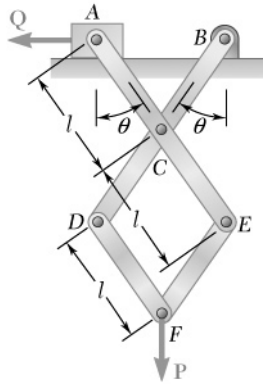


PROBLEM 10.51



Denoting by μ_s the coefficient of static friction between the block attached to rod ACE and the horizontal surface, derive expressions in terms of P , μ_s , and θ for the largest and smallest magnitudes of the force Q for which equilibrium is maintained.

SOLUTION

For the linkage:

$$+\circlearrowleft \Sigma M_B = 0: -x_A + \frac{x_A}{2}P = 0 \quad \text{or} \quad A = \frac{P}{2} \uparrow$$

Then: $F = \mu_s A = \mu_s \frac{P}{2} = \frac{1}{2} \mu_s P$

Now $x_A = 2l \sin \theta$

$$\delta x_A = 2l \cos \theta \delta \theta$$

and $y_F = 3l \cos \theta$

$$\delta y_F = -3l \sin \theta \delta \theta$$

Virtual Work:

$$\delta U = 0: (Q_{\max} - F) \delta x_A + P \delta y_F = 0$$

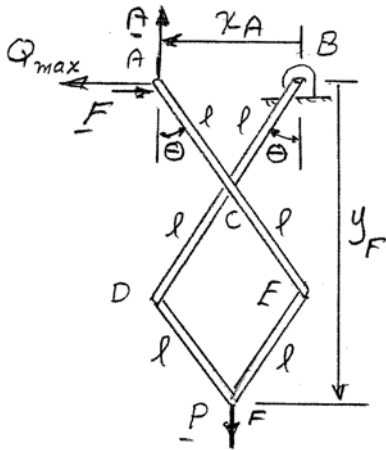
$$\left(Q_{\max} - \frac{1}{2} \mu_s P \right) (2l \cos \theta \delta \theta) + P (-3l \sin \theta \delta \theta) = 0$$

or $Q_{\max} = \frac{3}{2} P \tan \theta + \frac{1}{2} \mu_s P$

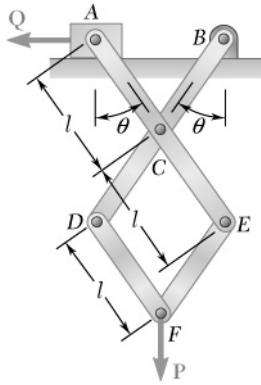
$$Q_{\max} = \frac{P}{2} (3 \tan \theta + \mu_s) \blacktriangleleft$$

For Q_{\min} , motion of A impends to the right and F acts to the left. We change μ_s to $-\mu_s$ and find

$$Q_{\min} = \frac{P}{2} (3 \tan \theta - \mu_s) \blacktriangleleft$$



PROBLEM 10.52



Knowing that the coefficient of static friction between the block attached to rod ACE and the horizontal surface is 0.15, determine the magnitudes of the largest and smallest force Q for which equilibrium is maintained when $\theta = 30^\circ$, $l = 8$ in., and $P = 160$ lb.

SOLUTION

Using the results of Problem 10.52 with

$$\theta = 30^\circ, l = 8 \text{ in.}, P = 160 \text{ lb, and } \mu_s = 0.15$$

We have

$$Q_{\max} = \frac{(160 \text{ lb})}{2}(3 \tan 30^\circ + 0.15) = 150.56 \text{ lb}$$

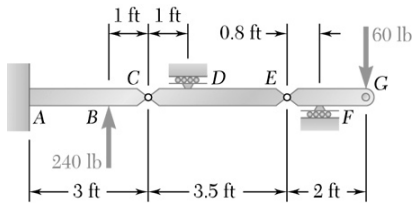
$$Q_{\max} = 150.6 \text{ lb} \blacktriangleleft$$

and

$$Q_{\min} = \frac{(160 \text{ lb})}{2}(3 \tan 30^\circ - 0.15) = 126.56 \text{ lb}$$

$$Q_{\min} = 126.6 \text{ lb} \blacktriangleleft$$

PROBLEM 10.53



Using the method of virtual work, determine separately the force and the couple representing the reaction at A.

