

## Summary

(13)

$$\omega^2 \hat{V} + 2i\omega \left( V_0 \frac{\partial \hat{V}}{\partial z} + \hat{V} \frac{\partial V_0}{\partial z} \right) + \frac{\partial^2 \hat{V}}{\partial z^2} (1 - V_0^2) + P \frac{\partial \hat{V}}{\partial z} + Q \hat{V} = 0$$

$$P = -V_0' \left( \frac{1}{V_0} + 3V_0 \right) \quad Q = V_0'^2 \left( \frac{1}{V_0^2} - 1 \right) - V_0'' \left( V_0 + \frac{1}{V_0} \right)$$

$$\omega = \omega_r + i\gamma \quad |\hat{V}|^2 = \hat{V} \hat{V}^*$$

Variation forms

$$\begin{aligned} (\omega_r^2 - \gamma^2) \langle |\hat{V}|^2 \rangle - 2\omega_r \langle V_0 \operatorname{Im} \left( \hat{V} \frac{\partial \hat{V}^*}{\partial z} \right) \rangle \\ - \gamma \langle V_0' |\hat{V}|^2 \rangle - \langle (1 - V_0^2) \left| \frac{\partial \hat{V}}{\partial z} \right|^2 \rangle \\ + \langle (Q - P') |\hat{V}|^2 \rangle = 0 \end{aligned}$$

$$\begin{aligned} 2\omega_r \gamma \langle |\hat{V}|^2 \rangle + \omega_r \langle |\hat{V}|^2 V_0'' \rangle \\ + 2\gamma \langle V_0 \operatorname{Im} \left( \hat{V} \frac{\partial \hat{V}^*}{\partial z} \right) \rangle \\ + \langle P \operatorname{Im} \left( \hat{V}^* \frac{\partial \hat{V}}{\partial z} \right) \rangle = 0 \end{aligned}$$

$$\text{Assume} \quad \operatorname{Im} \left( \hat{V} \frac{\partial \hat{V}^*}{\partial z} \right) \rightarrow K |\hat{V}|^2, \quad K \rightarrow 0$$

$$\omega_r \rightarrow 0$$



(14)

$$-\gamma^2 \langle |\hat{V}|^2 \rangle - \gamma \langle v_0' |\hat{V}|^2 \rangle$$

$$+ \langle (Q-P') |\hat{V}|^2 \rangle = 0$$

$$|\hat{V}|^2 \approx \text{const.}$$

$$\boxed{\gamma^2 \approx \langle (Q-P') \rangle}$$

$$Q-P' = 2(v_0'^2 - v_0'')$$

For the instability

$$\langle Q-P' \rangle > 0 \text{ is required}$$

More accurate would be to use a  
test function  $\hat{V} = (z+1)(z-1)$

and

$$\gamma^2 \approx \frac{2 \int_{-1}^1 (v_0'^2 - v_0'') |\hat{V}|^2 dz}{\int_{-1}^1 |\hat{V}|^2 dz.}$$