

各杆抗拉刚度均为EA, 各杆均视为二力杆.

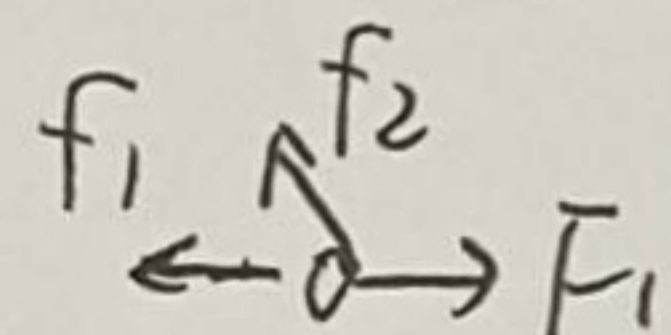
已知 $Af = \bar{F}$, $Bx = \Delta$. 其中, f 为杆内力矩阵, \bar{F} 为结点力矩阵.

x 为结点位移矩阵. Δ 为杆变形矩阵.

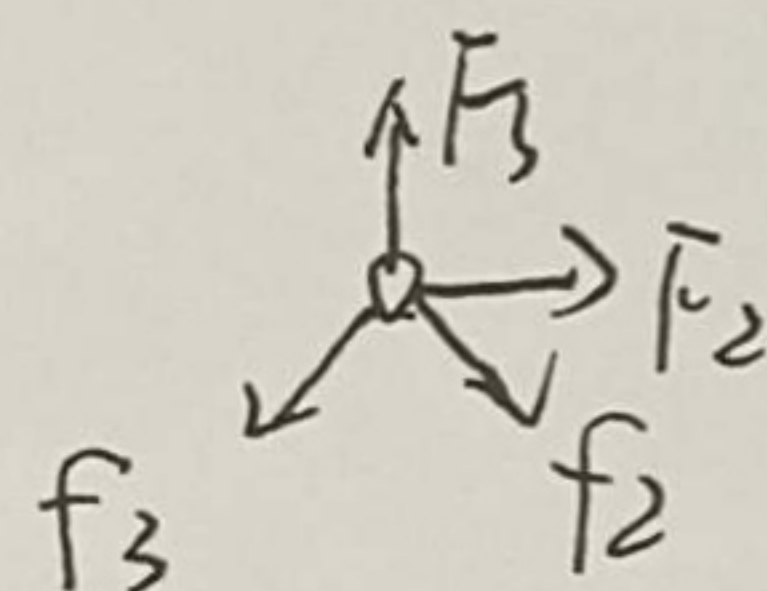
证: $A = B^T$.

证: ① 求 A . 由 $Af = \bar{F}$. 即
$$\begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ A_{31} & A_{32} & A_{33} \end{bmatrix} \begin{pmatrix} f_1 \\ f_2 \\ f_3 \end{pmatrix} = \begin{pmatrix} \bar{F}_1 \\ \bar{F}_2 \\ \bar{F}_3 \end{pmatrix} \Leftrightarrow \begin{cases} A_{11}f_1 + A_{12}f_2 + A_{13}f_3 = \bar{F}_1 \\ \vdots \\ A_{31}f_1 + \dots + A_{33}f_3 = \bar{F}_3 \end{cases}$$

对结点 1. 列平衡方程有: $\sum \bar{F}_x = 0$, $\bar{F}_1 - f_1 - \frac{1}{2}f_2 = 0$



对结点 3 同理有: $\sum \bar{F}_x = 0$, $\bar{F}_2 + \frac{1}{2}f_2 - \frac{\sqrt{3}}{2}f_3 = 0$



