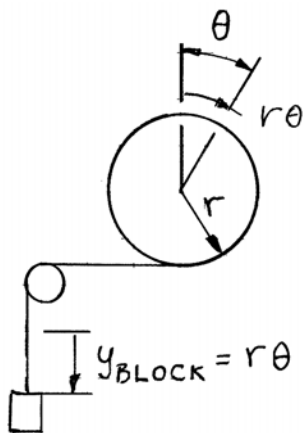


PROBLEM 10.81

Spring AB of constant 10 lb/in. is attached to two identical drums as shown. Knowing that the spring is unstretched when $\theta = 0$, determine (a) the range of values of the weight W of the block for which a position of equilibrium exists, (b) the range of values of θ for which the equilibrium is stable.

SOLUTION



Have

$$V = \frac{1}{2} k x_{SP}^2 - W y_{\text{block}}$$

where

$$x_{SP} = 2r_A \sin \theta, \quad r_A = 6 \text{ in.}$$

and

$$y_{\text{block}} = r\theta, \quad r = 8 \text{ in.}$$

Then

$$V = \frac{1}{2} k (2r_A \sin \theta)^2 - Wr\theta$$

$$= 2kr_A^2 \sin^2 \theta - Wr\theta$$

and

$$\frac{dV}{d\theta} = 2kr_A^2 (2 \sin \theta \cos \theta) - Wr$$

$$= 2kr_A^2 \sin 2\theta - Wr$$

$$\frac{d^2V}{d\theta^2} = 4kr_A^2 \cos 2\theta \quad (1)$$

For equilibrium

$$\frac{dV}{d\theta} = 0: \quad 2kr_A^2 \sin 2\theta - Wr = 0$$

Substituting,

$$2(10 \text{ lb/in.})(6 \text{ in.})^2 \sin 2\theta - W(8 \text{ in.}) = 0$$

or

$$W = 90 \sin 2\theta \text{ (lb)}$$

(a) From Equation (2), with $W \geq 0$:

$$0 \leq W \leq 90 \text{ lb} \quad \blacktriangleleft$$

(b) From Stable equilibrium

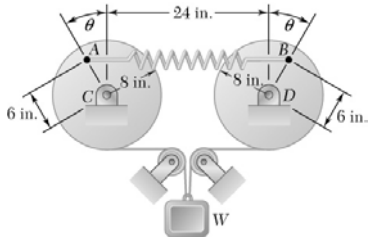
$$\frac{d^2V}{d\theta^2} > 0$$

Then from Equation (1),

$$\cos 2\theta > 0$$

$$\text{or } 0 \leq \theta \leq 45^\circ \quad \blacktriangleleft$$

PROBLEM 10.82



Spring AB of constant 10 lb/in. is attached to two identical drums as shown. Knowing that the spring is unstretched when $\theta = 0$ and that $W = 40$ lb, determine the values of θ less than 180° corresponding to equilibrium. State in each case whether the equilibrium is stable, unstable, or neutral.

SOLUTION

See sketch, Problem 10.81.

Using Equation (2) of Problem 10.81, with $W = 40$ lb

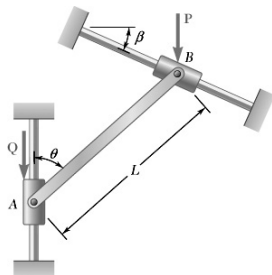
$$40 = 90 \sin 2\theta \quad (\text{for equilibrium})$$

Solving $\theta = 13.1939^\circ$ and $\theta = 76.806^\circ$

Using Equation (1) of Problem 10.81, we have

At $\theta = 13.1939^\circ$: $\frac{d^2V}{d\theta^2} = 4kr_A^2 \cos(2 \times 13.1939^\circ) > 0$ $\therefore \theta = 13.19^\circ$, Stable ◀

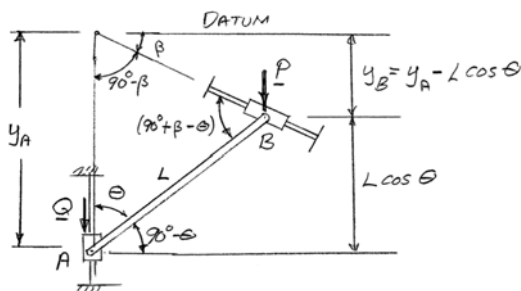
At $\theta = 76.806^\circ$: $\frac{d^2V}{d\theta^2} = 4kr_A^2 \cos(2 \times 76.806^\circ) < 0$ $\therefore \theta = 76.8^\circ$, Unstable ◀



