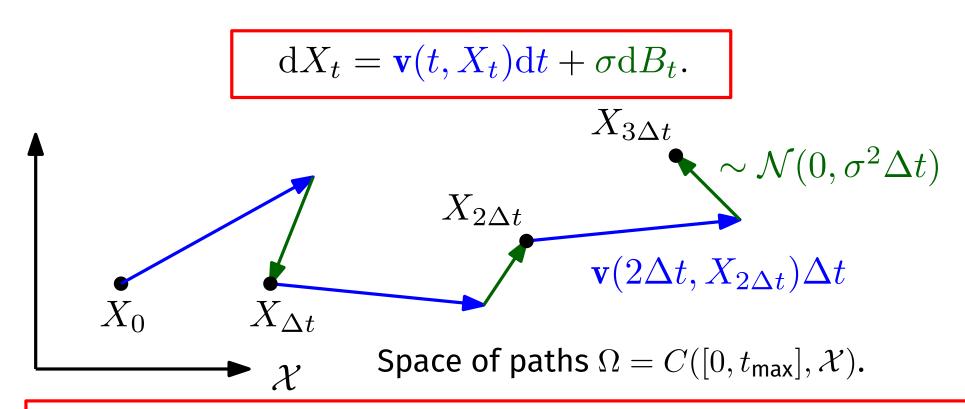


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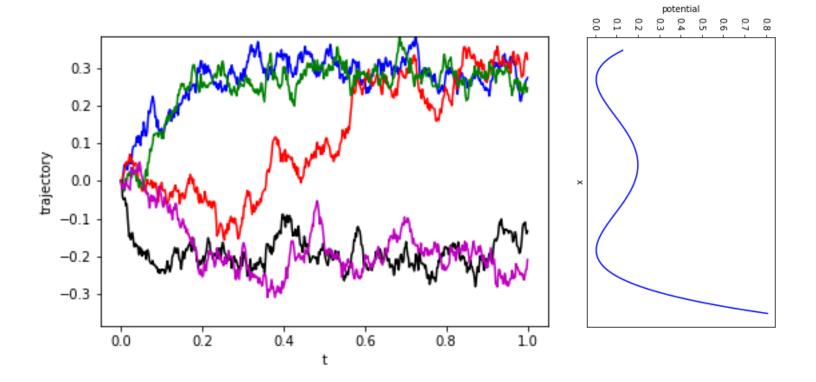
The position of each cell X_t follows a **Stochastic Differential Equation** (SDE):



A SDE is entirely characterized by (\mathbf{v}, σ) , or by $\mathbf{P} \in \mathcal{P}(\Omega)$ the probability distribution it induces on Ω .

Potential SDEs

Potential $\Psi = \Psi(t,x)$ such that $\mathbf{v}(t,x) = -\nabla \Psi(t,x)$



Informal result: SDE and optimal transport

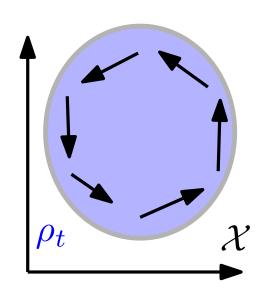
Take the potential SDE

$$dX_t = -\nabla \Psi(t, X_t) dt + \sigma dB_t.$$

If Δt small enough, the law of $(X_t, X_{t+\Delta t})$ is well approximate by the solution of

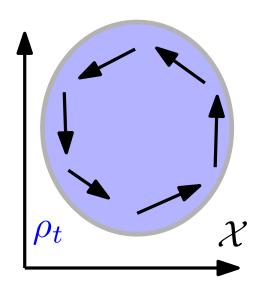
$$\mathrm{OT}_{\sigma^2 \Delta t}(\mathrm{Law}(X_t), \mathrm{Law}(X_{t+\Delta t}))$$

Intuitive explanation: removing identifiability issue



Impossible to distinguish periodic motion from cells at rest.

Intuitive explanation: removing identifiability issue



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Assuming

$$\mathbf{v}(t,x) = -\nabla \Psi(t,x)$$

prevents the velocity field to create periodic motion

Rigorous result: a variational characterization

$$\Omega = C([0, t_{\sf max}])$$
, unknown $\mathbf{R} \in \mathcal{P}(\Omega)$.

$$\operatorname{Reg}((\mathbf{R}_{t_i})_i) \sim \sum_{i=1}^{T-1} \operatorname{OT}_{\sigma^2 \Delta t}(\mathbf{R}_{t_i}, \mathbf{R}_{t_{i+1}}) \sim H(\mathbf{R}|\mathbf{W}^{\sigma})$$

where \mathbf{W}^{σ} law of Brownian motion with diffusivity σ .

