# Graph-Theoretic Analysis of Finite Markov Chains

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### Outline

- How to represent an MC using a graph?
  - Aperiodic, Recurrent or Transient
- Problem 1: State Classification
  - Algorithm: based on Depth-First Search Algorithm
- Problem 2: Periodicity
  - Algorithm
    - \* Breadth-First Search Algorithm
    - \* Calculate gcd

### Introduction

- Specifications of Markov Models
  - A Markov chain model is specified by identifying
    - (a) the set of states  $S = \{1, ..., m\}$ ,
    - (b) the set of possible transitions, namely, those pairs (i,j) for which  $p_{ij}>0$
    - (c) the numerical values of those  $p_{ij}$  that are positive.
  - The Markov chain specified by this model is a sequence of random variables  $X_0, X_1, X_2, \ldots$ , that take values in S and which satisfy

$$P(X_{n+1} = j | X_n = i, X_{n-1} = i_{n-1}, ..., X_0 = i_0) = P(X_{n+1} = j | X_n = i),$$

for all times n, all states  $i, j \in S$ , and all possible sequences  $i_0, \dots, i_{n-1}$  earlier states.

### How to represent an MC using a graph?

Motivation: Markov Models look like "frog on the lily pad"

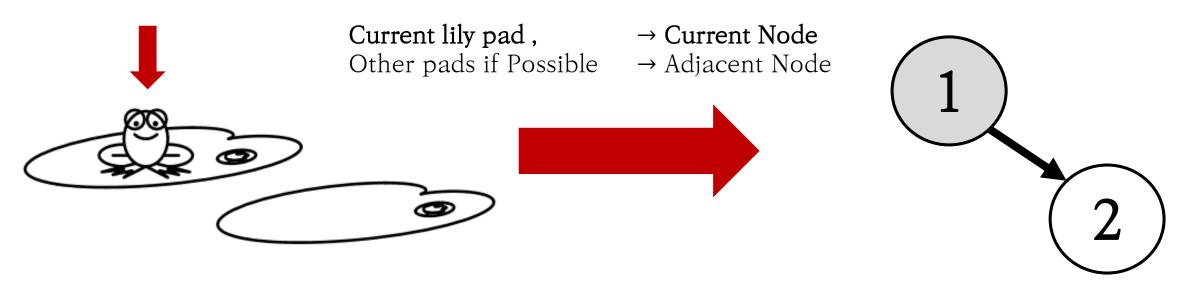


Fig 1. A randomly jumping frog. Whenever he tosses heads, he jumps to the other lily pad. [1],page 3

### How to represent an MC using a graph?

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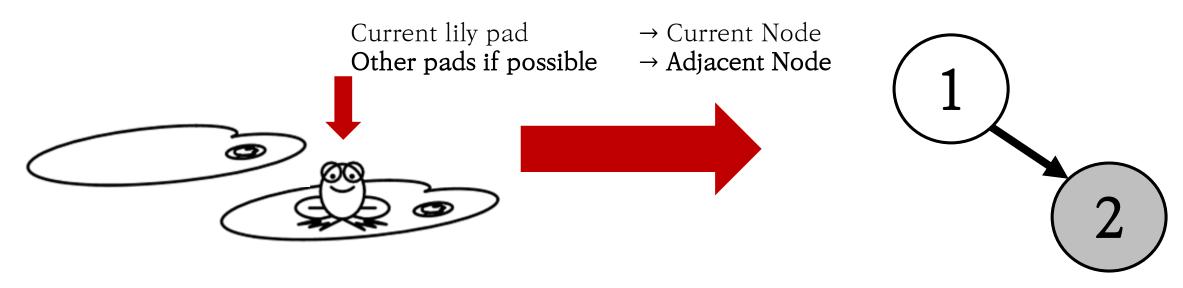
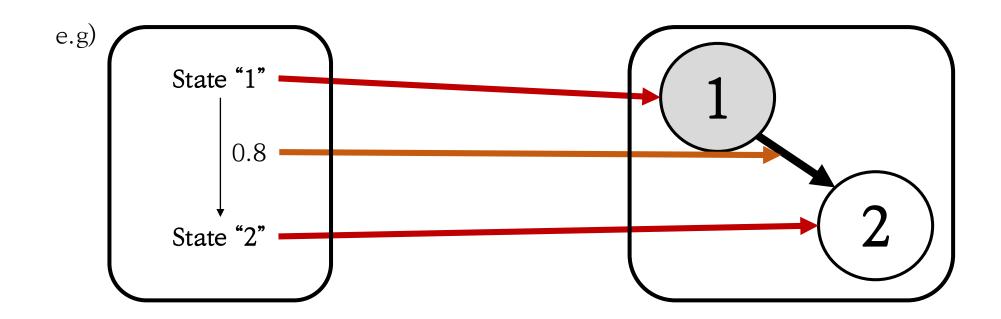