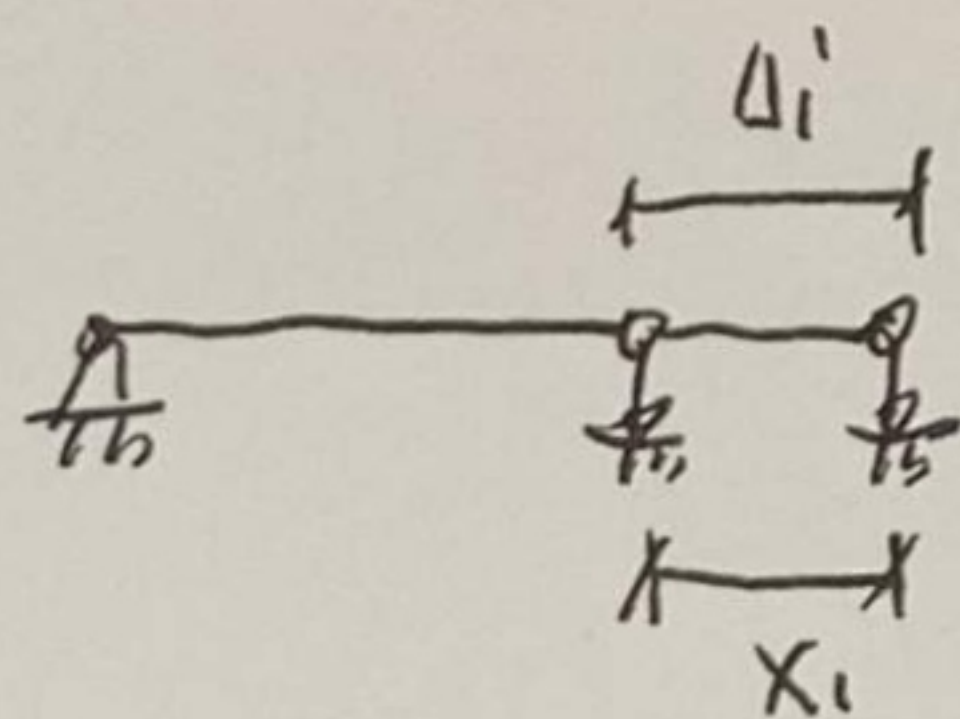
$\sum \bar{F}_y = 0$, $\bar{F}_3 - \frac{\sqrt{3}}{2}f_2 - \frac{\sqrt{3}}{2}f_3 = 0$.

$$\Rightarrow A = \begin{bmatrix} 1 & \frac{1}{2} & 0 \\ 0 & -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ 0 & \frac{\sqrt{3}}{2} & \frac{\sqrt{3}}{2} \end{bmatrix}$$

② 求 B . 由 $Bx = \Delta$. 同理有

$$\begin{cases} B_{11}x_1 + \dots + B_{13}x_3 = \Delta_1 \\ \vdots \\ B_{31}x_1 + \dots + B_{33}x_3 = \Delta_3 \end{cases}$$

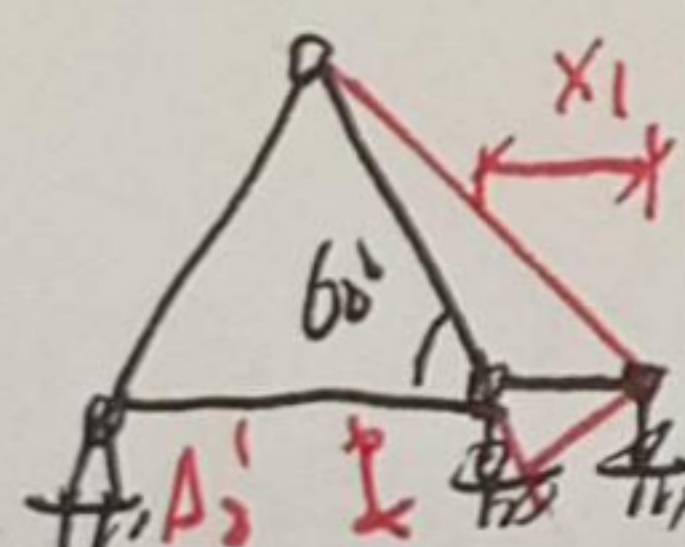
对 Δ_1 :



