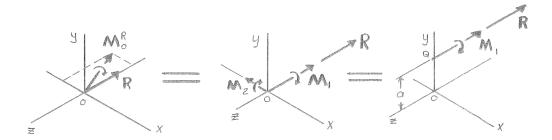


A block of wood is acted upon by three forces of the same magnitude P and having the directions shown. Replace the three forces with an equivalent wrench and determine (a) the magnitude and direction of the resultant \mathbf{R} , (b) the pitch of the wrench, (c) the point where the axis of the wrench intersects the xy plane.

SOLUTION



First, reduce the given force system to a force-couple at the origin.

Have

$$\Sigma \mathbf{F}$$
: $P\mathbf{i} - P\mathbf{i} - P\mathbf{k} = \mathbf{R}$

$$\therefore \mathbf{R} = -P\mathbf{k}$$

Have

$$\Sigma \mathbf{M}_O$$
: $-P(3a)\mathbf{k} - P(3a)\mathbf{j} + P(-a\mathbf{i} + 3a\mathbf{j}) = \mathbf{M}_O^R$

$$\therefore \mathbf{M}_{O}^{R} = Pa(-\mathbf{i} - 3\mathbf{k})$$

Then let vectors $(\mathbf{R}, \mathbf{M}_1)$ represent the components of the wrench, where their directions are the same.

$$\mathbf{R} = -P\mathbf{k}$$

or Magnitude of $\mathbf{R} = P \blacktriangleleft$

Direction of **R**: $\theta_x = 90^\circ$, $\theta_y = 90^\circ$, $\theta_z = -180^\circ$

$$M_{1} = \lambda_{R} \cdot \mathbf{M}_{O}^{R}$$
$$= -\mathbf{k} \cdot \left[Pa(-\mathbf{i} - 3\mathbf{k}) \right]$$
$$= 3Pa$$

and pitch

$$p = \frac{M_1}{R} = \frac{3Pa}{P} = 3a$$

or $p = 3a \blacktriangleleft$

PROBLEM 3.129 CONTINUED

(c) Have
$$\mathbf{M}_{O}^{R} = \mathbf{M}_{1} + \mathbf{M}_{2}$$

$$\therefore \ \mathbf{M}_2 = \mathbf{M}_O^R - \mathbf{M}_1 = Pa(-\mathbf{i} - 3\mathbf{k}) - (-3Pa\mathbf{k}) = -Pa\mathbf{i}$$

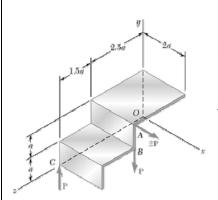
Require $\mathbf{M}_2 = \mathbf{r}_{Q/Q} \times \mathbf{R}$

$$-Pa\mathbf{i} = (x\mathbf{i} + y\mathbf{j}) \times (-P)\mathbf{k} = Px\mathbf{j} - Py\mathbf{i}$$

From **i**: -Pa = -Py or y = a

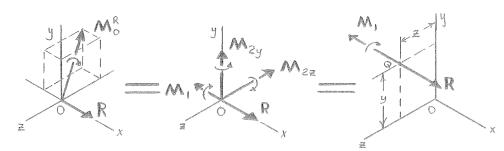
j: x = 0

 \therefore The axis of the wrench is parallel to the z-axis and intersects the xy plane at x = 0, $y = a \blacktriangleleft$



A piece of sheet metal is bent into the shape shown and is acted upon by three forces. Replace the three forces with an equivalent wrench and determine (a) the magnitude and direction of the resultant \mathbf{R} , (b) the pitch of the wrench, (c) the point where the axis of the wrench intersects the yz plane.

SOLUTION



First, reduce the given force system to a force-couple system at the origin.

Have

$$\Sigma \mathbf{F}$$
: $(2P)\mathbf{i} - (P)\mathbf{j} + (P)\mathbf{j} = \mathbf{R}$

$$\therefore \mathbf{R} = (2P)\mathbf{i}$$

Have

$$\Sigma \mathbf{M}_O$$
: $\Sigma (\mathbf{r}_O \times \mathbf{F}) = \mathbf{M}_O^R$

$$\mathbf{M}_{O}^{R} = Pa \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 2 & 2 & 2.5 \\ 2 & -1 & 0 \end{vmatrix} + \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 0 & 4 \\ 0 & 1 & 0 \end{vmatrix} = Pa(-1.5\mathbf{i} + 5\mathbf{j} - 6\mathbf{k})$$

