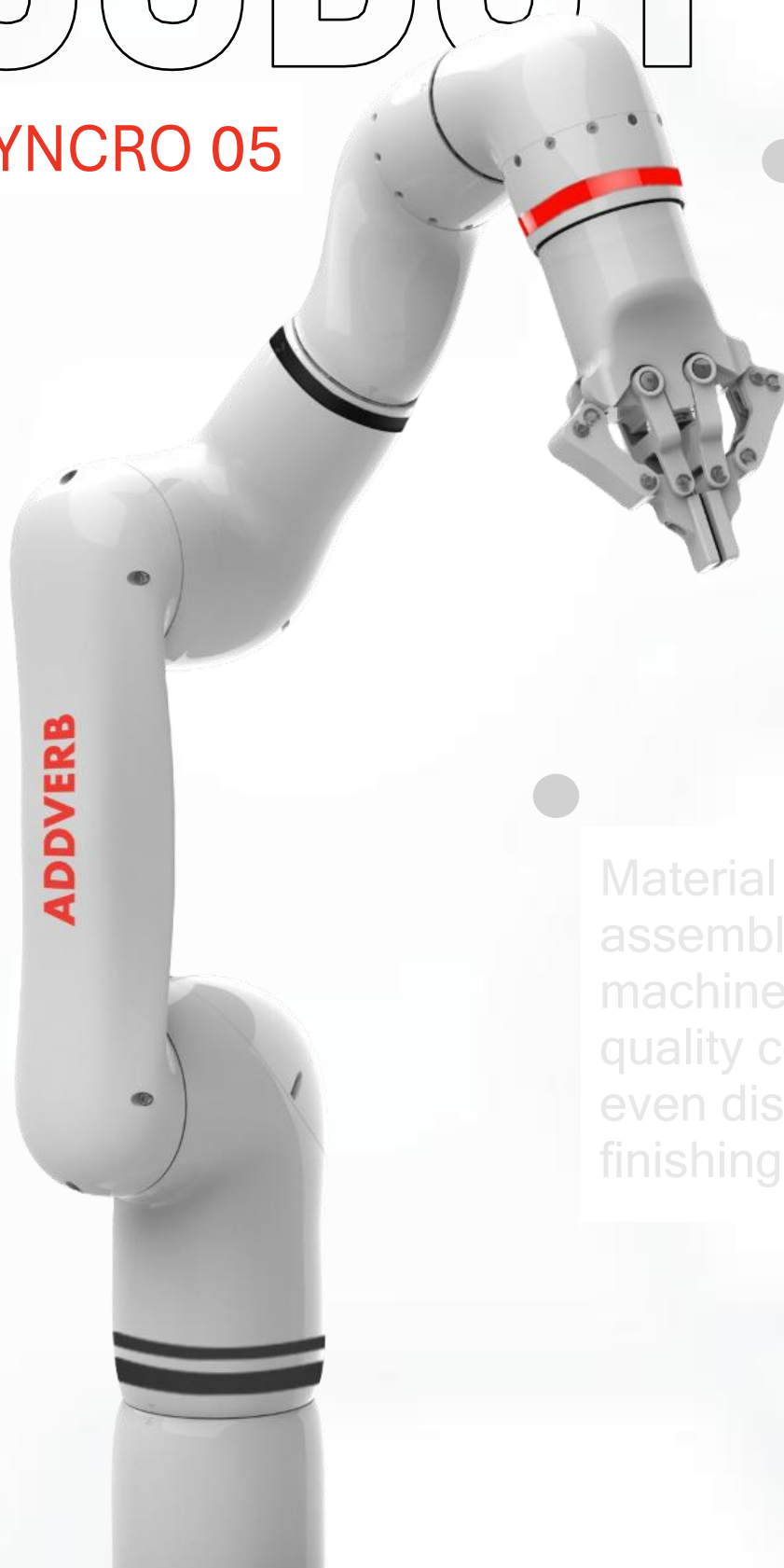


# COBOT

**SYNCRO 05**



Addverb's  
Advanced  
Robotics  
Solutions

Material handling,  
assembly, packaging,  
machine tending,  
quality control and  
even dispensing and  
finishing tasks

**ADDVERB**

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- Addverb makes no representations or warranties regarding the accuracy, completeness, or reliability of the information contained in this user guide.
- Addverb shall not be held responsible for any damages, direct or indirect, arising from the use or inability to use the Syncro 5 cobot, including any incidental or consequential damages.
- Any modifications or repairs carried out by unauthorized personnel will void the warranty and may result in damage or injury.
- Addverb is not responsible for any third-party software or accessories used in conjunction with the Syncro 5 cobot.

Revision History

Revision No.	Manual Name	Date	Comment
0.0	Syncro 5 cobot User Manual	August, 2025	Original Version

# Table of Contents

DISCLAIMER .....	2
REVISION HISTORY .....	3
TABLE OF CONTENTS.....	4
ABOUT THE DOCUMENT .....	7
PURPOSE .....	7
SCOPE .....	7
AUDIENCE.....	7
SUPPORT .....	7
RESOURCES .....	8
CHAPTER 1: SAFETY AND COMPLIANCE .....	9
1.1    VALIDITY AND RESPONSIBILITY .....	9
1.2    LIMITATION OF LIABILITY .....	9
1.3    TERMS AND CONDITIONS .....	9
1.4    GENERAL WARNING AND CAUTION MESSAGES .....	10
1.5    GENERAL SAFETY GUIDELINES .....	11
1.6    RISK ASSESSMENT.....	12
1.7    PRE-USE SAFETY CHECKS .....	12
1.8    WARNINGS AND POTENTIAL HAZARDS .....	13
1.9    INTENDED USE .....	13
1.10   MAINTENANCE SAFETY PRECAUTIONS .....	13
CHAPTER 2: INTRODUCTION TO SYNCRO 5 COBOT.....	14
2.1    OVERVIEW .....	14
2.2    KEY FEATURES OF SYNCRO 5 COBOT .....	15
2.2.1 <i>Six Degrees of Freedom</i> .....	15
2.2.2 <i>Advanced Design and Construction</i> .....	15
2.2.3 <i>Intuitive Control System</i> .....	15
2.2.4 <i>Collaborative Safety Features</i> .....	15
2.2.5 <i>Enhanced Adaptability and Longevity</i> .....	15
2.3    WHAT'S IN THE BOX.....	16
CHAPTER 3: HARDWARE REQUIREMENTS .....	17
3.1    PHYSICAL COMPONENT OVERVIEW .....	17
3.2    HARDWARE SPECIFICATIONS .....	18
3.3    ENVIRONMENTAL CONDITION .....	18
3.4    EMERGENCY STOP.....	19
3.4.1 <i>Using the Emergency Stop</i> .....	19
3.4.2 <i>Resetting the Emergency Stop</i> .....	19
3.4.3 <i>Recovering from Emergency Conditions</i> .....	20
3.5    CONTROL BOX DETAILS .....	20
3.5.1 <i>Precautions and Safety Measures</i> .....	20
3.5.3 <i>Control Box LED Indicators</i> .....	24
CHAPTER 4: ELECTRICAL REQUIREMENTS .....	25
4.1    ELECTRICAL WARNING AND CAUTION .....	25
4.2    ELECTRICAL CABLES AND CONNECTOR LIST.....	25
4.3    ELECTRICAL SPECIFICATIONS.....	27

4.4	ELECTRICAL CONNECTION ILLUSTRATION .....	27
<b>CHAPTER 5: INSTALLATION OF SYNCRO 5 COBOT .....</b>		<b>28</b>
5.1	WARNING AND CAUTION MESSAGES .....	28
5.2	WORKSPACE AND OPERATING SPACE .....	29
5.2.1	<i>Mechanical Dimension of Syncro 5 cobot</i> .....	29
5.2.2	<i>Syncro 5 cobot Mounting Specification</i> .....	30
5.3	SECURING THE SYNCRO 5 COBOT .....	30
5.3.1	<i>Load and Torque Criteria</i> .....	32
5.4	PLACING CONTROL BOX .....	33
5.5	CONNECTING THE SYNCRO 5 COBOT TO CONTROL BOX .....	34
5.5.1	<i>Electrical Safety Requirements</i> .....	34
5.5.2	<i>Electrical Connection Illustration</i> .....	35
5.5.3	<i>Making the Connection</i> .....	36
<b>CHAPTER 6: GETTING STARTED .....</b>		<b>38</b>
6.1	POWERING ON/OFF THE SYNCRO 5 COBOT .....	38
6.1.1	<i>Preparation before Power Up</i> .....	38
6.1.2	<i>Powering on the Cobot System</i> .....	38
6.2	CONNECTING MOUNTING TOOL .....	38
<b>CHAPTER 7: RECOMMENDED STORAGE CONDITIONS .....</b>		<b>40</b>
7.1	TEMPERATURE LIMITS .....	40
7.2	STORAGE BEST PRACTICES .....	40
<b>CHAPTER 8: PACKING AND TRANSPORTATION .....</b>		<b>42</b>
8.1	PRECAUTION AND SAFETY MEASURES .....	42
8.2	TRANSPORTATION DETAILS .....	42
8.2.1	<i>Transportation Box Specifications</i> .....	43
8.2.2	<i>Preparation for Transport</i> .....	43
8.2.3	<i>Handling Instructions</i> .....	44
8.2.4	<i>Transport Mode</i> .....	44
8.2.5	<i>Loading and Unloading</i> .....	44
8.2.6	<i>Environmental Considerations</i> .....	44
<b>CHAPTER 9: ROBOT CLEANING AND INSPECTION .....</b>		<b>45</b>
9.1	INSPECTION CHECKLIST .....	45
9.2	VISUAL INSPECTIONS .....	47
9.3	CONTROL BOX .....	48
9.4	ROBOT CLEANING .....	48
9.4.1	<i>Cobot Cleaning</i> .....	48
9.4.2	<i>Control Box and Teach Pendant Cleaning</i> .....	48
<b>CHAPTER 10: DISCARD AND DISPOSAL INSTRUCTIONS .....</b>		<b>49</b>
10.1	END OF SERVICE LIFE CONSIDERATIONS .....	49
10.2	DISPOSAL OF ELECTRONIC COMPONENTS .....	49
10.3	MECHANICAL PARTS AND FRAME .....	50
10.4	COMPLIANCE WITH LOCAL AND INTERNATIONAL STANDARDS .....	50
10.5	MATERIAL GROUP DISPOSAL METHODS .....	50
10.6	ENVIRONMENTAL CONDITION .....	51
<b>CHAPTER 11: COMMON ISSUES AND RESOLUTIONS .....</b>		<b>52</b>
<b>CHAPTER 12: FREQUENTLY ASKED QUESTIONS (FAQS) .....</b>		<b>54</b>

**CHAPTER 13: WARRANTY DETAILS ..... 55**

**13.1 WARRANTY COVERAGE..... 55**

**13.2 CUSTOMER OBLIGATIONS ..... 55**

**13.3 EXCLUSIVES FROM WARRANTY ..... 55**

**13.4 WARRANTY CLAIM PROCESS ..... 56**

**13.4.1 Limitations of Liability..... 56**

**13.4.2 Additional Notes ..... 56**

## About the Document

### Purpose

The purpose of this user guide is to provide comprehensive instructions for the safe, efficient, and effective operation of the Syncro 5 cobot. It serves as a reference for understanding the cobot's features, installation, maintenance, and troubleshooting. This guide ensures users can maximize the cobot's potential while adhering to safety protocols and operational guidelines.