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Take $P \in \mathcal{P}(\Omega)$ law of the SDE

$$dX_t = -\nabla \Psi(t, X_t) dt + \sigma dB_t.$$

For any $\mathbf{R} \in \mathcal{P}(\Omega)$ such that

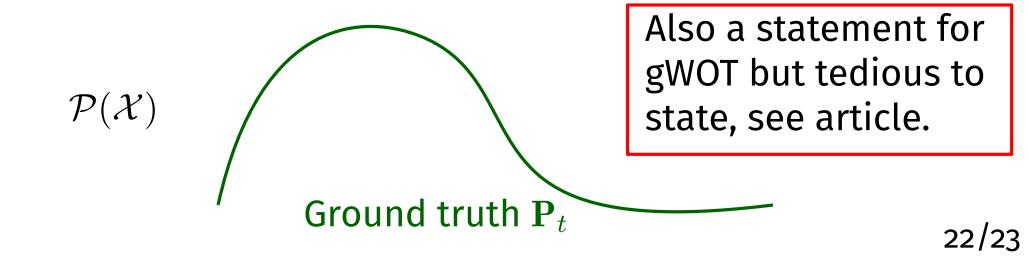
$$\forall t \in [0, t_{\mathsf{max}}], \, \mathrm{Law}_{\mathbf{P}}(X_t) = \mathrm{Law}_{\mathbf{R}}(X_t)$$
, then

$$H(\mathbf{P}|\mathbf{W}^{\sigma}) \leq H(\mathbf{R}|\mathbf{W}^{\sigma}).$$

Take $P \in \mathcal{P}(\Omega)$ (and $\rho_t = \text{Law}_P(X_t)$) the law of the SDE

$$dX_t = -\nabla \Psi(t, X_t) dt + \sigma dB_t.$$

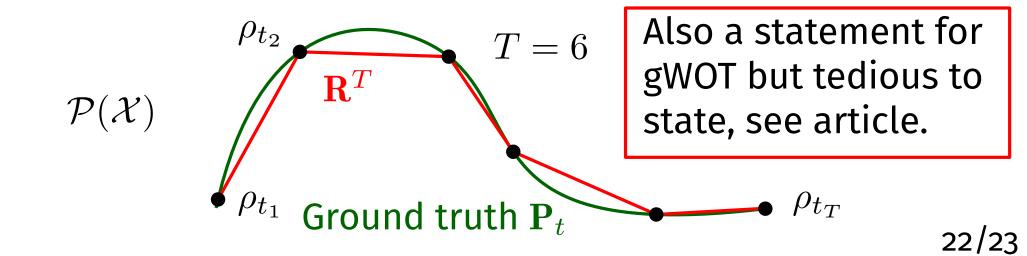
For $0 \le t_1 \le t_2 \ldots \le t_T \le 1$, run WOT with $\varepsilon_i = \sigma^2(t_{i+1} - t_i)$ and call \mathbf{R}^T the output.



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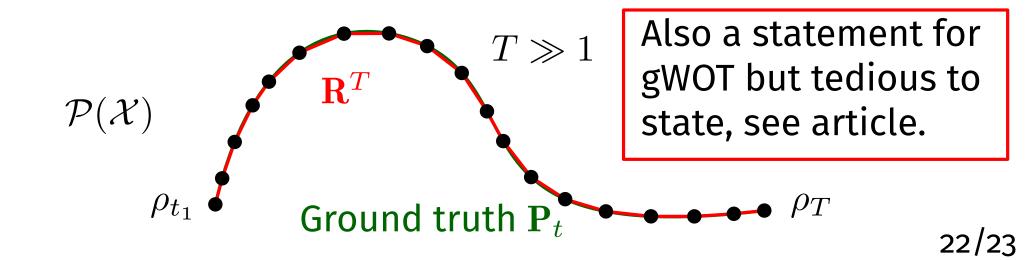
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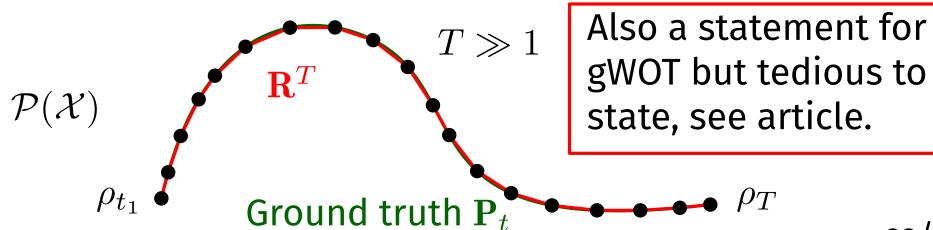


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In the limit $T \to +\infty$ (infinite sampling frequency), the probability distribution \mathbf{R}^T converges narrowly in $\mathcal{P}(\Omega)$ to the "ground truth" \mathbf{P} .



