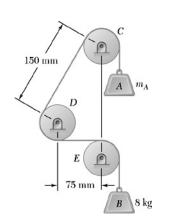
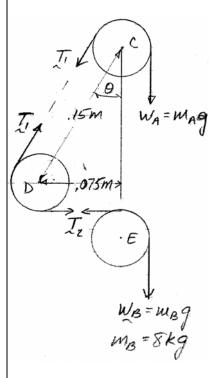
# PROBLEM 8.121 A cable passes around



A cable passes around three 30-mm-radius pulleys and supports two blocks as shown. Two of the pulleys are locked to prevent rotation, while the third pulley is rotated slowly at a constant speed. Knowing that the coefficients of friction between the cable and the pulleys are  $\mu_s = 0.20$  and  $\mu_k = 0.15$ , determine the largest mass  $m_A$  which can be raised (a) if pulley C is rotated, (b) if pulley E is rotated.

#### **SOLUTION**



Note: 
$$\theta = \sin^{-1} \frac{0.075 \text{ m}}{0.15 \text{ m}} = 30^{\circ} = \frac{\pi}{6} \text{ rad}$$

So 
$$\beta_C = \frac{5}{6}\pi, \ \beta_D = \frac{2}{3}\pi, \ \beta_E = \frac{1}{2}\pi$$

(a) To raise maximum  $m_A$ , with C rotating  $W_A = T_1 e^{\mu_S \beta_C}$ . If D and E are fixed, cable must slip there, so  $T_2 = T_1 e^{\mu_K \beta_D}$ 

and 
$$W_B = T_2 e^{\mu_k \beta_E} = T_1 e^{\mu_k (\beta_D + \beta_E)}$$
 
$$= W_A e^{-\mu_s \beta_C} e^{\mu_k (\beta_D + \beta_E)}$$

$$(8 \text{ kg}) g = m_A g e^{-0.2(\frac{5}{6}\pi)} e^{0.15(\frac{2}{3} + \frac{1}{2})\pi}$$

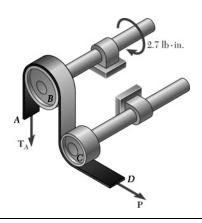
$$m_A = 7.79 \text{ kg} \blacktriangleleft$$

(b) With E rotating  $\int_{C} T_2 = W_B e^{\mu_S \beta_E}$ . With C and D fixed.

$$T_1=W_Ae^{\mu_keta_C}$$
 and  $T_2=T_1e^{\mu_keta_D}=W_Ae^{\mu_k\left(eta_C+eta_D
ight)}$  so 
$$W_B=W_Ae^{\mu_k\left(eta_C+eta_D
ight)}e^{-\mu_seta_E}$$

$$(8 \text{ kg})g = m_A g e^{0.15(\frac{5}{6} + \frac{2}{3})\pi} e^{-0.2(\frac{1}{2}\pi)}$$

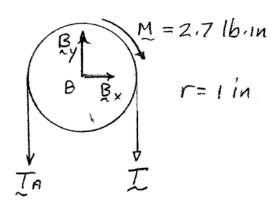
 $m_A = 5.40 \,\mathrm{kg}$ 



A recording tape passes over the 1-in.-radius drive drum B and under the idler drum C. Knowing that the coefficients of friction between the tape and the drums are  $\mu_s = 0.40$  and  $\mu_k = 0.30$  and that drum C is free to rotate, determine the smallest allowable value of P if slipping of the tape on drum B is not to occur.

#### **SOLUTION**

FBD drive drum:



$$\sum M_B = 0$$
:  $r(T_A - T) - M = 0$  
$$T_A - T = \frac{M}{r} = \frac{2.7 \text{ lb} \cdot \text{in.}}{1 \text{ in.}} = 2.7 \text{ lb}$$

Impending slipping:

$$T_A = Te^{\mu_S \beta} = Te^{0.4\pi}$$

So

$$T(e^{0.4\pi} - 1) = 2.7 \text{ lb}$$

or

$$T = 1.0742 \, \text{lb}$$

If C is free to rotate, P = T

 $P = 1.074 \text{ lb} \blacktriangleleft$ 

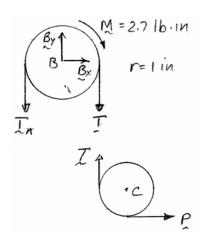
# 2.7 lb·in.