### Scope

This user guide covers the following key aspects of the Syncro 5 cobot:

- **Setup and Installation:** Step-by-step instructions for proper installation and setup of the cobot in your environment
- **Operating Instructions:** Detailed information on how to operate the cobot, including control modes, task programming, and safety protocols
- **Maintenance and Calibration:** Guidance on maintaining and calibrating the cobot to ensure longevity and precision
- **Troubleshooting:** A list of common issues and solutions to ensure smooth operation and reduce downtime
- **Safety Considerations:** Best practices and safety measures to ensure the safe use of the cobot in collaborative workspaces. This guide does not cover third-party integrations, advanced programming techniques, or modifications to the cobot that fall outside the manufacturer's recommendations

### Audience

- **Operators:** Individuals responsible for the day-to-day operation of the cobot
- **Technicians:** Professionals handling installation, programming, and maintenance tasks
- **Supervisors and Managers:** Decision-makers overseeing cobot usage in their workflows  
Prior experience with robotics or automation systems is recommended but not mandatory

### Support

For technical assistance or inquiries regarding the Syncro 5 cobot, users can contact Addverb's dedicated support team. **Support services include:**

- Installation and configuration assistance
- Guidance on programming and operational features
- Troubleshooting and maintenance support

**Contact information:**

- **Email:** [support@addverb.com](mailto:support@addverb.com)
- **Phone:** [+91 9871590101](tel:+919871590101)
- **Website:** [www.addverb.ai](http://www.addverb.ai)

## Resources

This guide includes references to additional resources for users seeking more detailed information or advanced use cases:

- **Documentation:** Supplementary manuals, datasheets, and programming guides are available at [www.addverb.com/documentation](http://www.addverb.com/documentation)
- **Training:** Access online or in-person training programs through Addverb's training portal
- **Community:** Join the Addverb user community for tips, best practices, and peer support
- **Safety Standards:** Refer to ISO 12100:2010, Annex I of 2006/42/EC, EN 60204-1:2018, and ISO 10218-1:2011 standards for collaborative robots. By utilizing these resources, users can ensure the optimal performance and longevity of their Syncro 5 cobot.



## Chapter 1: Safety and Compliance

This section introduces the principles and norms that should be followed while operating the Cobot. Users must read the relevant description in this section carefully.

**This section includes safety precautions for protecting the user and preventing any damage to the Cobot:**

### 1.1 Validity and Responsibility

The Syncro 5 cobot safety section outlines operational guidelines but does not include comprehensive instructions on designing, installing, or integrating the robot application. The safety of the overall application, including its peripheral equipment, depends on adherence to the relevant standards and regulations of the deployment country.

**Responsibility of Integrators:**

Integrators must ensure compliance with applicable regulations and reduce risks associated with the Syncro 5 cobot. **Their responsibilities include:**

- Conducting a risk assessment for the entire robotic system
- Interfacing the Syncro 5 cobot with other machines and implementing additional safeguarding measures as needed
- Configuring safety settings correctly in the software
- Preventing unauthorized modifications to safety measures
- Validating the design, installation, and integration of the robotic application
- Providing clear operational instructions and displaying relevant safety signage at the installation site
- Maintaining documentation, including risk assessments, integration guidelines, and this manual

### 1.2 Limitation of Liability

The guidance provided in this manual should not be considered a guarantee that the Syncro 5 cobot will eliminate all risks of injury or damage. Even with all safety measures in place, unforeseen risks may occur.

Addverb disclaims any warranty for injuries, property damage, or other incidents resulting from improper use or failure to adhere to these safety instructions.

### 1.3 Terms and Conditions





**Follow these instructions while using the cobot to ensure safe and efficient operation:**

- Install the cobot and all electrical equipment exactly as described in this manual
- Press the Emergency Stop switch immediately to halt any unexpected or undesired cobot movements

- Avoid frequently powering the cobot ON and OFF, as the Syncro joint module contains internal brakes
- Maintain a minimum clearance of 1.5 meters around the cobot when operating at speeds greater than 0.5 m/sec to ensure safety

1.4 General Warning and Caution Messages

This section provides an overview of the safety icons and warning symbols used throughout this guide. These icons are designed to highlight critical information, ensuring safe and effective operation of the Syncro 5 cobot. Icons are visual cues to draw attention to important safety instructions, warnings, and operational guidelines. Familiarize yourself with these icons to mitigate risks and prevent harm.

Icons	
	<p><b>WARNING</b></p> <p><i>Indicates a hazardous situation that, if not avoided, can result in death or serious injury.</i></p>
	<p><b>WARNING: ELECTRICITY</b></p> <p><i>Indicates a hazardous situation that, if not avoided, can result in death or serious injury.</i></p>
	<p><b>CAUTION</b></p> <p><i>Indicates a hazardous situation that, if not avoided, can result in serious injury.</i></p>
	<p><b>NOTICE</b></p> <p><i>Indicates the risk of damage to equipment and/or information to be noted.</i></p>

## 1.5 General Safety Guidelines

To ensure safe operation of the Syncro 5 cobot, adhere to the following:



### **CAUTION: INSTALLATION AND SETUP**

**Before operating the Syncro 5 cobot:**

- Ensure the cobot arm and end effector are securely installed
- Provide sufficient operational space to avoid collisions with objects or personnel
- Perform safety configuration during setup to match application requirements



### **CAUTION: OPERATIONAL SAFETY**

**Before operating the Syncro 5 cobot:**

- Prohibit the use of a damaged cobot
- Ensure all personnel are protected during the cobot's transport, installation, programming, operation, and maintenance
- Inform operators of the cobot's emergency stop locations and procedures



### **CAUTION: USER SAFETY**

**Before operating the Syncro 5 cobot:**

- Avoid wearing loose clothing, jewellery, or long hair near the cobot
- Maintain safe distances during cobot operation, especially during startup
- Regularly inspect the cobot for loose bolts or signs of wear and tear
- Ensure operators understand the direction of the cobot's movements when using the teach pendant
- Treat the cobot as active even when it appears stopped; it may be waiting for a signal
- Always keep the emergency stop (E-stop) switch easily accessible

## 1.6 Risk Assessment

A detailed risk assessment must be conducted prior to powering the Syncro 5 cobot for the first time and after any modifications. This includes:

- Evaluating the risks associated with teaching, troubleshooting, and normal operation
- Identifying and implementing safety settings, emergency stops, and safeguarding measures

### Safety Configuration Settings:

- **Force and Power Limiting:** Reduces clamping forces and pressures during collisions
- **Speed Limitation:** Limits movement speed to reduce impact forces
- **Orientation Restrictions:** Prevents hazardous positioning of sharp edges or tools toward operators

## 1.7 Pre-Use Safety Checks



### **CAUTION: ELECTRICAL HAZARDS**

#### **Before operating the Syncro 5 cobot:**

- Verify all safety inputs and outputs are correctly connected
- Test emergency stop functionality and safeguard inputs
- Confirm operational modes change as indicated on the interface
- Test reduced-speed mode to ensure safe manual operation
- Connect 10A MCB in line with the Control box power
- Before powering on the control box make sure the earthing voltage is less than 2V

## 1.8 Warnings and Potential Hazards



### **WARNING**

#### **Potential Hazards Include:**

- Injuries from sharp edges or points on tools, obstacles, or workpieces
- Bruising or fractures due to collisions
- Loose bolts causing unintended movement
- Incorrect safety configurations or unauthorized changes
- Items falling from or flying off the cobot due to poor grip or mechanical failure

## 1.9 Intended Use

The Syncro 5 cobot is designed for industrial use, such as handling tools, transferring products, or performing collaborative tasks. Ensure the application adheres to low-risk requirements identified in the risk assessment.



### **PROHIBITED USES**

- Direct handling of hazardous materials
- Situations requiring compliance with food-grade or hygiene standards
- Any application outside the cobot's specified operational parameters

## 1.10 Maintenance Safety Precautions

**To ensure the safety of operators and equipment during maintenance, follow these precautions:**

- **Power Off Completely:** Always turn off the power and remove the main input cable from the control box to ensure the system is completely powered off before performing any maintenance tasks
- **Electrical Ground Check:** Verify the electrical grounding of the system before turning it back on to prevent electrical hazards
- **No Unauthorized Disassembly:** Avoid disassembling the power supplies or any internal components inside the control box to prevent electrical shocks or system damage
- **Prevent Environmental Hazards:** Ensure no water or dust enters the cobot or control box to maintain operational safety and reliability

These safety precautions must be strictly adhered to during maintenance to avoid injuries or system failures. For detailed Maintenance procedure refer to Maintenance section in this guide.

## Chapter 2: Introduction to Syncro 5 cobot

This section introduces the Syncro 5 cobot detailing the necessary features :

### 2.1 Overview

The Syncro 5 cobot by Addverb revolutionizes collaborative robotics with its advanced design and user-focused capabilities. Featuring six degrees of freedom, this cobot performs complex tasks with exceptional precision and flexibility, making it ideal for a wide range of applications, from assembly to material handling. Equipped with six actuators, it offers a broad range of motion to adapt to diverse operational needs. The cobot integrates seamlessly with human operators, using an intuitive teach pendant and a dedicated control box for simple programming and control. With built-in safety features the Syncro 5 cobot ensures safe and efficient operation in shared workspaces, enhancing productivity while maintaining a strong focus on user safety. Following are some of common use cases of the Syncro 5 cobot:

- Picking and packing in warehouses
- Loading and unloading goods
- Inventory management and tracking
- Assembly tasks on production lines
- Quality control inspections
- Material handling in manufacturing
- Delivering medical supplies in healthcare
- Supporting physiotherapy exercises
- Shelf stocking in retail and warehouses
- Product testing and calibration
- Prototyping in R&D



Figure 1: Syncro cobot

## 2.2 Key Features of Syncro 5 cobot

Following are a few of the key features that Addverb's Syncro 5 cobot supports:

### 2.2.1 Six Degrees of Freedom

The Syncro 5 cobot operates with six degrees of freedom, enabling precise and versatile movement. It performs rotational motions along pitch, yaw, and roll axes while executing translational movements along the same axes. This design mimics the complex mobility of a human arm, making the cobot highly adaptable for intricate tasks. Its ability to manipulate objects in various orientations allows seamless operation in dynamic environments and enhances collaboration with human workers.

