

3061 - Pit Scouting

Your name(s):

team #:

team name:

Drivetrain type:

Number of motors:

Describe motors:

Shifters?: (y / n)

Top speed(s):

Goal(s) the robot can shoot into:

How far can the robot shoot from?:

Blocker?: (y / n)

Describe blocker:

Type of collector: JVN el-toro horizontal ball clamps on other (describe):

Where do they collect balls from?: ground air from robot air from human

How heavy is the robot?