## BATCH NORMALIZATION

- it is a technique that is used to speed up the train speed of the our round network.

What is Botch Norm?

Batch Mormalization (BH) is an algorithm method.

which roakes the toaining of Deep Heural Network. (DHH) fester and reare stable

it consists of normalizing activation rectors from hidden layers wing the mean and variance of the current batch. This normalisation. step is applied right before (or right often) the non-linear function.

injent here \$1,9 x2 is normalized injent. man 20 , sd21

4

9

-

•

-

8

and also in batch normalization narmalize Ale activation function also 911, me de this for all hidden layer in the neural retworks.

why was Batch Normalization? if input date is if injent data is not normalized. romalized. (ALA) contour plot touring slaw contour plot training is foster as well as faster Covariate shift: MAN a model I model. on frommy data on testing data.

even a the relation between the. Yeard Y are som. in bothe case, retrain the madel. Interval covariate shift: me define internal covariate shift as the change in the distribution of network activations due to change in network parameters during training. X1. - Q Q1, Q Q K2 0 0 here P, and Pr are ture neural network corrected to each other.

11 and 42 are output of neural network P, but Y, and 1/2 are injent for reveral returnt 1/2 But in the newal whole never network. Bockpropagation) in internal areights and blases are continuously change, due to this the internal distributions values (for example Y1 and Y2) continuently change and that's rwell the au neural naturant become instable to hartle this situation in round notwork. we apply Botch normalization. with Botch Normalization TE ensure ARTI & for Ex Layer to end Fi distribution are no normalized means mean = 0 and standard deviation=1 things that we keep in round while using. Batch Normalisation: - it is apply with. Mini-Batch Gradient - it applies layer by layer descent Botch Normalization Works: Igpa ig placed placed 19 ( gpp a 1 100 8.9 0 89 6.2 0 9) 9.1 76 7.7.

otal map tugai

besilon for tuggi

-

0

6

let batch size = 4 Z = 100 W, coppa + W, iq + b here there is two ways to normalized the distributions for each layer. (i)  $Z_{II} \rightarrow Z_{II}^{N} \rightarrow g(Z_{II}^{N}) = \alpha_{II}$  $(ii) Z_{ii} \rightarrow g(z_{ii}) \rightarrow a_{ii} = a_{ii}^{N}$ the first are is mostly used approach Z11 -4 = ZN u- nnean o-standard deviation. mean is calculated for each batch differently  $M_{g} = \frac{1}{m} \sum_{i=1}^{m} Z_{ii}^{i}$   $\sigma_{g} = \frac{1}{m} \sum_{i=1}^{m} (Z_{ii}^{i} - M_{g})$ thus, m = 4the m=4 calculate UB and of for each botch neuron. differently. for every rewar. er ever term  $Z_{ii}^{i} = Z_{ii}^{i} - M_{B}$ then all value come under the range go-1 0B+ E on uzo, 0=1

- Z" - Z"

Shy -> VZN+B here I and B learnable paramameter like was the initial value of. I and B is I and O respectively

Z" -> Z" -> Z" -> d (Z") = 0"

the above restrad is apply for each reusian in reural network. and each neuran has it's am Vand & value

Batch Mormalization Step:

-> Botch Hormolize

- 8 cale and shift (V and B)

- in round network. Botch Noon con be considere as a layer, often each layer.

Y or A B are update also wing gradient

6

each neuron stor four. your 2 is bournable ( (I and B) and 2 is unlocarnable. (M, o)

Advantages. - note training more stable.

- Training becomes faster.

- Batch normalization com act as regularizer - reduce the impact of usight initialization.