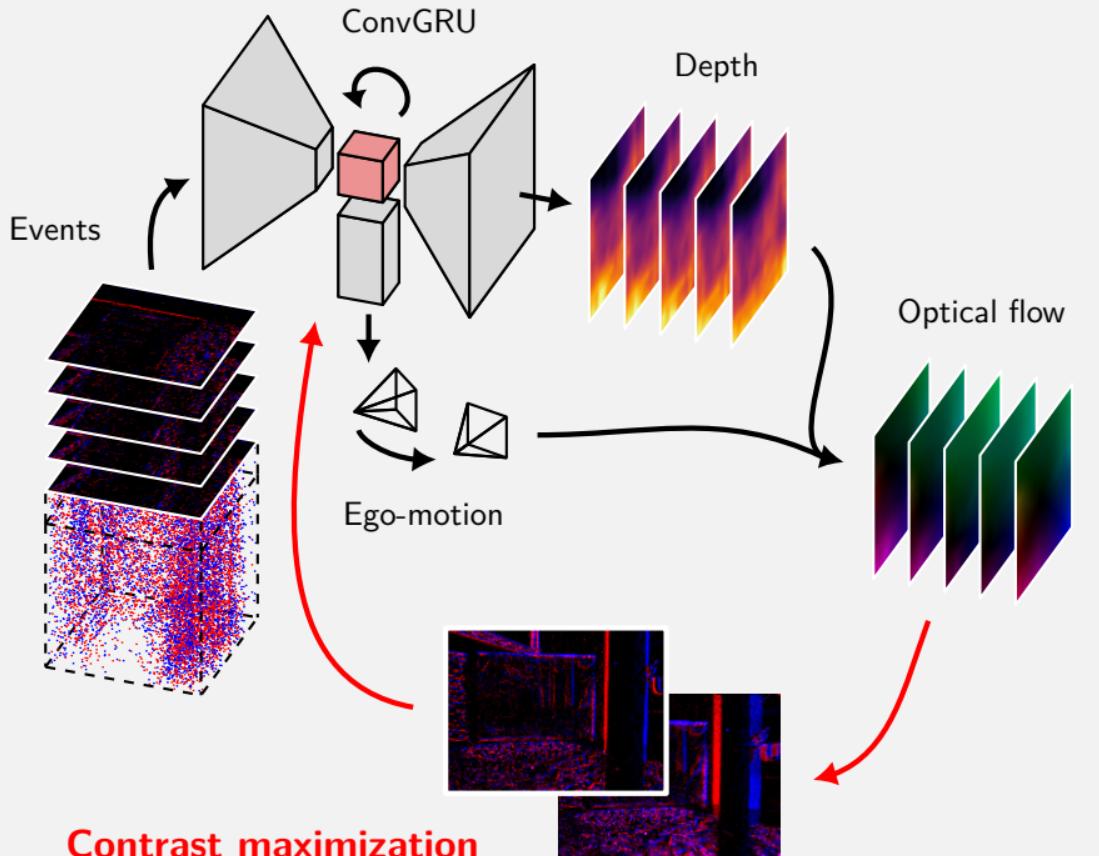
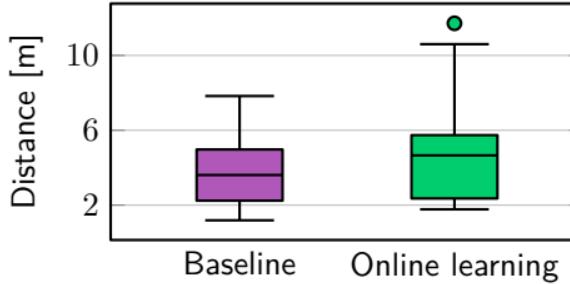


## Self-supervised learning from events

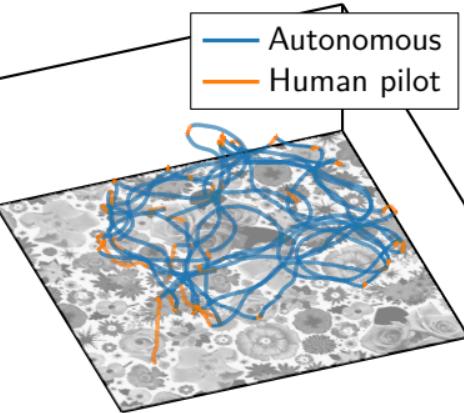
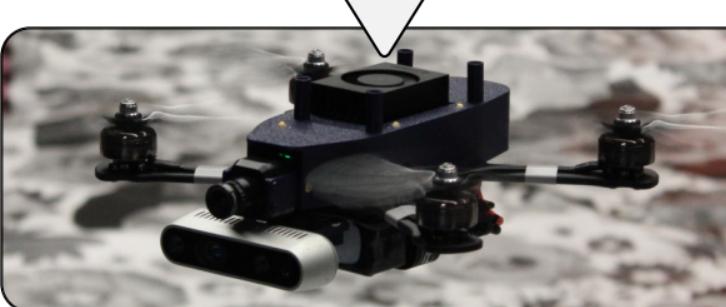


## Real-world obstacle avoidance

### Distance between interventions



### + On-device optimizations



### Yaw rate control

