		Supported Devices					Application Credit						
		p300	c300	p500	3200 C	c5x0 / c750	0	25	50	100	150	200	300
FAST Runtime		x	x	x	x	x	x						
FAST Motion (Kinematics see below)	Motion Control (L_MC1P, L_MC2P)	No	x	x	x	x						x	
	Coordinated Motion (L_MC4P)	No	No	x	x	x							x
	Robot Kinematics (L_MK4P)	No	No	x	x	x							
	Robot Kinematics Export (L_MK4E)	No	No	No	No	x							
	FAST ApplicationTemplate 2.0	x	x	x	x	x	x						
FAST Technology modules V1 (L_TT1P)	Basic Motion	No	x	x	x	x		x					
	Electrical Shaft	No	x	x	x	x		x					
	Virtual Master	No	x	x	x	x		x					
	Traversing Drive (only available in AKB)	No	x	x	x	x				X			
	Table Positioning	No	x	x	x	x			x				
	FlexCam	No	x	x	x	x			x				
	Winder	No	x	x	x	x				x			
	Register Control	No	x	x	x	x				x			
	Smart Track	No	x	x	x	x		X					
	Magic Track (only available in AKB)	No	x	x	x	x			X				
	CrossCutter	No	x	x	x	x				x			
	FlyingSaw	No	x	x	x	x				x			
	Track Pick & Place (only on request)	No	No	x	x	x						X	
	Pick & Place	No	No	x	x	x				x			
FAST Technology modules V2	Temperature Control (L_TP2P)	No	x	x	x	x			x				
	Basic Motion (L_TB2P)	No	No	No	No	x		x					
	Speed Control (L_TF2P)	No	No	No	No	x		x					
	Virtual Master (L_TF2P)	No	No	No	No	x		x					
	Table Positioning (L_TF2P)	No	No	No	No	x			x				
	Electronic Gearbox (L_TS2P)	No	No	No	No	x			x				
	FlexCam (L_TS2P)	No	No	No	No	x			x				
	CrossCutter (L_TS2P)	No	No	No	No	x				x			
	Sync & Correction (L_TS2P)	No	No	No	No	x				x			
	Winder (L_TW2P)	No	No	No	No	x				x			
FAST Robot Kinematics	Portal (3 and 4 dof)	No	No	x	x	x	x						
	Belt Kinematic (2 dof)	No	No	x	x	x	x						
	Scara robot (3 and 4 dof)	No	No	x	x	x				x			
	Delta2 (2 dof)	No	No	x	x	x				x			
	Delta3 (3 and 4 dof)	No	No	x	x	x				x			
	Linear Delta3 (3 and 4 dof)	No	No	x	x	x				x			
	ArticulatedP (Palletizer; 4 dof)	No	No	x	x	x				x			
Additional	L_CT1P_TorquePreControl	No	x	x	x	x		x					
	L_CT1P_OscillationComp	No	x	x	x	x			x				
	L_CT1P_OnlineIdentStiffMechanics	No	x	x	x	x		x					
	L_CT1P_OnlineIdentStiffMechanicsDouble	No	x	x	x	x		x					
	L_MC4P_GroupTorquePreControl	No	No	x	x	x			x				