(a)
$$\mathbf{R} = 2P\mathbf{i}$$

or Magnitude of $\mathbf{R} = 2P \blacktriangleleft$

Direction of **R**: $\theta_x = 0^\circ$, $\theta_y = -90^\circ$, $\theta_z = 90^\circ \blacktriangleleft$

$$M_{1} = \lambda_{R} \cdot \mathbf{M}_{O}^{R} \qquad \lambda_{R} = \frac{\mathbf{R}}{R}$$
$$= \mathbf{i} \cdot \left(-1.5Pa\mathbf{i} + 5Pa\mathbf{j} - 6Pa\mathbf{k}\right)$$
$$= -1.5Pa$$

and pitch

$$p = \frac{M_1}{R} = \frac{-1.5Pa}{2P} = -0.75a$$

or p = -0.75a

PROBLEM 3.130 CONTINUED

(c) Have
$$\mathbf{M}_O^R = \mathbf{M}_1 + \mathbf{M}_2$$

$$\therefore \quad \mathbf{M}_2 = \mathbf{M}_O^R - \mathbf{M}_1 = (5Pa)\mathbf{j} - (6Pa)\mathbf{k}$$

Require $\mathbf{M}_2 = \mathbf{r}_{O/O} \times \mathbf{R}$

$$(5Pa)\mathbf{j} - (6Pa)\mathbf{k} = (y\mathbf{j} + z\mathbf{k}) \times (2P\mathbf{i}) = -(2Py)\mathbf{k} + (2Pz)\mathbf{j}$$

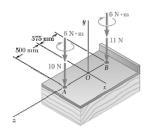
From **i**: 5Pa = 2Pz

 $\therefore z = 2.5a$

From **k**: -6Pa = -2Py

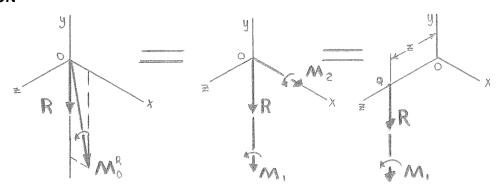
 $\therefore y = 3a$

 \therefore The axis of the wrench is parallel to the x-axis and intersects the yz-plane at y = 3a, z = 2.5a



The forces and couples shown are applied to two screws as a piece of sheet metal is fastened to a block of wood. Reduce the forces and the couples to an equivalent wrench and determine (a) the resultant force \mathbf{R} , (b) the pitch of the wrench, (c) the point where the axis of the wrench intersects the xz plane.

SOLUTION



First, reduce the given force system to a force-couple at the origin.

Have

$$\Sigma \mathbf{F}$$
: $-(10 \text{ N})\mathbf{j} - (11 \text{ N})\mathbf{j} = \mathbf{R}$

$$\therefore \mathbf{R} = -(21\,\mathrm{N})\mathbf{j}$$

Have

$$\Sigma \mathbf{M}_O$$
: $\Sigma (\mathbf{r}_O \times \mathbf{F}) + \Sigma \mathbf{M}_C = \mathbf{M}_O^R$

$$\mathbf{M}_{O}^{R} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 0 & 0.5 \\ 0 & -10 & 0 \end{vmatrix} \mathbf{N} \cdot \mathbf{m} + \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 0 & -0.375 \\ 0 & -11 & 0 \end{vmatrix} \mathbf{N} \cdot \mathbf{m} - (12 \text{ N} \cdot \text{m}) \mathbf{j}$$

$$= (0.875 \text{ N} \cdot \text{m})\mathbf{i} - (12 \text{ N} \cdot \text{m})\mathbf{j}$$

$$\mathbf{R} = -(21\,\mathrm{N})\mathbf{j}$$

or
$$\mathbf{R} = -(21 \,\mathrm{N})\mathbf{j} \blacktriangleleft$$

$$M_{1} = \boldsymbol{\lambda}_{R} \cdot \mathbf{M}_{O}^{R} \qquad \boldsymbol{\lambda}_{R} = \frac{\mathbf{R}}{R}$$

$$= (-\mathbf{j}) \cdot \left[(0.875 \text{ N} \cdot \text{m}) \mathbf{i} - (12 \text{ N} \cdot \text{m}) \mathbf{j} \right]$$

$$= 12 \text{ N} \cdot \text{m} \qquad \text{and} \qquad \mathbf{M}_{1} = -(12 \text{ N} \cdot \text{m}) \mathbf{j}$$

and pitch

$$p = \frac{M_1}{R} = \frac{12 \text{ N} \cdot \text{m}}{21 \text{ N}} = 0.57143 \text{ m}$$

or $p = 0.571 \,\text{m}$

PROBLEM 3.131 CONTINUED

$$\mathbf{M}_{O}^{R} = \mathbf{M}_{1} + \mathbf{M}_{2}$$

$$\therefore \mathbf{M}_2 = \mathbf{M}_O^R - \mathbf{M}_1 = (0.875 \,\mathrm{N} \cdot \mathrm{m})\mathbf{i}$$

