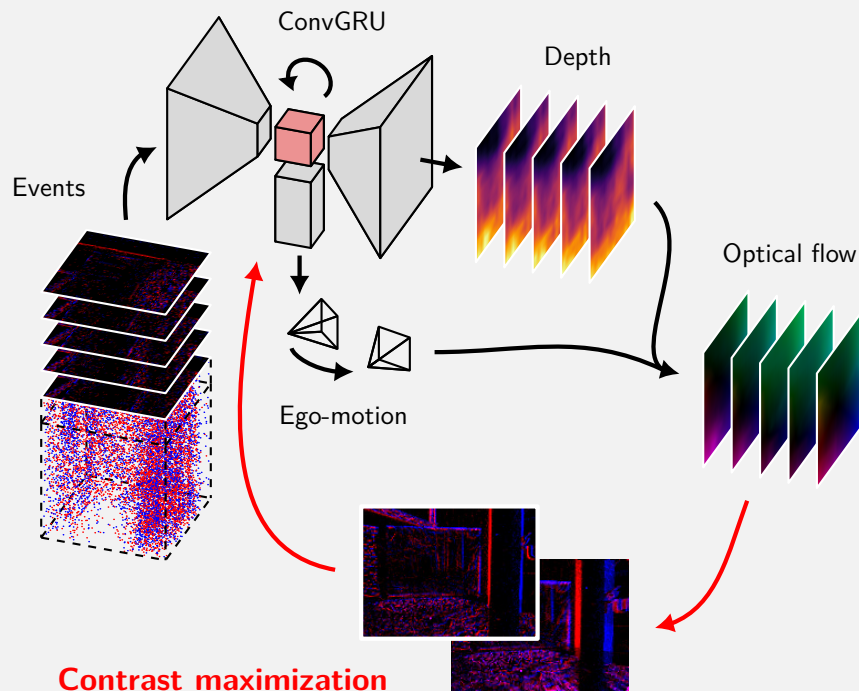
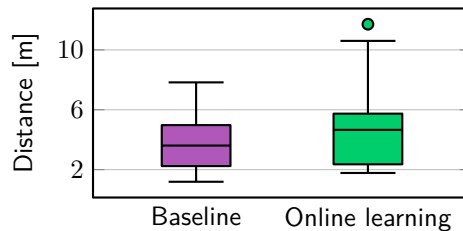


Self-supervised learning from events

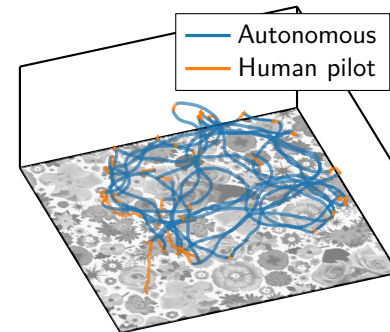
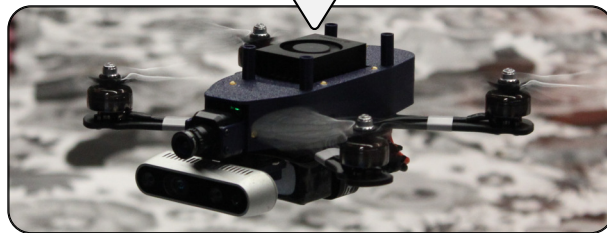


Real-world obstacle avoidance

Distance between interventions



+ On-device optimizations



Yaw rate control

