DCBA 3D Scanner

Low-Cost, High-Precision, User-Friendly

Vision

Our Vision:

All work in measurement, design, art, and manufacturing will soon take advantage of the accuracy and speed of 3D scanning.

Our Goal:

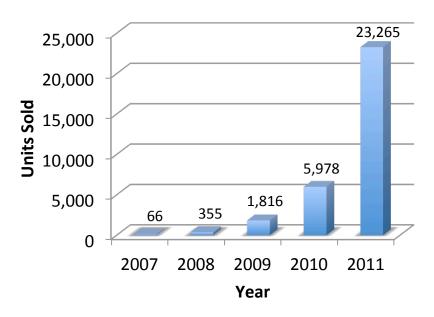
We will develop high-quality 3D scanners accessible to individuals and businesses on small budgets.

Market

- Existing \$350 million 3D scanning market targets large businesses – similar accuracy and lower price exposes a much larger market
- Potential users
 - Research labs
 - Hobbyist builders
 - Artists
 - Product Designers
 - Small manufactures
- Interest in and use in 3D of printing is growing wildly. 3D scanning is the other part of this revolution

Global Personal 3D Printer Sales

Machines or kits priced between \$500 and \$4,000



Data from Wohlers Report 2012: Additive Manufacturing and 3D Printing State of the Industry

Relevant Technology Advances

Optics and Digital Imaging

 Notably emergence of high-quality, compact, and cheap cell phone cameras

Computing

High-power computers are practically ubiquitous

Digital Fabrication

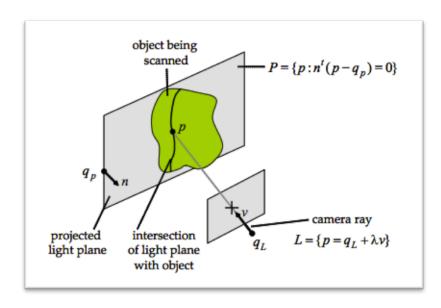
 High-precision laser cutting and CNC machining is now easily attainable

Scanning Techniques

- Existing methods include
 - Structured Light
 - Image Reconstruction
 - Laser Time of Flight
 - Laser Triangulation
 - Computed Tomography
 - Serial Sectioning
 - Contact Scanning
- Recent interest in 3D scanning has spurred academic research advances, particularly in structured light and image reconstruction

Structured Light Scanning

- 1. Known light pattern is projected onto scene
- 2. Scene is imaged using one or more cameras
- 3. Point cloud calculated by triangulation





Product Goals

Accurate

- 0.025 mm accuracy
- This level of precision comparable to or better than most manufacturing processes
- Low-cost less than \$500

Usable

- Intuitive website and software UI
- Computer-controlled calibration

Modular

- Easily alter the workspace
- Enables scanning a single face of large objects, all faces of a small object, or even an entire room with one system
- Allows easy upgrading, maintenance, and expansion
- **Compact** fits on top of a desk

Our Team



Troy Astorino Year: 2013

Major: Physics/AeroAstro

Job: Team Lead/Programming



Gus Downs Year: 2013

Major: Physics, Math

Job: Mechanical & Electrical

Engineering



Craig Cheney

Year: 2014

Major: Mech. Eng.

Job: Mechanical Engineering



Turner Bohlen

Year: 2014

Major: Physics

Job: Programming

Our Current State

- Ideas we want to explore:
 - Fixed and moving gratings over LEDs instead of projectors
 - Redundant arrays of cheap CMOS cameras
 - Merging multiple scanning techniques

[CAD model here]

Next Steps

- Prototype Prototype!
- Explore algorithmic methods for combining multiple scanning methods and reducing error
- Forward-facing software development to allow for various input devices (allows rapid modification during prototyping and future additions)