Fig 1. A randomly jumping frog. Whenever he tosses heads, he jumps to the other lily pad. [1], page 3

### How to represent an MC using a graph!

- Generate digraph G = (V, E) which has two property
  - 1) Each node corresponds to a state of **M** 
    - \* e.g)  $f: S \rightarrow V$  be a bijection which maps "state i" onto "vertex i"
  - 2) **G** contains edge  $e = (i, j) \in E$  if and only if  $p_{ij} > 0$

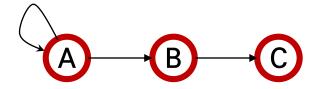


### Recurrent or Transient?

- Concepts of recurrent and transient
  - Transient
    - \* vertex *i* is transient

iff there exists some vertex *j* for which  $i \rightarrow j$  but  $j \not\rightarrow i$ 

- Recurrent
  - \* vertex *i* is recurrent iff *i* is not transient,
  - \* In other words, for all  $j \in V$ , i and j communicate. i.e  $i \leftrightarrow j$



State A is transient; Because of "C"

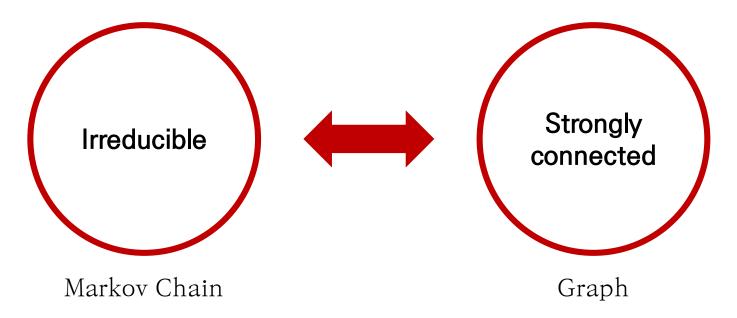


State E is recurrent

# Irreducible or Strongly connected?

#### Additional

- The Markov chain M is called irreducible if, for every pair of states i and j, there exist  $r,s \ge 0$  with  $p_{ij}^r > 0$  and  $p_{ji}^s > 0$ .
- So, Since there is a path between every pair of nodes *i, j*, Graph *G* in which Markov chain *M* is expressed is strongly connected.



#### Goal

- To find out which node is a recurrent.

#### Main Idea

- Suppose that M is a Markov chain,  $G_M = (V, E)$  be associated with the Markov chain M, and  $i, j \in V$
- **Lemma 1**: *The relation*  $\leftrightarrow$  *is an equivalence relation*:
  - (a)  $i \leftrightarrow i for all i \in V$
  - (b) if  $i \leftrightarrow j$ , then  $j \leftrightarrow i$  for all  $i, j \in V$
  - (c) if  $i \leftrightarrow j$  and  $j \leftrightarrow k$ , then  $i \leftrightarrow k$  for all  $i, j, k \in V$ .
- So, we can reduce "State Classification of M" to "Classification of equivalence classes" with respect to "  $\leftrightarrow$  ".