### 2.2.2 Advanced Design and Construction

The cobot's robust framework integrates six high-performance actuators, ensuring optimal control and dexterity. These actuators maximize the cobot's reach, allowing it to navigate tight spaces and handle detailed operations effortlessly. The lightweight yet durable construction maintains structural strength while ensuring agility. Its modular architecture supports easy upgrades and modifications, making the Syncro 5 cobot adaptable to evolving operational demands.

### 2.2.3 Intuitive Control System

The Syncro 5 cobot simplifies operation with a user-friendly control system, combining a teach pendant that the user can purchase if they require and a dedicated control box. The teach pendant provides an intuitive graphical user interface (GUI), enabling operators to program tasks and make real-time adjustments efficiently. The control box synchronizes actuator movements, ensuring precise and coordinated actions for complex tasks. Operators can refer to the Teach Pendant User Manual for detailed guidance on programming and customization.

### 2.2.4 Collaborative Safety Features

This robot is equipped with torque safety, meaning it automatically stops whenever it detects a force opposing its motion. This ensures that if the robot comes into contact with a human or any unexpected obstacle, it halts immediately to prevent injury or damage.

### 2.2.5 Enhanced Adaptability and Longevity

The Syncro 5 cobot's modular and flexible design ensures long-term adaptability to diverse applications. Its scalable architecture supports integration into various industrial settings, ensuring consistent productivity and operational efficiency.

## 2.3 What's in the Box

When you place an order, you receive the following items in a box:

Item List	Quantity
Syncro 5 cobot	1
Control Box	1
Cobot Cable	1
AC Power Cable	1
Emergency Stop kit	1
Teach Pendant (Optional)	1


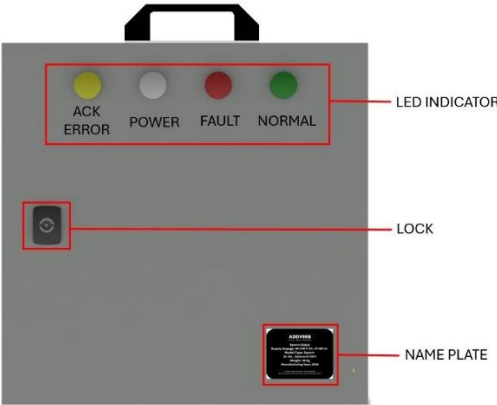



Chapter 3: Hardware Requirements

This section details the hardware specifications and requirements:

3.1 Physical Component Overview

Refer to this table for the physical component list and its description:

Component	Description
	<p><b>Cobot:</b></p> <p>The collaborative robot (Cobot) is designed to work safely alongside human operators in various industrial environments. It is a flexible, programmable robotic arm that can perform tasks such as material handling, assembly, or welding.</p>
	<p><b>Control Box:</b></p> <p>The control box is the central hub for managing the cobot's operations and safety features. It houses the necessary electronics and power systems to control the robot's movements, monitor system status, and communicate with external devices. The control box typically includes input/output (I/O) interfaces for actuators and other connected components.</p>
	<p><b>Emergency Stop (E-stop):</b></p> <p>The Emergency Stop (E-stop) is a critical safety feature that instantly halts all robot operations in case of an emergency or unsafe situation. Attached to the control box, the E-stop is a red, mushroom-shaped push-button that, when pressed, immediately disables the Cobot's motion to prevent injury or damage.</p>

## 3.2 Hardware Specifications

Parameter	Specification
Cobot Model	Syncro
Payload Capacity	Up to 5 kg
Reach	650 mm
Number of Axes	6 Degrees of Freedom
Weight	Up to 30 Kgs
Material	Aerospace-grade aluminum or equivalent durable material
Mounting Options	Floor
End-Effector Compatibility	User-defined
Control Box Dimension	(400L X 400B X 210H) mm

## 3.3 Environmental Condition

Parameter	Specification
Operating Temperature	0°C to 50°C
Storage Temperature	-10°C to 50°C <b>Note:</b> Start when the equipment is at normal temperature
Humidity	0% - 85% RH (Non-condensing)

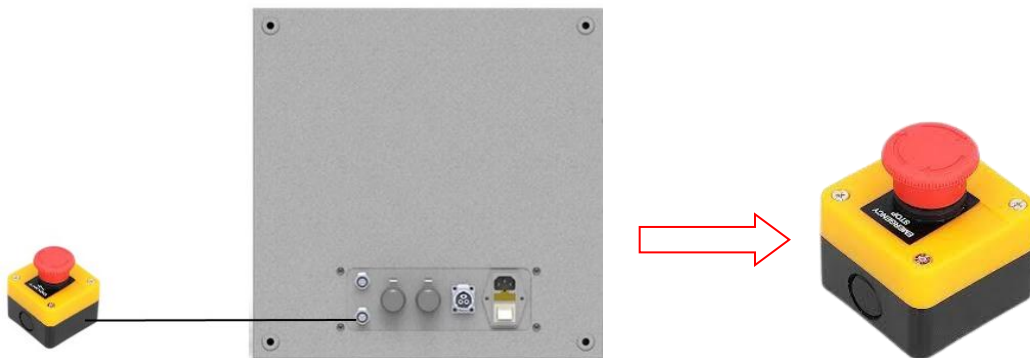


### NOTE

- Emergency stops are complementary protective measures, not safeguards (ISO 12100). They do not fully prevent injury.
- Perform a risk assessment to determine whether additional emergency stop pushbuttons are required.
- Ensure the emergency stop and actuating device comply with ISO 13850.

## 3.4 Emergency Stop

The emergency stop (E-stop) is a red push-button located on the Teach Pendant and the control box (see *Figure 2: Emergency stop*). Use the E-stop to immediately stop all robot motion during emergencies or dangerous situations. Pressing the E-stop activates a stop category one, as defined in IEC 60204-1.



**Figure 2: Emergency stop connection**

### 3.4.1 Using the Emergency Stop

- Press the E-stop button to halt all robot operations immediately
- Once activated, the E-stop latches into the pressed position and requires manual resetting

### 3.4.2 Resetting the Emergency Stop

- Before resetting, visually inspect the entire system to identify and resolve the cause of the E-stop activation
- Hold the E-stop button and twist it anticlockwise until the latch disengages. You will feel the button release when it is reset
- Confirm that all issues have been resolved before proceeding
- Once the E-stop is reset, the power is restored and the cobot resumes operation

### 3.4.3 Recovering from Emergency Conditions

- The E-stop button is equipped with a locking function that engages during activation
- Rotate the E-stop button to release the lock and exit the emergency stop state

## 3.5 Control Box Details

The control box serves as the central hub for operating the Syncro 5 cobot, providing a safe and efficient control system. It houses critical components, including a primary computer, a secondary computer, two switching power supplies, and a safety PCB to ensure user and cobot safety.

### 3.5.1 Precautions and Safety Measures

To ensure safety during installation and operation of the cobot and control box, the following precautions must be adhered to:

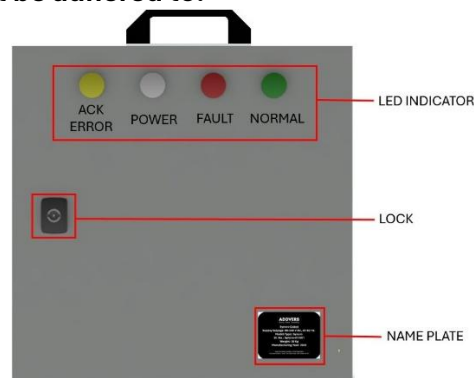


Figure 3: Control box (Front view)



#### **CAUTION: ELECTRICAL HAZARDS**

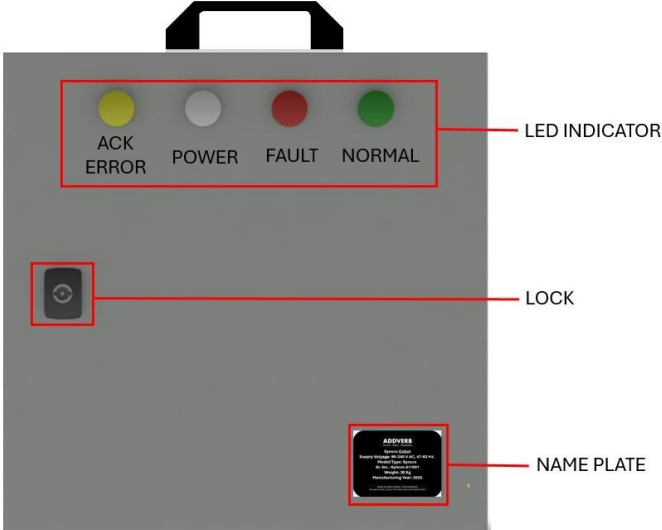
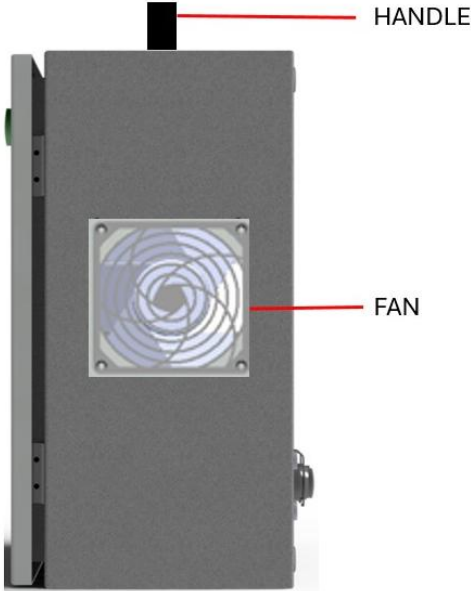
##### **Before operating the Syncro 5 cobot:**