SOLUTION

A_y : Consider an upward displacement δy_A of ABC

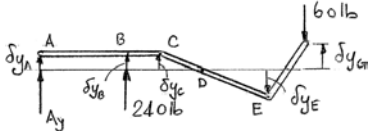
ABC: $\delta y_A = \delta y_B = \delta y_C$

CDE: $\frac{\delta y_C}{1 \text{ ft}} = \frac{\delta y_E}{2.5 \text{ ft}}$

or $\delta y_E = 2.5 \delta y_A$

EFG: $\frac{\delta y_E}{0.8 \text{ ft}} = \frac{\delta y_G}{1.2 \text{ ft}}$

or $\delta y_G = \frac{1.2 \text{ ft}}{0.8 \text{ ft}} (2.5 \delta y_A)$
 $= 3.75 \delta y_A$



Virtual Work:

$$\delta U = 0: A_y \delta y_A + (240 \text{ lb}) \delta y_B - (60 \text{ lb}) \delta y_G = 0$$

or $A_y \delta y_A + (240 \text{ lb}) \delta y_A - (60 \text{ lb}) 3.75 \delta y_A = 0$

or $A_y = 15 \text{ lb} \downarrow$

A_x : Consider a horizontal displacement δx_A :

Virtual Work: $\delta U = 0: A_x \delta x_A = 0$

or $A_x = 0 \quad \therefore \mathbf{A} = 15.00 \text{ lb} \downarrow \blacktriangleleft$

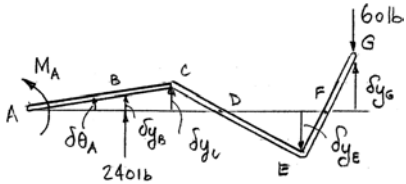
M_A : Consider a counterclockwise rotation about A:

ABC: $\delta y_B = 2 \delta \theta_A, \quad \delta y_C = 3 \delta \theta_A$

CDE: $\frac{\delta y_C}{1 \text{ ft}} = \frac{\delta y_E}{2.5 \text{ ft}}$

or $\delta y_E = 2.5 (3 \delta \theta_A)$
 $= 7.5 \delta \theta_A$

EFG: $\frac{\delta y_E}{0.8 \text{ ft}} = \frac{\delta y_G}{1.2 \text{ ft}}$



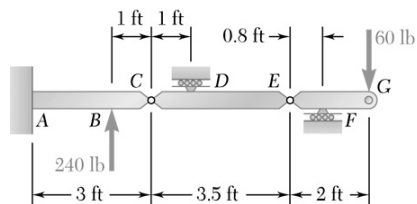
PROBLEM 10.53 CONTINUED

$$\begin{aligned}\text{or} \quad \delta y_G &= \frac{(1.2 \text{ ft})}{(0.8 \text{ ft})}(7.5\delta\theta_A) \\ &= 11.25\delta\theta_A\end{aligned}$$

$$\text{Virtual Work:} \quad \delta U = 0: \quad M_A \delta\theta_A + (240 \text{ lb})\delta y_B - (60 \text{ lb})\delta y_G = 0$$

$$\text{or} \quad M_A \delta\theta_A + (240 \text{ lb})(2\delta\theta_A) - (60 \text{ lb})(11.25\delta\theta_A) = 0$$

$$\text{or } \mathbf{M}_A = 195.0 \text{ lb}\cdot\text{ft} \quad \curvearrowleft$$



PROBLEM 10.54

Using the method of virtual work, determine the reaction at D .

