
Homework 7

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April 24, 2017

1. Sensor Model

Based on the assumption of independent measurements.

$$\begin{aligned} p(\mathbf{z} \mid \mathbf{x}, \mathbf{l}) &= \prod_{k=1}^K p(z_k \mid \mathbf{x}, \mathbf{l}) \\ &= p(z_r \mid \mathbf{x}, \mathbf{l}) p(z_\theta \mid \mathbf{x}, \mathbf{l}) \\ &= \frac{1}{\sigma_r \sqrt{2\pi}} e^{-(z_r - \|\mathbf{x} - \mathbf{l}\|)^2 / 2\sigma_r^2} \cdot \frac{1}{\sigma_\theta \sqrt{2\pi}} e^{-(z_\theta - \theta_x^{\mathbf{l}})^2 / 2\sigma_\theta^2} \end{aligned}$$

In the equation above, $\theta_x^{\mathbf{l}} = \arctan(\mathbf{l}(2) - \mathbf{x}(2), \mathbf{l}(1) - \mathbf{x}(1))$.

2. Bayesian Inference

a)

$$\begin{aligned} p(\mathbf{x} \mid d_0, d_1) &= \frac{p(d_0, d_1 \mid \mathbf{x}) p(\mathbf{x})}{p(d_0, d_1)} \\ &= p(d_0 \mid \mathbf{x}) p(d_1 \mid \mathbf{x}) \frac{p(\mathbf{x})}{p(d_0, d_1)} \\ &= \frac{1}{\sigma_0 \sqrt{2\pi}} e^{-(d_0 - \|\mathbf{x} - \mathbf{x}_0\|)^2 / 2\sigma_0^2} \cdot \frac{1}{\sigma_1 \sqrt{2\pi}} e^{-(d_1 - \|\mathbf{x} - \mathbf{x}_1\|)^2 / 2\sigma_1^2} \cdot \frac{p(\mathbf{x})}{p(d_0, d_1)} \\ p(\mathbf{p}_0 \mid d_0, d_1) &= 0.0979 \frac{p(\mathbf{p}_0)}{p(d_0, d_1)} \\ p(\mathbf{p}_1 \mid d_0, d_1) &= 0.0114 \frac{p(\mathbf{p}_1)}{p(d_0, d_1)} \end{aligned}$$

My friend is more likely to be at university if no further information will be provided.

b)

$$p(\mathbf{p}_0 \mid d_0, d_1) = 0.0294 \frac{1}{p(d_0, d_1)}$$

$$p(\mathbf{p}_1 \mid d_0, d_1) = 0.0080 \frac{1}{p(d_0, d_1)}$$

Given that my friend can only be either at university or home, the total probability is summed to 1.

$$p(\mathbf{p}_0 \mid d_0, d_1) = 0.7861$$

$$p(\mathbf{p}_1 \mid d_0, d_1) = 0.2193$$

3. Motion Model

