Data Structures Using C++ 2E

Chapter 10 Sorting Algorithms

Objectives

- Learn the various sorting algorithms
- Explore how to implement selection sort, insertion sort, Shellsort, quicksort, mergesort, and heapsort
- Discover how the sorting algorithms discussed in this chapter perform
- Learn how priority queues are implemented

Sorting Algorithms

- Several types in the literature
 - Discussion includes most common algorithms
- Analysis
 - Provides a comparison of algorithm performance
- Functions implementing sorting algorithms
 - Included as public members of related class

```
template <class elemType>
class arrayListType
{
public:
    void selectionSort();
    ...
};
```

Selection Sort: Array-Based Lists

- List sorted by selecting elements in the list
 - Select elements one at a time
 - Move elements to their proper positions
- Selection sort operation
 - Find location of the smallest element in unsorted list portion
 - Move it to top of unsorted portion of the list
 - First time: locate smallest item in the entire list
 - Second time: locate smallest item in the list starting from the second element in the list, and so on

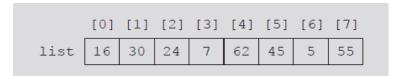


FIGURE 10-1 List of 8 elements

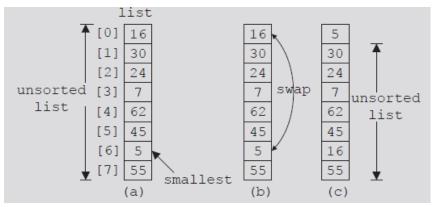


FIGURE 10-2 Elements of list during the first iteration

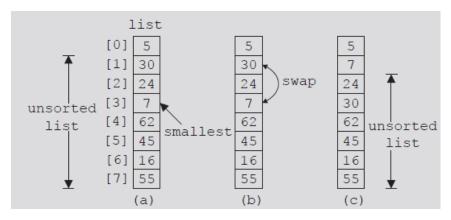


FIGURE 10-3 Elements of list during the second iteration

- Selection sort steps
 - In the unsorted portion of the list
 - Find location of smallest element
 - Move smallest element to beginning of the unsorted list
- Keep track of unsorted list portion with a for loop

```
for (index = 0; index < length - 1; index++)
{
    1. Find the location, smallestIndex, of the smallest element in
        list[index]...list[length - 1].
    2. Swap the smallest element with list[index]. That is, swap
        list[smallestIndex] with list[index].
}</pre>
```

- Given: starting index, first, ending index, last
 - C++ function returns index of the smallest element in

```
list[first]...list[last]
```

```
template <class elemType>
int arrayListType<elemType>::minLocation(int first, int last)
{
    int minIndex;

    minIndex = first;
    for (int loc = first + 1; loc <= last; loc++)
        if( list[loc] < list[minIndex])
            minIndex = loc;

    return minIndex;
} //end minLocation</pre>
```

- Function swap
- Definition of function selectionSort

```
template <class elemType>
void arrayListType<elemType>::swap(int first, int second)
    elemType temp;
    temp = list[first];
    list[first] = list[second];
    list[second] = temp;
}//end swap
template <class elemType>
void arrayListType<elemType>::selectionSort()
   int minIndex:
   for (int loc = 0; loc < length - 1; loc++)
       minIndex = minLocation(loc, length - 1);
       swap(loc, minIndex);
```

 Add functions to implement selection sort in the definition of class arrayListType

```
template<class elemType>
class arrayListType
{
public:
    //Place the definitions of the function given earlier here.
    void selectionSort();
    ...

private:
    //Place the definitions of the members given earlier here.
    void swap(int first, int second);
    int minLocation(int first, int last);
};
```

Analysis: Selection Sort

- Search algorithms
 - Concerned with number of key (item) comparisons
- Sorting algorithms
 - Concerned with number of key comparisons and number of data movements
- Analysis of selection sort
 - Function swap
 - Number of item assignments: 3(n-1)
 - Function minLocation
 - Number of key comparisons of $O(n^2)$