SOLUTION

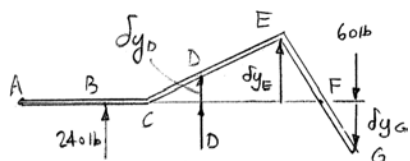
Consider an upward displacement δy_E of pin E .

$$CDE: \quad \frac{\delta y_D}{1 \text{ ft}} = \frac{\delta y_E}{3.5 \text{ ft}}$$

$$\text{or} \quad \delta y_D = \frac{1}{3.5} \delta y_E$$

$$EFG: \quad \frac{\delta y_E}{0.8 \text{ ft}} = \frac{\delta y_G}{1.2 \text{ ft}}$$

$$\text{or} \quad \delta y_G = 1.5 \delta y_E$$



Virtual Work:

$$\delta U = 0: \quad D \delta y_D + 60 \delta y_G = 0$$

$$\text{or} \quad D \left(\frac{1}{3.5} \delta y_E \right) + (60 \text{ lb})(1.5 \delta y_E) = 0$$

$$\text{or} \quad \mathbf{D = 315 \text{ lb} \downarrow \blacktriangleleft}$$

PROBLEM 10.55

Referring to Problem 10.41 and using the value found for the force exerted by the hydraulic cylinder AB , determine the change in the length of AB required to raise the 480-N load 18 mm.

SOLUTION

From the solution to Problem 10.41

$$F_{\text{cyl}} = 397.08 \text{ N}$$

And, Virtual Work:

$$\delta U = 0: F_{\text{cyl}} \delta S_{AB} - P \delta y_D = 0$$

where $\delta S_{AB} < 0$ for $\delta y_D > 0$

Then

$$(397.08 \text{ N}) \delta S_{AB} - (480 \text{ N})(18 \text{ mm}) = 0$$

$$\text{or } \delta S_{AB} = 21.8 \text{ mm (shortened) } \blacktriangleleft$$

PROBLEM 10.56

Referring to Problem 10.45 and using the value found for the force exerted by the hydraulic cylinder BD , determine the change in the length of BD required to raise the platform attached at C by 50 mm.

SOLUTION

Virtual Work: Assume that both δy_C and δ_{BD} increase

$$\delta U = 0: -(2000 \text{ N})\delta y_C + F_{BD}\delta_{BD} = 0$$

$$\delta y_C = 0.05 \text{ m} \quad \text{and} \quad F_{BD} = 9473 \text{ N (from Problem 10.45)}$$

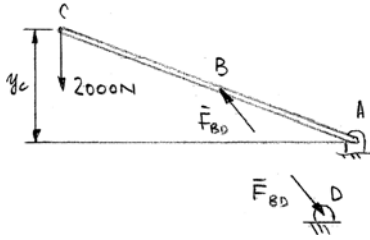
$$-2000(0.05 \text{ m}) + 9473\delta_{BD} = 0$$

$$\delta_{BD} = 0.010556 \text{ m}$$

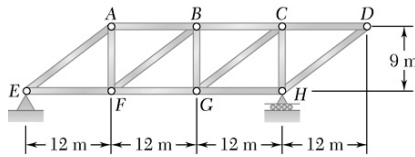
$$= 10.556 \text{ mm}$$

The positive sign indicates that BD gets longer.

$$\delta_{BD} = 10.56 \text{ mm} \blacktriangleleft$$



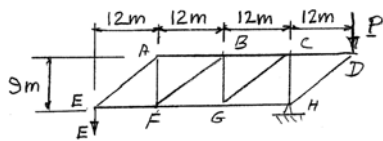
PROBLEM 10.57



Determine the vertical movement of joint D if the length of member BF is increased by 75 mm. (Hint: Apply a vertical load at joint D , and, using the methods of Chapter 6, compute the force exerted by member BF on joints B and F . Then apply the method of virtual work for a virtual displacement resulting in the specified increase in length of member BF . This method should be used only for small changes in the lengths of members.)

SOLUTION

Apply vertical load P at D .

