



SEE
Simulation Exploration Experience



The SEE HLA Starter Kit

An introduction tutorial

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Outline

- Main Objectives and Information
- The “Services” provided by the Kit
- The Starter Kit software Framework (SKF)
- Live Demo: Let’s build a SKF-based Federate from the scratch...



What is the SEE HLA Starter kit ?

The idea of a *SEE Starter Kit* was born in Tampa during the “Review and Analysis” meeting of the 2014 edition of the SEE (Wednesday the 16th of April 2014).



What is the SEE HLA Starter kit ?

The key point: “How to improve the reliability of SEE Federates and thus reduce the problems arising during the final integration and testing phases of the SEE project?”

After Tampa, a working team at DIMES Department (UNICAL) was set up

- └ Alfredo Garro (coordinator)
- Alberto Falcone (main developer)
- Andrea Tundis (developer)

and started working in cooperation with Edwin (Zack) Crues (NASA JSC)

Work started at the end of April 2014

First Beta Version released on the 29th of July 2014

Version 1.0.0 released on the 3rd of November 2014

Version 1.1.0 released on the 14th of January 2015

Current software license: Lesser GNU Public License (LGPL)

Current Code Repository: Google Code - <https://code.google.com/p/see-hla-starterkit/>
and soon reachable from the official SEE 2015 website and repository...



What is the SEE HLA Starter kit ?

The **SEE HLA Starter Kit** aims to ease the development of HLA federates in the context of the **SEE Project** by providing a **software framework (SKF - Starter Kit software Framework)** with related **documentation, user guide and reference examples.**

The SEE HLA Starter Kit allows teams to focus on the specific aspects of their own SEE Federates rather than dealing with the common HLA issues (such as *the management of the simulation time, the connection to the RTI, the information publishing/subscribing*) that are handled by specific SKF classes and services.



What is the SEE HLA Starter kit ?

Expected Results:

- ✓ **Much Faster learning curve**
(especially for new teams/team members);
- ✓ **Reduction of the development time**
(both for *full-fledged* and *Dummy/Tester Federates*);
- ✓ **More compact and much easier to test code;**
- ✓ **Enhancement of the SEE-oriented capabilities of the Federates;**
- ✓ **Improvement of the reliability of the SEE Federates;**
- ✓ **Write once run anywhere**
(on *PITCH*, *VT MÄK*, *PoRTIco*, *CERTI*, ...).



What does the SEE HLA Starter Kit provide?

The SEE HLA Starter Kit provides the team with the following main components:

- 1) A Java software framework (called SKF) for developing SEE Federates;
- 2) The Javadoc documentation of the SKF;
- 3) A set of reference examples of SEE Federates created by using the SKF (including *Dummy* and *Tester* Federates);
- 4) A technical report that describes the SEE HLA Starter Kit and guides the teams in its effective exploitation.

All the materials listed above can be downloaded by the current website of the SEE HLA Starter Kit:

<https://code.google.com/p/see-hla-starterkit/>

...soon reachable from the official SEE 2015 Project website.



What does a SEE team need to use the SEE HLA Starter Kit ?

To use the **SEE HLA Starter Kit** a team needs:

- ✓ **a HLA RTI** (e.g. *PITCH*, *VT MÄK*);
- ✓ **a JDK** (*version 1.7 or higher*);
- ✓ **a Java Integrated Development Environment** (e.g. *Eclipse IDE for Java Developers*, *NetBeans*);
- ✓ **the core SEE components/resources** (*Environment Federate*, *Space FOM*, etc.).

