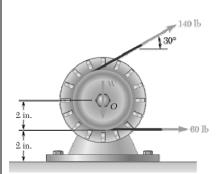
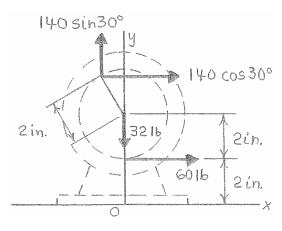
### **PROBLEM 3.151**



A 32-lb motor is mounted on the floor. Find the resultant of the weight and the forces exerted on the belt, and determine where the line of action of the resultant intersects the floor.

# **SOLUTION**



Have

$$\Sigma$$
**F**:  $(60 \text{ lb})\mathbf{i} - (32 \text{ lb})\mathbf{j} + (140 \text{ lb})(\cos 30^{\circ}\mathbf{i} + \sin 30^{\circ}\mathbf{j}) = \mathbf{R}$ 

$$\therefore$$
 **R** =  $(181.244 \text{ lb})\mathbf{i} + (38.0 \text{ lb})\mathbf{j}$ 

or  $\mathbf{R} = 185.2 \text{ lb } \angle 11.84^{\circ} \blacktriangleleft$ 

Have

$$\Sigma M_O$$
:  $\Sigma M_O = xR_y$ 

$$- [(140 \text{ lb})\cos 30^\circ][(4 + 2\cos 30^\circ)\text{in.}] - [(140 \text{ lb})\sin 30^\circ][(2 \text{ in.})\sin 30^\circ]$$

$$- (60 \text{ lb})(2 \text{ in.}) = x(38.0 \text{ lb})$$

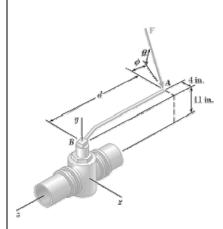
$$x = \frac{1}{38.0}(-694.97 - 70.0 - 120) \text{ in.}$$

and

$$x = -23.289$$
 in.

Or, resultant intersects the base (x axis) 23.3 in. to the left of the vertical centerline (y axis) of the motor.  $\triangleleft$ 

### **PROBLEM 3.152**



To loosen a frozen valve, a force **F** of magnitude 70 lb is applied to the handle of the valve. Knowing that  $\theta=25^{\circ}$ ,  $M_x=-61$  lb·ft, and  $M_z=-43$  lb·ft, determine  $\theta$  and d.

## **SOLUTION**

Have

$$\Sigma \mathbf{M}_O$$
:  $\mathbf{r}_{A/O} \times \mathbf{F} = \mathbf{M}_O$ 

where

$$\mathbf{r}_{A/O} = -(4 \text{ in.})\mathbf{i} + (11 \text{ in.})\mathbf{j} - (d)\mathbf{k}$$

 $\mathbf{F} = F(\cos\theta\cos\phi\mathbf{i} - \sin\theta\mathbf{j} + \cos\theta\sin\phi\mathbf{k})$ 

For

$$F = 70 \text{ lb}, \theta = 25^{\circ}$$

$$\mathbf{F} = (70 \text{ lb}) \left[ (0.90631 \cos \phi) \mathbf{i} - 0.42262 \mathbf{j} + (0.90631 \sin \phi) \mathbf{k} \right]$$

∴ 
$$\mathbf{M}_O = (70 \text{ lb})$$
  $\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -4 & 11 & -d \\ -0.90631\cos\phi & -0.42262 & 0.90631\sin\phi \end{vmatrix}$  in.

= 
$$(70 \text{ lb})[(9.9694 \sin \phi - 0.42262d)\mathbf{i} + (-0.90631d \cos \phi + 3.6252 \sin \phi)\mathbf{j}]$$

$$+(1.69048 - 9.9694\cos\phi)\mathbf{k}$$
 in.

and

$$M_x = (70 \text{ lb})(9.9694 \sin \phi - 0.42262d) \text{ in.} = -(61 \text{ lb} \cdot \text{ft})(12 \text{ in./ft})$$
 (1)

$$M_y = (70 \text{ lb})(-0.90631d\cos\phi + 3.6252\sin\phi)\text{in}.$$
 (2)

$$M_z = (70 \text{ lb})(1.69048 - 9.9694\cos\phi) \text{ in.} = -43 \text{ lb} \cdot \text{ft}(12 \text{ in./ft})$$
 (3)