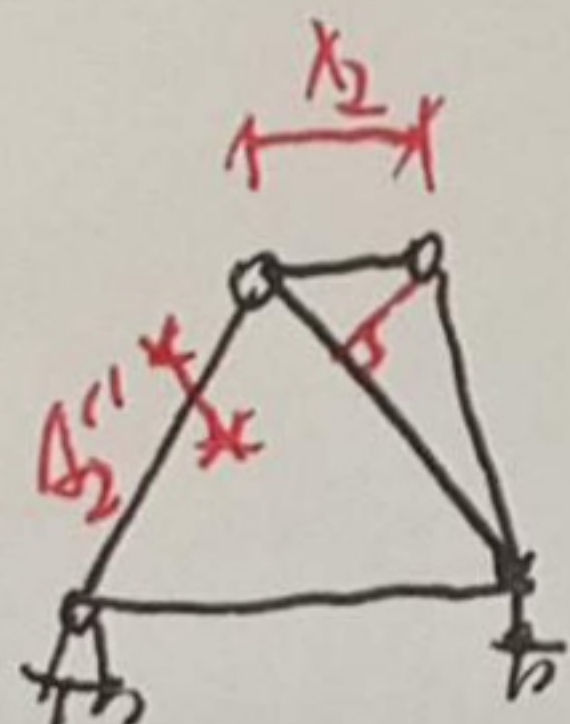
$$\Delta_1 = \Delta_1' = x_1$$

Δ_1

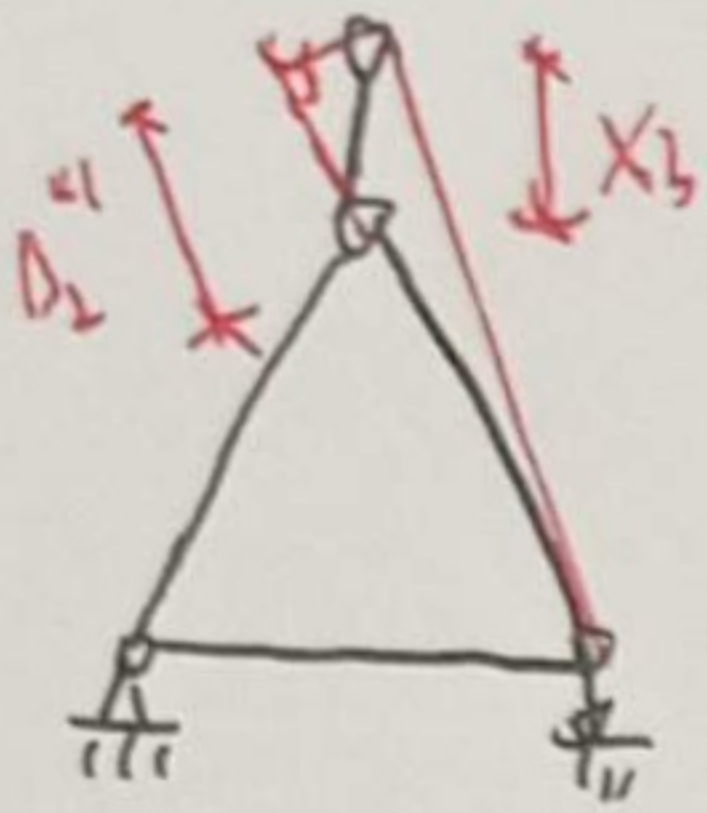
对 Δ_2 :



$$\Delta_2' = \frac{1}{2}x_1$$



$$\Delta_2'' = -\frac{1}{2}x_2$$



$$\Delta_2''' = \frac{\sqrt{3}}{2} X_3 \Rightarrow \Delta_2 = \Delta_2' + \Delta_2'' + \Delta_2''' = \frac{1}{2} X_1 + -\frac{1}{2} X_2 + \frac{\sqrt{3}}{2} X_3$$

同理得 $\Delta_3 = \frac{1}{2} X_2 + \frac{\sqrt{3}}{2} X_3$.

$$\Rightarrow B = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ 0 & \frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix}$$

$$\text{而 } A = \begin{bmatrix} 1 & \frac{1}{2} & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} \\ 0 & \frac{\sqrt{3}}{2} & \frac{\sqrt{3}}{2} \end{bmatrix}$$

$$\Rightarrow A = B^T. \quad \text{证毕!}$$