PROBLEM 10.83

A slender rod AB of negligible weight is attached to two collars A and B that can move freely along the guide rods shown. Knowing that $\beta = 30^\circ$ and $P = Q = 100$ lb, determine the value of the angle θ corresponding to equilibrium.

SOLUTION



Law of Sines

$$\frac{y_A}{\sin(90^\circ + \beta - \theta)} = \frac{L}{\sin(90^\circ - \beta)}$$

$$\frac{y_A}{\cos(\theta - \beta)} = \frac{L}{\cos \beta}$$

or

$$y_A = L \frac{\cos(\theta - \beta)}{\cos \beta}$$

From the figure:

$$y_B = L \frac{\cos(\theta - \beta)}{\cos \beta} - L \cos \theta$$

Potential Energy:

$$V = -Py_B - Qy_A = -P \left[L \frac{\cos(\theta - \beta)}{\cos \beta} - L \cos \theta \right] - QL \frac{\cos(\theta - \beta)}{\cos \beta}$$

$$\frac{dV}{d\theta} = -PL \left[-\frac{\sin(\theta - \beta)}{\cos \beta} + \sin \theta \right] + QL \frac{\sin(\theta - \beta)}{\cos \beta}$$

$$= L(P + Q) \frac{\sin(\theta - \beta)}{\cos \beta} - PL \sin \theta$$

Equilibrium

$$\frac{dV}{d\theta} = 0: L(P + Q) \frac{\sin(\theta - \beta)}{\cos \beta} - PL \sin \theta = 0$$

or

$$(P + Q) \sin(\theta - \beta) = P \sin \theta \cos \beta$$

$$(P + Q)(\sin \theta \cos \beta - \cos \theta \sin \beta) = P \sin \theta \cos \beta$$

PROBLEM 10.83 CONTINUED

or

$$-(P + Q)\cos\theta\sin\beta + Q\sin\theta\cos\beta = 0$$

$$-\frac{P + Q}{Q}\frac{\sin\beta}{\cos\beta} + \frac{\sin\theta}{\cos\theta} = 0$$

$$\tan\theta = \frac{P + Q}{Q}\tan\beta \quad (2)$$

With

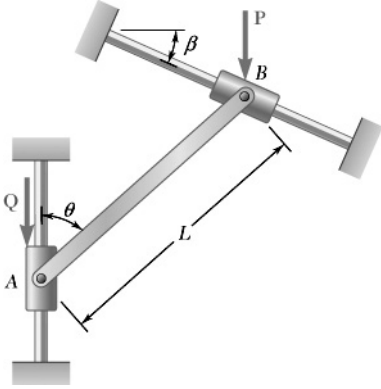
$$P = Q = 100 \text{ lb}, \quad \beta = 30^\circ$$

$$\tan\theta = \frac{200 \text{ lb}}{100 \text{ lb}}\tan 30^\circ = 1.1547$$

$$\theta = 49.1^\circ \blacktriangleleft$$

PROBLEM 10.84

A slender rod AB of negligible weight is attached to two collars A and B that can move freely along the guide rods shown. Knowing that $\beta = 30^\circ$, $P = 40$ lb, and $Q = 10$ lb, determine the value of the angle θ corresponding to equilibrium.



