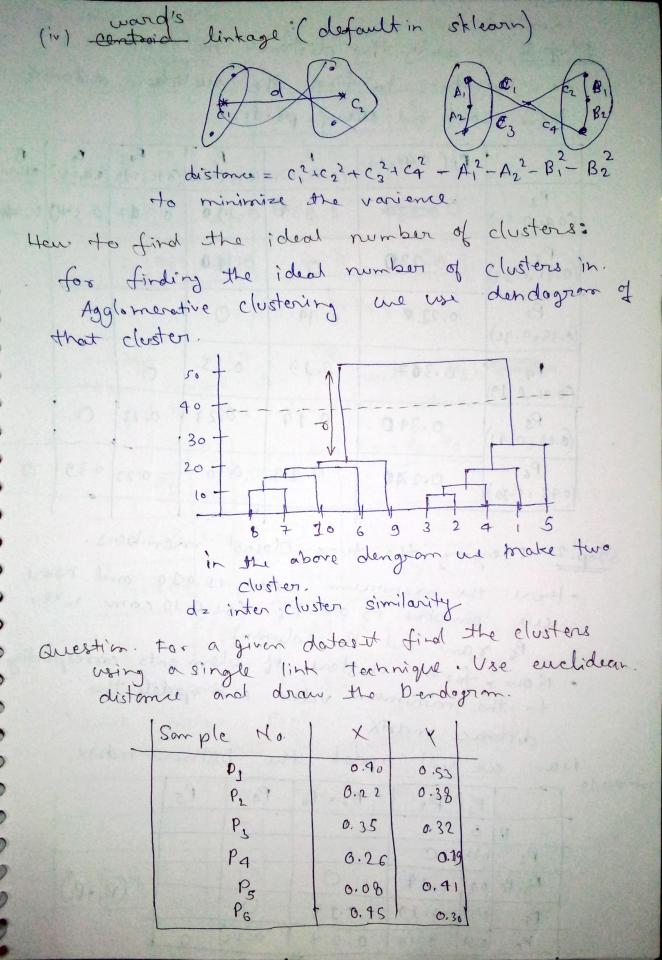
Dote - 19-Oct - 2023 Agglomenative Hierarchical Clustering Agglomerative clustering is a type of hierarchical clustering algorithm. it's an unsupervised machine learning technique that divides a population into clusters bossed on similarity. The clusters are created in a bottom up approach. Agglomenative clustering mosts by - Treating each data point as a single cluster - Merging the clusters based on similarity Repeating the process untill all objects are in one big cluster \* Agglomerative clustering is good at identifying small clusters. it creates. a tree-like structure that shows the relationships between clusters and their heirarchy. \* The time complexity of a naive agglomerative clustering is  $O(n^3)$ . This can be reduced to  $O(n^2\log n)$  using. a priority que ue data stoucture. 

How agosithm cooks: Step-1. Initialize the proximity matrix Step-2. Make each point a cluster Step-3. Inside a loop (a) Menge the two closest clusters (b) Update the proximity Matrix Step 4. Until only one cluster is left. Types of Agglomenative Clustering (ii) Max (complete linkage) (v) centroid linkage. (') Min (single linkage) (iii) Average dinkage (iv) Word's linkage types of agglormenative In the above the types of agglormenative clustering is based on how we measure the distance between the two cluster. (i) single linkage agglomerative cluster. d, = min (single linkage) d (A,B) = min (d (a;, bj)) (ii) Max (complete linkage): d1 = max (complete linkage)  $d_1 = \max(\text{complete lin})$   $d(A, B) = \max(d(A, b))$ (iii) Average linkage:  $\frac{d_1 + d_2 + d_3 + d_4}{4} = d$   $\frac{d_1 + d_2 + d_3 + d_4}{4} = d$   $\frac{d_1 + d_2 + d_3 + d_4}{4} = d$   $\frac{d_1 + d_2 + d_3 + d_4}{4} = d$   $\frac{d_1 + d_2 + d_3 + d_4}{4} = d$   $\frac{d_1 + d_2 + d_3 + d_4}{4} = d$ 



