

view_frames Result

Recorded at time: 317.554

map

Broadcaster: /amcl
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

odom_true

Broadcaster: /odometry_true
Average rate: 20.208
Buffer length: 4.899
Most recent transform: 317.528
Oldest transform: 312.629

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

chassis

Broadcaster: /robot_state_publisher
Average rate: 50.0
Buffer length: 4.96
Most recent transform: 317.552
Oldest transform: 312.592

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

camera

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

hokuyo_link

Broadcaster: /robot_state_publisher
Average rate: 50.0
Buffer length: 4.96
Most recent transform: 317.552
Oldest transform: 312.592

right_wheel