#### Problem Setting

- Let **M** be a finite-state Markov chain
  - \* The set of State  $S = \{1, 2, 3, ..., m\}$
  - \* The transitions probability matrix  $\mathbf{M} = [p_{ij}] \in \mathbf{R}^{m \times m}$ , where  $p_{ij}$  is the transition probability from "state i" to "state j" and for evert  $p_{ij} > 0$
- We can generate the directed graph  $G = G_M$  having the set of nodes  $V = \{1,2,3,...,m\}$  and the set of edges E
  - \* Each node corresponds to a state of **M**
  - \* G contains edge  $e = (i, j) \in E$  if  $P_{ij} > 0$  except (i, i)

Real task: Should find the roots of each strong component!!



#### back edge

lab(6) = 4

### Problem 1: State Classification

forward edge

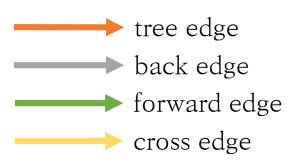
lab(3) = 3

lab(4) = 4

#### Pseudocode

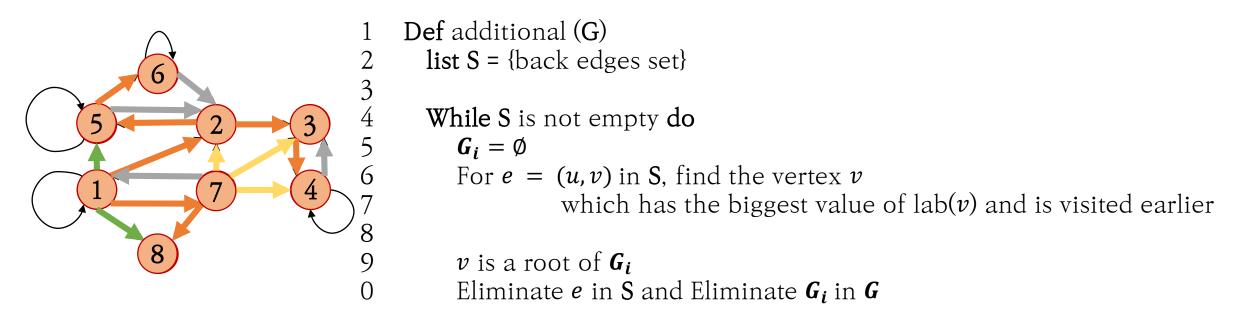
```
lab(2) = 2
     lab(v) = 1
                                                            lab(5) = 3
                             //label v as discovered
   procedure DFS(G, v):
 3
      for all edges from v to w in adj(v) do
        if vertex w is not yet labeled as discovered then
           lab(w) = lab(v) + 1;
                                                                                      lab(7) = 2
                                                                     lab(1) = 1
           edge (v, w) is classified as a tree edge
           recursively call DFS(G, w)
                                                                                 lab(8) = 3
 8
        if vertex w has already been labeled then
           if lab(v) > lab(w) and v is a descendant of w in the tree then
              edge (v, w) is classified as a back edge
10
           if lab(v) \langle lab(w)  and w is a descendant of v in the tree then
11
              edge (v, w) is classified as a forward edge
12
           if lab(v) > lab(w) and w is neither a descendant of v nor a ancestor of v then
13
              edge (v, w) is classified as a cross edge
14
```

input: G is graph, v is a start node

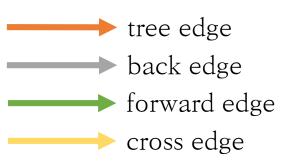


• Toy Problem ( $\mathbf{R} = \emptyset$ )

*input:* Graph **G** *output:* Condensed Graph **G** 

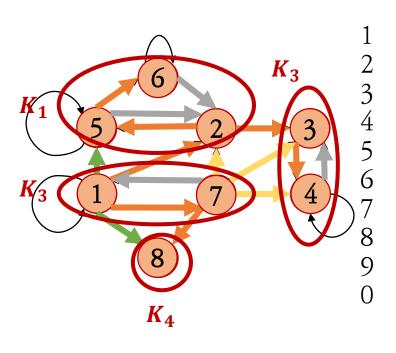


#### G<sub>i</sub>: Strongly component. R: the set of Roots



• Toy Problem ( $\mathbf{R} = \emptyset$ )

