Optimization Methods. Seminar 1. Introduction.

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Survey for students

- Name
- Base chair
- Final project in Computer Science course
- Familiarity with LATEX
- Expectations of this course
- Favorite course for 2 study-years and why
- Future directions: academia, industry, etc.

Expected outcome of this course

- Formalization of the problem: how to select an element from a set?
- Justification of the decision correctness
- Wide range of applications:
 - machine learning: classification, clustering, regression
 - molecular modeling
 - risk analysis
 - portfolio optimization
 - optimal control
 - sigmal processing
 - parameters estimation in statistic
 - many-many others¹

http://www.cvxpy.org/en/latest/examples/index.html

Short syllabus — general

Fall term (theory):

- Convex analysis
- Duality theory
- Optimality conditions

Spring term (practice):

- Methods for uncontrained optimization problems first and second orders
- Methods for constrained optimization problems
- Linear programming: simplex method and others
- Optimal methods
- ..



Fall term syllabus — detailed

- Lecture and seminar once a week
- Two problem sets
- Final test in the end of term (and midterm test in the middle of the term)
- Oral exam in the end of term. Grading policy average the following grades:
 - grade for the term
 - grade for the exam
- Minitests at the beginning of every seminar
- Homework after every seminar LATEX

Prerequisities¹

- Linear algebra
- Calculus
- Programming: Python (NumPy, SciPy, CVXPY) or MATLAB
- Selected topics of computational mathematics

Methodology

Main steps of usage optimization methods in solving real-world problems:

- 1. Define objective function
- 2. Define feasible set
- 3. Optimization problem statement and its analysis
- 4. Selection of the best algorithm for stated problem
- 5. Algorithm implementation and verification its correctness

Problem statement

$$\min_{\mathbf{x} \in X} f_0(\mathbf{x})$$
s.t. $f_i(\mathbf{x}) = 0, i = 1, \dots, p$
 $f_j(\mathbf{x}) \le 0, j = n + 1, \dots, m,$

- $\mathbf{x} \in \mathbb{R}^n$ target variable
- $f_0(\mathbf{x}): \mathbb{R}^n \to \mathbb{R}$ objective function
- $f_j(\mathbf{x}): \mathbb{R}^n \to \mathbb{R}$ constraints functions

Example: selection items to invest money and defining how much money invest in every item:

- x amount of money to invest in every item
- f₀ total risk or revenue deviation
- f_j budget constraints, min/max invest in item, minimal accepted revenue...

How to solve?

General case:

- NP-hard
- randomized algorithms: time vs stability

BUT some families of problems can be solved very fast!

- Linear programming
- Least squares problem
- Lowrank approximation
- Convex optimization

Linear programming

$$\min_{\mathbf{x} \in \mathbb{R}^n} \mathbf{c}^\mathsf{T} \mathbf{x}$$
s.t. $\mathbf{a}_i^\mathsf{T} \mathbf{x} \le c_i, \ i = 1, \dots, m$

- no analytical solution
- effective algorithms exist
- developed technology
- simplex method for solving problem (1) is included in the TOP-10 algorithms of XX century²

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Least squares problem

$$\min_{\mathbf{x} \in \mathbb{R}^n} \|\mathbf{A}\mathbf{x} - \mathbf{b}\|_2^2, \tag{2}$$

where $\mathbf{A} \in \mathbb{R}^{m \times n}$ and $\mathbf{b} \in \mathbb{R}^m$

- analytical solution: $\mathbf{x}^* = (\mathbf{A}^\mathsf{T} \mathbf{A})^{-1} \mathbf{A}^\mathsf{T} \mathbf{b}$
- effective algorithms exist
- developed technology
- statistical interpretation

Lowrank approximation

$$\min_{\mathbf{X} \in \mathbb{R}^{m \times n}} \|\mathbf{A} - \mathbf{X}\|_{F}$$
s.t. $\operatorname{rank}(\mathbf{X}) \le k$ (3)

Theorem (Eckart-Young, 1993)

Let $\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^{\mathsf{T}}$ be a singular value decomposition of matrix \mathbf{A} , where $\mathbf{U} = [\mathbf{U}_k, \mathbf{U}_{r-k}] \in \mathbb{R}^{m \times r}$, $\mathbf{\Sigma} = \mathrm{diag}(\sigma_1, \ldots, \sigma_k, \ldots, \sigma_r)$, $\mathbf{V} = [\mathbf{V}_k, \mathbf{V}_{r-k}] \in \mathbb{R}^{n \times r}$ and $r = \mathrm{rank}(\mathbf{A})$. Then the solution of the problem (3) can be written as:

$$\mathbf{X} = \hat{\mathbf{U}}\hat{\boldsymbol{\Sigma}}\hat{\mathbf{V}}^{\mathsf{T}},$$

where $\hat{\mathbf{U}} \in \mathbb{R}^{m \times k}$, $\hat{\mathbf{\Sigma}} = \operatorname{diag}(\sigma_1, \dots, \sigma_k)$, $\hat{\mathbf{V}} \in \mathbb{R}^{n \times k}$.

Algorithms to compute SVD are stable and fast simultaneously

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Convex optimization

$$\min_{\mathbf{x} \in \mathbb{R}^n} f_0(\mathbf{x})$$
s.t. $f_i(\mathbf{x}) \leq b_i, \ i = 1, \dots, m$ (4)

• f_0, f_i — convex functions:

$$f(\alpha \mathbf{x}_1 + \beta \mathbf{x}_2) \leq \alpha f(\mathbf{x}_1) + \beta f(\mathbf{x}_2),$$

where $\alpha, \beta \geq 0$ and $\alpha + \beta = 1$.

- no analytical solution
- effective algorithms exist
- recognition convex optimization problem is often difficult
- techniques to reformulate a problem to the form (4) exist

What problem is easier?

Search independent alphabet of the maximum cardinality

$$\max_{\mathbf{x} \in \mathbb{R}^n} \sum_{i=1}^n x_i$$
s.t. $x_i^2 - x_i = 0$ $i = 1, ..., n$

$$x_i x_j = 0$$
 $\forall (i, j) \in \Gamma$,

where Γ is a set of pairs

Truss design

$$\min -2\sum_{i=1}^{k}\sum_{i=1}^{m}c_{ij}x_{ij}+x_{00}$$

s.t.
$$\sum_{i=1}^{k} x_i = 1$$
 $\lambda_{\min}(\mathbf{A}) \geq 0$,

where
$$\mathbf{A} = \begin{bmatrix} x_1 & \dots & \sum\limits_{j=1}^m b_{pj} x_{1j} \\ \vdots & \ddots & \vdots \\ x_k & \sum\limits_{j=1}^m b_{pj} x_{kj} \\ \sum\limits_{j=1}^m b_{pj} x_{1j} & \dots & \sum\limits_{j=1}^m b_{pj} x_{kj} & x_{00} \end{bmatrix}$$

Why convexity is so important?

R. Tyrrell Rockafellar (1935 —)

The great watershed in optimization is not between linearity and non-linearity, but convexity and non-convexity.

- Local optimum is global
- Necessary optimality condition is sufficient

Questions:

- Is any convex optimization problem solved efficiently?
- Could non-convex optimization problems be solved efficiently?

Recap

- Admistrative issues
- Objective of the Optimization Methods course
- General optimization problem statement
- Classical optimization problems