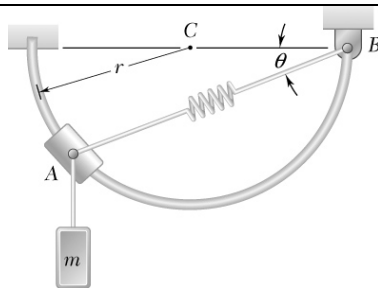
SOLUTION

Using Equation (2) of Problem 10.83, with $P = 40$ lb, $Q = 10$ lb, and $\beta = 30^\circ$, we have

$$\tan \theta = \frac{(40 \text{ lb})(10 \text{ lb})}{(10 \text{ lb})} \tan 30^\circ = 2.88675$$

$$\theta = 70.89^\circ$$

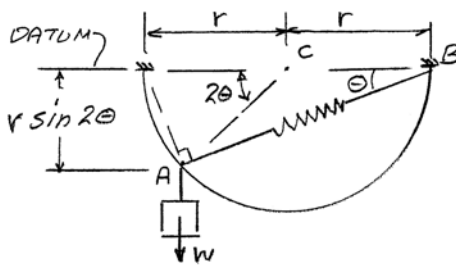
$$\theta = 70.9^\circ \blacktriangleleft$$



PROBLEM 10.85

Collar A can slide freely on the semicircular rod shown. Knowing that the constant of the spring is k and that the unstretched length of the spring is equal to the radius r , determine the value of θ corresponding to equilibrium when $m = 20 \text{ kg}$, $r = 180 \text{ mm}$, and $k = 3 \text{ N/mm}$.

SOLUTION



Stretch of Spring

$$s = AB - r$$

$$s = 2(r \cos \theta) - r$$

$$s = r(2 \cos \theta - 1)$$

Potential Energy:

$$V = \frac{1}{2}ks^2 - Wr \sin 2\theta \quad W = mg$$

$$V = \frac{1}{2}kr^2(2 \cos \theta - 1)^2 - Wr \sin 2\theta$$

$$\frac{dV}{d\theta} = -kr^2(2 \cos \theta - 1)2 \sin \theta - 2Wr \cos 2\theta$$

Equilibrium

$$\frac{dV}{d\theta} = 0: -kr^2(2 \cos \theta - 1)\sin \theta - 2Wr \cos 2\theta = 0$$

$$\frac{(2 \cos \theta - 1)\sin \theta}{\cos 2\theta} = -\frac{W}{kr}$$

Now

$$\frac{W}{kr} = \frac{(20 \text{ kg})(9.81 \text{ m/s}^2)}{(3000 \text{ N/m})(0.180 \text{ m})} = 0.36333$$

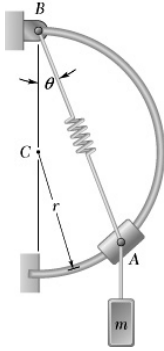
Then

$$\frac{(2 \cos \theta - 1)\sin \theta}{\cos 2\theta} = -0.36333$$

Solving numerically,

$$\theta = 0.9580 \text{ rad} = 54.9^\circ$$

$$\theta = 54.9^\circ \blacktriangleleft$$

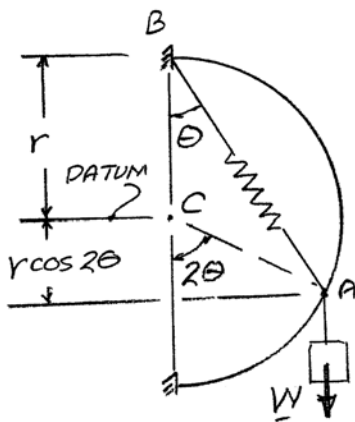


PROBLEM 10.86

Collar A can slide freely on the semicircular rod shown. Knowing that the constant of the spring is k and that the unstretched length of the spring is equal to the radius r , determine the value of θ corresponding to equilibrium when $m = 20 \text{ kg}$, $r = 180 \text{ mm}$, and $k = 3 \text{ N/mm}$.

SOLUTION

Stretch of spring



$$s = AB - r = 2(r \cos \theta) - r$$

$$s = r(2 \cos \theta - 1)$$

$$V = \frac{1}{2}ks^2 - Wr \cos 2\theta$$

$$= \frac{1}{2}kr^2(2 \cos \theta - 1)^2 - Wr \cos 2\theta$$

$$\frac{dV}{d\theta} = -kr^2(2 \cos \theta - 1)2 \sin \theta + 2Wr \sin 2\theta$$