# **PROBLEM 3.152 CONTINUED**

From Equation (3)

$$\phi = \cos^{-1} \left( \frac{634.33}{697.86} \right) = 24.636^{\circ}$$

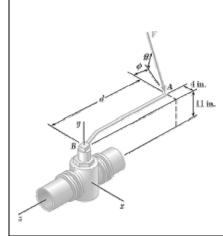
or  $\phi = 24.6^{\circ} \blacktriangleleft$ 

From Equation (1)

$$d = \left(\frac{1022.90}{29.583}\right) = 34.577 \text{ in.}$$

or d = 34.6 in.

### **PROBLEM 3.153**



When a force **F** is applied to the handle of the valve shown, its moments about the x and z axes are, respectively,  $M_x = -77 \text{ lb} \cdot \text{ft}$  and  $M_z = -81 \text{ lb} \cdot \text{ft}$ . For d = 27 in., determine the moment  $M_y$  of **F** about the y axis.

#### **SOLUTION**

Have

$$\Sigma \mathbf{M}_{O}$$
:  $\mathbf{r}_{A/O} \times \mathbf{F} = \mathbf{M}_{O}$ 

where

$$\mathbf{r}_{A/O} = -(4 \text{ in.})\mathbf{i} + (11 \text{ in.})\mathbf{j} - (27 \text{ in.})\mathbf{k}$$

 $\mathbf{F} = F(\cos\theta\cos\phi\mathbf{i} - \sin\theta\mathbf{j} + \cos\theta\sin\phi\mathbf{k})$ 

$$\therefore \mathbf{M}_{O} = F \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -4 & 11 & -27 \\ \cos\theta\cos\phi & -\sin\theta & \cos\theta\sin\phi \end{vmatrix} \text{lb·in.}$$

$$= F \Big[ \Big( 11 \cos \theta \sin \phi - 27 \sin \theta \Big) \mathbf{i} + \Big( -27 \cos \theta \cos \phi + 4 \cos \theta \sin \phi \Big) \mathbf{j} \Big]$$

$$+(4\sin\theta - 11\cos\theta\cos\phi)\mathbf{k}](\mathrm{lb}\cdot\mathrm{in.})$$

and

$$M_x = F(11\cos\theta\sin\phi - 27\sin\theta)(1b\cdot\text{in.}) \tag{1}$$

$$M_{y} = F(-27\cos\theta\cos\phi + 4\cos\theta\sin\phi)(\text{lb}\cdot\text{in.})$$
 (2)

$$M_z = F(4\sin\theta - 11\cos\theta\cos\phi)(\text{lb}\cdot\text{in.})$$
(3)

$$\cos\theta\sin\phi = \frac{1}{11} \left( \frac{M_x}{F} + 27\sin\theta \right) \tag{4}$$

$$\cos\theta\cos\phi = \frac{1}{11} \left( 4\sin\theta - \frac{M_z}{F} \right) \tag{5}$$

Substituting Equations (4) and (5) into Equation (2),

$$M_{y} = F \left\{ -27 \left[ \frac{1}{11} \left( 4\sin\theta - \frac{M_{z}}{F} \right) \right] + 4 \left[ \frac{1}{11} \left( \frac{M_{x}}{F} + 27\sin\theta \right) \right] \right\}$$

or

$$M_y = \frac{1}{11} (27M_z + 4M_x)$$

# **PROBLEM 3.153 CONTINUED**

Noting that the ratios  $\frac{27}{11}$  and  $\frac{4}{11}$  are the ratios of lengths, have

$$M_y = \frac{27}{11} (-81 \text{ lb} \cdot \text{ft}) + \frac{4}{11} (-77 \text{ lb} \cdot \text{ft}) = 226.82 \text{ lb} \cdot \text{ft}$$

or  $M_y = -227 \text{ lb} \cdot \text{ft} \blacktriangleleft$