Require

$$\mathbf{M}_2 = \mathbf{r}_{O/O} \times \mathbf{R}$$

$$\therefore (0.875 \text{ N} \cdot \text{m})\mathbf{i} = (x\mathbf{i} + z\mathbf{k}) \times [-(21 \text{ N})\mathbf{j}]$$

$$0.875\mathbf{i} = -(21x)\mathbf{k} + (21z)\mathbf{i}$$

From i:

$$0.875 = 21z$$

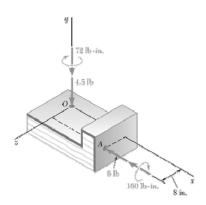
$$z = 0.041667 \text{ m}$$

From k:

$$0 = -21x$$

$$\therefore z = 0$$

 \therefore The axis of the wrench is parallel to the y-axis and intersects the xz-plane at x = 0, z = 41.7 mm



The forces and couples shown are applied to two screws as a piece of sheet metal is fastened to a block of wood. Reduce the forces and the couples to an equivalent wrench and determine (a) the resultant force \mathbf{R} , (b) the pitch of the wrench, (c) the point where the axis of the wrench intersects the xz plane.

SOLUTION

First, reduce the given force system to a force-couple system.

Have $\Sigma \mathbf{F}$: $-(6 \text{ lb})\mathbf{i} - (4.5 \text{ lb})\mathbf{j} = \mathbf{R}$ R = 7.5 lb

Have $\Sigma \mathbf{M}_{Q}$: $\Sigma (\mathbf{r}_{Q} \times \mathbf{F}) + \Sigma \mathbf{M}_{C} = \mathbf{M}_{Q}^{R}$

$$\mathbf{M}_O^R = -6 \text{ lb} (8 \text{ in.}) \mathbf{j} - (160 \text{ lb} \cdot \text{in.}) \mathbf{i} - (72 \text{ lb} \cdot \text{in.}) \mathbf{j}$$
$$= -(160 \text{ lb} \cdot \text{in.}) \mathbf{i} - (120 \text{ lb} \cdot \text{in.}) \mathbf{j}$$

$$M_Q^R = 200 \text{ lb} \cdot \text{in.}$$

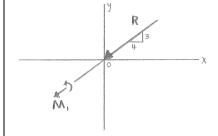
(a)
$$\mathbf{R} = -(6 \text{ lb})\mathbf{i} - (4.5 \text{ lb})\mathbf{j} \blacktriangleleft$$

(b) Have
$$M_1 = \boldsymbol{\lambda}_R \cdot \mathbf{M}_O^R \qquad \boldsymbol{\lambda} = \frac{\mathbf{R}}{R}$$
$$= (-0.8\mathbf{i} - 0.6\mathbf{j}) \cdot \left[-(160 \text{ lb} \cdot \text{in.})\mathbf{i} - (120 \text{ lb} \cdot \text{in.})\mathbf{j} \right]$$
$$= 200 \text{ lb} \cdot \text{in.}$$

and
$$\mathbf{M}_1 = 200 \text{ lb} \cdot \text{in.} (-0.8\mathbf{i} - 0.6\mathbf{j})$$

Pitch
$$p = \frac{M_1}{R} = \frac{200 \text{ lb} \cdot \text{in.}}{7.50 \text{ lb}} = 26.667 \text{ in.}$$

or p = 26.7 in.

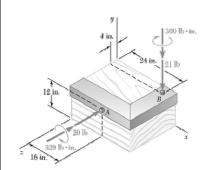


(c) From above note that

$$\mathbf{M}_1 = \mathbf{M}_O^R$$

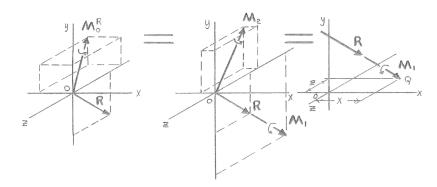
Therefore, the axis of the wrench goes through the origin. The line of action of the wrench lies in the *xy* plane with a slope of

$$\frac{dy}{dx} = \frac{3}{4} \blacktriangleleft$$



Two bolts A and B are tightened by applying the forces and couple shown. Replace the two wrenches with a single equivalent wrench and determine (a) the resultant \mathbf{R} , (b) the pitch of the single equivalent wrench, (c) the point where the axis of the wrench intersects the xz plane.