Equilibrium

$$\frac{dV}{d\theta} = 0: -kr^2(2 \cos \theta - 1)\sin \theta + Wr \sin 2\theta = 0$$

$$-kr^2(2 \cos \theta - 1)\sin \theta + Wr(2 \sin \theta \cos \theta) = 0$$

or

$$\frac{(2 \cos \theta - 1)\sin \theta}{2 \cos \theta} = \frac{W}{kr}$$

Now

$$\frac{W}{kr} = \frac{(20 \text{ kg})(9.81 \text{ m/s}^2)}{(3000 \text{ N/m})(0.180 \text{ m})} = 0.36333$$

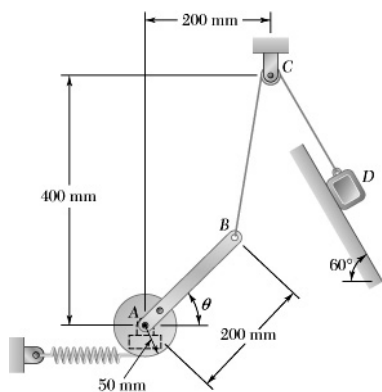
Then

$$\frac{2 \cos \theta - 1}{2 \cos \theta} = 0.36333$$

Solving

$$\theta = 38.2482^\circ$$

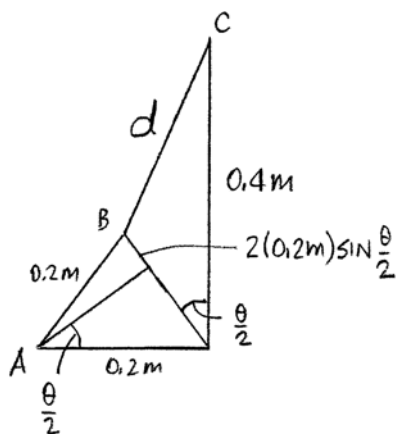
$$\theta = 38.2^\circ \blacktriangleleft$$



PROBLEM 10.87

The 12-kg block D can slide freely on the inclined surface. Knowing that the constant of the spring is 480 N/m and that the spring is unstretched when $\theta = 0$, determine the value of θ corresponding to equilibrium.

SOLUTION



First note, by Law of Cosines

$$d^2 = (0.4)^2 + \left(0.2 \sin \frac{\theta}{2}\right)^2 - 2(0.4)\left(0.2 \sin \frac{\theta}{2}\right) \cos \frac{\theta}{2}$$

or

$$d = 0.4 \sqrt{1 + \sin^2 \frac{\theta}{2} - \sin \theta} \text{ m}$$

Now

$$V = \frac{1}{2} k x_{SP}^2 - m_D g y_D$$

$$= \frac{1}{2} k (r_A \theta)^2 - m_D g \left[(y_D)_0 + (0.4 - d) \sin 60^\circ \right]$$

$$= \frac{1}{2} k r_A^2 \theta^2 - m_D g \left[(y_D)_0 + \left(0.4 - 0.4 \sqrt{1 + \sin^2 \frac{\theta}{2} - \sin \theta} \right) \sin 60^\circ \right]$$

For equilibrium

$$\frac{dV}{d\theta} = 0:$$

$$k r_A^2 \theta + 0.4 m_D g \sin 60^\circ \frac{2 \left(\frac{1}{2} \right) \left(\sin \frac{\theta}{2} \cos \frac{\theta}{2} - \cos \theta \right)}{2 \sqrt{1 + \sin^2 \frac{\theta}{2} - \sin \theta}} = 0$$

or

$$k r_A^2 \theta + 0.1 m_D g \sin 60^\circ \frac{\sin \theta - 2 \cos \theta}{\sqrt{1 + \sin^2 \frac{\theta}{2} - \sin \theta}} = 0$$

PROBLEM 10.87 CONTINUED

Substituting,

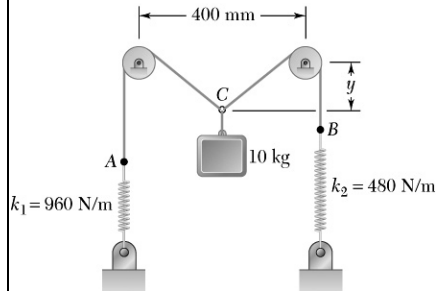
$$(480 \text{ N/m})(0.050 \text{ m})^2 \theta \sqrt{1 + \sin^2 \frac{\theta}{2}} - \sin \theta \\ + (0.1 \text{ m})(12 \text{ kg})(9.81 \text{ m/s}^2) \frac{\sqrt{3}}{2} (\sin \theta - 2 \cos \theta) = 0$$

or
$$\theta \sqrt{1 + \sin^2 \frac{\theta}{2}} - \sin \theta + 8.4957 (\sin \theta - 2 \cos \theta) = 0$$