Insertion Sort: Array-Based Lists

- Attempts to improve high selection sort key comparisons
- Sorts list by moving each element to its proper place
- Given list of length eight

```
[0] [1] [2] [3] [4] [5] [6] [7]
list 10 18 25 30 23 17 45 35
```

FIGURE 10-4 list

- Elements list[0], list[1], list[2], list[3] in order
- Consider element list[4]
 - First element of unsorted list

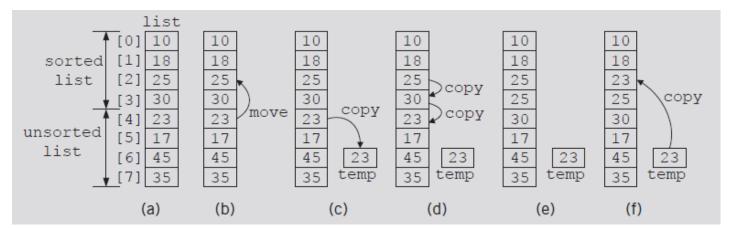


FIGURE 10-5 list elements while moving list[4] to its proper place

- Array containing list divided into two sublists
 - Upper and lower
- Index firstOutOfOrder
 - Points to first element in the lower sublist

- length = 8
- Initialize firstOutOfOrder to one

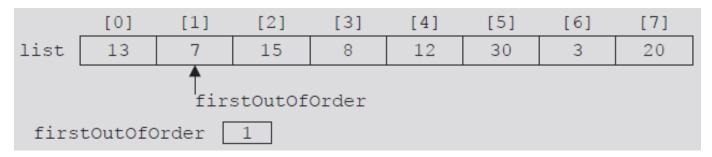


FIGURE 10-6 firstOutOfOrder = 1

- list[firstOutOfOrder] = 7
- list[firstOutOfOrder 1] = 13
 - -7 < 13
- Expression in if statement evaluates to true
 - Execute body of if statement
 - temp = list[firstOutOfOrder] = 7
 - location = firstOutOfOrder = 1
 - Execute the do...while loop
 - list[1] = list[0] = 13
 - location = 0

- do...while loop terminates
 - Because location = 0
 - Copy temp into list[location] (list[0])

```
[0] [1] [2] [3] [4] [5] [6] [7]
list 7 13 15 8 12 30 3 20

firstOutOfOrder
firstOutOfOrder 1 temp 7
```