#### **PROBLEM 8.123**

Solve Problem 8.122 assuming that the idler drum C is frozen and cannot rotate.

#### **SOLUTION**

#### FBD drive drum:



$$\sum M_B = 0$$
:  $r(T_A - T) - M = 0$  
$$T_A - T = \frac{M}{r} = \frac{2.7 \text{ lb} \cdot \text{in.}}{1 \text{ in.}} = 2.7 \text{ lb}$$

Impending slipping:

$$T_A = Te^{\mu_S \beta} = Te^{0.4\pi}$$

So

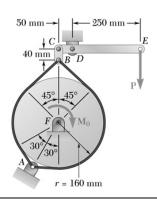
$$(e^{0.4\pi} - 1)T = 2.7 \text{ lb}$$

or

$$T = 1.07416 \, \text{lb}$$

If C is fixed, the tape must slip (

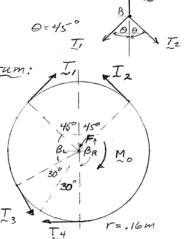
$$P = Te^{\mu_k \beta_C} = 1.07416 \text{ lb } e^{0.3\frac{\pi}{2}} = 1.7208 \text{ lb}$$



For the band brake shown, the maximum allowed tension in either belt is 5.6 kN. Knowing that the coefficient of static friction between the belt and the 160-mm-radius drum is 0.25, determine (a) the largest clockwise moment  $\mathbf{M}_0$  that can be applied to the drum if slipping is not to occur, (b) the corresponding force  $\mathbf{P}$  exerted on end E of the lever.

#### **SOLUTION**

#### FBD pin B:



(a) By symmetry:  $T_1 = T_2$ 

$$\uparrow \Sigma F_y = 0$$
:  $B - 2\left(\frac{\sqrt{2}}{2}T_1\right) = 0$  or  $B = \sqrt{2}T_1 = \sqrt{2}T_2$  (1)

For impending rotation ):

$$T_3 > T_1 = T_2 > T_4$$
, so  $T_3 = T_{\text{max}} = 5.6 \text{ kN}$ 

Then 
$$T_1 = T_3 e^{-\mu_s \beta_L} = (5.6 \text{ kN}) e^{-0.25 \left(\frac{\pi}{4} + \frac{\pi}{6}\right)}$$

or 
$$T_1 = 4.03706 \text{ kN} = T_2$$

and 
$$T_4 = T_2 e^{-\mu_s \beta_R} = (4.03706 \text{ kN}) e^{-0.25 \left(\frac{3\pi}{4}\right)}$$

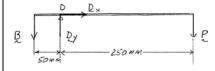
or 
$$T_4 = 2.23998 \,\text{kN}$$

$$(\Sigma M_F = 0: M_0 + r(T_4 - T_3 + T_2 - T_1) = 0$$

or 
$$M_0 = (0.16 \text{ m})(5.6 \text{ kN} - 2.23998 \text{ kN}) = 0.5376 \text{ kN} \cdot \text{m}$$

$$\mathbf{M}_0 = 538 \,\mathrm{N \cdot m}$$

#### Lever:

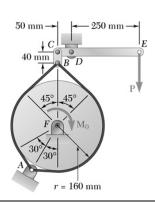


(b) Using Equation (1)

$$B = \sqrt{2}T_1 = \sqrt{2} (4.03706 \text{ kN})$$
$$= 5.70927 \text{ kN}$$

$$(\Sigma M_D = 0: (0.05 \text{ m})(5.70927 \text{ kN}) - (0.25 \text{ m})P = 0$$

 $\mathbf{P} = 1.142 \,\mathrm{kN}$ 

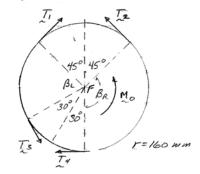


Solve Problem 8.124 assuming that a counterclockwise moment is applied to the drum.