Solving numerically, $\theta = 1.07223 \text{ rad}$

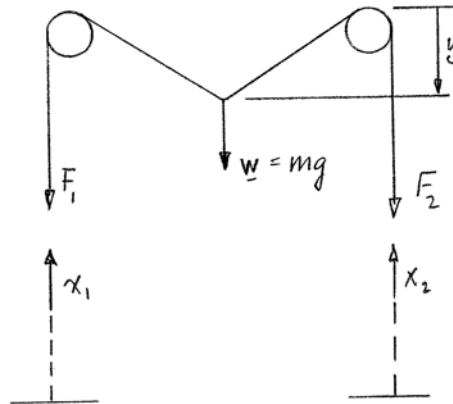
or $\theta = 61.4^\circ \blacktriangleleft$

PROBLEM 10.88



Cable AB is attached to two springs and passes through a ring at C . Knowing that the springs are unstretched when $y = 0$, determine the distance y corresponding to equilibrium.

SOLUTION



First note that the tension in the cable is the same throughout.

$$\therefore F_1 = F_2$$

or

$$k_1 x_1 = k_2 x_2$$

or

$$\begin{aligned} x_2 &= \frac{k_1}{k_2} x_1 \\ &= \frac{960 \text{ N/m}}{480 \text{ N/m}} x_1 \\ &= 2x_1 \end{aligned}$$

Now, point C is midway between the pulleys.

$$\begin{aligned} \therefore y^2 &= \left[0.2 + \frac{1}{2}(x_1 + x_2) \right]^2 - (0.2)^2 \\ &= 0.2(x_1 + x_2) + \frac{1}{4}(x_1 + x_2)^2 \\ &= 0.2(x_1 + 2x_1) + \frac{1}{4}(x_1 + 2x_1)^2 \\ &= 0.6x_1 + \frac{9}{4}x_1^2 \text{ (m}^2\text{)} \end{aligned}$$

PROBLEM 10.88 CONTINUED

Now

$$\begin{aligned} V &= \frac{1}{2}k_1x_1^2 + \frac{1}{2}k_2x_2^2 - mgy \\ &= \frac{1}{2}k_1x_1^2 + \frac{1}{2}k_2(2x_1)^2 - mg\left(\frac{1}{4}\sqrt{2.4x_1 + 9x_1^2}\right) \\ &= \frac{1}{2}(k_1 + 4k_2)x_1^2 - mg\left(\frac{1}{4}\sqrt{2.4x_1 + 9x_1^2}\right) \end{aligned}$$

For equilibrium

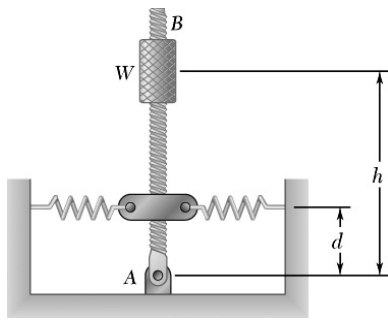
$$\frac{dV}{dx_1} = 0: (k_1 + 4k_2)x_1 - mg\left(\frac{2.4 + 18x_1}{2\sqrt{2.4x_1 + 9x_1^2}}\right) = 0$$

$$\text{or} \quad (980 + 4 \times 490) \text{ N/m} \times (x_1)(\text{m}) \left(\sqrt{2.4x_1 + 9x_1^2} \right)(\text{m}) - \frac{1}{2}(10 \text{ kg})(9.81 \text{ m/s}^2)(1.2 + 9x_1)(\text{m}) = 0$$

$$\text{or} \quad 288x_1\sqrt{2.4x_1 + 9x_1^2} - 5.886(1 + 7.5x_1) = 0$$

$$\text{Solving,} \quad x_1 = 0.068151 \text{ m}$$

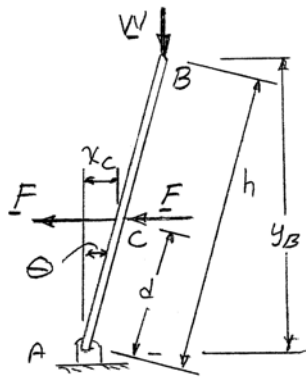
$$\text{Then} \quad y^2 = 0.6(0.068151) + \frac{9}{4}(0.068151)^2 \quad \text{or } y = 227 \text{ mm} \blacktriangleleft$$