SOLUTION



First, reduce the given force system to a force-couple at the origin.

Have

$$\Sigma \mathbf{F}$$
: $-(20 \text{ lb})\mathbf{k} - (21 \text{ lb})\mathbf{j} = -(21 \text{ lb})\mathbf{j} - (20 \text{ lb})\mathbf{k} = \mathbf{R}$ $R = 29 \text{ lb}$

$$R = 29 \text{ lb}$$

and

$$\Sigma \mathbf{M}_O$$
: $\Sigma (\mathbf{r}_O \times \mathbf{F}) + \Sigma \mathbf{M}_C = \mathbf{M}_O^R$

$$20 \text{ lb} (4 \text{ in.}) \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 4 & 3 & 0 \\ 0 & 0 & -1 \end{vmatrix} + 21 \text{ lb} (4 \text{ in.}) \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 6 & 0 & 1 \\ 0 & -1 & 0 \end{vmatrix} + (-300\mathbf{j} - 320\mathbf{k}) \text{ lb} \cdot \text{in.} = \mathbf{M}_O^R$$

$$\therefore \mathbf{M}_O^R = -(156 \text{ lb} \cdot \text{in.})\mathbf{i} + (20 \text{ lb} \cdot \text{in.})\mathbf{j} - (824 \text{ lb} \cdot \text{in.})\mathbf{k}$$

(a)

$$\mathbf{R} = -(21 \text{ lb})\mathbf{j} - (20 \text{ lb})\mathbf{k} \blacktriangleleft$$

$$M_1 = \boldsymbol{\lambda}_R \cdot \mathbf{M}_O^R \qquad \boldsymbol{\lambda}_R = \frac{\mathbf{R}}{R}$$

$$= -\frac{-21\mathbf{j} - 20\mathbf{k}}{29} \cdot \left[-(156 \text{ lb} \cdot \text{in.})\mathbf{i} + (20 \text{ lb} \cdot \text{in.})\mathbf{j} - (824 \text{ lb} \cdot \text{in.})\mathbf{k} \right]$$

$$= 553.80 \text{ lb} \cdot \text{in.}$$

PROBLEM 3.133 CONTINUED

and
$$\mathbf{M}_1 = M_1 \lambda_R = -(401.03 \text{ lb} \cdot \text{in.}) \mathbf{j} - (381.93 \text{ lb} \cdot \text{in.}) \mathbf{k}$$

Then pitch $p = \frac{M_1}{R} = \frac{553.80 \text{ lb} \cdot \text{in.}}{29 \text{ lb}} = 19.0964 \text{ in.}$

or p = 19.10 in.

(c) Have

$$\mathbf{M}_{O}^{R} = \mathbf{M}_{1} + \mathbf{M}_{2}$$

$$\mathbf{M}_{2} = \mathbf{M}_{O}^{R} - \mathbf{M}_{1} = \left[\left(-156\mathbf{i} + 20\mathbf{j} - 824\mathbf{k} \right) - \left(-401.03\mathbf{j} - 381.93\mathbf{k} \right) \right] \text{lb} \cdot \text{in}.$$

$$= - \big(156.0 \text{ lb} \cdot \text{in.}\big) \mathbf{i} + \big(421.03 \text{ lb} \cdot \text{in.}\big) \mathbf{j} - \big(442.07 \text{ lb} \cdot \text{in.}\big) \mathbf{k}$$

Require

$$\mathbf{M}_2 = \mathbf{r}_{Q/O} \times \mathbf{R}$$

$$(-156\mathbf{i} + 421.03\mathbf{j} - 442.07\mathbf{k}) = (x\mathbf{i} + z\mathbf{k}) \times (-21\mathbf{j} - 20\mathbf{k})$$

$$= (21z)\mathbf{i} + (20x)\mathbf{j} - (21x)\mathbf{k}$$

From **i**: -156 = 21z

z = -7.4286 in.

or z = -7.43 in.

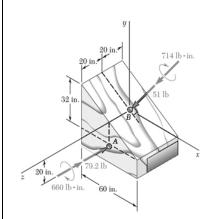
From **k**: -442.07 = -21x

 $\therefore x = 21.051 \text{ in.}$

or x = 21.1 in.

