			Supported Devices							Application Credit											
		300	36	0	ş	0	320	oc	0		\$		50		20	5/	150	//	200	/	
T Runtime		х	x		x		x		x												
ST Motion	Motion Control (L_MC1P, L_MC2P)	No	x		x		х										х				
	Coordinated Motion (L_MC4P)	No	No		X		х														
	FAST ApplicationTemplate 2.0	х	x		x		x		х												
FAST schnology nodules		No											v								
	Temperature Control		х		X		Х						х								
	Basic Motion	No	х		X		X				Х										
	Electrical Shaft	No	Х		X		X				X										
	Virtual Master	No	х		X		х				X										
	Traversing Drive	No	х		X		X								X						
	Table Positioning	No	×		х		х						x			H					
	FlexCam	No	х		X		X						X								
	Winder	No	х		X		х								X						
	Register Control	No	х		X		х								X						
	Smart Track	No	x		х		х				Х										
	Magic Track	No	x		X		х						X								
	CrossCutter	No	x		X		х								X						
	Track Pick & Place	No	No		X		х												Х		
	Pick & Place	No	No		x		x								X						
													-		^						
.ST Robot nematics	Portal	No	No		X		X		X			٥									
	Belt Kinematic	No	No		X		Х		х												
	Scara robot	No	No		X		Х								X						
	Delta 2	No	No		X		Х								X						
	Delta 3	No	No		X		Х								X						
	ArticulatedP (Palletizer)	No	No		х		х								X						
	Linear Delta 3	No	No		X		х								X						
dditional	L_CT1P_TorquePreControl	No	х		X		х				X										
	L_CT1P_OscillationComp	No	х		X		X						x								
	L_CT1P_OnlineIdentStiffMechanics	No	x		X		x				X										
	L_CT1P_OnlineIdentStiffMechanicsDo	No	х		х		X				X										
	L_MC4P_GroupTorquePreControl	No	No		x		x						х								
																				123	