Note: *The SKF has been developed according to the concept of Object HLA, thus the development of the Federates could benefit also from the Object HLA features and functionalities provided by the Pitch Developer Studio or similar IDE.*



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Target Main Services

CONNECTION MANAGEMENT services (RTI-Coordination Services):

- management of the connection parameters of the VPN;
- management of the connection of the federates to a SEE Federation execution;
- management of the resign of the federates from a SEE Federation execution;
- ...;

FOM MANAGEMENT services (RTI-Information Services):

- FOM module publication services;
- ...;

INTERACTION MANAGEMENT services (RTI-Information Services):

- publishing services;
- subscribing services;
-;



The SEE HLA Starter Kit

Target Main Services

SIMULATION TIME MANAGEMENT services (RTI-Synchronization Services):

- simulation time handling;
- time standard conversions;
- ...;

COORDINATES FRAME MANAGEMENT services:

- transformations among SEE Coordinate Systems;
- publication and subscription of SEE Reference Frames;
- ...;

OWNERSHIP TRANSFER services:

- ...;

DATA DISTRIBUTION MANAGEMENT services:

- ...;



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Target Main Services

LOGGING services:

- management of SEE-specific logs;
- ...;

TESTING services:

- IP Configuration testing;
- MS Windows Firewall testing ;
- LRC/CRC parameters testing;
- ...;



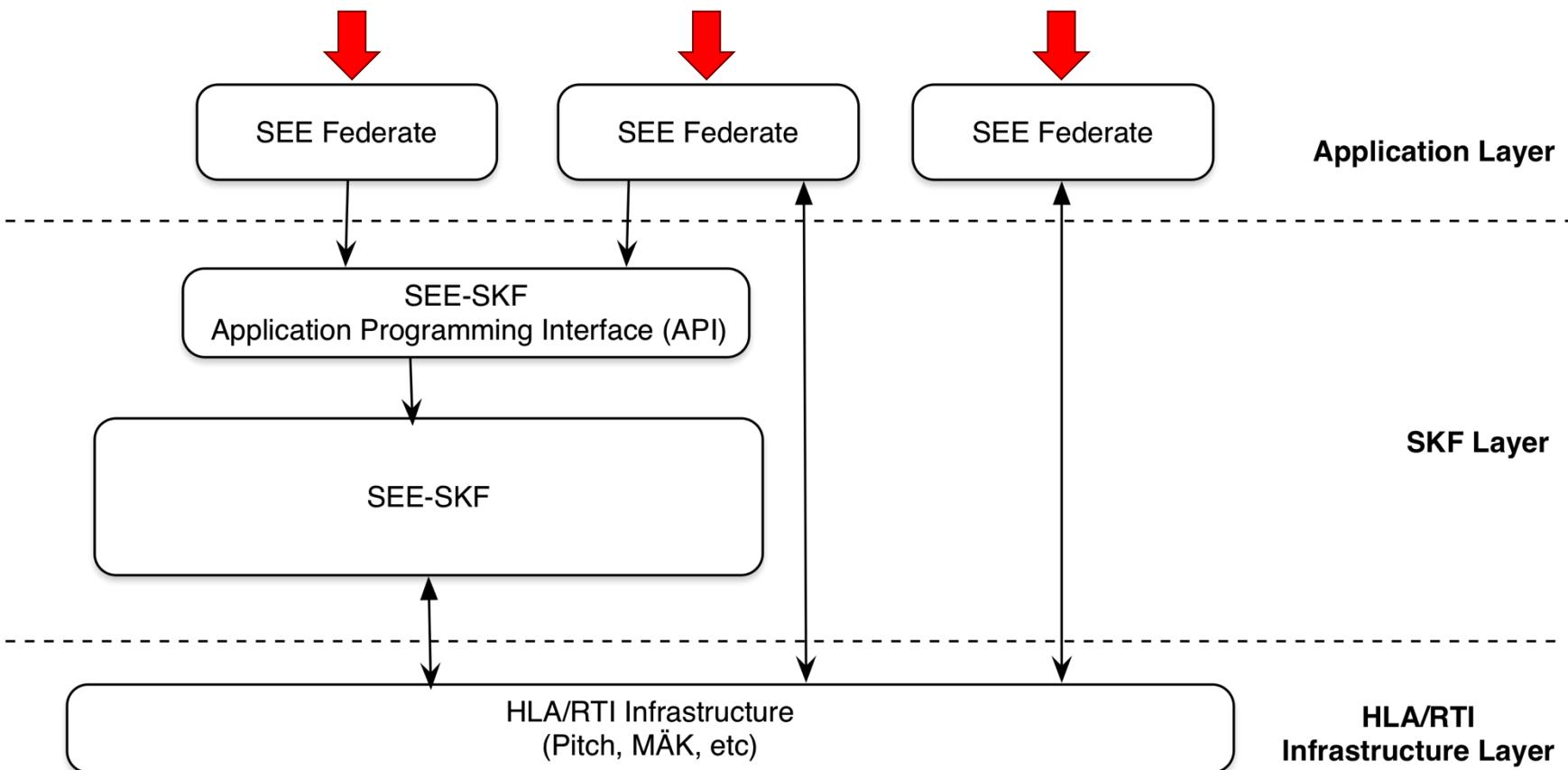
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Features Available (Version 1.1.0)