#### **SOLUTION**

FBD pin B:

FBD Drum



(a) By symmetry:

$$\uparrow \Sigma F_y = 0: B - 2\left(\frac{\sqrt{2}}{2}T_1\right) = 0 \quad \text{or} \quad B = \sqrt{2}T_1$$
 (1)

For impending rotation :

$$T_4 > T_2 = T_1 > T_3$$
, so  $T_4 = T_{\text{max}} = 5.6 \text{ kN}$ 

Then 
$$T_2 = T_4 e^{-\mu_s \beta_R} = (5.6 \text{ kN}) e^{-0.25 \left(\frac{3\pi}{4}\right)}$$

or 
$$T_2 = 3.10719 \text{ kN} = T_1$$

and 
$$T_3 = T_1 e^{-\mu_s \beta_L} = (3.10719 \text{ kN}) e^{-0.25(\frac{\pi}{4} + \frac{\pi}{6})}$$

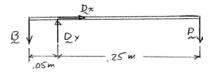
or 
$$T_3 = 2.23999 \text{ kN}$$

$$\sum M_F = 0$$
:  $M_0 + r(T_2 - T_1 + T_3 - T_4) = 0$ 

$$M_0 = (160 \text{ mm})(5.6 \text{ kN} - 2.23999 \text{ kN}) = 537.6 \text{ N} \cdot \text{m}$$

$$\mathbf{M}_0 = 538 \,\mathrm{N \cdot m} \,\mathrm{M}$$

**FBD Lever:** 



(b) Using Equation (1)

$$B = \sqrt{2}T_1 = \sqrt{2} (3.10719 \text{ kN})$$
$$B = 4.3942 \text{ kN}$$

$$(\Sigma M_D = 0: (0.05 \text{ m})(4.3942 \text{ kN}) - (0.25 \text{ m})P = 0$$

 $\mathbf{P} = 879 \,\mathrm{N} \,\mathbf{I} \blacktriangleleft$ 

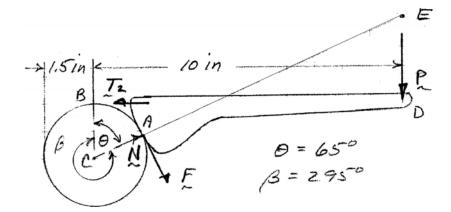


The strap wrench shown is used to grip the pipe firmly without marring the surface of the pipe. Knowing that the coefficient of static friction is the same for all surfaces of contact, determine the smallest value of  $\mu_s$  for which the wrench will be self-locking when a = 10 in., r = 1.5 in., and  $\theta = 65^{\circ}$ .

#### **SOLUTION**

For the wrench to be self-locking, friction must be sufficient to maintain equilibrium as P is increased from zero to  $P_{\text{max}}$ , as well as to prevent slipping of the belt on the pipe.

#### FBD wrench:



$$\longrightarrow \Sigma F_x = 0: \quad -T_2 + N\sin 65^\circ + F\cos 65^\circ = 0$$

Impending slipping:

$$N = F/\mu_s$$

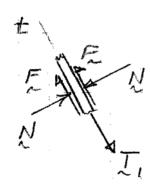
$$F\left(\frac{\sin 65^{\circ}}{\mu_s} + \cos 65^{\circ}\right) = T_2$$

$$\frac{0.90631}{\mu_s} + 0.42262 = \frac{T_2}{F} \tag{2}$$

Solving Equations (1) and (2) yields  $\mu_s = 0.3497$ ; must still check belt on pipe.