FIGURE 10-7 list after the first iteration of insertion sort

- Suppose list given in Figure 10-8(a)
 - Walk through code

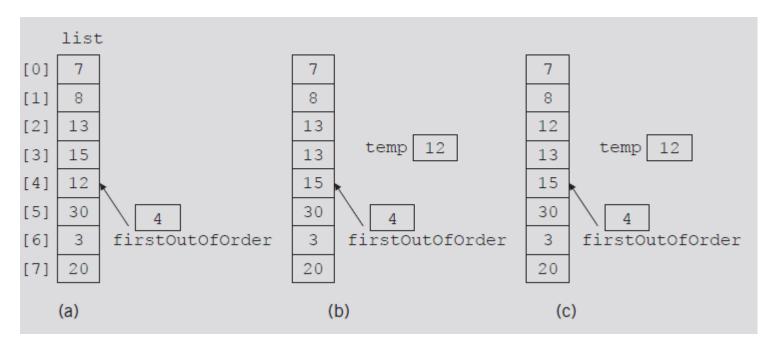


FIGURE 10-8 list elements while moving list[4] to its proper place

- Suppose list given in Figure 10-9
 - Walk through code

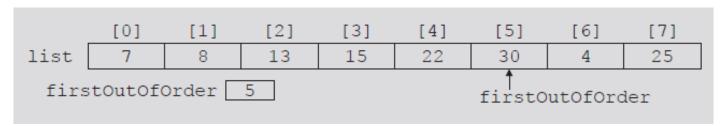


FIGURE 10-9 First out-of-order element is at position 5

C++ function implementing previous algorithm

```
template <class elemType>
void arrayListType<elemType>::insertionSort()
    int firstOutOfOrder, location;
    elemType temp;
    for (firstOutOfOrder = 1; firstOutOfOrder < length;</pre>
                               firstOutOfOrder++)
        if (list[firstOutOfOrder] < list[firstOutOfOrder - 1])</pre>
            temp = list[firstOutOfOrder];
            location = firstOutOfOrder;
            do
                 list[location] = list[location - 1];
                 location--;
            while (location > 0 && list[location - 1] > temp);
            list[location] = temp;
} //end insertionSort
```

Insertion Sort: Linked List-Based Lists

- If list stored in an array
 - Traverse list in either direction using index variable
- If list stored in a linked list
 - Traverse list in only one direction
 - Starting at first node: links only in one direction



FIGURE 10-10 Linked list

- firstOutOfOrder
 - Pointer to node to be moved to its proper location
- lastInOrder
 - Pointer to last node of the sorted portion of the list

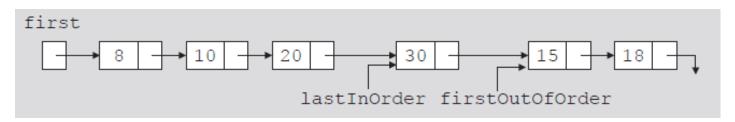


FIGURE 10-11 Linked list and pointers lastInOrder and firstOutOfOrder

- Compare firstOutOfOrder info with first node info
 - If firstOutOfOrder info smaller than first node info
 - firstOutOfOrder moved before first node
 - Otherwise, search list starting at second node to find location where to move firstOutOfOrder
- Search list using two pointers
 - current
 - trailCurrent: points to node just before current
- Handle any special cases

```
if (firstOutOfOrder->info is less than first->info)
   move firstOutOfOrder before first
else
    set trailCurrent to first
    set current to the second node in the list first->link:
     //search the list
   while (current->info is less than firstOutOfOrder->info)
        advance trailCurrent;
        advance current;
    }
    if (current is not equal to firstOutOfOrder)
        //insert firstOutOfOrder between current and trailCurrent
        lastInOrder->link = firstOutOfOrder->link;
        firstOutOfOrder->link = current;
        trailCurrent->link = firstOutOfOrder;
           //firstOutOfOrder is already at the first place
        lastInOrder = lastInOrder->link;
```

- Case 1
 - firstOutOfOrder->info less than first->info
 - Node firstOutOfOrder moved before first
 - Adjust necessary links

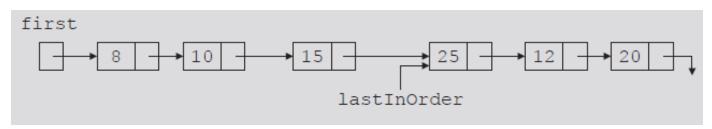


FIGURE 10-13 Linked list after moving the node with info 8 to the beginning

- Review Case 2 on page 546
- Review Case 3 on page 546
- Review function linkedInsertionSort on page
 547
 - Implements previous algorithm

Analysis: Insertion Sort

TABLE 10-1 Average-case behavior of the selection sort and insertion sort for a list of length *n*

Algorithm	Number of comparisons	Number of swaps/item assignments
Selection sort	$(1/2)n(n-1) = O(n^2)$	3(n-1)=O(n)
Insertion sort	$(1/4)n^2 + O(n) = O(n^2)$	$(1/4)n^2 + O(n) = O(n^2)$

Shellsort

- Reduces number of item movements in insertion sort by modifying it
 - Introduced in 1959 by D.E. Shell
 - Also known as diminishing-increment sort
- List elements viewed as sublists at a particular distance
 - Each sublist sorted
 - Elements far apart move closer to their final position

