

# Huize Huang

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## EDUCATION

### UNIV. OF PENNSYLVANIA

#### MS IN ELECTRICAL ENGINEERING

Expected May 2020 | Philadelphia, PA  
Cum. GPA: 3.9/4.0

### POLITECNICO DI MILANO

#### BS IN COMPUTING SYSTEMS

Grad. July 2018 | Milan, Italy  
Cum. GPA: 99 / 110

### TONGJI UNIVERSITY

#### BS IN ELECTRONIC AND

#### INFORMATION ENGINEERING

Grad. July 2018 | Shanghai, China  
Cum. GPA: 4.3/5.0

## LINKS

Github:// [HuizeHuang](#)

LinkedIn:// [HuizeHuang](#)

## COURSEWORK

### GRADUATE

Machine Perception  
Statistics for Data Science  
Programming Languages and Techniques  
System-on-a-Chip Architecture  
Intro. to Networks and Protocols

### UNDERGRADUATE

Database System  
Software Engineering  
Robotics  
Knowledge Engineering  
Information Systems  
Algorithms and Data Structures

### COURSERA

Programming Foundations with  
JavaScript, HTML and CSS  
Java Programming: Solving Problems with  
Software

## SKILLS

### PROGRAMMING

Proficient:

Java • C • Python • JavaScript  
• Assembly • HTML • CSS

Familiar:

C++ • Matlab • MySQL

## EXPERIENCE

### URUMQI SOCIAL SECURITY BUREAU INFORMATION CENTER |

#### TECHNICAL INTERN

Jul 2017 – Aug 2017 | Urumqi, China

- Ensured computers' smooth operations of whole company by maintaining computer software and hardware
- Daily checks peripheral devices of computers and helping staff deal with all kinds of problems with computers in time
- Earned hands-on experience and capability to solve practical problems of malfunction of computers and devices.

## PROJECTS

### OPENMV | PYTHON | COMPUTER VISION

Apr 2018 – Jun 2018 | Milan, Italy | Github:// [HuizeHuang/openmv-project](#)

- Worked with a group of 2 to implement simulation of Position Guided Vision robots by using Openmv camera sensor with python programming.
- Programmed the sensor to detect and track different color tapes, identify QR Code, and make branch decisions.
- Worked out the trade-off between high sensor frame rate and stable output to prepare it with angle and distance outputs as parameters for guiding robot vehicles in real use.

### DEDUPLICATION & COMPRESSION | C | ZEDBOARD | FPGA

Oct 2018 – Dec 2018 | Philadelphia, PA | Team of 3

- Developed a compressor which received data in real time at modern Ethernet speeds and compress it into memory using deduplication and compression.
- Implemented Content-Defined Chunking to break the input into chunks, SHA-256 hashes to screen for duplicate chunks, and LZW compression to compress non-duplicate chunks based on C.
- Worked on both software acceleration and hardware acceleration to achieve higher speed; worked on software design and hardware mapped design to find a trade-off between energy, space and time.

### MININET | PYTHON | NETWORK PROTOCOLS | LINUX | WIRESHARK

Nov 2018 – Dec 2018 | Philadelphia, USA | Team of 2

- Created a virtual network topology using Mininet on Linux system, showcasing routing protocol BGP by using Quagga routing software suit.
- Designed a scenario where BGP attacks happened, setup BGP across ASs and an attacker hijacked a route, checking iptables to show how attacker worked.

### CRACK VIGENÈRE CIPHERS | JAVA

Jan 2019 | Philadelphia, PA | Github:// [HuizeHuang/VigenereCipher](#)

- Solo project, working on breaking messages encrypted by Vigenere ciphers with unknown key and languages based on objected-oriented design.
- Chose corresponding data structures to enhance the program's efficiency.

## STRENGTHS

- Benefit from breadth of education; Work well in both solo and group environments
- Quick adaptability and flexible with exposure to new tools, languages