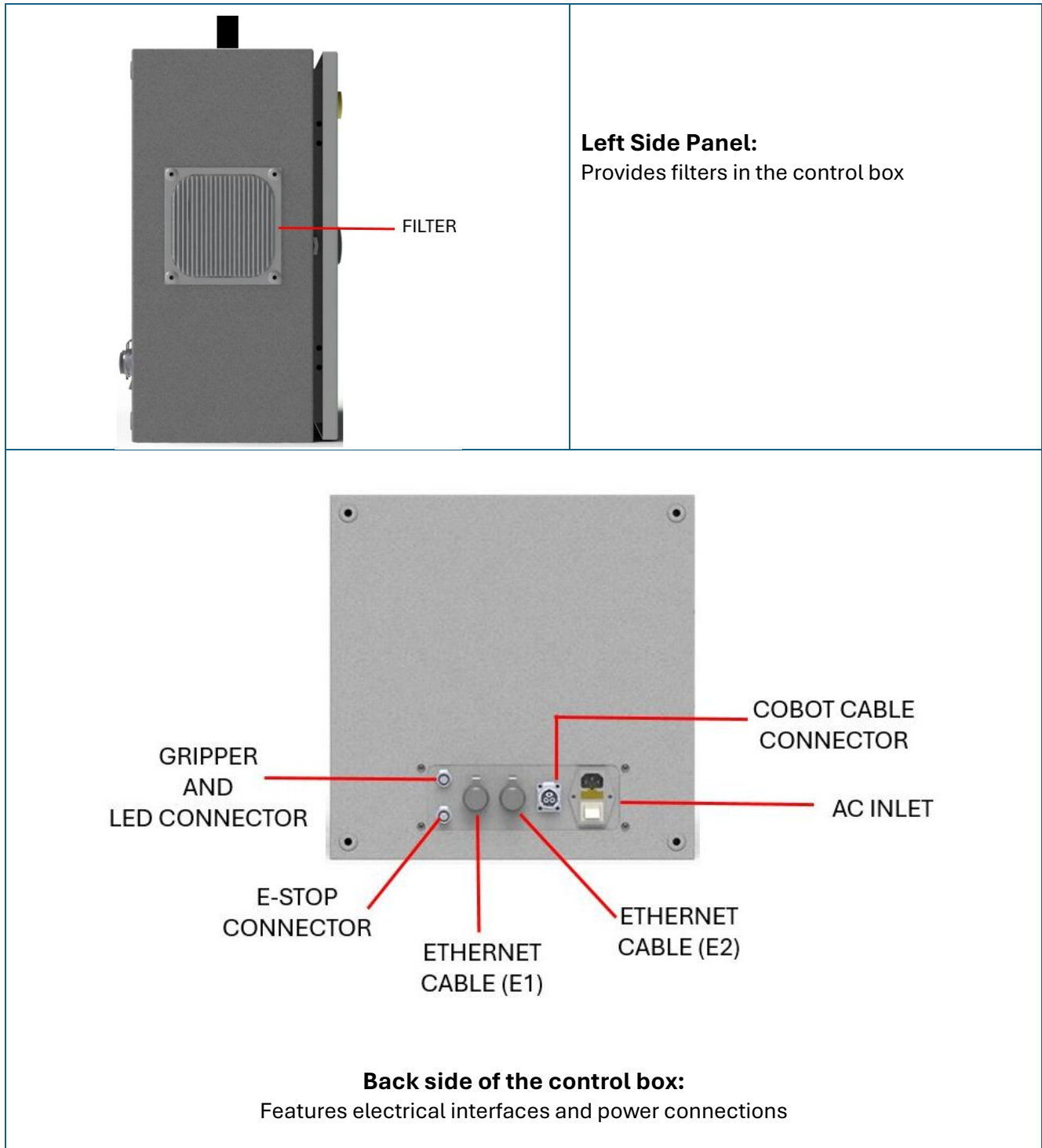
- Always disconnect the control box from the power source before performing maintenance, adjustments, or connections
- Avoid Overheating: Ensure adequate ventilation around the control box. Do not block ventilation slots or place the control box near heat sources
- No Water Exposure: Keep the control box dry at all times. If water enters the box, immediately shut off the power and contact Addverb's support team for assistance
- Authorized Access Only: Only trained personnel should open the control box for troubleshooting or repair. Tampering by unauthorized individuals can result in electrical hazards or void the warranty

***CAUTION: CONTROL BOX SAFETY***

- Secure the control box in a stable and vibration-free location to prevent accidental movement or tipping
- Use only the original cables supplied by Addverb and ensure that all connections to and from the control box are securely fastened and free from tension
- Operate the control box within the specified temperature and humidity ranges outlined in the manual to avoid operational failures
- Connect the control box to a surge protector or UPS to prevent damage from voltage spikes or power fluctuations
- Regularly inspect the control box for signs of wear, loose connections, or damage, and address any issues promptly

The control box is equipped with the following panels for efficient interaction and connectivity:

Electrical Component	Description
	<p><b>Front Panel</b></p> <p>Houses LED Indicators and lock to open the Control box</p>
	<p><b>Right-Side Panel:</b></p> <p>Provides fans for cooling the control box</p>



**3.5.3 Control Box LED Indicators**

The control box features **four LEDs** that provide real-time visual feedback about the cobot's operational status.

LED Color	Indication	Description
White	Power Status	Indicates the control box is powered
Red	E-stop/Error	Indicates that the emergency stop (E-stop) is pressed, or the system is in error
Green	Running Status	Indicates the cobot is running, and the system status is healthy
Yellow	Error Acknowledge	Indicates an error that needs to be acknowledged using the Teach Pendant or a connected computer



## Chapter 4: Electrical Requirements

This section details all the required electrical specifications for the Syncro 5 cobot system:

### 4.1 Electrical Warning and Caution



#### **WARNING: ELECTRICAL HAZARDS**

**Failure to follow these instructions may result in serious injury, death, or equipment damage due to electrical hazards:**

- Ensure that all equipment not rated for water exposure remains dry. If water enters the product, immediately lock out and tag out all power sources before contacting Addverb's support team
- Only use the original cables supplied with the Syncro 5 cobot. Substituting cables or using the cobot in applications where cables are frequently flexed can result in damage or failure
- When installing interface cables to the cobot's I/O ports, remove the bottom metal plate for proper cable management. Use appropriate tools and gland sizes. Ensure that all metal shavings or debris from drilling are thoroughly removed before reattaching the plate

### 4.2 Electrical Cables and Connector List

Following lists the electrical component cables and connectors that is used for connecting to the cobot:

#### **Cable Types:**

- **Power Cable:** Connects the Control Box to the mains power supply
- **Ethernet Cable (E1 and E2):** Provides communication between devices and the Control Box
- **Robot Cable:** Establishes the connection between the robot arm and the Control Box
- **E-Stop Cable:** Connects Emergency Stop Buttons for safety

Electrical Component	Description
	<p><b>Cobot cable connector:</b></p> <p>This connector serves as the interface between the robot arm and the control box, facilitating the transfer of data and power required for the robot's operation. It ensures secure and reliable connectivity to maintain seamless performance.</p>
	<p><b>Power cable:</b></p> <p>The power cable delivers electrical energy to the control box and Cobot, ensuring uninterrupted operation. Its robust insulation and secure connections are designed for industrial environments, providing safety and durability.</p>
	<p><b>Ethernet cable:</b></p> <p>This cable enables high-speed communication between the Cobot and external devices, such as PCs or networked systems. It is essential for data transmission, remote monitoring, and control functions. There are two ethernet cable E1 and E2.</p> <p>E1 (Interfacing Device Connection): Connects the interfacing device such as your Personal computer or controller to the cobot.</p> <p>E2 (Control Box to Cobot Connection): Connects the Control Box to the Syncro 5 cobot for data communication.</p>
	<p><b>E-stop Cable Connector (4 Pin):</b></p> <p>The E-stop cable connector integrates the emergency stop functionality into the system. It provides a secure connection to ensure rapid response in emergency scenarios, halting all operations when the E-stop button is activated.</p>

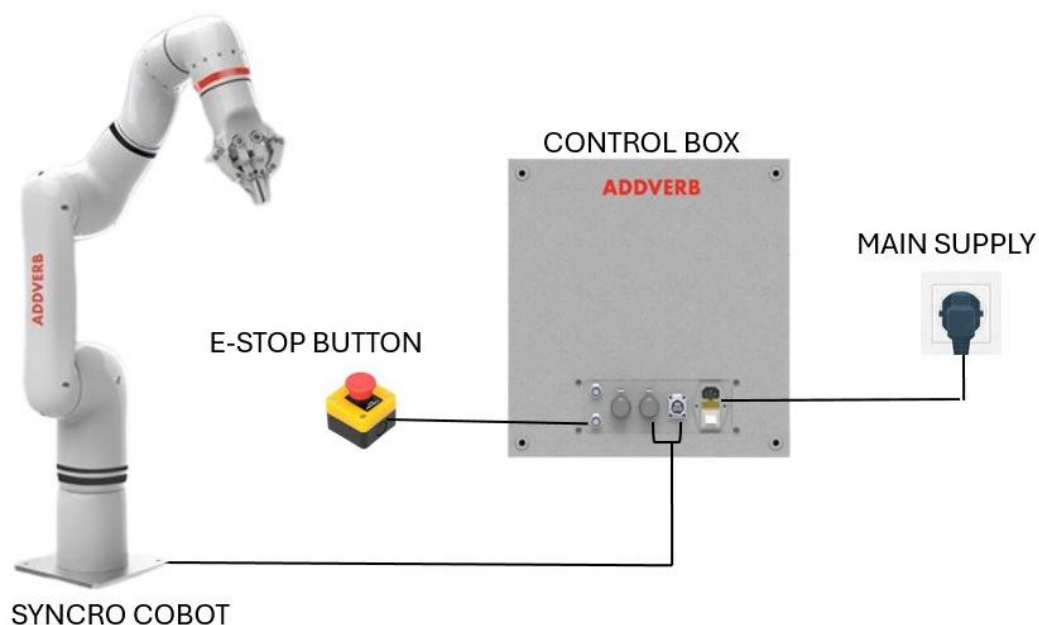
## 4.3 Electrical Specifications

Following are the electrical specifications' requirements for operating the Syncro 5 cobot:

Parameter	Specification
Input Voltage	90-240 VAC
Input Current	16 A/115 VAC, 10A/230 VAC
Frequency	47-63 Hz

## 4.4 Electrical Connection Illustration

Refer to the following illustration to understand the connection of the cobot and its various parts using the cable and connectors mentioned in section Electrical Cables and Connector List.



**Figure 4: Electrical Connection Illustration**

## Chapter 5: Installation of Syncro 5 cobot

This section details the assembly instructions and requirements required to install the Syncro 5 cobot:

### 5.1 Warning and Caution Messages



#### **WARNING: INSTALLATION SAFETY**

- Ensure that the main power supply is completely disconnected before starting the installation. Failure to do so could result in serious injury or death
- Use only approved voltage and frequency ratings as specified in the user guide. Incorrect power configurations may lead to electrical fires or equipment damage
- Always use appropriate lifting tools when handling the cobot during installation. Attempting to lift or move the cobot manually could result in serious injury
- Do not install the cobot in areas prone to water exposure unless it has been rated for such environments. Electrical components can malfunction or cause injury if exposed to water



#### **CAUTION: INSTALLATION SAFETY**

- Route all cables properly to prevent tripping hazards or damage to connections. Avoid placing cables near sharp edges or areas with frequent movement
- Ensure the cobot is mounted on a flat and stable surface. An improperly secured cobot may result in operational errors or damage
- When securing bolts and connections, do not overtighten, as this may damage components or impair alignment
- Install the cobot in a temperature-controlled environment, as extreme temperatures may impact performance and longevity
- Ensure the installation area is free of excessive dust, debris, or contaminants that could interfere with the cobot's operation or compromise its components

## 5.2 Workspace and Operating Space

The **workspace** refers to the total area within which the Syncro 5 cobot can physically operate or perform tasks. This includes the reach of the robotic arm, its range of motion, and the defined boundaries that the cobot should not exceed to ensure safe and efficient operations. The **operating space** is a subset of the workspace, focusing on the area actively used for specific tasks. This is where the cobot interacts with objects, tools, or humans during its operations. The operating space is often customized based on the task requirements and safety protocols.