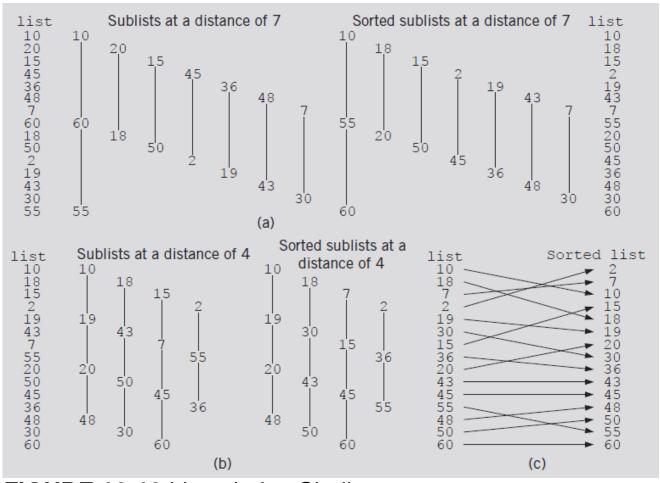


FIGURE 10-19 Lists during Shellsort

- Figure 10-19
 - Sort elements at a distance of 7, 4, 1
 - Called increment sequence
- Desirable to use as few increments as possible
- D.E. Knuth recommended increment sequence
 - 1, 4, 13, 40, 121, 364, 1093, 3280. . . .
 - Ratio between successive increments: about one-third
 - i^{th} increment = 3 (i-1)th increment + 1
- Certain increment sequences must be avoided
 - 1, 2, 4, 8, 16, 32, 64, 128, 256. . . .
 - Bad performance

Function implementing Shellsort algorithm

- Function shellSort
 - Uses function intervalInsertionSort
 - Modified version of insertion sort for array-based lists
- intervalInsertionSort
 - Sublist starts at variable begin
 - Increment between successive elements given by variable inc instead of one
- Analysis of Shellsort
 - Difficult to obtain

Lower Bound on Comparison-Based Sort Algorithms

- Comparison tree
 - Graph tracing comparison-based algorithm execution
 - Node: comparison drawn as a circle
 - Leaf: rectangle representing final node ordering
 - Root node: top node in the figure
 - Branch: straight line connecting two nodes
 - Path: sequence of branches between nodes

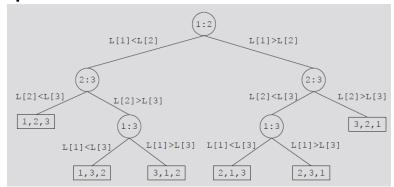


FIGURE 10-20 Comparison tree for sorting three items

Lower Bound on Comparison-Based Sort Algorithms (cont'd.)

- Unique permutation of the elements
 - Associated with each path from the root to a leaf
- Theorem
 - Let L be a list of n distinct elements. Any sorting algorithm that sorts L by comparison of the keys only, in its worst case, makes at least O(nlog₂n) key comparisons

Quicksort: Array-Based Lists

- Uses the divide-and-conquer technique to sort a list
 - List partitioned into two sublists
 - Two sublists sorted and combined into one list
 - Combined list then sorted using quicksort (recursion)
- Trivial to combine sorted lowerSublist and upperSublist
- All sorting work done in partitioning the list

```
if (the list size is greater than 1)
{
   a. Partition the list into two sublists, say lowerSublist and upperSublist.
   b. Quicksort lowerSublist.
   c. Quicksort upperSublist.
   d. Combine the sorted lowerSublist and sorted upperSublist.
}
```

Quicksort: Array-Based Lists (cont'd.)