*input:* Graph **G** *output:* Condensed Graph **G** 



Def additional (G)
 list S = {back edges set}

While S is not empty do

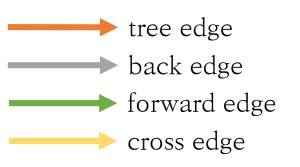
 $G_i = \emptyset$ 

For e = (u, v) in S, find the vertex v

which has the biggest value of lab(v) and is visited earlier

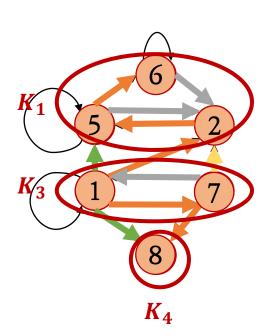
v is a root of  $G_i$ 

Eliminate e in S and Eliminate  $G_i$  in G



• Toy Problem ( $\mathbf{R} = \{3\}$ )

*input:* Graph **G** *output:* Condensed Graph **G** 



```
Def additional (G)
list S = {back edges set}

While S is not empty do

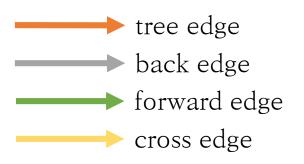
G<sub>i</sub> = Ø

For e = (u, v) in S, find the vertex v

which has the biggest value of lab(v) and is visited earlier

v is a root of G<sub>i</sub>

Eliminate e in S and Eliminate G<sub>i</sub> in G
```



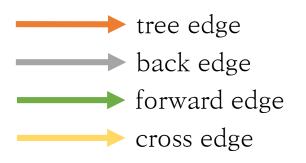
• Toy Problem (**R** $= {3, 2}$ )

*input:* Graph **G** *output:* Condensed Graph **G** 

```
While S is not empty do
G_{i} = \emptyset
For e = (u, v) \text{ in S, find the vertex } v
which has the biggest value of lab(v) and is visited earlier
v \text{ is a root of } G_{i}
Eliminate e \text{ in S and Eliminate } G_{i} \text{ in } G
```

**Def** additional (**G**)

list S = {back edges set}



• Toy Problem ( $\mathbf{R} = \{3,2,1\}$ )

*input:* Graph **G** *output:* Condensed Graph **G** 

```
Def additional (G)
list S = {back edges set}

While S is not empty do

G<sub>i</sub> = Ø

For e = (u, v) in S, find the vertex v

which has the biggest value of lab(v) and is visited earlier

v is a root of G<sub>i</sub>

Eliminate e in S and Eliminate G<sub>i</sub> in G
```



Then, We can identify the roots  $r_i$  of  $G_i$ 

• Toy Problem ( $\mathbf{R} = \{3,2,1,8\}$ )

```
Def additional (G)

2 list S = {back edges set}

3

While S is not empty do

G_i = \emptyset

For e = (u, v) in S, find the vertex v

which has the biggest value of lab(v) and is visited earlier

v is a root of v

Eliminate v in S and Eliminate v

Eliminate v in v
```

Additional, if there exist edges between  $G_i$  and  $G_j$ , Then plus an edge in condensed graph  $\widehat{G}$ 

- Convergence behavior to an Optimal solution
  - By lemma 3, we can say that for every vertax  $v \in K_1, K_3$ , v is recurrent and for every vertax  $w \in K_2, K_4$ , w is recurrent
  - Time Complexity: O(|V| + |E|)
    - \* Therefore, we are able to solve this problem using *DFS* in a polynomial time.

**Lemma 3:** The recurrent nodes of graph G are precisely those nodes whose corresponding supernodes have no leaving edges in  $\widehat{G}$ .

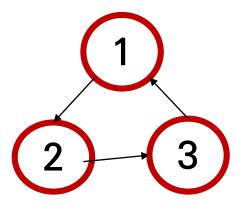
### Why we need to represent an MC using a graph?