# **PROBLEM 8.126 CONTINUED**

# Small portion of belt at A:



$$\sum F_t = 0: \quad 2F - T_1 = 0$$

or

$$T_1 = 2F$$

Belt impending slipping:

$$\ln \frac{T_2}{T_1} = \mu_s \beta$$

So

$$\mu_s = \frac{1}{\beta} \ln \frac{T_2}{T_1} = \frac{1}{\beta} \ln \frac{T_2}{2F}$$

Using Equation (1)

$$\mu_s = \frac{180}{295\pi} \ln 1.50703$$

$$= 0.0797$$

∴ for self-locking, need  $\mu_s = 0.350$  ◀

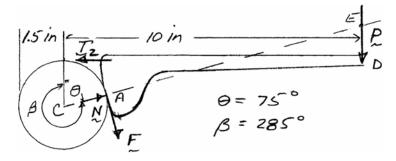


Solve Problem 8.126 assuming that  $\theta = 75^{\circ}$ .

#### **SOLUTION**

For the wrench to be self-locking, friction must be sufficient to maintain equilibrium as P is increased from zero to  $P_{\text{max}}$ , as well as to prevent slipping of the belt on the pipe.

#### FBD wrench:



$$\left(\sum M_E = 0: \left(\frac{10 \text{ in.}}{\sin 75^\circ} - 1.5 \text{ in.}\right) F - \left(\frac{10 \text{ in.}}{\tan 75^\circ} - 1.5 \text{ in.}\right) T_2 = 0$$

or

$$\frac{T_2}{F} = 7.5056\tag{1}$$

$$\rightarrow \Sigma F_x = 0$$
:  $-T_2 + N \sin 75^\circ + F \cos 75^\circ = 0$ 

Impending slipping:

$$N = F/\mu_{\rm s}$$

$$F\left(\frac{\sin 75^{\circ}}{\mu_{s}} + \cos 75^{\circ}\right) = T_{2}$$

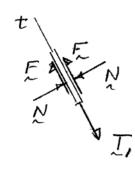
or

$$\frac{T_2}{F} = \frac{0.96593}{\mu_s} + 0.25882\tag{2}$$

Solving Equations (1) and (2):  $\mu_s = 0.13329$ ; must still check belt on pipe.

# **PROBLEM 8.127 CONTINUED**

# Small portion of belt at A:



$$\sum \Sigma F_t = 0: \quad 2F - T_1 = 0$$

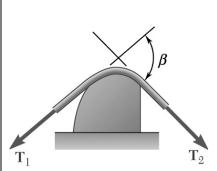
or  $T_1 = 2F$ 

Impending belt slipping:  $\ln \frac{T_2}{T_1} = \mu_s \beta$ 

So  $\mu_s = \frac{1}{\beta} \ln \frac{T_2}{T_1} = \frac{1}{\beta} \ln \frac{T_2}{2F}$ 

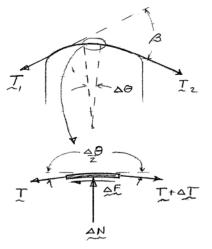
Using Equation (1):  $\mu_s = \frac{180}{285\pi} \ln \frac{7.5056}{2}$ = 0.2659

∴ for self-locking,  $\mu_s = 0.266$ 



Prove that Equatins (8.13) and (8.14) are valid for any shape of surface provided that the coefficient of friction is the same at all points of contact.

#### **SOLUTION**



$$\uparrow \Sigma F_n = 0: \quad \Delta N - \left[T + \left(T + \Delta T\right)\right] \sin \frac{\Delta \theta}{2} = 0$$

$$\Delta N = (2T + \Delta T) \sin \frac{\Delta \theta}{2}$$

$$\longrightarrow \Sigma F_t = 0$$
:  $\left[ \left( T + \Delta T \right) - T \right] \cos \frac{\Delta \theta}{2} - \Delta F = 0$ 

$$\Delta F = \Delta T \cos \frac{\Delta \theta}{2}$$

Impending slipping:

$$\Delta F = \mu_s \Delta N$$

So 
$$\Delta T \cos \frac{\Delta \theta}{2} = \mu_s 2T \sin \frac{\Delta \theta}{2} + \mu_s \Delta T \frac{\sin \Delta \theta}{2}$$

In limit as  $\Delta\theta \to 0$ :  $dT = \mu_s T d\theta$ , or  $\frac{dT}{T} = \mu_s d\theta$ 