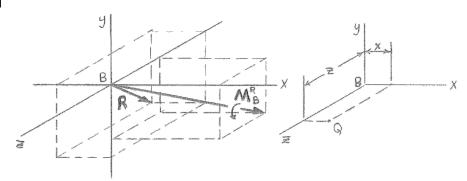
 \therefore The axis of the wrench intersects the xz-plane at

 $x = 21.1 \text{ in.}, z = -7.43 \text{ in.} \blacktriangleleft$



Two bolts A and B are tightened by applying the forces and couple shown. Replace the two wrenches with a single equivalent wrench and determine (a) the resultant \mathbf{R} , (b) the pitch of the single equivalent wrench, (c) the point where the axis of the wrench intersects the xz plane.

SOLUTION



First reduce the given force system to a force-couple at the origin at *B*.

$$\Sigma \mathbf{F}$$
: $-(79.2 \text{ lb})\mathbf{k} - (51 \text{ lb})(\frac{8}{17}\mathbf{i} + \frac{15}{17}\mathbf{j}) = \mathbf{R}$

∴
$$\mathbf{R} = -(24.0 \text{ lb})\mathbf{i} - (45.0 \text{ lb})\mathbf{j} - (79.2 \text{ lb})\mathbf{k} \blacktriangleleft$$

and

$$R = 94.2 \text{ lb}$$

Have

$$\Sigma \mathbf{M}_B$$
: $\mathbf{r}_{A/B} \times \mathbf{F}_A + \mathbf{M}_A + \mathbf{M}_B = \mathbf{M}_B^R$

$$\mathbf{M}_{B}^{R} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & -20 & 0 \\ 0 & 0 & -79.2 \end{vmatrix} - 660\mathbf{k} - 714 \left(\frac{8}{17} \mathbf{i} + \frac{15}{17} \mathbf{j} \right) = 1584\mathbf{i} - 660\mathbf{k} - 42(8\mathbf{i} + 15\mathbf{j})$$

$$\therefore \mathbf{M}_{B}^{R} = (1248 \text{ lb} \cdot \text{in.})\mathbf{i} - (630 \text{ lb} \cdot \text{in.})\mathbf{j} - (660 \text{ lb} \cdot \text{in.})\mathbf{k}$$

$$M_1 = \boldsymbol{\lambda}_R \cdot \mathbf{M}_O^R \qquad \boldsymbol{\lambda}_R = \frac{\mathbf{R}}{R}$$

$$= \frac{-24.0\mathbf{i} - 45.0\mathbf{j} - 79.2\mathbf{k}}{94.2} \cdot \left[(1248 \text{ lb} \cdot \text{in.})\mathbf{i} - (630 \text{ lb} \cdot \text{in.})\mathbf{j} - (660 \text{ lb} \cdot \text{in.})\mathbf{k} \right]$$

$$= 537.89 \text{ lb} \cdot \text{in.}$$

PROBLEM 3.134 CONTINUED

and

$$\mathbf{M}_1 = M_1 \lambda_R$$

= -(137.044 lb·in.) \mathbf{i} - (256.96 lb·in.) \mathbf{j} - (452.24 lb·in.) \mathbf{k}

Then pitch

$$p = \frac{M_1}{R} = \frac{537.89 \text{ lb} \cdot \text{in.}}{94.2 \text{ lb}} = 5.7101 \text{ in.}$$

or p = 5.71 in.

(c) Have

$$\mathbf{M}_B^R = \mathbf{M}_1 + \mathbf{M}_2$$

Require

$$\mathbf{M}_2 = \mathbf{r}_{O/B} \times \mathbf{R}$$

$$1385.04\mathbf{i} - 373.04\mathbf{j} - 207.76\mathbf{k} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ x & 0 & z \\ -24 & -45 & -79.2 \end{vmatrix}$$

=
$$(45z)\mathbf{i} - (24z)\mathbf{j} + (79.2x)\mathbf{j} - (45x)\mathbf{k}$$

From i:

$$1385.04 = 45z$$
 $\therefore z = 30.779 \text{ in.}$

$$z = 30.779 \text{ in}$$

From **k**:

$$-207.76 = -45x$$
 $\therefore x = 4.6169 \text{ in.}$

 \therefore The axis of the wrench intersects the xz-plane at

 $x = 4.62 \text{ in.}, z = 30.8 \text{ in.} \blacktriangleleft$