

Truss Throw Accuracy Sort

Team	Avg. trussThrowScores	trussT1
3936	0.1111	

Alliance

TEAM_NUM	3936
allianceAutoPoints	830
HASH	7,449
allianceFoulPoints	1,090
allianceTeleopPoi..	648
allianceTotalPoints	3,768
endTime	3,074
fumbles	10
Scores-Colored	0
Scores-Goalie	0
Scores-White	0
Shots-Colored	0
Shots-Goalie	0
Shots-White	0
lowGoalScores	6
lowGoalShots	6
numAssists	4
passRecvHuman	1
passRecvRobot	3
passStarts	2
preBallsOnField	54
robotSpeed	46
shotsBlocked	0
startTime	19
trussCatchScores	0
trussCatchShots	0
trussThrowScores	4
trussThrowShots	4
Number of Records	29

Measure Names
highGoalScores
highGoalShots

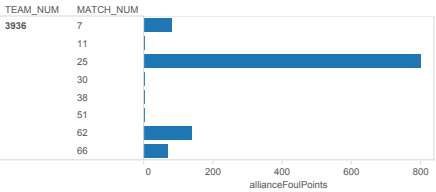
Comments

matchComments	breakDescrip..
Carried the team	Abc
Defense	Abc
It was super slow	Abc
Mainly blocked, did little else	Abc

Preferred Shot Position

Team	Match Number	Maneuve..	Records	Scores-C..	Scores-..	Scores-..	Sh
3936	7	0.000	1.000	0.000	0.000	0.000	0.000
	11	0.000	1.000	0.000	0.000	0.000	0.000
	25	2.000	2.000	0.000	0.000	0.000	0.000
	30	0.000	1.000	0.000	0.000	0.000	0.000
	38	0.000	1.000	0.000	0.000	0.000	0.000
	51	0.000	1.000	0.000	0.000	0.000	0.000
	62	0.000	1.000	0.000	0.000	0.000	0.000
	66	0.000	1.000	0.000	0.000	0.000	0.000

Alliance Foul Points



Alliance Foul Descriptions

TEAM_NUM	MATCH_..	No Measure Value
3936	7	Possibly unintentional damage of other robots outside frame .. perimeter
	11	
	25	
	30	
	38	
	51	
	62	Ball stolen
	66	Touched robot on other side of truss during auto

This team had 1 match out of 1 where they did not shoot any balls in autonomous.

Accuracy

	7	11	25	30	38	51	62	66
	3936	3936	3936	3936	3936	3936	3936	3936
highGoalScores								
highGoalShots								
highGoalScores								
highGoalShots								
highGoalScores								
highGoalShots								
highGoalScores								
highGoalShots								
highGoalScores								
highGoalShots								
highGoalScores								
highGoalShots								

Avg

Team	3936
highGoalAccuracy	
autoAccuracy	
Sum of fumbles	4.00
Scores-Colored	0.00
Scores-Goalie	0.00
Scores-White	0.00
Shots-Colored	0.00
Shots-Goalie	0.00
Shots-White	0.00
lowGoalScores	5.00
lowGoalShots	5.00
passRecvHuman	1.00
passRecvRobot	3.00
passStarts	2.00
robotSpeed	13.00
shotsBlocked	0.00
trussCatchScores	0.00
trussCatchShots	0.00
trussThrowScores	1.00
trussThrowShots	1.00
ManeuveredTF	2.00
Number of Records	9.00
ShotsColoredPropor..	
ShotsGoalieProporti..	
ShotsTotal	0.00
ShotsWhiteProporti..	
assister	3.00
assisterProportion	3.00
ballOneAutoPoints	0.00
ballOneAutoScored	0.00
ballThreeAutoPoints	0.00
ballThreeAutoScored	0.00
ballTwoAutoPoints	0.00
ballTwoAutoScored	0.00
catcher(role)	0.00
catcherProportion	0.00
defense	3.00
defenseInGoalie	0.00
defenseProportion	3.00
defenseStopGetting..	0.00
defenseStopRobot	0.00
highGoalScores	0.00
highGoalShots	0.00
humanTrussThrow	0.00
numBallsAutoScored	0.00
numBallsAutoUsed	0.00
pushedTF	2.00
shooter	0.00
shooterProportion	0.00
soloCycler	0.00
soloCyclerProportion	0.00
soloTrussCatcher	0.00
soloTrussCatcherPr..	0.00
trussThrowAccuracy	1.00

Booleans

Team	3936
humanTrussThrow	0.00
fumbles	3.00
Scores-Colored	0.00
Scores-Goalie	0.00
Scores-White	0.00
Shots-Colored	0.00
Shots-Goalie	0.00
Shots-White	0.00
lowGoalScores	5.00
lowGoalShots	5.00
passRecvHuman	1.00
passRecvRobot	3.00
passStarts	2.00
robotSpeed	13.00
shotsBlocked	0.00
trussCatchScores	0.00
trussCatchShots	0.00
trussThrowScores	1.00
trussThrowShots	1.00
ManeuveredTF	2.00
Number of Records	9.00
ShotsColoredPropor..	
ShotsGoalieProporti..	
ShotsTotal	0.00
ShotsWhiteProporti..	
assister	3.00
assisterProportion	3.00
autoAccuracy	
ballOneAutoPoints	0.00
ballOneAutoScored	0.00
ballOneAutoUsed	0.00
ballThreeAutoPoints	0.00
ballThreeAutoScored	0.00
ballThreeAutoUsed	0.00
ballTwoAutoPoints	0.00
ballTwoAutoScored	0.00
ballTwoAutoUsed	0.00
catcher(role)	0.00
catcherProportion	0.00
defense	3.00
defenseInGoalie	0.00
defenseProportion	3.00
defenseStopGettingBall	0.00
defenseStopRobot	0.00
highGoalAccuracy	
highGoalColoredAccuracy1	
highGoalScores	0.00
highGoalShots	0.00
numBallsAutoScored	0.00
numBallsAutoUsed	0.00
pushedTF	2.00
shooter	0.00
shooterProportion	0.00
soloCycler	0.00
soloCyclerProportion	0.00
soloTrussCatcher	0.00
soloTrussCatcherProportion	0.00
trussThrowAccuracy	1.00

Auto Accuracy