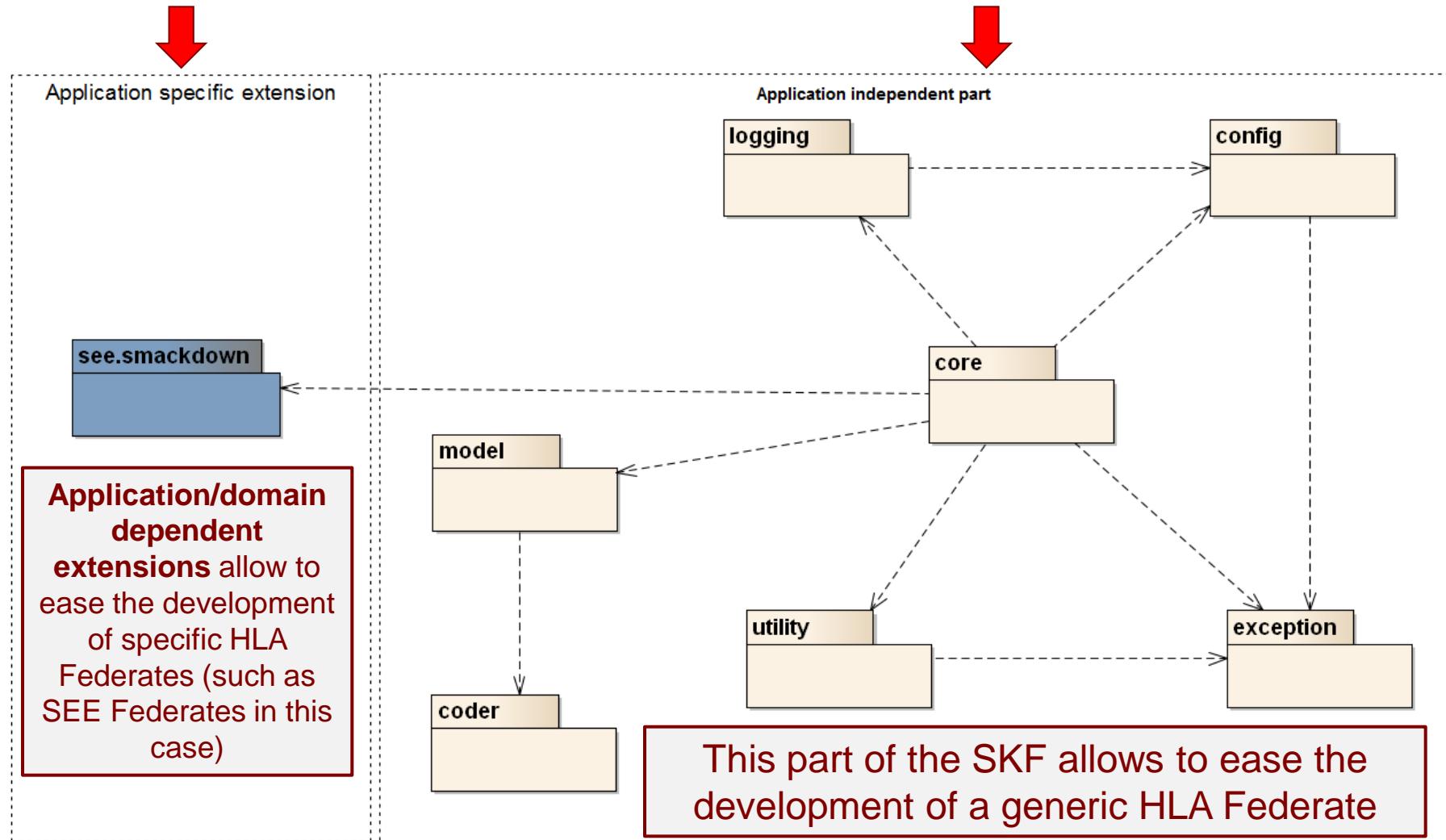
	Feature	Available
	Mechanisms to manage the connection (set-up, hold-up and close-up) of a SEE Federate on the RTI.	<input checked="" type="checkbox"/>
	Mechanisms to facilitate the management and the publication of FOM modules.	<input checked="" type="checkbox"/>
	Mechanisms to facilitate the management of the configuration parameters.	<input checked="" type="checkbox"/>
	Mechanisms to facilitate publishing and updating of information on the RTI.	<input checked="" type="checkbox"/>
	Mechanisms to manage the simulation time.	<input checked="" type="checkbox"/>
	Mechanisms for time standard conversions.	<input checked="" type="checkbox"/>
	Mechanisms to manage the transformations among SEE Coordinate Systems.	<input type="checkbox"/>
	Functionalities for subscribing SEE Reference Frames.	<input checked="" type="checkbox"/>
	Check of the IP Configuration.	<input checked="" type="checkbox"/>
	Check of the MS Windows Firewall state.	<input checked="" type="checkbox"/>
	Logging.	<input checked="" type="checkbox"/>
	Ownership transfer and data distribution management.	<input type="checkbox"/>



