

FU ZHENGYU

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EDUCATION

The Hong Kong University of Science and Technology

Sep. 2018 – present

BSc in Integrative Systems and Design & Computer Engineering

- Current CGA: 3.86
- Awards & Scholarships: Dean's List, University's Scholarship of Continuing Undergraduate Students, HKSAR Government Scholarship Fund - Talent Development Scholarship
- Relevant Courses: Introduction to Aerial Robots, Modern Robotics, Control System Design, Optimal Control, Fundamentals of Computer Vision, System Thinking and Design

PUBLICATIONS

Motion Planning for Mobile Robots with Uncertainty: A Model Predictive Control Approach

Jiawei Tang*, Yik Ben Wong*, **Zhengyu Fu***, Nachuan Yang, Sil Kwong Tse, Winnie Suk Wai Leung, Ling Shi.

Submitted to IROS2021

WORK EXPERIENCES & PROJECTS

Robotic Manipulation, Hong Kong Centre for Logistics Robotics

Jan. 2020 – Feb. 2022

Software engineer (Internship)

- Implement ros2_control-compatible hardware interface for NACHI MZ25 manipulator in ROS2 Foxy

Multi-agent System Control, Department of ECE, HKUST

Jun. 2020 – present

Undergraduate research assistant

- Implement MPC-iLQR controller for differential wheeled robot
- Implement graph-based formation controllers in ROS Melodic
- Set up the simulation environment in Gazebo

IMU-based Motion Capture System, HKUST

Mar. 2020 – Jun. 2020

Software engineer

- Deploy the complementary filter to fuse data from accelerometers and gyroscopes
- Map the captured motion to a humanoid skeleton in Unity in real-time
- The demonstration can be viewed on https://youtu.be/I017_Ufs-Fg

Online Course System, Division of ISD, HKUST

Jan. 2019 – Oct. 2019

Full-stack developer

- Design and deploy an online course system delivering tutorial videos and customized assignments to students.
- Develop a grading system for instructors to comment and grade each submission of students
- The project is currently hosted on <http://mooc.isd.ust.hk/>

RoboMaster Competition, ENTERPEIZE, HKUST Robotics team

Oct. 2018 – Sep. 2019

Software engineer

- In charge of designing and implementing a quaternion-based orientation controller for a 2-axis stabilizer
- Implement a forward kinematics solver and motor controllers of the Mecanum mobile platform
- Develop and maintain the software of Infantry robots

ACTIVITIES & LEADERSHIP

Engineering Student Ambassador (ESA), HKUST

May. 2020 – present

Student Ambassador

- Work as a student representative of the Faculty of Engineering
- Introduce engineering through interacting with prospective students, parents, scholars and the general public

Design Thinking for Urban Challenges, Asian Universities Alliance

Jan. 2020 – Jan. 2020

Participant

- An AUA Overseas Study Program hosted by Seoul National University(SNU)
- The program was aimed to help participants to gain an understanding of the characteristics of the 4th industrial revolution through introducing newly emerging technology, like VR, AR, AI, big data and digital marketing
- The learning was consolidated by numerous site visits such as Samsung D'light and SKT

TEACHING EXPERIENCE

Mechatronic Systems Design with Embedded Computing, HKUST

Feb. 2021 – present

Teaching Assistant

- Design lab manuals and programming exercise to familiarise students with Arm® based microcontrollers
- In charge of leading laboratory sessions

AWARDS & CERTIFICATIONS

- Modern Robotics: Mechanics, Planning, and Control, Northwestern University Robot Kinematics certificate
- 2019 RoboMaster International qualification tournament, RoboMaster 1st Prize
- “Cyber Defenders Challenge – Team Up for the Good Fight”, China Everbright Bank & HKUST 1st Prize
- 2016 RoboCup Junior Rescue Line International Competition in Leipzig, Germany 1st Prize

SKILLS

Programming

(Well-experienced in)C++, Python, MATLAB, ROS;**(Capable of)**Julia, JavaScript

Mechanical

CAD software(Rhino, Solidworks), Physical prototyping(CNC, Laser cutter, water jet)