So 
$$\int_{T_1}^{T_2} \frac{dT}{T} = \int_0^\beta \mu_s d\theta;$$

and 
$$\ln \frac{T_2}{T_1} = \mu_s \beta$$

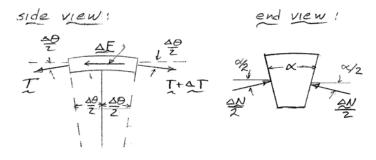
or 
$$T_2 = T_1 e^{\mu_s \beta}$$

Note: Nothing above depends on the shape of the surface, except it is assumed smooth.

Complete the derivation of Equation (8.15), which relates the tension in both parts of a V belt.

#### **SOLUTION**

**Small belt section:** 



$$\uparrow \Sigma F_y = 0: \quad 2\frac{\Delta N}{2}\sin\frac{\alpha}{2} - \left[T + \left(T + \Delta T\right)\right]\sin\frac{\Delta\theta}{2} = 0$$

$$\rightarrow \Sigma F_x = 0$$
:  $\left[ \left( T + \Delta T \right) - T \right] \cos \frac{\Delta \theta}{2} - \Delta F = 0$ 

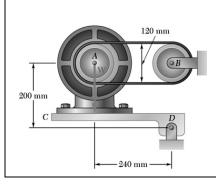
Impending slipping: 
$$\Delta F = \mu_s \Delta N \Rightarrow \Delta T \cos \frac{\Delta \theta}{2} = \mu_s \frac{2T + \Delta T}{\sin \frac{\alpha}{2}} \sin \frac{\Delta \theta}{2}$$

In limit as 
$$\Delta\theta \to 0$$
: 
$$dT = \frac{\mu_s T d\theta}{\sin\frac{\alpha}{2}} \qquad \text{or} \qquad \frac{dT}{T} = \frac{\mu_s}{\sin\frac{\alpha}{2}} d\theta$$

So 
$$\int_{T_1}^{T_2} \frac{dT}{T} = \frac{\mu_s}{\sin \frac{\alpha}{2}} \int_0^\beta d\theta$$

or 
$$\ln \frac{T_2}{T_1} = \frac{\mu_s \beta}{\sin \frac{\alpha}{2}}$$

or  $T_2 = T_1 e^{\mu_s \beta / \sin \frac{\alpha}{2}} \blacktriangleleft$ 

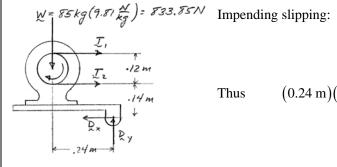


Solve Problem 8.107 assuming that the flat belt and drums are replaced by a V belt and V pulleys with  $\alpha = 36^{\circ}$ . (The angle  $\alpha$  is as shown in Figure 8.15a.)

#### **SOLUTION**

FBD motor + mount:

$$(\Sigma M_D = 0: (0.24 \text{ m})W - (0.26 \text{ m})T_1 - (0.14 \text{ m})T_2 = 0$$



$$T_2 = T_1 e^{\mu_S \beta / \sin \frac{\alpha}{2}}$$

$$T_2 = T_1 e^{\frac{0.4\pi}{\sin 18^\circ}} = 58.356T_1$$

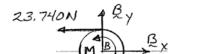
Thus

$$(0.24 \text{ m})(833.85 \text{ N}) - [0.26 \text{ m} + (0.14 \text{ m})(58.356)]T_1 = 0$$

$$T_1 = 23.740 \text{ N}$$

$$T_2 = 1385.369 \text{ N}$$

**FBD Drum:** 



1385,369N

 $(\Sigma M_B = 0: M_B + (0.06 \text{ m})(23.740 \text{ N} - 1385.369 \text{ N}) = 0$ 

$$M_B = 81.7 \text{ N} \cdot \text{m} \blacktriangleleft$$

(Compare to  $M_B = 40.1 \text{ N} \cdot \text{m}$  using flat belt, Problem 8.107.)