Note: Linear Regression Model

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## 1 Model Representation

Remind that regression algorithms are tying to infer a function predicting continuous values when given training samples. Let's first focus on the notation of the training samples. Regarding to Table1, training samples are represented by a vector of  $\mathbf{x}$  and a vector of  $\mathbf{y}$  with identical length of m and each sample becomes a pair of  $(x^{(i)}, y^{(i)})$ . The inferred function h(which means hypothesis) is shown as below:

$$h_{\Theta}(x) = \Theta_0 + \Theta_1 x \tag{1}$$

For simplicity, formula(1) consists of only one variable, thus we call this linear regression as univariate linear regression.

## 2 Cost Function

 $\Theta_0$  and  $\Theta_1$  are the two arguments of hypothesis function, so the idea here is to choose optimal values of  $\Theta_0$  and  $\Theta_1$ . Intuitively, the optimal h should minimize average the error distance between the predict values of each  $x^{(i)}$  and  $y^{(i)}$ . Then we can define the cost function as below:

$$J(\Theta_0, \Theta_1) = \frac{1}{2m} \sum_{1}^{m} (h_{\Theta}(x^{(i)}) - y^{(i)})^2$$
 (2)

Obviously, the object function is defined as:

$$\underset{\Theta_0,\Theta_1}{minimize} \frac{1}{2m} \sum_{1}^{m} (h_{\Theta}(x^{(i)}) - y^{(i)})^2$$
 (3)

Using the cost function, we can easily calculate the cost value of any hypothesis functions. For example, Figure 1 shows three samples (cross pointers) and a hypothesis function h(x) = 0.5x. The cost value of it is calculated as:

$$J(0.5) = \frac{1}{2 \times 3} [(0.5 - 1)^2 + (1 - 2)^2 + (1.5 - 3)^2] = \frac{3.5}{6}$$
 (4)

## 3 Gradient Descent

Now we turn to the calculation methods of the objection function. Suppose we have a training set as shown in Figure 3. We can enumerate all the possible values of  $\Theta_0$  and  $\Theta_1$  and calculate the corresponding cost  $J(\Theta_0, \Theta_1)$  and show them in a 3D space like Figure 2. In Figure 2, if we start from a random pointer  $(\Theta_0, \Theta_1, J(\Theta_0, \Theta_1))$ , we can iteratively migrate a small step through the negative direction of the gradient direction of this point and hopefully, we will converge to the lowest point of the surface.