# Google JAX

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### Code

### In this lecture series we will code in Python

#### Favorite libraries

- Google JAX
- Google JAX
- Google JAX...

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## **Topics**

- Scientific computing: history and background
- JIT compilation
- Autodiff
- Array operations
- Functional programming

# History: Setting the stage

Before we can understand JAX, we need to know a bit about the history of scientific computing

Let's recall some of the major paradigms and ideas:

- Languages and compilers
- Dynamic and static types
- Background on vectorization / JIT compilers

# Fortran / C — static types and AOT compilers

Example. Suppose we want to compute the sequence

$$k_{t+1} = sk_t^\alpha + (1-\delta)k_t$$

from some given  $k_0$ 

Let's write a function in C that

- 1. implements the loop
- 2. returns the last  $k_t$

```
int main() {
    double k = 0.2;
    double alpha = 0.4;
    double s = 0.3;
    double delta = 0.1;
    int i;
    int n = 1000:
    for (i = 0; i < n; i++) {
        k = s * pow(k, alpha) + (1 - delta) * k;
    printf("k = %f \setminus n", k);
```

First we compile the whole program (ahead-of-time compilation):

Now we execute:

#### Pros

- fast arithmetic
- fast loops

#### Cons

- slow to write
- lack of portability
- hard to debug
- hard to parallelize
- low interactivity

### For comparison, the same operation in Python:

```
\alpha = 0.4
s = 0.3
\delta = 0.1
n = 1_{000}
k = 0.2
for i in range(n-1):
     k = s * k**\alpha + (1 - \delta) * k
print(k)
```

### Python is **interpreted** rather than compiled

- code is executed statement by statement
- data types are queried on the fly
- arithmetic operations require method resolution

#### Pros

- easy to write
- high portability
- immediate feedback high interactivity
- easy to debug

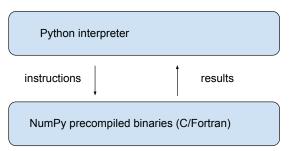
#### Cons

slow

So how can we get

good execution speeds and high productivity / interactivity?

# Python + NumPy



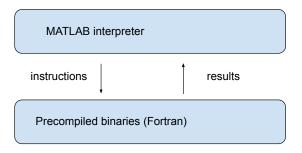
#### import numpy

A = 
$$((2.0, -1.0), (5.0, -0.5))$$
  
b =  $(0.5, 1.0)$   
A, b = np.array(A), np.array(b)  
x = np.inv(A) @ b

- 1. Arrays defined with high-level commands
  - (Python / NumPy API)
- 2. Execution takes place in an efficient low-level environment
  - Efficient machine code (compiled C / Fortran)
- 3. Results are returned to the high-level interface

#### **MATLAB**

NumPy is similar to and borrows from the older MATLAB programming environment



### Advantages of NumPy / MATLAB

- Operations are passed to specialized machine code
- Type-checking is paid per array, not per array element

#### Disadvantages

- Can be highly memory intensive (intermediate arrays)
- Fails to specialize on array shapes
- Limited how would you accelerate the Solow code using NumPy?

## Julia — rise of the JIT compilers

Can do MATLAB / NumPy style vectorized operations

```
A = [2.0 -1.0 \\ 5.0 -0.5]
b = [0.5 1.0]'
x = inv(A) * b
```

But also has fast loops via an efficient JIT compiler

Example. Suppose, again, that we want to compute

$$k_{t+1} = sk_t^\alpha + (1-\delta)k_t$$

from some given  $k_0$ 

Iterative, not easily vectorized

```
function solow(k0, \alpha=0.4, \delta=0.1, n=1 000)
    k = k0
    for i in 1:(n-1)
         k = s * k^{\alpha} + (1 - \delta) * k
    end
    return k
end
solow(0.2) # JIT-compiled at first call
```

Julia accelerates solow at runtime via a JIT compiler

#### Pros:

- fast execution assuming correct type inference
- dynamically typed...(but compiler wants type stability)
- close to the maths

#### Cons:

- Everything compiled might not be optimal
  - debugging is more challenging
  - slow first runs
- Package instability
- Repeated breaking changes

## Python + Numba — same architecture, same speed

```
from numba import jit
@jit(nopython=True)
def solow(k0, \alpha=0.4, \delta=0.1, n=1 000):
    k = k0
    for i in range(n-1):
         k = s * k**\alpha + (1 - \delta) * k
    return k
solow(0.2)
```

Runs at same speed as Julia / C / Fortran

 $\ensuremath{\mathsf{OK}},$  let's talk about the next generation...



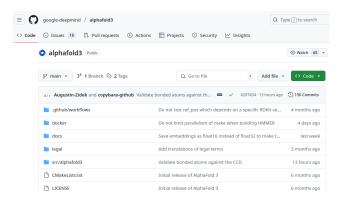
https://jax.readthedocs.io/en/latest/

### A high-performance numerical computing library

- Developed by Google Research (prev. Google Brain)
- NumPy-style API for array operations
- GPU/TPU acceleration
- Automatic differentiation
- Math-centric library semantics
- Rising popularity among ML researchers

"The JAX compiler aims to enable researchers to write Python programs...that are automatically compiled and scaled to leverage accelerators and supercomputers"

#### Example. AlphaFold3 is built with Google JAX



### Highly accurate protein structure prediction with AlphaFold

John Jumper, Richard Evans, Alexander Pritzel, Tim Green, Michael Figurnov, Olaf Ronneberger, Kathryn Tunyasuvunakool,...