- So we can induce that
  - Theorem 1: If G is strongly connected then there is a unique stationary distribution  $\pi$  for M.
    - \* Proof: Since G is strongly connected, Markov chain M is irreducible. By steady-state convergence theorem in chap.6, we induce that Markov chain M has a unique stationary distribution  $\pi$ . And so for  $\pi_i$ ,  $\pi_i > 0$ .
  - Theorem 2: If the condensed graph  $\hat{G}$  for G has a single supernode with no leaving edges then there is a unique stationary distribution  $\pi$  for M.

    Moreover,  $\pi_i > 0$  for all  $j \in R$ , and  $\pi_i = 0$  for all  $j \in T$ .
    - \* Proof: Since  $\hat{\mathbf{G}}$  has the supernode with no leaving edges,  $\mathbf{G}$  is strongly connected and Markov chain  $\mathbf{M}$  is irreducible and a single recurrent class.

#### Goal

- To find out the "limiting behavior" of a Markov chain
- In other words, to find out the "Periodicity" of a Markov chain
  - \* Definition
    - The period of state i is the largest integer d such that  $p_{ii}^k = 0$  whenever k is not a positive integer multiple of d (that is,  $k \neq d, 2d, 3d, ...$ ).



For any  $k \neq 3, 6, 9, ...$ ,

If we start in state 1, we can **not go back** to state 1



- **Lemma 5**: if x has a period d and  $x \leftrightarrow y$ , y has also a period d
  - Let d(i) and d(j) be period of i and j.
  - Suppose that  $i \neq j$ . so there exists  $r, s \geq 0$  with  $p_{ii}^r > 0$  and  $p_{ii}^s > 0$ . (i.e i  $\rightarrow j$ ,  $i \leftarrow j$ )
    - (a)  $P_{ii}^{r+s} \ge p_{ij}^r * p_{ji}^s > 0$  and hence  $r+s = 0 \mod d(i)$
    - (b) Suppose that n is a positive integer with  $P_{jj}^n > 0$ . Hence,  $P_{xx}^{j+k+n} > 0$  and hence  $j + k + n = 0 \mod d(i)$
    - Since (a) and (b), we induce that d(i)|n and then by the definition of period, d(j)|d(i) and similarly, d(i)|d(j)

 $p_{ji}^{s} > 0$   $p_{jj}^{r} > 0$   $p_{jj}^{n} > 0$ 

And ~ is an equivalence relation

Therefore, we can get a period of M by clustering equivalence classes with respect to "~"

Algorithm Design: How to calculate?

**Theorem 4**: **M** has period d iff its digraph G can be partitioned into d sets  $C_0, C_1, ..., C_{d-1}$  such that (a) if  $i \in C_k$  and  $(i,j) \in E$  then  $j \in C_{(k+1) \mod d}$  (b) d is the largest integer with this property.

For every pair of nodes i and j in G, all (i,j) — paths in G have the same length modulo d.

#### Algorithm Design

**Theorem 4**: **M** has period d iff its digraph G can be partitioned into d sets  $C_0, C_1, ..., C_{d-1}$  such that (a) if  $i \in C_k$  and  $(i,j) \in E$  then  $j \in C_{(k+1) \mod d}$ 

(b) d is the largest integer with this property.

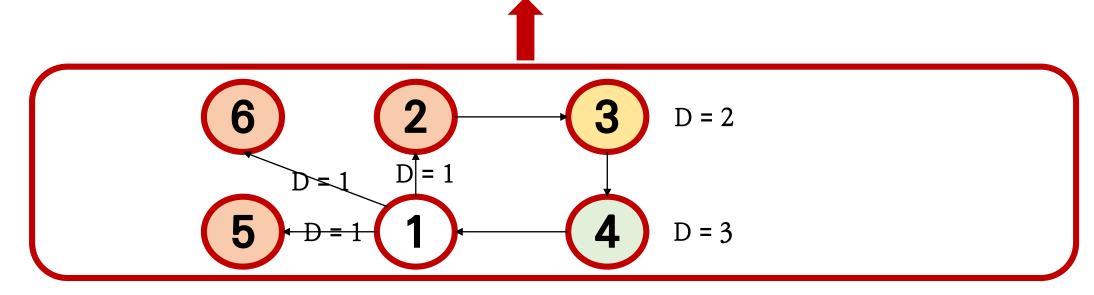
For every pair of nodes i and j in G, all **CYCLE** including i and j have the same length modulo d.