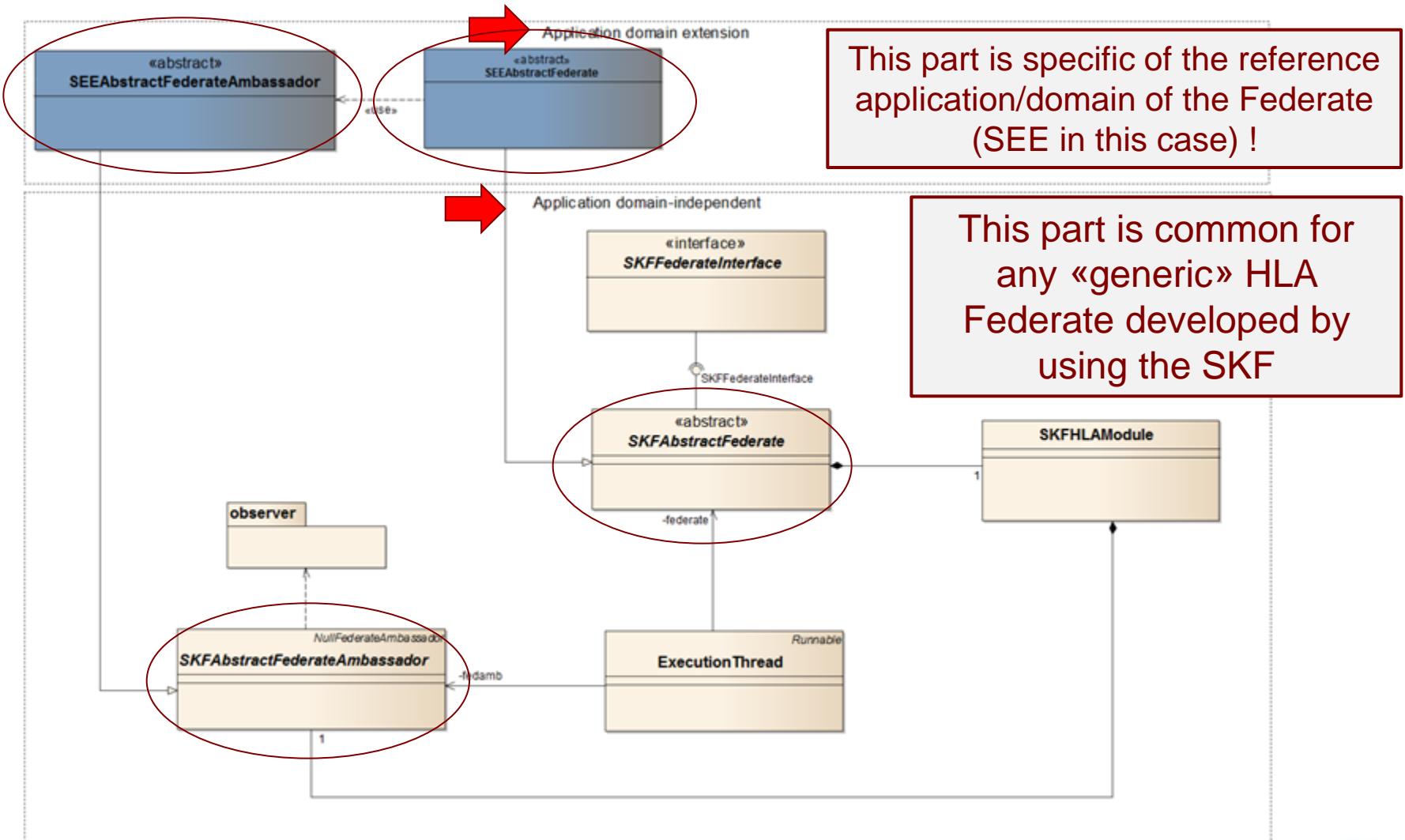
SEE Federations and SKF-based Federates



The Architecture of the SEE HLA Starter Kit software Framework (SKF)