Conclusion

- Mathematical framework for trajectory inference.
- Guarantees of reconstruction.
- Convex method, but with parameters tuning.

What I have not described

- How we handle branching.
- Extensive numerical experiments.

Conclusion

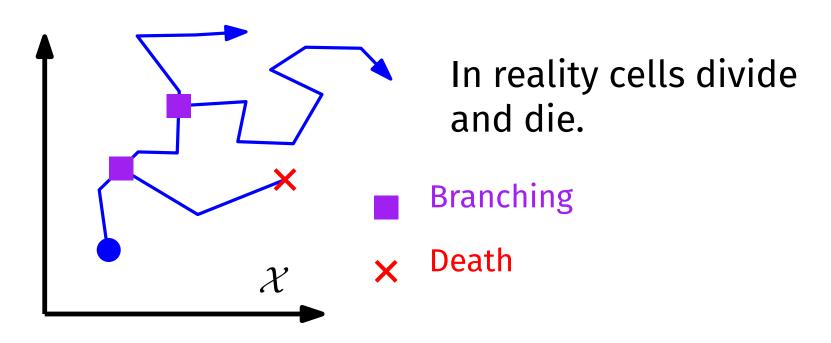
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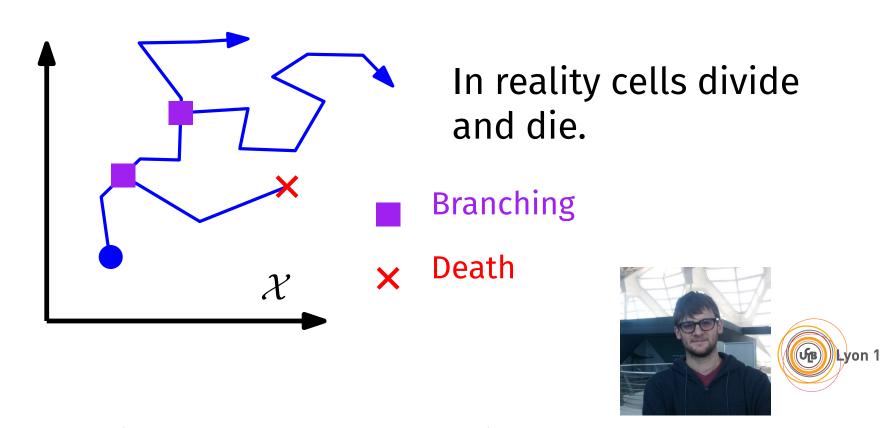
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Thank you for your attention

What about branching?



What about branching?



In progress (with Aymeric Baradat): studying entropy minimization with respect to the law of the **Branching Brownian Motion**.

Handling growth in our paper: splitting

Unknowns: marginals \mathbf{R}_{t_i} ,

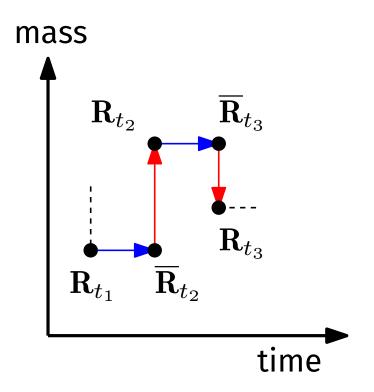
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To handle **branching**: alternance of transport and growth phases.

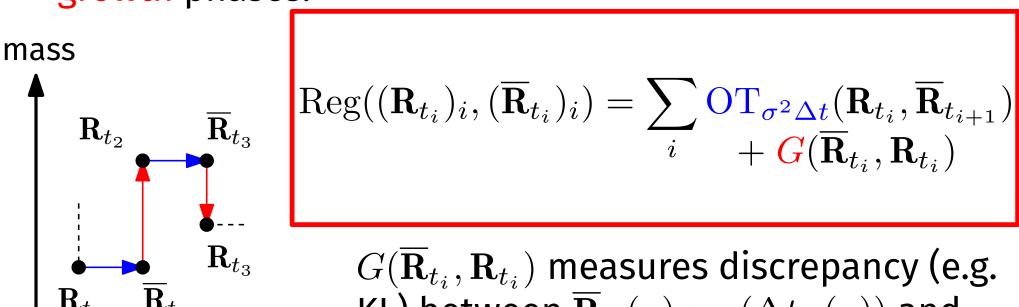


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To handle **branching**: alternance of transport and growth phases.



 $G(\mathbf{R}_{t_i}, \mathbf{R}_{t_i})$ measures discrepancy (e.g KL) between $\overline{\mathbf{R}}_{t_i}(x) \exp(\Delta t \, g(x))$ and $\mathbf{R}_{t_i}(x)$ with $g: \mathcal{X} \to \mathbb{R}$ a priori growth rate.