#### Algorithm Design

**Theorem 4**: **M** has period d

iff its digraph G can be partitioned into d sets  $C_0, C_1, \dots, C_{d-1}$  such that

- (a) if  $i \in C_k$  and  $(i,j) \in E$  then  $j \in C_{(k+1) \mod d}$
- (b) d is the largest integer with this property.



#### Algorithm Design

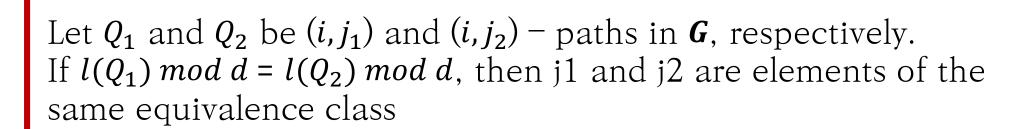
**Theorem 4**: **M** has period d iff its digraph G can be partitioned into d sets  $C_0, C_1, ..., C_{d-1}$  such that (a) if  $i \in C_k$  and  $(i,j) \in E$  then  $j \in C_{(k+1) \mod d}$ 

(b) d is the largest integer with this property.

Let  $Q_1$  and  $Q_2$  be  $(i, j_1)$  and  $(i, j_2)$  – paths in G, respectively. If  $l(Q_1)$  mod  $d = l(Q_2)$  mod d, then j1 and j2 are elements of the same equivalence class

#### Algorithm Design

**Theorem 4**: **M** has period d iff its digraph G can be partitioned into d sets  $C_0, C_1, ..., C_{d-1}$  such that (a) if  $i \in C_k$  and  $(i,j) \in E$  then  $j \in C_{k+1 \mod d}$  (b) d is the largest integer with this property.



#### Algorithm Design

- By collecting nodes having the length of path  $x \mod d$ , the set of distinct equivalence classes forms a partition of V.
- In the irreducible Markov chain M, every transition moves from a node in  $C_k$  to a node in  $C_{k+1 \mod d}$  by Theorem 4.
- Using this property, we can find the sets of nodes  $C_k$  in G by examining the nodes of G in order of non-decreasing path length from an arbitrary starting node.
- So, use *Breadth First Search!!*

#### Problem Setting

- Suppose that **M** is finite-state Markov chain and it is irreducible
  - \* The set of State  $S = \{1, 2, 3, ..., m\}$
  - \* The transitions probability matrix  $\mathbf{M} = [p_{ij}] \in \mathbf{R}^{m \times m}$ , where  $p_{ij}$  is the transition probability from "state i" to "state j" and for evert  $p_{ii} > 0$
- We can generate the directed graph  $G = G_M$  having the set of nodes  $N = \{1,2,3,...,m\}$  and the set of edges E
  - \* Each node corresponds to a state of **M**
  - \* G contains edge  $e = (i, j) \in E$  if  $p_{ij} > 0$

#### Real task: Find the period of strong component

#### Pseudocode

```
procedure BFS (G, v):
                                                             Algorithm 1: Finding the period d of M
       level(v) = 0
        create a queue \boldsymbol{Q}
                                                             1. From an arbitrary root node, perform a breadth-
        enqueue source on to \boldsymbol{Q}
                                                                 first search of \boldsymbol{G} producing the rooted tree \boldsymbol{T}.
        mark v
                                                             2. The period g is given by gcd\{val(e) | e \notin T\}
       while Q is not empty:
           v \leftarrow \text{dequeue} \text{ an item from } Q
           r = level(v)
8
           for each edge e incident on v in G do
              let \boldsymbol{w} be the other end of \boldsymbol{e}
              if w is not yet labeled as discovered then
10
                 level(\mathbf{w}) = \mathbf{r} + 1 \qquad \# mark \mathbf{w}
                 add e in tree edge set
13
                 enqueue \boldsymbol{w} on to \boldsymbol{Q}
              else
15
                 s = level(w)
                 If s < r then
                                  # i is an ancestor of i in the search tree
16
                     add e in back edge
17
                                                                                   BFS algorithm
                 else # (s \le r + 1)
18
                                                                                   input: G is graph, v is a start node
19
                     add e in cross edge
                                                                                   Output: T is a Spanning Tree
```