- Pivot divides list into two sublists
 - lowerSublist: elements smaller than pivot
 - upperSublist: elements greater than pivot
- Choosing the pivot
 - lowerSublist and upperSublist nearly equal

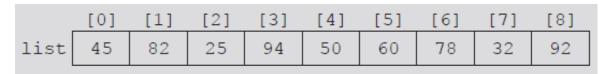


FIGURE 10-21 List before the partition

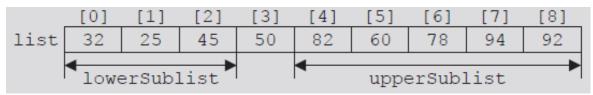


FIGURE 10-22 List after the partition

Quicksort: Array-Based Lists (cont'd.)

- Partition algorithm
 - Determine pivot; swap pivot with first list element
 - Suppose index smallIndex points to last element smaller than pivot. smallIndex initialized to first list element
 - For the remaining list elements (starting at second element): If current element smaller than pivot
 - Increment smallIndex
 - Swap current element with array element pointed to by smallindex
 - Swap first element (pivot) with array element pointed to by smallIndex

Quicksort: Array-Based Lists (cont'd.)

- Function partition
 - Passes starting and ending list indices
 - Swaps certain elements of the list

```
template <class elemType>
int arrayListType<elemType>::partition(int first, int last)
    elemType pivot;
    int index, smallIndex;
    swap(first, (first + last) / 2);
                                                       template <class elemType>
                                                       void arrayListType<elemType>::swap(int first, int second)
    pivot = list[first];
    smallIndex = first;
                                                            elemType temp;
    for (index = first + 1; index <= last; index++)</pre>
                                                           temp = list[first];
        if (list[index] < pivot)</pre>
                                                            list[first] = list[second];
                                                           list[second] = temp;
            smallIndex++;
                                                       }
            swap(smallIndex, index);
        }
    swap(first, smallIndex);
    return smallIndex;
}
```

Quicksort: Array-Based Lists (cont'd.)

- Given starting and ending list indices
 - Function recQuickSort implements the recursive version of quicksort
- Function quickSort calls recQuickSort

```
template <class elemType>
void arrayListType<elemType>::recQuickSort(int first, int last)
{
    int pivotLocation;

    if (first < last)
    {
        pivotLocation = partition(first, last);
        recQuickSort(first, pivotLocation - 1);
        recQuickSort(pivotLocation + 1, last);
    }
}

template <class elemType>
void arrayListType<elemType>::quickSort()
{
    recQuickSort(0, length -1);
}
```

Analysis: Quicksort

	Number of comparisons	Number of swaps				
Average case	$1.39 n \log_2 n + O(n) = O(n \log_2 n)$	$0.69 n \log_2 n + O(n) = O(n \log_2 n)$				
Worst case	$(1/2)(n^2 - n) = O(n^2)$	$(1/2)n^2 + (3/2)n - 2 = O(n^2)$				

TABLE 10-2 Analysis of quicksort for a list of length *n*

Mergesort: Linked List-Based Lists

- Quicksort
 - Average-case behavior: O(nlog₂n)
 - Worst-case behavior: $O(n^2)$
- Mergesort behavior: always O(nlog₂n)
 - Uses divide-and-conquer technique to sort a list
 - Partitions list into two sublists
 - Sorts sublists
 - Combines sorted sublists into one sorted list
- Difference between mergesort and quicksort
 - How list is partitioned

Mergesort: Linked List-Based Lists (cont'd.)

