

Chapter 1: Markov processes (MP)

• State: $S_t \in \mathcal{S}$ $t = 0, 1, 2, \dots$
state space

• Markov evolution:

$$P(\underset{\text{future}}{S_{t+1} = s'} \mid \underset{\text{present}}{S_t = s}, \underset{\text{past}}{S_{t-1}, S_{t-2}, \dots, S_0})$$

$$= P(\underset{\text{future}}{S_{t+1} = s'} \mid \underset{\text{present}}{S_t = s})$$

- Future independent of past given present
- Markov chain: $S_0 \rightarrow S_1 \rightarrow S_2 \rightarrow \dots$

• Transition probability:

$$p(s' | s) = P(S_{t+1} = s' | S_t = s)$$

• Assumed homogeneous (stationary, time-independent)

• Normalization: $\sum_{s'} p(s' | s) = 1 \quad \forall s$

• Transition matrix: $P_{ij} = \underset{\text{column}}{p(j|i)} = \underset{\text{row}}{P(i \rightarrow j)}$

• $|\mathcal{S}| \times |\mathcal{S}|$ matrix

• $\sum_j P_{ij} = 1 \quad \forall i$ (row sums = 1)

• $0 \leq P_{ij} \leq 1$ (stochastic matrix)

• Probability distribution: $P_t(s) = P(S_t = s)$

• Probability vector: P_t , $P_{t,i} = P_t(i)$

• $|\mathcal{S}|$ -dim vector

• Row vector

· Evolution equation :

$$p_{t+1}(s') = \sum_s p(s'|s) p_t(s)$$

· Matrix notation: $p_{t+1} = p_t P$ right product

$$(- p_{t+1} -) = (- p_t -) \begin{pmatrix} P \end{pmatrix}$$

$$(p_{t+1})_j = \sum_i (p_t)_i P_{ij}$$

· Expectations :



$$E[f(s_{t+1}) | s_t = s] = \sum_{s'} f(s') p(s'|s)$$

· Matrix notation :

$$F_i = E[f(s_{t+1}) | s_t = i] = \sum_j f(j) p(j|i)$$

$$\begin{pmatrix} F \\ 1 \end{pmatrix} = \begin{pmatrix} P \end{pmatrix} \begin{pmatrix} f \\ 1 \end{pmatrix} = \sum_j P_{ij} f(j)$$

$$\Rightarrow F = P f \quad \text{left product}$$

· Marginalization: $p(x) = \sum_y p(x, y)$

$$p(x|z) = \sum_y p(x, y|z)$$

· Chain rule: $p(x, y) = p(x|y) p(y) = p(y|x) p(x)$

$$p(x, y|z) = p(x|y, z) p(y|z)$$

· Deterministic transition: $p(s'|s) = \begin{cases} 1 & \text{for same } s^* \\ 0 & \text{otherwise} \end{cases} = \delta_{s', s^*(s)}$
 $s \rightarrow s'$