#### Toy Problem

```
procedure BFS (G, v):
        level(\boldsymbol{v}) = 0
        create a queue \boldsymbol{Q}
        enqueue source on to \boldsymbol{Q}
        mark v
        while Q is not empty:
            v \leftarrow \text{dequeue an item from } Q
            r = level(v)
            \mathbf{for} each edge \mathbf{e} incident on \mathbf{v} in \mathbf{G} do
9
               let \boldsymbol{w} be the other end of \boldsymbol{e}
10
               if w is not yet labeled as discovered then
                   level(\mathbf{w}) = \mathbf{r} + 1 \qquad \# mark \mathbf{w}
11
                   add e in tree edge set
12
13
                   enqueue \boldsymbol{w} on to \boldsymbol{Q}
               else
15
                   s = level(w)
                   If s < r then
                                             #j is an ancestor of i in the search tree
16
                                                                                                                               tree edge
                       add e in back edge
17
                                                                                                                              back edge
18
                   else # (s \leq r + 1)
19
                       add e in cross edge
                                                                                                                               cross edge
```

#### Toy Problem

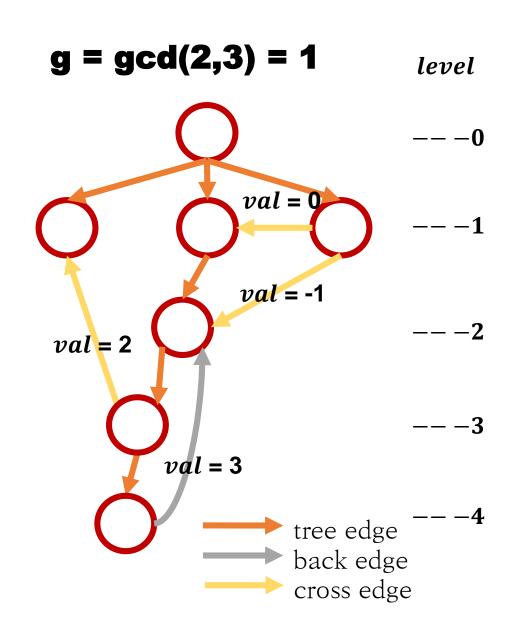
Algorithm 1: Finding the period d of M

- 1. From an arbitrary root node, perform a breadth-first search of *G* producing the rooted tree *T*.
- 2. The period g is given by  $gcd\{val(e) > 0 | e \notin T\}$

#### Second line!!

- Input: T is Spanning Tree
- Output: a period g of M

Let 
$$e = (u, v)$$
.  
**Define**  $val(e)$  by  $val(e) = val(u, v)$   
 $= level(u) - level(v) + 1$   
Therefore, if  $e \notin T$ ,  $val(e) > 0$ , else  $val(e) = 0$ 



- Convergence behavior to an Optimal solution
  - To establish the correctness of Algorithm 1, it is sufficient to show that  $g = gcd\{val(e) > 0 | e \notin T\}$  divides the length of an arbitrary cycle W in G.
    - \* 1) g|d: because d is period and g is the gcd of all cycle.
    - \* 2) since we have already seen d|g, then we must has g = d
  - Algorithm 1: two parts
    - \* executing the breadth-first search  $\rightarrow$  Time Complexity: O(|E|)
    - \* finding the greatest common divisor  $\rightarrow$  Time Complexity: O(|E|)

### Reference

- [1] Levin, David Asher, Yuval Peres, and Elizabeth Lee Wilmer. Markov chains and mixing times. American Mathematical Soc., 2009.
- [2] J. P. Jarvis, D. R. Shier. Graph-Theoretic Analysis of Finite Markov Chains.