### 5.2.1 Mechanical Dimension of Syncro 5 cobot

- The workspace of the cobot is a sphere with a radius of **650 mm (2.132 ft)**
- Ensure no obstructions within this range during installation to avoid interference with the cobot's operations

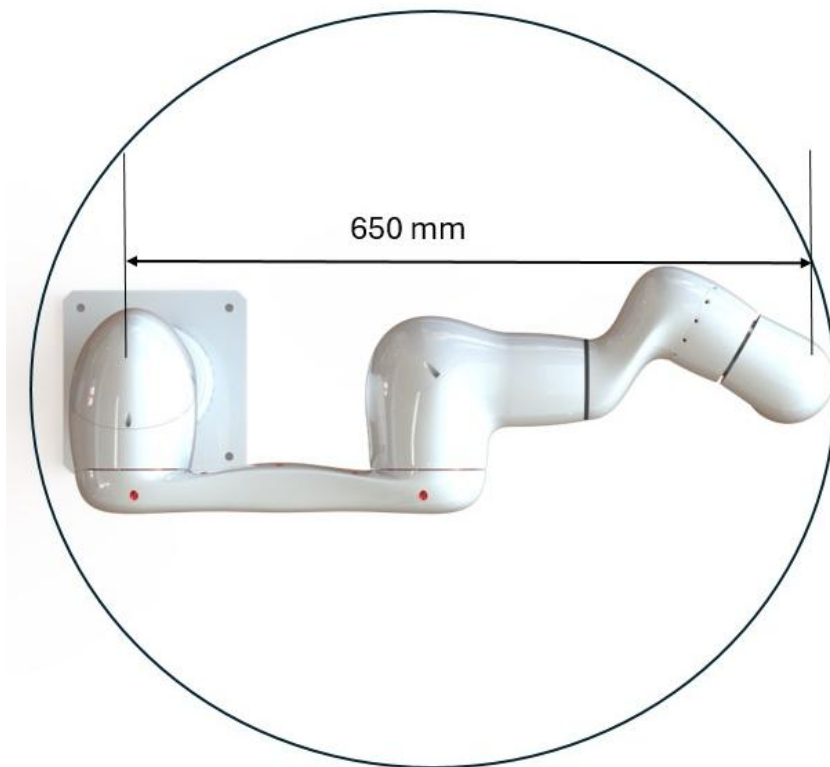


Figure 5: Syncro Cobot Workspace

### 5.2.2 Syncro 5 cobot Mounting Specification

Parts	Description
Syncro 5 cobot	Mounted with four M8 x 75 mm bolts. For improved installation accuracy, it is advisable to use four $\Phi 9$ mm holes for the bolts on the base.
Mounting Tool	Use four M6 thread holes for attaching a tool to the robot. The M6 bolts shall be tightened with 8 Nm, strength class 8.8. For accurate tool repositioning, use a pin in the $\Phi 6$ hole provided.
Control Box	The Control Box can be hung on a wall or placed on the ground. You can buy extra brackets for mounting the Control Box.
Teach Pendant (Optional)	The Teach Pendant handheld and is an optional component.

## 5.3 Securing the Syncro 5 cobot

STEP 1: Place the robot arm on the surface on which it is to be mounted. The surface must be even and clean.



**Figure 6: Place Syncro Cobot on the Surface**

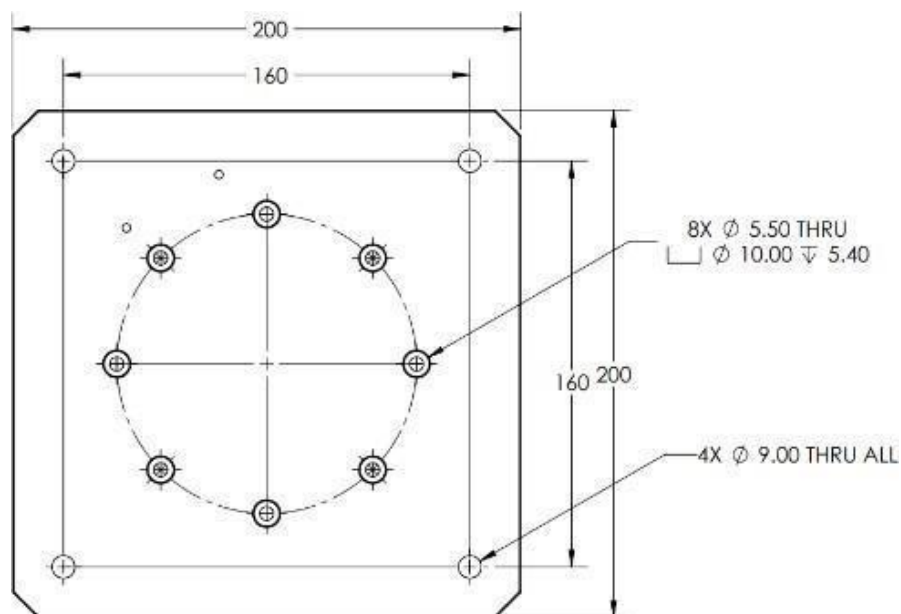
STEP 2: Attach the Syncro 5 cobot to the base using four M8 x 75mm bolts.



**Figure 7: Attach the Syncro Cobot**

STEP 3: For accurate installation, make four 9 mm holes on the base, spaced 160 mm apart from each other as shown in

Figure 8: Mounting Specifications.



**Figure 8: Mounting Specifications**

STEP 4: Tighten the four M8 bolts to a torque of 20 Nm.

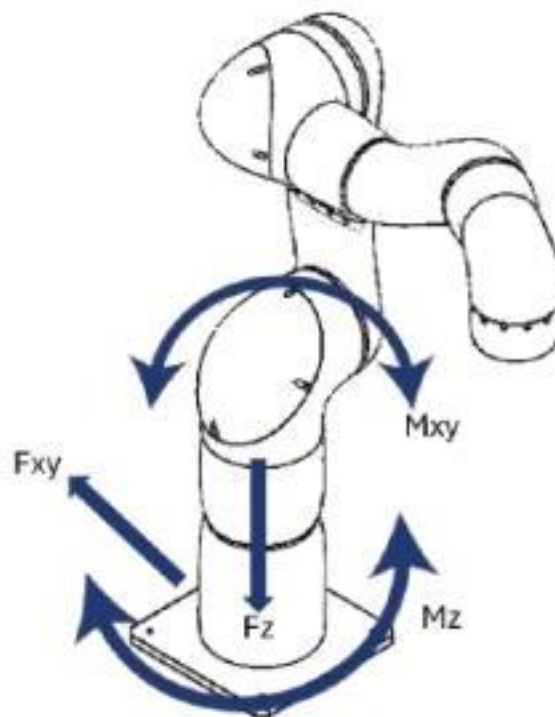
## 5.3.1 Load and Torque Criteria

Use the following section for adhering to the following torque requirements and accounting for both normal and stopping motion loads to ensure a safe and efficient cobot installation. This section explains the direction of the forces and the amount of the force exerted in those directions when the cobot is moving

### Importance of the robot stand

The structure (stand) on which the cobot arm is mounted is a critical component of the installation. It must be robust and free from vibrations caused by external sources to ensure smooth and safe operation. During operation, each robot joint generates torque, which enables movement and stopping of the robot arm. This joint torques transfer loads to the robot stand in the following ways:

- $M_z$ : Torque around the base z-axis
- $F_z$ : Forces along the base z-axis
- $M_{xy}$ : Tilting torque in any direction of the base xy plane
- $F_{xy}$ : Force in any direction within the base xy plane



Robot Model	$M_z$ [Nm]	$F_z$ [Nm]	$M_{xy}$ [Nm]	$F_{xy}$ [Nm]
Syncro	170	300	162	80

Figure 9: Joint torques loads transferred to the robot stand.

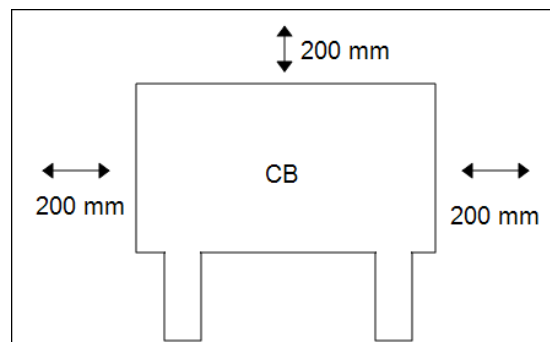


## 5.4 Placing Control Box

Place the control box on a stable surface, ensuring it meets the required clearance guidelines. Inadequate airflow around the control box can cause overheating and lead to equipment malfunction.

To maintain proper cooling:

- Ensure a minimum clearance of 50 mm on each side of the control box.
- For optimal performance, a clearance of 200 mm is recommended.



**Figure 10: Recommended clearance of space around the control box**

## 5.5 Connecting the Syncro 5 cobot to Control Box

To ensure the proper functioning of the Syncro 5 cobot, all electrical connections must be completed according to the guidelines provided. The connection process involves two primary steps: making the connection to the Control Box and establishing the connection to the Syncro 5 cobot.