The example architecture of a SEE SKF-based Federate



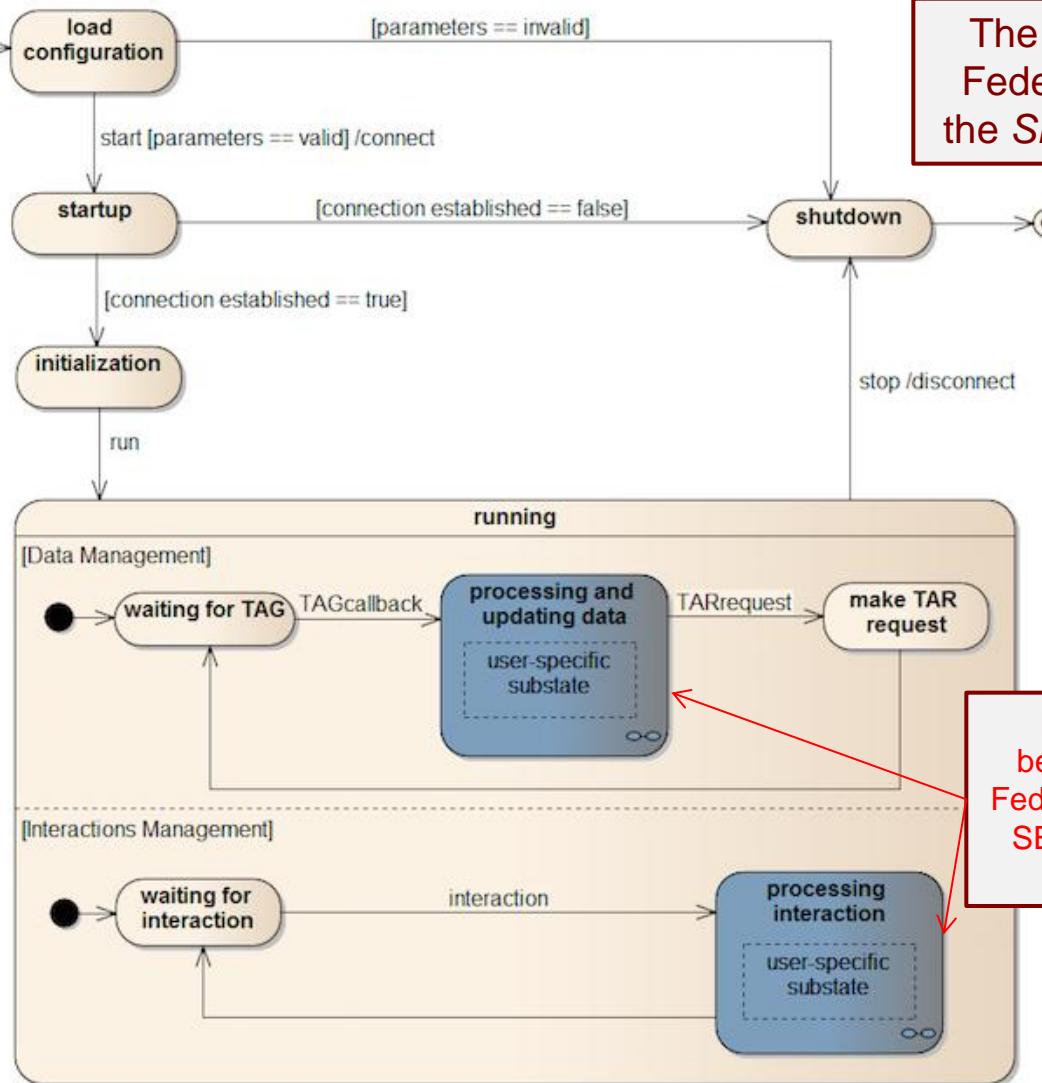
The example life cycle of a SEE SKF-based Federate

Here the SKF loads the configuration parameters from a .json file

Here the SKF checks the connection status

Here the SEE Federate could perform additional operation for exchanging initialization objects before entering the "running" state

The life cycle of a SEE Federate is provided by the *SEEAbstractFederate*



The SEE HLA Starter Kit

LIVE DEMO !!!!!

Let's build from the scratch a dummy *Lunar Rover* moving on the Moon surface!

- The *Lunar Rover* entity inherits from *PhysicalEntity* (see *SISO_SpaceFOM_entity.xml*) and redefines four attributes:

1. ***entity_name***: a non-empty string that identifies the vehicle in the SEE Federation.
2. ***parent_reference_frame***: a non-empty string that identifies the reference frame with respect to which the kinematic state attributes of this vehicle are calculated.
3. ***position***: a 3-vector that specifies the position of the vehicle body frame origin with respect to the parent reference frame.
4. ***entity_type***: a non-empty string that identifies the entity type.



The SEE HLA Starter Kit

LIVE DEMO !!!!!

- During the simulation scenario the position of the ***Lunar Rover*** is updated every simulation step of 10 meters along the x axis so as to reflect its moving on the Moon.
- To develop the ***Lunar Rover*** by using the SKF we need to implement:
 - the ***LunarRover model***, which defines the structure and attributes of the vehicle;
 - a ***Federate***, which defines the life cycle of the ***LunarRover***;
 - a ***FederateAmbassador***, which allows the Federate to interact with the RTI.

LET'S DEVELOP IT !!!



Acknowledgments

- Edwin Z. Crues and the SEE NASA people (Michael Conroy, Dan Dexter, Priscilla Elfrey, Daniel Oneil, Stephen Paglialonga)
- Björn Möller (PITCH Technologies)
- The Alberta and Brunel SEE 2015 teams that are experimenting the SEE HLA Starter Kit
- and... all of you!



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