PROBLEM 10.89

Rod AB is attached to a hinge at A and to two springs, each of constant k . If $h = 50$ in., $d = 24$ in., and $W = 160$ lb, determine the range of values of k for which the equilibrium of the rod is stable in the position shown. Each spring can act in either tension or compression.

SOLUTION



Have $x_C = d \sin \theta$ $y_B = h \cos \theta$

Potential Energy: $V = 2 \left(\frac{1}{2} k x_C^2 + W y_B \right)$
 $= k d^2 \sin^2 \theta + W h \cos \theta$

Then $\frac{dV}{d\theta} = 2 k d^2 \sin \theta \cos \theta - W h \sin \theta$
 $= k d^2 \sin 2\theta - W h \sin \theta$

and $\frac{d^2V}{d\theta^2} = 2 k d^2 \cos 2\theta - W h \cos \theta$ (1)

For equilibrium position $\theta = 0$ to be stable, we must have

$$\frac{d^2V}{d\theta^2} = 2 k d^2 - W h > 0$$

or $k d^2 > \frac{1}{2} W h$ (2)

Note: For $k d^2 = \frac{1}{2} W h$, we have $\frac{d^2V}{d\theta^2} = 0$, so that we must determine which is the first derivative that is not equal to zero. Differentiating Equation (1), we write

$$\frac{d^3V}{d\theta^3} = -4 k d^2 \sin 2\theta + W h \sin \theta = 0 \quad \text{for } \theta = 0$$

$$\frac{d^4V}{d\theta^4} = -8 k d^2 \cos 2\theta + W h \cos \theta$$

PROBLEM 10.89 CONTINUED

For $\theta = 0$:

$$\frac{d^4V}{d\theta^4} = -8kd^2 + Wh$$

Since $kd^2 = \frac{1}{2}Wh$, $\frac{d^4V}{d\theta^4} = -4Wh + Wh < 0$, we conclude that the equilibrium is unstable for $kd^2 = \frac{1}{2}Wh$ and the $>$ sign in Equation (2) is correct.

With $W = 160 \text{ lb}$, $h = 50 \text{ in.}$, and $d = 24 \text{ in.}$

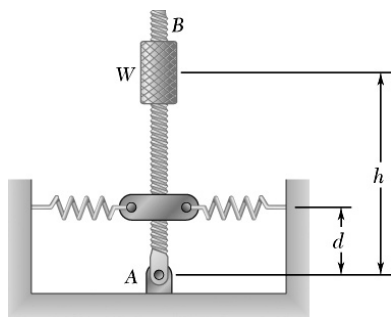
Equation (2) gives

$$k(24 \text{ in.})^2 > \frac{1}{2}(160 \text{ lb})(50 \text{ in.})$$

or

$$k > 6.944 \text{ lb/in.}$$

$$k > 6.94 \text{ lb/in.} \blacktriangleleft$$



PROBLEM 10.90

Rod AB is attached to a hinge at A and to two springs, each of constant k . If $h = 30$ in., $k = 4$ lb/in., and $W = 40$ lb, determine the smallest distance d for which the equilibrium of the rod is stable in the position shown. Each spring can act in either tension or compression.

SOLUTION

Using Equation (2) of Problem 10.89 with

$$h = 30 \text{ in.}, k = 4 \text{ lb/in.}, \text{ and } W = 40 \text{ lb}$$

$$(4 \text{ lb/in.})d^2 > \frac{1}{2}(40 \text{ lb})(30 \text{ in.})$$

or

$$d^2 > 150 \text{ in}^2$$

$$d > 12.247 \text{ in.}$$

smallest $d = 12.25 \text{ in.} \blacktriangleleft$