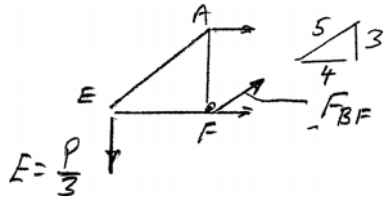


$$+\circlearrowleft \Sigma M_H = 0: -P(12 \text{ m}) + E(36 \text{ m}) = 0$$

$$E = \frac{P}{3} \downarrow$$

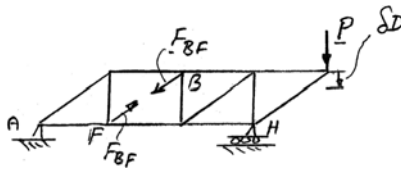
$$+\uparrow \Sigma F_y = 0: \frac{3}{5} F_{BF} - \frac{P}{3} = 0$$

$$F_{BF} = \frac{5}{9} P$$



Virtual Work:

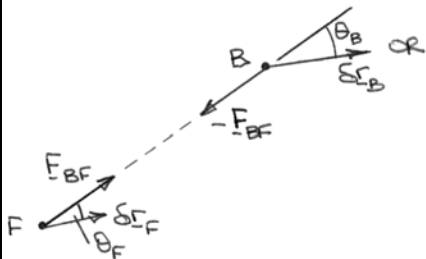
We remove member BF and replace it with forces \mathbf{F}_{BF} and $-\mathbf{F}_{BF}$ at pins F and B , respectively. Denoting the virtual displacements of points B and F as $\delta \mathbf{r}_B$ and $\delta \mathbf{r}_F$, respectively, and noting that \mathbf{P} and $\delta \mathbf{D}$ have the same direction, we have



$$\text{Virtual Work: } \delta U = 0: P \delta D + \mathbf{F}_{BF} \cdot \delta \mathbf{r}_F + (-\mathbf{F}_{BF}) \cdot \delta \mathbf{r}_B = 0$$

$$P \delta D + F_{BF} \delta r_F \cos \theta_F - F_{BF} \delta r_B \cos \theta_B = 0$$

$$P \delta D - F_{BF} (\delta r_B \cos \theta_B - \delta r_F \cos \theta_F) = 0$$



where $(\delta r_B \cos \theta_B - \delta r_F \cos \theta_F) = \delta_{BF}$, which is the change in length of member BF . Thus,

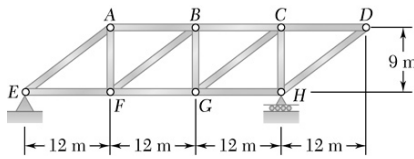
$$P \delta D - F_{BF} \delta_{BF} = 0$$

$$P \delta D - \left(\frac{5}{9} P \right) (75 \text{ mm}) = 0$$

$$\delta D = +41.67 \text{ mm}$$

$$\delta D = 41.7 \text{ mm} \downarrow \blacktriangleleft$$

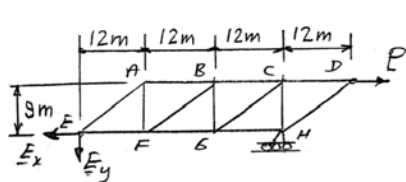
PROBLEM 10.58



Determine the horizontal movement of joint D if the length of member BF is increased by 75 mm. (See the hint for Problem 10.57.)

SOLUTION

Apply horizontal load P at D .

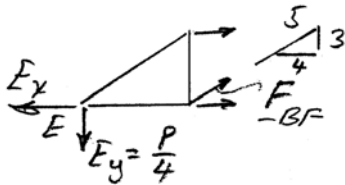


$$+\circlearrowleft \Sigma M_H = 0: P(9 \text{ m}) - E_y(36 \text{ m}) = 0$$

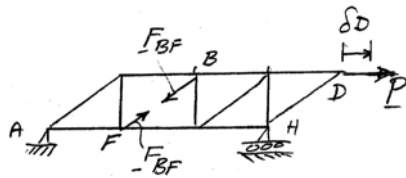
$$E_y = \frac{P}{4} \downarrow$$

$$+\uparrow \Sigma F_y = 0: \frac{3}{5} F_{BF} - \frac{P}{4} = 0$$

$$F_{BF} = \frac{5}{12} P$$



We remove member BF and replace it with forces \mathbf{F}_{BF} and $-\mathbf{F}_{BF}$ at pins F and B , respectively. Denoting the virtual displacements of points B and F as $\delta \mathbf{r}_B$ and $\delta \mathbf{r}_F$, respectively, and noting that \mathbf{P} and $\delta \mathbf{D}$ have the same direction, we have



