

Quantum Computing Assignment 11 - Group 18

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Exercise 11.1

(Fidelity of the Amplitude Damping Channel)

(a) The Operator-Sum representation of Amplitude Damping is given by

$$\varepsilon_{AD}(\rho) = E_0 \rho E_0^\dagger + E_1 \rho E_1^\dagger$$

$$F(|\psi\rangle, \varepsilon_{AD}(|\psi\rangle\langle\psi|)) = \text{tr} \left(\sqrt{\langle\psi| \sum_k E_k |\psi\rangle\langle\psi| E_k^\dagger |\psi\rangle} \right)$$

Consider $|\psi\rangle = (\alpha \ \beta)^T$, where $E_0 = \begin{pmatrix} 1 & 0 \\ 0 & \sqrt{1-\gamma} \end{pmatrix}$ & $E_1 = \begin{pmatrix} 0 & \sqrt{\gamma} \\ 0 & 0 \end{pmatrix}$

$$\Rightarrow F(|\psi\rangle, \varepsilon_{AD}(|\psi\rangle\langle\psi|)) = \text{tr} \left(\sqrt{\underbrace{\langle\psi| E_0 |\psi\rangle\langle\psi| E_0^\dagger |\psi\rangle}_A + \underbrace{\langle\psi| E_1 |\psi\rangle\langle\psi| E_1^\dagger |\psi\rangle}_B} \right)$$

$$\Rightarrow A = (\alpha \ \beta) \begin{pmatrix} 1 & 0 \\ 0 & \sqrt{1-\gamma} \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = (\alpha \ \beta \sqrt{1-\gamma}) \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = (\alpha^2 + \beta^2 \sqrt{1-\gamma})$$

$$\Rightarrow B = (\alpha \ \beta) \begin{pmatrix} 1 & 0 \\ 0 & \sqrt{1-\gamma} \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = (\alpha \ \beta \sqrt{1-\gamma}) \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = (\alpha^2 + \beta^2 \sqrt{1-\gamma})$$

$$\Rightarrow C = (\alpha \ \beta) \begin{pmatrix} 0 & \sqrt{\gamma} \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \alpha\beta\sqrt{\gamma} \quad \& \quad D = (\alpha \ \beta) \begin{pmatrix} 0 & 0 \\ \sqrt{\gamma} & 0 \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \alpha\beta\sqrt{\gamma}$$

Since $A = B$ & $C = D$

$$\Rightarrow \text{tr} \left(\sqrt{\langle\psi| E_0 |\psi\rangle\langle\psi| E_0^\dagger |\psi\rangle + \langle\psi| E_1 |\psi\rangle\langle\psi| E_1^\dagger |\psi\rangle} \right) = \text{tr} \left(\sqrt{\sum_k |\langle\psi| E_k |\psi\rangle|^2} \right)$$

Solving $F(|\psi\rangle, \varepsilon_{AD}(|\psi\rangle\langle\psi|))$ using $A, B, C,$ & D

$$\Rightarrow F(|\psi\rangle, \varepsilon_{AD}(|\psi\rangle\langle\psi|)) = \text{tr} \left(\sqrt{(\alpha^2 + \beta^2 \sqrt{1-\gamma})^2 + (\alpha\beta\sqrt{\gamma})^2} \right)$$

$$\Rightarrow F(|\psi\rangle, \varepsilon_{AD}(|\psi\rangle\langle\psi|)) = \text{tr} \left(\sqrt{(\alpha^2 + \beta^2)^2 - \beta^2((\alpha^2 + \beta^2)\gamma)} \right)$$

Consider $|\alpha|^2 = \cos^2(\frac{\theta}{2})$ & $|\beta|^2 = \sin^2(\frac{\theta}{2})$

$$\Rightarrow F(|\psi\rangle, \varepsilon_{AD}(|\psi\rangle\langle\psi|)) = \text{tr} \left(\sqrt{1 - \sin^2(\frac{\theta}{2})\gamma} \right)$$

To minimize $F(|\psi\rangle, \varepsilon_{AD}(|\psi\rangle\langle\psi|))$, $\sin^2(\frac{\theta}{2})\gamma$ should take the maximum value

$$\Rightarrow F_{\min}(|\psi\rangle, \varepsilon_{AD}(|\psi\rangle\langle\psi|)) = \text{tr}(\sqrt{1-\gamma}) = \sqrt{1-\gamma} \quad (\because \sin^2(\frac{\theta}{2}) = 1, \theta = n\pi \ \forall \ n \in \mathbb{Z} - \{0\})$$

Exercise 11.2

(Pauli Group & Check Matrix)

(a) Let us verify for 3 cases

$$\begin{aligned}\alpha = 1, \beta = 2 \\ \sigma_1 \sigma_2 &= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} \\ \sigma_2 \sigma_1 &= \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} -i & 0 \\ 0 & i \end{pmatrix} = -\sigma_1 \sigma_2\end{aligned}$$

$$\begin{aligned}\alpha = 1, \beta = 3 \\ \sigma_1 \sigma_3 &= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \\ \sigma_3 \sigma_1 &= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = -\sigma_1 \sigma_3\end{aligned}$$

$$\begin{aligned}\alpha = 2, \beta = 3 \\ \sigma_2 \sigma_3 &= \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} \\ \sigma_3 \sigma_2 &= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} -i & 0 \\ 0 & i \end{pmatrix} = -\sigma_2 \sigma_3\end{aligned}$$

