view frames Result Recorded at time: 3.718 world Broadcaster: /robot_state_publisher Average rate: 50.794 Hz Most recent transform: 4.200 (-0.482 sec old) Buffer length: 1.260 sec camera Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.794 Hz Most recent transform: 4.200 (-0.482 sec old) Most recent transform: 4.200 (-0.482 sec old) Buffer length: 1.260 sec one_psm_base_link two_psm_base_link davinci_endo right_camera_link left_camera_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /rcamera_frame_bdcst Broadcaster: /lcamera_frame_bdcst Average rate: 50.781 Hz Average rate: 50.781 Hz Average rate: 20.833 Hz Average rate: 20.781 Hz Most recent transform: 3.712 (0.006 sec old) Most recent transform: 3.729 (-0.011 sec old) Most recent transform: 3.735 (-0.017 sec old) Most recent transform: 3.712 (0.006 sec old) Buffer length: 1.280 sec Buffer length: 1.280 sec Buffer length: 1.200 sec Buffer length: 1.203 sec two_outer_yaw_link right_camera_optical_frame one_outer_yaw_link left_camera_optical_frame Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.781 Hz Most recent transform: 3.712 (0.006 sec old) Most recent transform: 3.712 (0.006 sec old) Most recent transform: 3.712 (0.006 sec old) Most recent transform: 3.712 (0.006 sec old) Most recent transform: 3.712 (0.006 sec old) Most recent transform: 3.712 (0.006 sec old) Buffer length: 1.280 sec one_outer_pitch_back_link one_outer_pitch_front_link two_outer_pitch_link two_outer_pitch_back_link one_outer_pitch_link two_outer_pitch_front_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher 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one_tool_tip_link two_tool_wrist_sca_ee_link_2 two_tool_tip_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.794 Hz Average rate: 50.794 Hz Average rate: 50.794 Hz Average rate: 50.794 Hz Most recent transform: 4.200 (-0.482 sec old) Most recent transform: 4.200 (-0.482 sec old) Most recent transform: 4.200 (-0.482 sec old) Most recent transform: 4.200 (-0.482 sec old) Buffer length: 1.260 sec Buffer length: 1.260 sec Buffer length: 1.260 sec Buffer length: 1.260 sec one_fingertip2 two_fingertip1 one_fingertip1 two_fingertip2