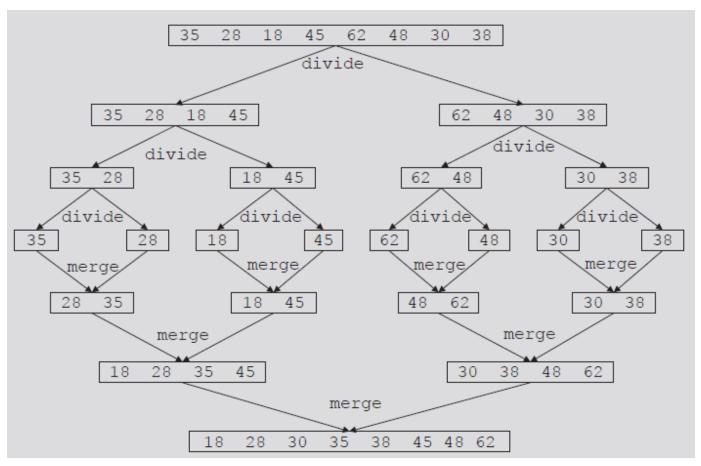


FIGURE 10-32 Mergesort algorithm

Mergesort: Linked List-Based Lists (cont'd.)

- Most sorting work done in merging sorted sublists
- General algorithm for mergesort

```
if the list is of a size greater than 1
{
   1. Divide the list into two sublists.
   2. Mergesort the first sublist.
   3. Mergesort the second sublist.
   4. Merge the first sublist and the second sublist.
}
```

Divide

- To divide list into two sublists
 - Need to find middle node
 - Use two pointers: middle and current
 - Advance middle by one node, advance current by one node
 - current becomes NULL; middle points to last node
 - Divide list into two sublists
 - Using the link of middle: assign pointer to node following middle
 - Set link of middle to NULL
- See function divideList on page 561



FIGURE 10-33 Unsorted linked list

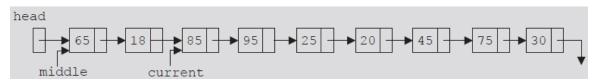


FIGURE 10-34 middle and current before traversing the list

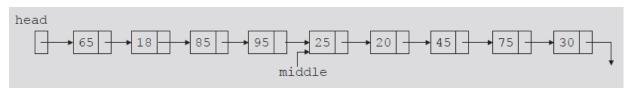


FIGURE 10-35 middle after traversing the list

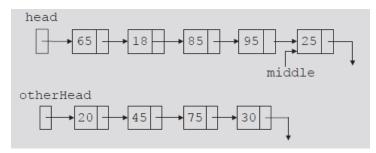


FIGURE 10-36 List after dividing it into two lists

Merge

- Once sublists sorted
 - Next step: merge the sorted sublists
- Merge process
 - Compare elements of the sublists
 - Adjust references of nodes with smaller info
- See code on page 564 and 565

Analysis: Mergesort

- Maximum number of comparisons made by mergesort: O(n log₂n)
- If W(n) denotes number of key comparisons
 - Worst case to sort *L*: $W(n) = O(n \log_2 n)$
- Let A(n) denote number of key comparisons in the average case
 - Average number of comparisons for mergesort
 - If n is a power of 2
 - $A(n) = n \log_2 n 1.25n = O(n \log_2 n)$

Heapsort: Array-Based Lists

- Overcomes quicksort worst case
- Heap: list in which each element contains a key
 - Key in the element at position k in the list
 - At least as large as the key in the element at position 2k + 1 (if it exists) and 2k + 2 (if it exists)
- C++ array index starts at zero
 - Element at position k
 - k + 1th element of the list

							L - 3					[12]
85	70	80	50	40	75	30	20	10	35	15	62	58

FIGURE 10-41 A heap

Heapsort: Array-Based Lists (cont'd.)

- Data given in Figure 10-41
 - Can be viewed in a complete binary tree
- Heapsort
 - First step: convert list into a heap
 - Called buildHeap
 - After converting the array into a heap
 - Sorting phase begins

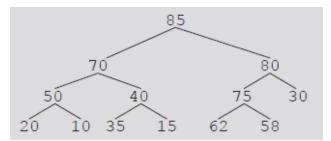


FIGURE 10-42 Complete binary tree corresponding to the list in Figure 10-41

Build Heap

```
int largeIndex = 2 * low + 1; //index of the left child
while (largeIndex <= high)</pre>
{
   if ( largeIndex < high)</pre>
       if (list[largeIndex] < list[largeIndex + 1])</pre>
          largeIndex = largeIndex + 1; //index of the larger child
   if (list[low] > list[largeIndex]) //the subtree is already in
                                        //a heap
       break;
   else
       swap(list[low], list[largeIndex]); //Line swap**
       low = largeIndex; //go to the subtree to further
                          //restore the heap
       largeIndex = 2 * low + 1;
   } //end else
}//end while
```

Build Heap (cont'd.)