$$\text{Virtual Work: } \delta U = 0: P\delta D + \mathbf{F}_{BF} \cdot \delta \mathbf{r}_F + (-\mathbf{F}_{BF}) \cdot \delta \mathbf{r}_B = 0$$

$$P\delta D + F_{BF}\delta r_F \cos \theta_F - F_{BF}\delta r_B \cos \theta_B = 0$$

$$P\delta D - F_{BF}(\delta r_B \cos \theta_B - \delta r_F \cos \theta_F) = 0$$

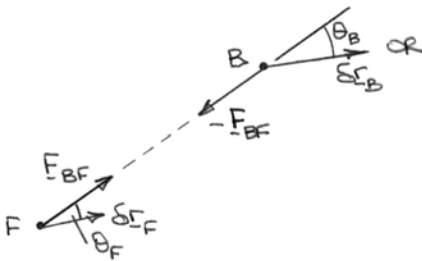
where $(\delta r_B \cos \theta_B - \delta r_F \cos \theta_F) = \delta_{BF}$, which is the change in length of member BF . Thus,

$$P\delta D - F_{BF}\delta_{BF} = 0$$

$$P\delta D - \left(\frac{5}{12} P\right)(75 \text{ mm}) = 0$$

$$\delta D = 31.25 \text{ mm}$$

$$\delta D = 31.3 \text{ mm} \rightarrow \blacktriangleleft$$



PROBLEM 10.59

Using the method of Section 10.8, solve Problem 10.29.

SOLUTION

Spring:

$$AE = x = 2(2l \sin \theta) = 4l \sin \theta$$

Unstretched length:

$$x_0 = 4l \sin 30^\circ = 2l$$

Deflection of spring

$$s = x - x_0$$

$$s = 2l(2 \sin \theta - 1)$$

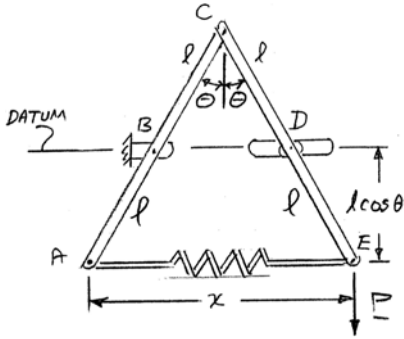
$$V = \frac{1}{2}ks^2 + Py_E$$

$$V = \frac{1}{2}k[2l(2 \sin \theta - 1)]^2 + P(-l \cos \theta)$$

$$\frac{dV}{d\theta} = 4kl^2(2 \sin \theta - 1)2 \cos \theta + Pl \sin \theta = 0$$

$$(2 \sin \theta - 1)\frac{\cos \theta}{\sin \theta} + \frac{P}{8kl} = 0$$

$$\frac{P}{8kl} = \frac{1 - 2 \sin \theta}{\tan \theta} \quad \blacktriangleleft$$



PROBLEM 10.60

Using the method of Section 10.8, solve Problem 10.30.

SOLUTION

Using the result of Problem 10.59, with

$$P = 160 \text{ N}, l = 200 \text{ mm, and } k = 300 \text{ N/m}$$

$$\frac{P}{8kl} = \frac{1 - 2 \sin \theta}{\tan \theta}$$

or

$$\begin{aligned} \frac{1 - 2 \sin \theta}{\tan \theta} &= \frac{160 \text{ N}}{8(300 \text{ N/m})(0.2 \text{ m})} \\ &= \frac{1}{3} \end{aligned}$$

Solving numerically,

$$\theta = 25.0^\circ \blacktriangleleft$$