### 5.5.1 Electrical Safety Requirements



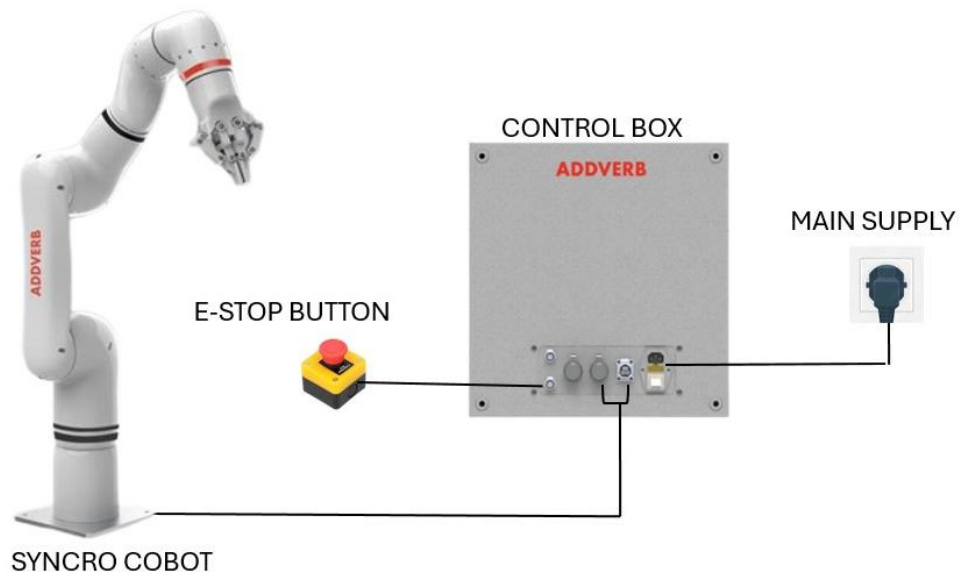
#### **WARNING: ELECTRICAL HAZARDS**

**Failure to follow these instructions may result in serious injury, death, or equipment damage due to electrical hazards:**

- Ensure the robot is grounded correctly (electrical connection to ground). Use the unused bolts associated with grounding symbols inside the Control Box to create common grounding of all equipment in the system. The grounding conductor shall have at least the current rating of the highest current in the system
- Ensure the input power to the Control Box is protected with a Residual Current Device (RCD) and a correct fuse.
- Lockout all power for the complete robot installation during service.
- Ensure other equipment shall not supply power to the robot I/O when the robot is locked out.
- Ensure all cables are connected correctly before the Control Box is powered. Always use the original power cord.


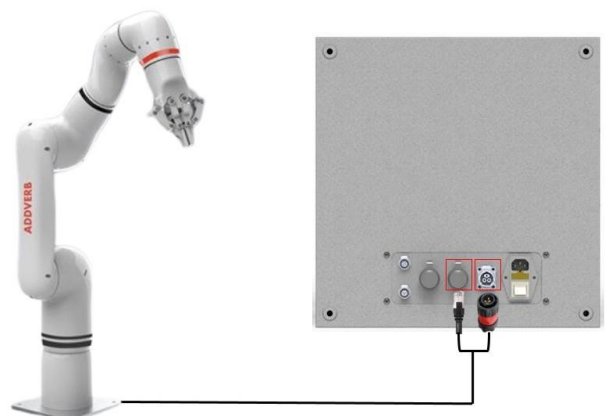
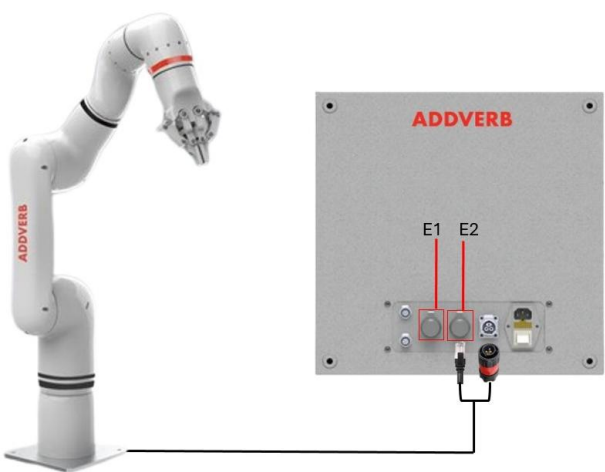
### 5.5.2 Electrical Connection Illustration

Refer to the following illustration to understand the connection of the cobot and its various parts using the cable and connectors mentioned in section Electrical Cables and Connector List.



**Figure 11: Electrical Connection Illustration**

5.5.3 Making the Connection

Steps	Images
<p><b>Power Connection:</b></p> <p>Use the provided power cable to connect the Control Box to the mains supply.</p> <p>Install a 10A Miniature Circuit Breaker (MCB) in the power line for additional safety.</p> <p>Ensure the earthing voltage is less than 2V before powering on the Control Box to avoid electrical issues.</p>	
<p><b>Robot Arm Connection:</b></p> <p>Establish the connection between the robot arm (Syncro 5 cobot) and the Control Box using the cobot power cable:</p> <p>One end of the robot cable connects to the cobot cable connector on the robot arm.</p> <p>The other end connects to the corresponding port at the bottom of the Control Box.</p> <p>Ensure the connection is secure by twisting the connector twice to lock it in place.</p>	
<p><b>Ethernet Connections:</b></p> <p>The Control Box uses two Ethernet ports:</p> <p><b>E1 (Interfacing Device Connection):</b> Connects the interfacing device such as your Personal computer or controller to the cobot.</p> <p><b>E2 (Control Box to Cobot Connection):</b> Connects the Control Box to the Syncro 5 cobot for data communication.</p> <p>Ensure cables are securely inserted into the correct ports. Interchanging Ethernet cables can cause communication failures.</p>	

**Emergency Stop (E-Stop) Connections:**

Connect the Emergency Stop Button to the E-Stop port on the Control Box.

For applications requiring additional safety, connect an additional Emergency Stop Button to the ES2 Port.



## Chapter 6: Getting Started

Use this section to get started with the Syncro 5 cobot once the installation of the cobot is completed:

### 6.1 Powering On/Off the Syncro 5 cobot

#### 6.1.1 Preparation before Power Up

- Check the connection of the cobot and the control box
- Check the connection of the power cable and the control box
- Check and confirm that the power switch of the control box is off when the cobot is unpowered
- Check whether the emergency stop button is released

#### 6.1.2 Powering on the Cobot System

- Connect the Estop connector
- Switch **ON** the AC mains

### 6.2 Connecting Mounting Tool



#### **WARNING: MOUNTING TOOL**

- Always disconnect the power supply to the cobot before installing the mounting tool. Failure to do so may result in unexpected cobot movement, leading to serious injury
- Improperly attached tools may detach during operation, posing a risk of injury or equipment damage. Ensure all connections are tight and secure
- Exceeding the cobot's payload capacity when attaching tools may cause joint failure, leading to operational hazards and potential harm to personnel

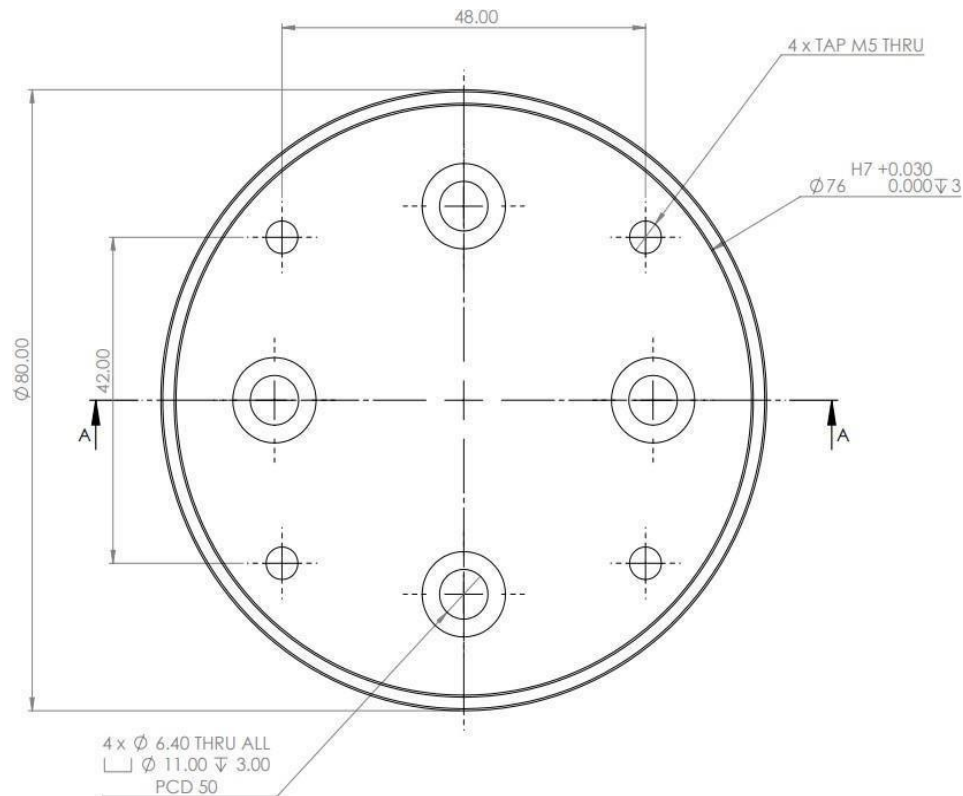


#### **NOTE**

- Failing to update parameters after mounting an external tool will result in a safety system failure

To mount the tool on the Syncro 5 cobot, follow these steps:

- Attach the tool to the tool mounting flange using M6 bolts, as illustrated in *Figure 12: Mounting Tool Illustration*.
- If an external tool is mounted on the cobot's end, update its respective mass and inertia parameters in the software.



**Figure 12: Mounting Tool Illustration**

## Chapter 7: Recommended Storage Conditions

Refer to this section for the recommended storage condition of the Syncro 5 cobot:



### NOTE

- Do not store a robot for more than six months without performing a visual inspection.

### 7.1 Temperature Limits

Proper temperature management is crucial to ensure the cobot's longevity and operational efficiency.

- **Room Temperature:**  
Store the cobot and control box at normal room temperature to avoid component degradation
- **Avoid Extreme Conditions:**  
Do not expose the cobot to extreme heat or cold, as this can cause material damage and malfunctions
- **Moisture Protection:**  
Prevent condensation, excess moisture, and water exposure to safeguard against corrosion and electrical malfunctions

### 7.2 Storage Best Practices

- **Clean Environment:**  
Ensure the cobot is stored in a dust-free, clean area, free from dirt, harmful chemicals, or contaminants
- **Protective Covering:**  
Use cases or covers to shield the cobot from dust and particulate matter when idle
- **Stable Surface:**  
Place the cobot on a stable, vibration-free surface to avoid physical damage during storage



- **Secure Positioning:**  
Position the cobot securely to prevent accidental falls, shifts, or mishandling
- **Disconnect Power:**  
Always disconnect the power supply during storage to prevent unnecessary discharge or electrical damage
- **Accessibility:**  
Store the cobot in a location that allows for easy access for visual inspections and periodic maintenance
- **Manuals and Documentation:**  
Keep technical manuals, maintenance logs, and other relevant documentation nearby for quick reference and compliance
- **Routine Inspections:**  
Conduct periodic inspections to monitor the cobot's condition, checking for any signs of wear, damage, or environmental impact

## Chapter 8: Packing and Transportation

### 8.1 Precaution and Safety Measures

***CAUTION: PACKING AND TRANSPORTATION***

- Incorrect lifting techniques, or using improper lifting equipment, can lead to injury.
- Avoid overloading your back or other body parts when lifting the equipment.
- Use proper lifting equipment.
- All regional and national lifting guidelines shall be followed.
- Make sure to mount the robot according to the instructions in Mechanical Interface.