- Function heapify
 - Restores the heap in a subtree
 - Implements the buildHeap function
 - Converts list into a heap

```
template<class elemType>
void arrayListType<elemType>::heapify(int low, int high)
{
   int largeIndex;
   elemType temp = list[low]; //copy the root node of the subtree
   largeIndex = 2 * low + 1; //index of the left child
   while (largeIndex <= high)</pre>
       if (largeIndex < high)</pre>
          if (list[largeIndex] < list[largeIndex + 1])</pre>
             largeIndex = largeIndex + 1; //index of the largest
                                            //child
       if (temp > list[largeIndex]) //subtree is already in a heap
          break;
       else
       {
          list[low] = list[largeIndex]; //move the larger child
                                         //to the root
          low = largeIndex; //go to the subtree to restore the heap
          largeIndex = 2 * low + 1;
   }//end while
   list[low] = temp; //insert temp into the tree, that is, list
} //end heapify
```

Build Heap (cont'd.)

```
template <class elemType>
void arrayListType<elemType>::buildHeap()
{
   for (int index = length / 2 - 1; index >= 0; index--)
        heapify(index, length - 1);
}
```

Build Heap (cont'd.)

The heapsort algorithm

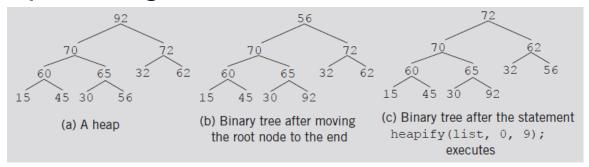


FIGURE 10-48 Heapsort

Analysis: Heapsort

- Given L a list of n elements where n > 0
- Worst case
 - Number of key comparisons to sort L
 - $2n\log_2 n + O(n)$
 - Number of item assignments to sort L
 - $n\log_2 n + O(n)$
- Average number of comparisons to sort L
 - $O(n\log_2 n)$
- Heapsort takes twice as long as quicksort
 - Avoids the slight possibility of poor performance

Priority Queues (Revisited)

- Customers or jobs with higher priorities
 - Pushed to front of the queue
- Assume priority of the queue elements is assigned using the relational operators
 - In a heap, largest list element is always the first element of the list
 - After removing largest list element
 - Function heapify restores the heap in the list
 - Implement priority queues as heaps
 - To ensure largest element of the priority queue is always the first element of the queue

Priority Queues (Revisited) (cont'd.)

- Insert an element in the priority queue
 - Insert new element in first available list position
 - Ensures array holding the list is a complete binary tree
 - After inserting new element in the heap, the list might no longer be a heap
 - Restore the heap (might result in moving the new entry to the root node)

while (the parent of the new entry is smaller than the new entry) swap the parent with the new entry.

Priority Queues (Revisited) (cont'd.)

- Remove an element from the priority queue
 - Assume priority queue implemented as a heap
 - Copy last element of the list into first array position
 - Reduce list length by one
 - Restore heap in the list
 - Other operations for priority queues
 - Can be implemented in the same way as implemented for queues

Summary

- Search algorithms may require sorted data
- Several sorting algorithms available
 - Selection sort, insertion sort, Shellsort, quicksort, mergesort, and heapsort
 - Can be applied to either array-based lists or linked lists
- Compare algorithm performance through analysis
 - Number of key comparisons
 - Number of data movements
- Functions implementing sorting algorithms
 - Included as public members of the related class