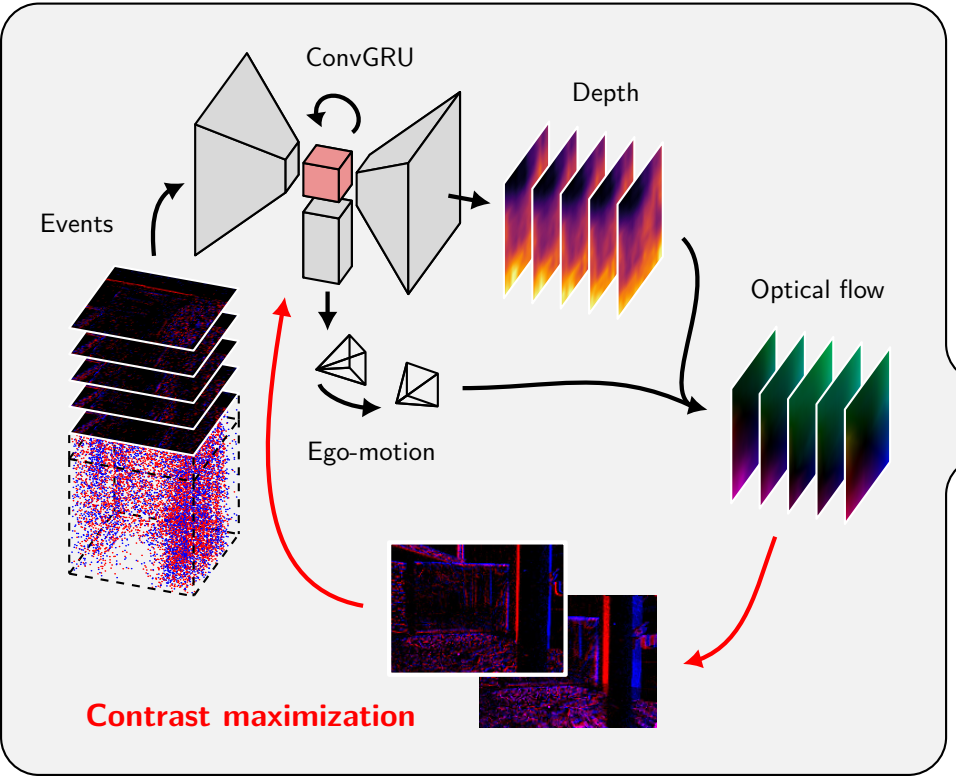
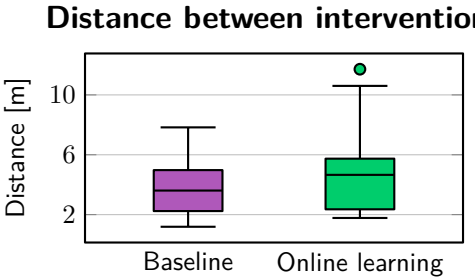
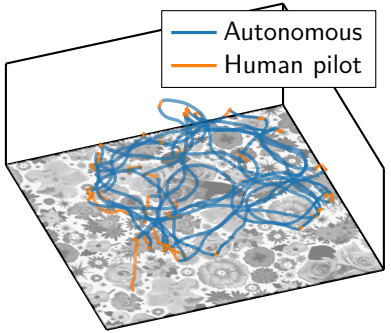
Self-supervised learning from events

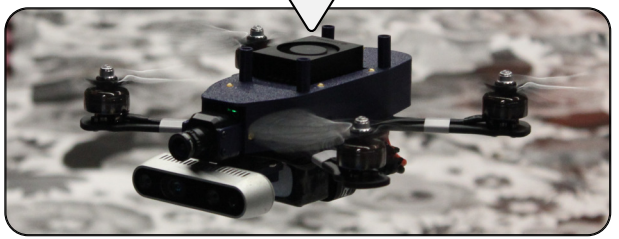
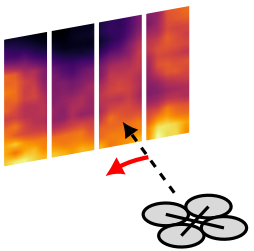


Real-world obstacle avoidance





+ On-device optimizations



Yaw rate control