### 8.2 Transportation Details

**Following material are used for packing:**

1. Wooden box: use original box provided by Addverb
2. Foam
3. Bubble wrap
4. Tape
5. Top EPE Fitment
6. Bottom EPE and EVA Fitment
7. 3D VCI Bag with Flap

### 8.2.1 Transportation Box Specifications

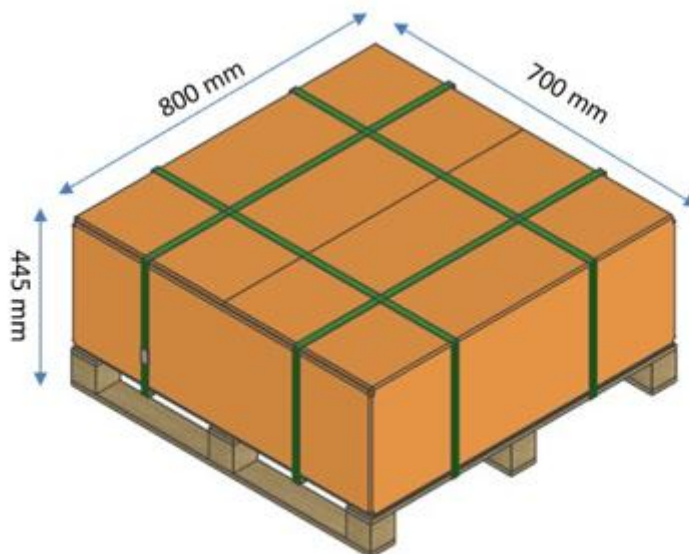


Figure 13: Packing box dimensions

Box Details	
Box OD	(800 X 700 X 445)mm
Gross Weight	45 Kg (Approx.)

### 8.2.2 Preparation for Transport

- Place the **Bottom EPE** and **EVA Fitment** in the cardbox
- Place the Syncro 5 cobot and control box and secure it with **3D VCI Bag with Flap**
- Ensure the cobot is securely packed within the cardboard box with appropriate cushioning materials to prevent movement and protect against impacts
- Place the **Top EPE Fitment** over the robot parts
- Seal the box with strong packing tape, ensuring all openings are secured
- Refer to *Figure 14: Packing Illustraton* to understand the packing details

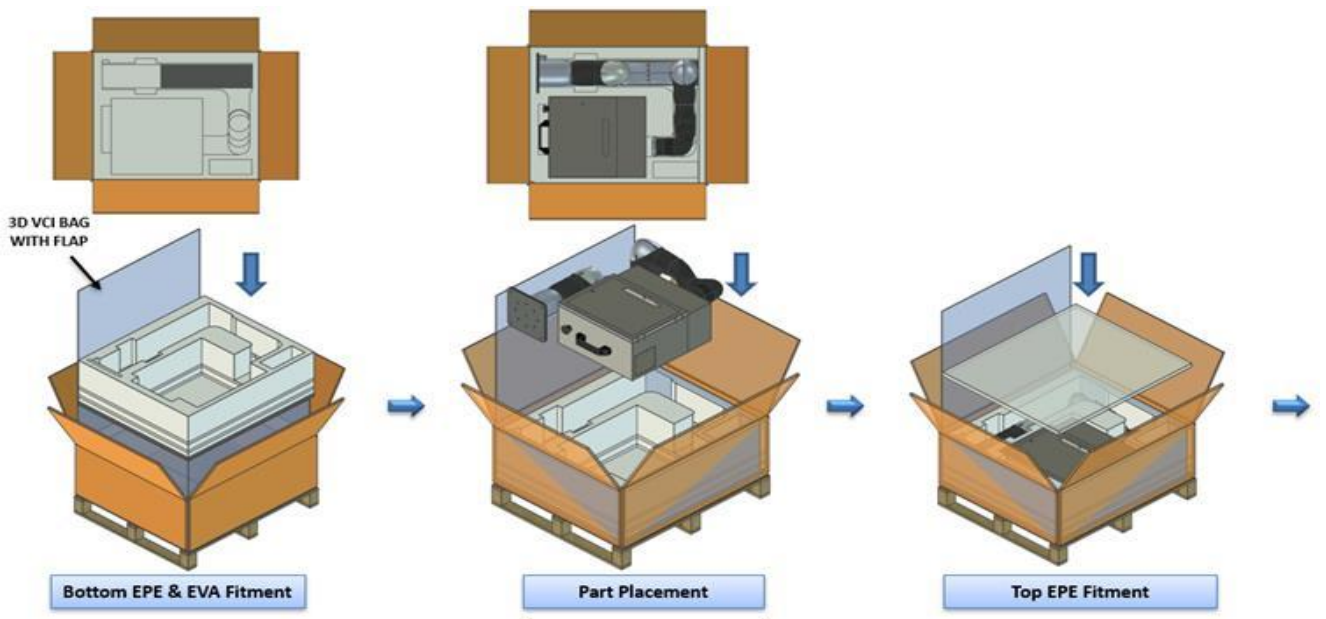


Figure 14: Packing Illustraton

## 8.2.3 Handling Instructions

- **Lift with Care:**  
Due to the weight, two people should lift the box to prevent strain and ensure safety.
- **Avoid Dropping:**  
Handle the package gently to prevent damage to the cobot and its components.

## 8.2.4 Transport Mode

- **Recommendation:**  
Use a pallet jack or forklift for moving the package, if possible, to minimize physical handling.
- **Transport Vehicle:**  
Ensure the vehicle has a flat loading area and can support the weight of the package without risk of damage.

## 8.2.5 Loading and Unloading

- Place the box on a stable surface within the vehicle to avoid tipping or sliding during transit.
- Secure the box using straps or ropes to prevent movement during transport.

## 8.2.6 Environmental Considerations

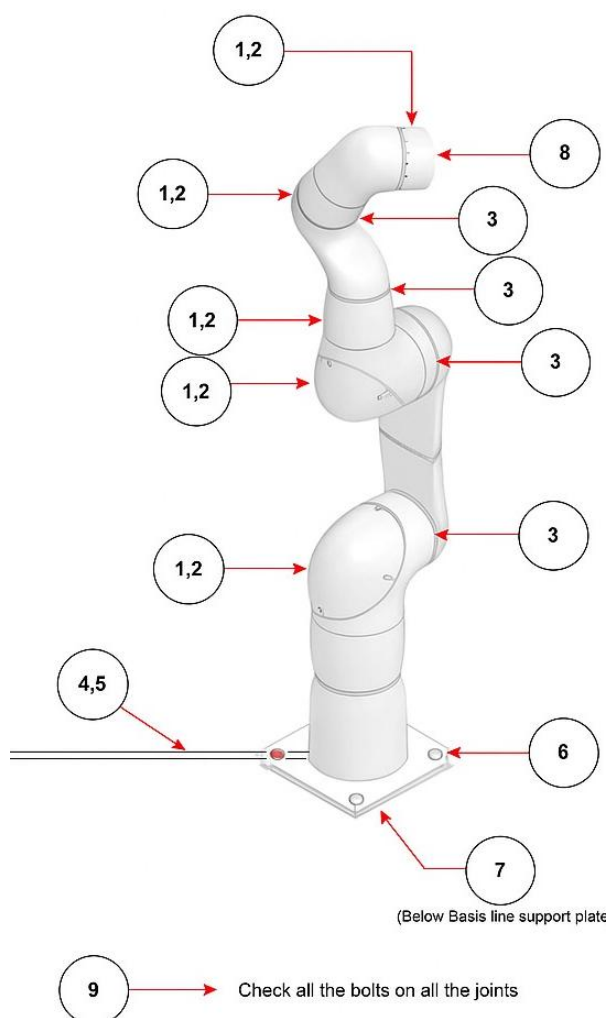
- Protect the package from extreme temperatures, humidity, and moisture during transport.
- Avoid exposure to direct sunlight for extended periods.

## Chapter 9: Robot Cleaning and Inspection

Regular cleaning and inspection are essential to ensure the optimal performance, longevity, and safety of the cobot and its accessories. This section provides guidelines for maintaining a clean cobot environment, including cleaning procedures for the Cobot, Teach Pendant, and Control Box. Proper cleaning practices help prevent issues caused by dirt, dust, or harmful substances, ensuring the robot functions efficiently and safely over time.

### 9.1 Inspection Checklist

This section details a checklist of inspections recommended by Addverb to be performed at the specified intervals. If any of the referenced parts are found to be in an unacceptable condition during inspection, please address the issues immediately to the [Addverb Customer Support](#). Refer to Figure 15: Inspection Points and the Table 1: Inspection Checklist for the details on the inspection parts.



**Figure 15: Inspection Points**

**Table 1: Inspection Checklist**

S.No	Items to Check	Type	Monthly	Semi-Annually	Annually
1	Check link covers <sup>*</sup>	Visual		X	
2	Check the link cover screws	Functional		X	
3	Check the rubber ring	Visual	X		
4	Check Cobot cable	Visual		X	
5	Check Cobot cable connection	Visual		X	
6	Check Cobot mounting bolts <sup>*</sup>	Functional	X		
7	Check Base-link support bolts <sup>*</sup>	Functional	X		
8	Check tool mounting bolts <sup>*</sup>	Functional	X		
9	Check screws/bolts on joints <sup>*</sup>	Functional		X	

(\* Must also be checked after heavy collision)

## 9.2 Visual Inspections

**Perform the following steps during the visual inspection of the cobot to ensure all components are in proper working condition:**

- Move the cobot Syncro to the zero position, if possible
- Turn off and disconnect the power cable from the control box
- Inspect the cable between the control box and cobot for any damage
- Check that the base mounting bolts are properly tightened
- Verify the tool flange bolts are securely fastened
- Inspect the rubber rings for wear or damage and replace them if necessary
- Examine the link covers for cracks or damage and replace them if required
- Ensure the screws used for the link covers are present and properly tightened



### **NOTE**

- Rubber rings are external parts exposed to the operating environment. Addverb recommends replacing all rubber rings when one or more are found worn or damaged
- For new or spare parts, contact [Addverb customer support](#)
- Do not store a robot for more than six months without performing a visual inspection
- If damage is observed on the robot within the warranty period, contact Addverb customer support. Refer to the last page of the user manual for warranty information

## 9.3 Control Box

Perform the following inspections at the specified intervals:

S.no	Items to Check	Type	Monthly	Semi-Annually	Annually
1	Before powering on the control box for the first time, make sure the earthing voltage is less than 2V.	Functional			X
2	Check safety input and outputs (if connected)	Functional	X		
3	Check the cooling fan and clean the filter	Visual	X		
4	Check terminals in control box	Functional		X	
5	Check main power to control box	Functional			X

### Emergency Stop Test:

- Press the Emergency Stop button
- Confirm the robot stops and shuts off power to the joints
- Power on the robot again to resume operations

## 9.4 Robot Cleaning

Proper cleaning practices help prevent issues caused by dirt, dust, or harmful substances, ensuring the robot functions efficiently and safely over time.