(b)

$$\begin{aligned}g &= X_1, g' = Z_1 \\ [g, g'] &= X_1 \cdot Z_1 \\ [g', g] &= Z_1 \cdot X_1 = -X_1 \cdot Z_1 = \textit{AntiCommute}\end{aligned}$$

$$\begin{aligned}g &= X_1, g' = Z_3 \\ [g, g'] &= (X_1 \otimes I \otimes I) \cdot (I \otimes I \otimes Z_3) = X \otimes I \otimes Z \\ [g', g] &= (I \otimes I \otimes Z_3) \cdot (X_1 \otimes I \otimes I) = X \otimes I \otimes Z = \textit{Commute}\end{aligned}$$

$$\begin{aligned}g &= X_1 X_2 X_3, g' = Y_2 Z_3 \\ [g, g'] &= (X_1 \otimes X_2 \otimes X_3) \cdot (I \otimes Y_2 \otimes Z_3) = X \otimes XY \otimes XZ \\ [g', g] &= (I \otimes Y_2 \otimes Z_3) \cdot (X_1 \otimes X_2 \otimes X_3) = X \otimes YX \otimes ZX = X \otimes -XY \otimes -XZ = X \otimes XY \otimes XZ \\ &= \textit{Commute}\end{aligned}$$

(c)

$$\begin{aligned}g_1 &= X_1 Z_2 Z_3 X_4 \\ g_2 &= X_2 Z_3 Z_4 X_5 \\ g_3 &= X_1 X_3 Z_4 Z_5 \\ g_4 &= Z_1 X_3 X_4 Z_5\end{aligned}$$

$$\text{Check Matrix} = \begin{pmatrix} r(g_1) \\ r(g_2) \\ r(g_3) \\ r(g_4) \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 1 & 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 & 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 1 \end{pmatrix}$$

(d) Given $r(X) = \begin{pmatrix} 1 & 0 \end{pmatrix}$, $r(Y) = \begin{pmatrix} 1 & 1 \end{pmatrix}$, $r(Z) = \begin{pmatrix} 0 & 1 \end{pmatrix}$, & $r(I) = \begin{pmatrix} 0 & 0 \end{pmatrix}$,

1. Consider $g = I$ & $g' = I$

$I \times I = I$ & $I + I = I$ (Following Modulo 2 Addition)

$$\text{Hence } r(I) + r(I) = r(I \times I)$$

2. Consider $g = X$ & $g' = X$

$$X \times X = I \text{ \& } r(X) + r(X) = \begin{pmatrix} 1 & 0 \end{pmatrix} + \begin{pmatrix} 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \end{pmatrix}$$

$$\text{Hence } r(X) + r(X) = r(X \times X)$$

Similarly $Y \times Y = I$ & $Z \times Z = I$

$$\text{Hence } r(Y) + r(Y) = r(Y \times Y) \text{ \& } r(Z) + r(Z) = r(Z \times Z)$$

3. Consider $g = X$ & $g' = Y$

$X \times Y = iZ = Z$ (Absorbing Prefactor Term)

$$r(X) + r(Y) = \begin{pmatrix} 1 & 0 \end{pmatrix} + \begin{pmatrix} 1 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \end{pmatrix} = r(Z)$$

$$\text{Hence } r(X) + r(Y) = r(X \times Y)$$

4. Consider $g = Y$ & $g' = Z$

$Y \times Z = iX = X$ (Absorbing Prefactor Term)

$$r(Y) + r(Z) = \begin{pmatrix} 1 & 1 \end{pmatrix} + \begin{pmatrix} 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \end{pmatrix} = r(X)$$

$$\text{Hence } r(Y) + r(Z) = r(Y \times Z)$$

5. Consider $g = X$ & $g' = Z$

$X \times Z = -iY = Y$ (Absorbing Prefactor Term)

$$r(X) + r(Z) = \begin{pmatrix} 1 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \end{pmatrix} = r(Y)$$

$$\text{Hence } r(X) + r(Z) = r(X \times Z)$$

From the above results we can conclude $r(g) + r(g') = r(gg') \forall g, g' \in G_n$

(e) Case 1: Consider $g = g'$

$$\text{Let } g = g' = I \implies \begin{pmatrix} 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} = 0 \equiv 0 \pmod{2}$$

$$\text{Let } g = g' = X \implies \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 0 \equiv 0 \pmod{2}$$

$$\text{Let } g = g' = Y \implies \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 2 \equiv 0 \pmod{2}$$

$$\text{Let } g = g' = Z \implies \begin{pmatrix} 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 0 \equiv 0 \pmod{2}$$

Case 2: Consider $g \neq g'$

$$\text{Let } g = X \text{ \& } g' = Y \implies \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 1 \equiv 1 \pmod{2}$$

$$\text{Let } g = X \text{ \& } g' = Z \implies \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 1 \equiv 1 \pmod{2}$$

$$\text{Let } g = Y \text{ \& } g' = Z \implies \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 1 \equiv 1 \pmod{2}$$

$$\text{Let } g = Y \text{ \& } g' = X \implies \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 1 \equiv 1 \pmod{2}$$

$$\text{Let } g = Z \text{ \& } g' = X \implies \begin{pmatrix} 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 1 \equiv 1 \pmod{2}$$

$$\text{Let } g = Z \text{ \& } g' = Y \implies \begin{pmatrix} 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 1 \equiv 1 \pmod{2}$$

Verifying results for “Case 2”

$$XY = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}, \text{ while } YX = \begin{pmatrix} -i & 0 \\ 0 & i \end{pmatrix} \implies [X, Y] \neq 0$$

$$XZ = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \text{ while } ZX = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \implies [X, Z] \neq 0$$

$$YZ = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix}, \text{ while } ZY = \begin{pmatrix} 0 & -i \\ -i & 0 \end{pmatrix} \implies [Y, Z] \neq 0$$