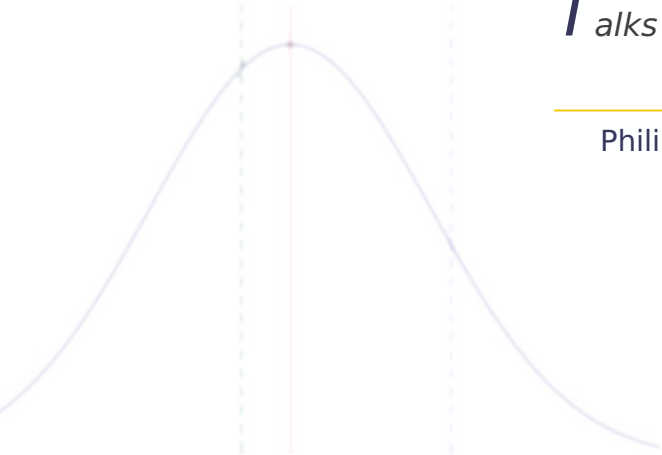


# $T_{alks}$

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Philipp Eisenhauer



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# Sensitivity analysis

Philipp Eisenhauer

I draw on the material presented in:

- ▶ Saltelli, A., Tarantola, S., Campolongo, F., & Ratto, M. (2004). *Sensitivity analysis in practice: A guide to assessing scientific models*. John Wiley & Sons.
- ▶ Saltelli, A., Ratto, M., Andres, T., Campolongo, F., Cariboni, J., Gatelli, D., . . . Tarantola, S. (2008). *Global sensitivity analysis: The primer*. John Wiley & Sons.

## Definitions

*Sensitivity analysis* The study of how uncertainty in the output of a model (numerical or otherwise) can be apportioned to different sources of uncertainty in the model input

- ▶ uncertainty propagation

## **Selected issues**

- ▶ computational challenges
- ▶ deterministic vs. probabilistic
- ▶ independent vs. dependent
- ▶ global vs. local

## **Selected issues**

- ▶ quantitative vs. qualitative
- ▶ interaction vs. dependence
- ▶ full model vs. surrogate

## Settings

- ▶ *factor prioritization*, i.e. which factor is the one that, if determined (i.e., fixed to its true, albeit unknown, value), would lead to the greatest reduction in the variance of the output.
- ▶ *factor fixing*, i.e. which factor or the subset of input factors that we can fix at any given value over their range of uncertainty without significantly reducing the output variance.

## **Sensitivity analysis in economics**

- ▶ Harenberg, D., Marelli, S., Sudret, B., & Winschel, V. (2019). Uncertainty quantification and global sensitivity analysis for economic models. *Quantitative Economics*, 10(1), 1–41.



# Notation

The model input vector  $\mathbf{X} = (X_1, \dots, X_N) \in \mathbb{R}^d$ . The quantity of interest  $y$  of the model  $f(\cdot)$ :

$$Y = f(\mathbf{X})$$

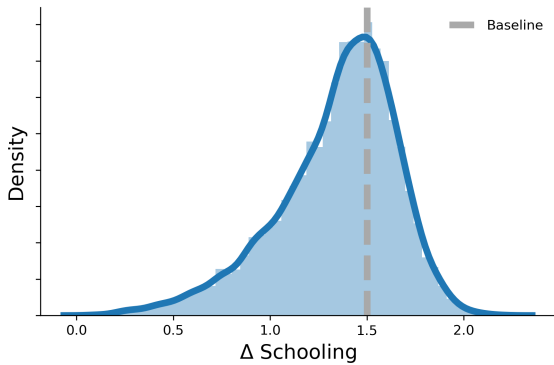
Following the literature, all parameters  $x_i$  are scaled to take on values in the interval  $[0, 1]$ , and the region of interest  $\Omega$  is the  $k$ - dimensional unit hypercube.

- ▶ We collect all parameter in  $\mathbf{x} = [x_1, \dots, x_n]$ .  $x_i$  denotes one
- ▶ particular value for input parameter  $i$  and  $\mathbf{x}_{\sim i} = [x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_n]$  as the complementary set of inputs.
- ▶ We use the notation  $x_i$  and  $\bar{x}_i$  to distinguish a random vector  $x_i$  generated from a joint probability density function  $p(x_i, \mathbf{x}_{\sim i})$  and a random vector  $\bar{x}_i$  generated from a conditional probability distribution  $p(\bar{x}_i, \mathbf{x}_{\sim i} \mid \mathbf{x}_{\sim i})$ .

# **Uncertainty propagation**

- ▶ We sample from the distribution of input parameters and assess the distribution of the quantity of interest.

Figure: Uncertainty propagation



# Qualitative

Morris method for independent and dependent factors.

- ▶ Morris, M. D. (1991). Factorial sampling plans for preliminary computational experiments. *Technometrics*, 33(2), 161–174.
- ▶ Ge, Q., & Menendez, M. (2017). Extending morris method for qualitative global sensitivity analysis of models with dependent inputs. *Reliability Engineering & System Safety*, 162, 28–39.



- ▶ The approach segments the model input ranges  $[x_i^-, x_i^+]$  in  $l$  levels. Given  $l$  levels with  $m$  inputs, there are  $l^m$  points in the grid from which a subset of  $r$  points is drawn at random. For each of the  $r$ , the model is evaluated performing a series of OAT sensitivities.

$$ee_i = \frac{f(x_1, \dots, x_{i-1}, x_i + \Delta, x_{i+1}, \dots, x_n) - f(\mathbf{x})}{\Delta}$$

$$ee_i^{ind} = \frac{f(\bar{x}_i, \mathbf{x}_{\sim i}) - f(x_i, \mathbf{x}_{\sim i})}{\Delta}$$

$$ee_i^{dep} = \frac{f(\bar{x}_i, \bar{\mathbf{x}}_{\sim i}) - f(x_i, \mathbf{x}_{\sim i})}{\Delta}$$

$$\mu_i^j = \frac{1}{N} \sum_{r=1}^n |ee_{ir}^j|$$

$$\sigma_i^j = \frac{1}{N-1} \sum_{r=1}^n (ee_{ir}^j - \mu_i^j)^2$$

# Quantitative

$$V[Y] = V_{X_i}[E_{X \sim i}[Y \mid X_i]] + E_{X_i}[V_{\mathbf{X} \sim i}[Y \mid X_i]] \quad (1)$$

## Main effect

- ▶ We rank all based on the smallest conditional variance  $V[Y | X_i = x_i]$  evaluated over all possible values  $x_i$  of  $X_i$ . Following Equation (1), this is equivalent to ranking factors by the largest  $V_{X_i}[E_{\mathbf{x}_{\sim i}}[Y | X_i]]$  and so the main effect is defined as:

$$S_i^M = \frac{V_{X_i}[E_{\mathbf{x}_{\sim i}}[Y | X_i]]}{V[Y]}$$

## Total effect

- ▶ We want to identify the factors that we can fix at their value without significantly reducing the output variance.

$$S_i^T = \frac{E_{\mathbf{x}_{\sim i}}[V_{X_i}[Y \mid \mathbf{X}_{\sim i}]]}{V[Y]} = 1 - S_{\sim i}^M$$



# Appendix

# *References*

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- Hahn, J., Todd, P. E., & van der Klaauw, W. (2001). Identification and estimation of treatment effects with a regression-discontinuity design. *Econometrica*, 69(1), 201–209.
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