### 9.4.1 Cobot Cleaning

**To remove dust, dirt, or oil from the cobot arm:**

- Use a cleaning cloth along with water, isopropyl alcohol, 10% ethanol, or 10% naphtha.
- For robots operating in harsh environments, clean regularly and replace flat rings as needed.
- Do not use bleach or any diluted cleaning solution containing bleach.

### 9.4.2 Control Box and Teach Pendant Cleaning

#### • Teach Pendant:

Use a standard, mild industrial cleaning agent without thinning agents or abrasive materials to clean the screen.

#### • Control Box:

Remove the outer plastic frame and gently clean the filters on both sides with low-pressure air or replace them if dirty or damaged. Do not use compressed air inside the Control Box as it can damage components.



## Chapter 10: Discard and Disposal Instructions

Proper disposal of the cobot and its components is critical to ensuring environmental responsibility, safety, and compliance with local and international waste management regulations. This section provides comprehensive guidelines for safely discarding the cobot, its control box, and associated materials, including electronic components, mechanical parts, and auxiliary agents. Adherence to these instructions will help minimize the environmental impact while maintaining compliance with applicable standards.

By following these discard and disposal instructions, you contribute to sustainable practices that protect the environment and comply with global standards. If you have questions or require additional assistance, contact **Addverb customer support** or consult with a certified waste management provider.

### 10.1 End of Service Life Considerations

**When the cobot has reached the end of its operational life, follow these steps for responsible decommissioning:**

- **Safe Decommissioning:**  
Have a trained technician handle the shutdown and disassembly process. This includes:
  - Powering off all systems safely
  - Disconnecting internal connections between components
  - Dismantling cobot parts as detailed in earlier sections of this guide
- **Proper Documentation:**  
Maintain records of the decommissioning process for compliance and traceability

### 10.2 Disposal of Electronic Components

Electronic components, such as printed circuit boards (PCBs), wires, and actuators, require careful handling due to potential environmental hazards. Follow these guidelines:

- **Classify as E-Waste:**  
Never dispose of electronic parts with general waste. These components should be treated as electronic waste.
- **Contact Certified Facilities:**  
Work with certified e-waste recycling centers to ensure proper disposal.
- **Organizational Policies:**  
Adhere to your organization's specific guidelines for handling and disposing of electronic waste.

## 10.3 Mechanical Parts and Frame

Non-electronic components, such as the cobot's frame, joints, and other mechanical elements, should be evaluated for recycling or safe disposal:

- **Recyclable Materials:**
  - **Metals:** Most metallic parts, including the frame and joints, can be recycled.
  - **Plastics:** Non-contaminated plastics may be processed through municipal waste facilities.
- **Contaminated or Non-Recyclable Materials:**
  - Dispose of contaminated materials at authorized hazardous waste facilities following local guidelines.

## 10.4 Compliance with Local and International Standards

Adhering to disposal regulations ensures responsible waste management. Key standards include:

- **WEEE Directive (Europe):** Governs the disposal of electrical and electronic equipment.
- **EPA Regulations (USA):** Enforces safe handling and disposal of hazardous waste.
- **Other Local Guidelines:** Familiarize yourself with country-specific or regional rules regarding e-waste and hazardous materials.

## 10.5 Material Group Disposal Methods

The following table outlines recommended disposal methods for different material groups associated with the cobot:

Material Group	Disposal Method
Contaminated materials/auxiliary agents	Hazardous waste
Wood	Municipal waste
Plastic	Municipal waste
Lubrication	Disposal in accordance with the safety data sheets
Metal	Scrap metal collection
Electrical material	E-waste
Electronic waste	E-waste

## 10.6 Environmental Condition

Taking an eco-friendly approach during disposal is imperative:

- **Reduce Waste:** Evaluate components for repair or reuse before disposal.
- **Recycle:** Separate recyclable materials like metals and plastics.
- **Minimize Harm:** Avoid dumping hazardous waste in general landfill sites to prevent environmental contamination.

## Chapter 11: Common Issues and Resolutions

Below is a comprehensive guide to address potential issues that may arise during the operation of the cobot and their corresponding resolutions:

This table can help operators and maintenance teams quickly identify and resolve common issues to ensure smooth cobot operation and maximize productivity. For further assistance, please contact **Addverb Customer Support**.

Issue	Description	Resolution
<b>Safety Concerns</b>	Cobots are designed to work alongside humans, but improper setup or lack of proper safety measures can lead to injuries.	Follow all safety protocols  Set speed limits  Regularly inspect the cobot's safety features
<b>Programming Errors</b>	Incorrect programming or configuration by the user can result in inaccurate task performance.	Double-check programming instructions  Use simulation tools, if available, to test the code before executing it on the cobot
<b>Limited Payload Capacity</b>	Cobots often have lower payload capacities than industrial robots, limiting the tasks they can perform.	Assign tasks within the cobot's specified weight limit  Use additional support or different robots for heavier tasks
<b>Communication Failures</b>	Disruptions when interacting with other devices, machines, or systems can affect cobot performance.	Consult with Addverb's support team for proper network configuration
<b>Integration Issues</b>	Integrating cobots with existing systems can be complex.	Use appropriate middleware or integration software  Seek support from Addverb's integrators for complex systems
<b>Limited Workspace</b>	Cobots may have restricted working radii, making it difficult to reach all parts of the workspace.	Deploy multiple cobots  Redesign the workspace for optimal reach
<b>Software Incompatibility</b>	Third-party software might not be compatible with the cobot's control system.	Verify software requirements with Addverb's support team before installation

<b>Overheating</b>	Prolonged operation can lead to overheating of the cobot's actuators.	Provide adequate ventilation or cooling systems  Monitor operational temperature
<b>Unstable Power Supply</b>	Fluctuating power supply can cause malfunctions or damage.	Use a UPS or surge protectors  Regularly check power cables and connections for wear and tear
<b>Limited Speed and Agility</b>	Cobots are slower and less agile than industrial robots, potentially reducing productivity.	Adjust speed settings to match task requirements  Use faster industrial robots for tasks demanding high speed and agility
<b>Human-Robot Interaction Challenges</b>	Unexpected cobot behavior during human interactions can cause confusion.	Train operators on safe collaboration  Implement intuitive interfaces and clear communication protocols
<b>Lack of Flexibility for Complex Tasks</b>	Cobots may struggle with tasks requiring high precision or decision-making.	Simplify complex tasks into manageable steps for the cobot

## Chapter 12: Frequently Asked Questions (FAQs)

This section addresses the most common questions and concerns related to the Syncro 5 cobot, providing concise and clear answers for users. The FAQs cover a wide range of topics, including operation, programming, maintenance, safety features, and troubleshooting. Whether you're new to using the cobot or looking to enhance its functionality, this section serves as a quick reference guide to help you operate and maintain the cobot effectively.

If you have additional questions that are not addressed here, please refer to the relevant sections of this manual or contact Addverb's support team for assistance.

### **Q1: What is the maximum load capacity of this Cobot?**

**A:** The maximum load capacity of this cobot is 5 kg. Refer to *Hardware Specifications* for details.

### **Q2: What kind of sensors does this Cobot use for collision detection?**

**A:** The Syncro 5 cobot does not utilize external sensors for collision detection. It relies on internal encoders and motor currents as reference indicators to identify collisions.

### **Q3: Can this Cobot be programmed through a computer, or does it require a physical teach pendant to operate?**

**A:** Both options are available:

- If a Teach Pendant is purchased, all control modes are accessible via the dedicated interface provided with the pendant.
- Alternatively, users can run various scripts as described in the user manual. In this case, direct control of the cobot (except for the emergency stop) is not possible, and the cobot performs tasks based on the specified script.

### **Q4: What type of power supply is required to operate this Cobot?**

**A:** The required Power supply is:

- Input Voltage: 90-240VAC, (47 – 63) Hz
- Input Current: 16A/115VAC, 10A/230VAC

### **Q5: How does a cobot detect and respond to human presence or contact?**

**A:** The Syncro 5 cobot operates in two modes to respond to contact:

- **Compliant Mode:** If the cobot encounters an object or human, it moves in the direction of the applied force.
- **Rigid Mode:** If contact force exceeds the safety limit (50N  $\approx$  5 Kgs), the cobot stops in a safe state.

## Chapter 13: Warranty Details

Addverb warrants that its products, including the cobot and associated components, are free from defects in design, materials, and workmanship for a period of twelve (12) months from the date of **Provisional Acceptance**. This warranty ensures that Addverb is solely responsible for addressing defects caused by manufacturing faults, design flaws, or material issues, provided the customer adheres to the outlined terms.

### 13.1 Warranty Coverage

The warranty applies to:

- Defects in the cobot or its components caused solely by faults in manufacture, design, or materials
- Issues identified and reported within the warranty period

### 13.2 Customer Obligations

For the warranty to remain valid, the customer must:

- Notify Addverb in writing of any defects promptly, without undue delay
  - Report defects within two (2) weeks of their occurrence
  - Ensure claims are made no later than the twelve (12)-month warranty period
- Failure to comply with these obligations may result in the nullification of the warranty

### 13.3 Exclusives from Warranty

The warranty does not cover the following:

- Failures due to inadequate maintenance
- Issues caused by improper or negligent operation of the cobot
- Batteries supplied with the system, regardless of their criticality
- Failures arising from usage conditions that deviate from Addverb's recommended operational guidelines
- Defects reported beyond two (2) weeks from their occurrence
- Defects resulting from customer-provided suggestions, instructions, or material
- Issues arising from unauthorized modifications or replacement of parts by the customer or a third party
- Defects caused by third-party installations, even if installation was initially within Addverb's scope
- Normal wear and tear or gradual deterioration over time under usual operational conditions

## 13.4 Warranty Claim Process

To initiate a warranty claim:

- **Document the Defect:**  
Provide a detailed description of the issue, including relevant observations and operational history.
- **Notify Addverb:**  
Submit the claim in writing to Addverb within the stipulated two (2)-week period from when the defect is observed.
- **Verification:**  
Allow Addverb representatives to inspect the defective equipment for validation.

### 13.4.1 Limitations of Liability

Addverb's responsibility under this warranty is limited to defects that are solely attributable to its design, materials, or workmanship. Addverb is not liable for defects arising from external factors, negligence, or improper use beyond its control.

### 13.4.2 Additional Notes

- Warranty claims must be supported by compliance with the recommended maintenance schedule and operational guidelines provided in this user guide.
- Customers are encouraged to retain all records of maintenance and operational logs to support warranty claims.
- For further information or assistance, please contact *Addverb Customer Support*.