Nature Vol. 596 (2021)

- Citation count = 35K
- Nobel Prize in Chemistry 2024

"The acronym JAX stands for Just After eXecution"

• monitor function execution once and then compile

#### Another acronym:

- Just-in-time compilation
- Automatic differentiation
- XLA (accelerated linear algebra)

# Familiar NumPy-style array API

```
import jax.numpy as jnp
A = ((2.0, -1.0),
     (5.0, -0.5))
b = (0.5, 1.0)
A, b = jnp.array(A), jnp.array(b)
x = jnp.inv(A) @ b
```

# Accelerated linear algebra (XLA)

#### Array operations are

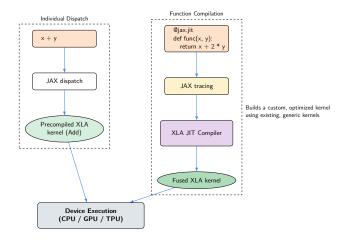
- sent to precompiled XLA device code that takes array shapes as a parameter
- automatically parallelized
- automatically optimized for and deployed to available hardware

## Explicit just-in-time compilation

```
@jax.jit
def f(x):
    term1 = 2 * jnp.sin(3 * x) * jnp.cos(x/2)
    term2 = 0.5 * x**2 * jnp.cos(5*x) / (1 + 0.1 * x**2)
    term3 = 3 * jnp.exp(-0.2 * (x - 4)**2) * jnp.sin(10*x)
    return term1 + term2 + term3
```

- Compiles at first call (e.g., result = f(x))
- Compiler specializes on both shape and data type

#### Precompiled vs compiled in JAX:



#### JIT compiler tools for optimization

- Operations combined into fused kernels for GPU/TPU
- Eliminate intermediate buffers / memory writes and reads
- Loop unrolling
- Specialized algorithms
- Memory layout optimization for multi-dimensional arrays

"JAX's JIT compiler acts like a master engineer"

#### Automatic differentiation

```
import jax.numpy as jnp
from jax import grad, jit
def f(\theta, x):
  for W, b in \theta:
    w = x \otimes W + b
    x = jnp.tanh(w)
  return x
def loss(\theta, x, y):
  return jnp.sum((y - f(\theta, x))**2)
grad loss = jit(grad(loss)) # Now use gradient descent
```

## Features of JAX

Let's review some other features

- Functional programming
- PyTrees

# **Functional Programming**

JAX adopts a functional programming style

Key feature: functions are pure!

- Deterministic: same input  $\implies$  same output
- Have no side effects (don't modify state outside their scope)

Functional programming usually adopts immutable data

#### A non-pure function

```
tax_rate = 0.1
prices = [10.0, 20.0]

def add_tax(prices):
    for i, price in enumerate(prices):
        prices[i] = price * (1 + tax_rate)
        print('Modified prices: ', prices)
```

Why is this not pure?

## A pure function

```
tax_rate = 0.1
prices = [10.0, 20.0]

def add_tax_pure(prices, tax_rate):
    return [price * (1 + tax_rate) for price in prices]
```

## General advantages:

- Helps testing: each function can operate in isolation
- Data dependencies are explicit, which helps with understanding and optimizing complex computations
- Promotes deterministic behavior and hence reproducibility
- Prevents bugs that arise from mutating shared state

## Advantages for JAX:

- Pure functions are easier to differentiate
- Pure functions are easier to parallelize and optimize (don't depend on shared mutable state)
- Transformations can be composed cleanly (predictable results)

# JAX PyTrees

A tree-like data structure built from Python containers

A concept, not a data type

### Examples.

- A list of dictionaries, each dictionary contains parameters
- A dictionary of lists
- A dictionary of lists of dictionaries
- etc.

#### JAX PyTree Structure

```
pytree = {
    "a": [1, 2, 3],
    "b": {"c": jnp.array([4, 5]), "d": jnp.array([[6, 7], [8, 9]])}
                "a"
                                                                 "b"
                                                                       [[6, 7], [8, 9]]
    Container nodes (dict, list, tuple)
   Leaf nodes (arrays, scalars)
```

#### JAX can

- apply functions to all leaves in a PyTree structure
- differentiate functions with respect to the leaves of PyTrees
- etc.

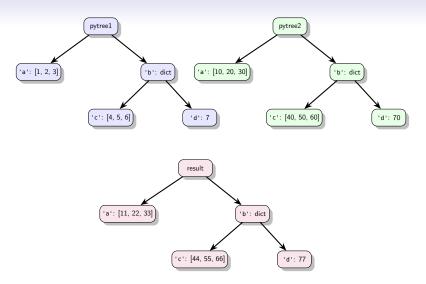


Figure: jax.tree.map(lambda x, y: x + y, pytree1, pytree2)

```
# Apply gradient updates to all parameters
def sgd update(params, grads, learning rate):
    return jax.tree.map(
        lambda p, g: p - learning rate * g,
        params,
        grads
# Calculate gradients (PyTree with same structure as params)
grads = jax.grad(loss fn)(params, inputs, targets)
# Update all parameters at once
updated params = sqd update(params, grads, 0.01)
```

# Summary

## Advantages over NumPy / MATLAB

- Can specialize machine code to data types and shapes!
- Automatically matches tasks with accelerators
- Same code, multiple backends (CPUs, GPUs, TPUs)
- Can fuse array operations for speed and memory efficiency
- Integrated efficient autodiff

Advantages of JAX (vs PyTorch / Tensorflow / etc.) for economists:

- elegant functional programming style close to maths
- elegant autodiff tools
- array operations follow standard NumPy API

Exposes low level functions / fewer off-the-shelf solutions