Step 1. Compute the distance neatrix. So are have to find the endiden distance be each and every points.

| 1 | AT PE                         | P1 (000,0.53 | P2 (0.22,0.36 | Ps (0.35,0.32) | P4<br>(0.26,0.15 | (0,08,041) | PL 0.45, 0.3 |
|---|-------------------------------|--------------|---------------|----------------|------------------|------------|--------------|
|   | P <sub>1</sub><br>(0.40,0.53) | 0 00234      | 0.231         | 0.21           | 0.367            |            |              |
|   | (0-22,0.38)                   | 0.230        | 000           | 0.140          | Charte           |            |              |
|   | P3<br>(0.35,0.32)             | 0.22         | 0.14          | 0              | toners of        | Set A      |              |
|   | P4 (0.26,0.19)                | 6.367        | 0.19          | 0.13           | 0                |            |              |
|   | (0.08, 0.41)                  | 0.340        | 0.19          | 0.23           | 0.23             | 0          |              |
|   | (0.45,0.30)                   | 0-2 246      | 0.24          | 0.10           | 6-22             | 0.39       | 0            |
|   | 2                             |              |               |                | 1                | 1          | 6            |

Step. ? Merging the two closest members.

· Here the minoreum value is 0:10 and heme use combine P3 and P6 (as 0:10 comm 12 9/2.

P6 raw and P3 column)

· Now , form clusters of elements corresponding to the minimum value and update the

(P3, P6)

distance motoix

than are us) updat the pistome motors

min=0.to

| , 1  |      | _      |
|------|------|--------|
| 0.01 |      |        |
|      |      |        |
| 0    |      |        |
| 0.23 | 0    | 1      |
|      | 0.23 | 0,23 0 |

Man we will update the distance motoix pa is rouge with (P3. Po)

| 1    |                   |   | -           |
|------|-------------------|---|-------------|
| PI   | P <sub>2</sub>    | P3, P6, P4  | Ps          |
| 0    |                   |   |             |
| 0.23 | 0                 |   |             |
| 0.22 | 0.14              | 0   |             |
| 0.34 | 0.14              | 0.28  | 0           |
|      | ©<br>6.23<br>6.22 | P <sub>3</sub> P <sub>2</sub> 0  0.23 0  0.22 0.14  0.34 0.14 | 0.22 0.14 0 |

(P3, P6). Pa}

Non myk the Ps with P2. From

update the distance roctorix

|              | PJ    | P29 P5     | P3, P6, Pa  |
|--------------|-------|------------|-------------|
| Pi           | 0     | 9.         | 9           |
|              |       | 0          |             |
| P3 , P6 , P4 | 0.22  | 6.14       | 0           |
|              | S (P. | 3, P6). P4 | and (P29P3) |

hen minimum 20.19 hence merge Ps. Ps. Ps with P24 Ps Now update the distance notifix

|                  | P1     | P2 ª Ps  | 9 P3 | , P6 , | P4 | 1 |
|------------------|--------|----------|------|--------|----|---|
| P <sub>1</sub>   | 0      |          |      |        |    |   |
| B, B, Pg, P6, P4 | 0.22   |          | 0    |        |    |   |
|                  | TS(P2) | Pa), Pa? | 60   | 71 0   |    |   |

[f(P3, P6), P4], (P2, P5)]

Man finally. merge P3,P6, P4, P2.P5 with P1 [{(P3,P6),P4},(P2,P5)],P1 Step. 3 draw the dendagrem. So ran me have reached to the. Solution, the dendagram for those questions und be or follows. [{(P3, P6), P4], (P2, P5)], Py or Plant and white P<sub>3</sub> P<sub>6</sub> P<sub>4</sub> P<sub>2</sub> P<sub>5</sub> P<sub>1</sub> -> computationally expensive for agglomenative clustering-> computationally expensive for Divisine clustering is O(2N) exhibit mother with its by worth and 1 P3 1 P3 - P3 - P6 - P4

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