

Comparison elliptic PDE and parabolic PDE: discretization in space

Elliptic

$$\left\{ \begin{array}{l} -u_{xx}(x) = f(x) \quad x \in (a, b) \\ u(a) = \alpha \\ u(b) = \beta \end{array} \right. \quad BC$$

Parabolic

$$\left\{ \begin{array}{l} u_t(x, t) - u_{xx}(x, t) = f(x, t) \\ x \in (a, b) \\ t > 0 \\ u(a, t) = \alpha(t) \\ u(b, t) = \beta(t) \\ u(x, 0) = g(x) \end{array} \right. \quad IC$$

Discretize in space: $x_j = a + \Delta x j$
 $j = 0, \dots, N$

$$x_0 = a$$

$$x_N = b$$

for interior points $x_j, j = 1, \dots, N-1$

$$-\frac{u_{j+1} - 2u_j + u_{j-1}}{\Delta x^2} = f_j$$

$$j = 1, \dots, N-1$$

$$\frac{du_j(t)}{dt} = \frac{u_{j+1}(t) - 2u_j(t) + u_{j-1}(t)}{\Delta x^2}$$

$$+ f_j(t)$$

$$u_j \approx u(x_j)$$

$$f_j = f(x_j)$$

$$j = 1, \dots, N-1$$

$$u_j(t) \approx u(x_j, t)$$

$$f_j(t) = f(x_j, t)$$

$$u_0 = \alpha$$

$$u_N = \beta$$

$$u_0(t) = \alpha(t)$$

$$u_N(t) = \beta(t)$$

- insert boundary values into equations $j=1$ and $j=N-1$

- move known values to RHS

$u_j, j=1, \dots, N-1$
are unknowns

obtained from
solving one linear
system

$$- A \bar{u} = \bar{f}$$

$$\bar{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_{N-1} \end{bmatrix}$$

$u_j(t), j=1, \dots, N-1$
unknowns

$u_j(t)$ obtained
by using ODE-
method to timestep
system

$$\frac{d\bar{u}}{dt} = A \bar{u}(t) + \bar{f}(t)$$

$$\bar{u}(t) = \begin{bmatrix} u_1(t) \\ u_2(t) \\ \vdots \\ u_{N-1}(t) \end{bmatrix}$$

for fully discrete

problem we obtain
a vector-solution
per time $t = 0, \Delta t, 2\Delta t,$

$\dots T - \Delta t, T$

until endtime $T.$

fully discrete solution
 $u_j^n \approx u(x_j, t_n)$

$$t_n = n \cdot \Delta t$$

$$\Delta t = \frac{T}{M} \quad , M \text{ time steps}$$

Let $u_j^0 = u(x_j, 0) = g(x_j)$

Matrix Solution: gives $\sim M \times L$

$x_1 -$	$u_1^0 \quad u_1^1$	u_1^M	$(N-1)$
$x_2 -$	$u_2^0 \quad u_2^1$	u_2^M	$x(M+1)$
\vdots	\vdots	\vdots	matrix
$x_{N-1} -$	$u_{N-1}^0 \quad u_{N-1}^1$	u_{N-1}^M	

$$\begin{aligned} \overbrace{\bar{u}(0)}^{\sim} &= \bar{u}(\Delta t) \\ &= \bar{g}(x) \quad \approx u(x_j, \Delta t) \\ &\quad j=1, \dots, N \end{aligned}$$

$$\overbrace{\bar{u}(T)}^{\sim}$$

Local truncation error for θ -scheme

Heat equation $u_t = u_{xx}$

θ -scheme:

$$u_j^{n+1} = u_j^n + \Delta t \cdot \left[\theta \frac{u_{j+1}^{n+1} - 2u_j^{n+1} + u_{j-1}^{n+1}}{\Delta x^2} \right]$$

$$+ (1-\theta) \frac{u_{j+1}^n - 2u_j^n + u_{j-1}^n}{\Delta x^2}$$

Define local truncation error
 l_j^n by inserting exact solution
 $u(x_j, t_n)$ into θ -scheme:

$$u(x_j, t_{n+1}) = u(x_j, t_n) +$$

$$\Delta t \left[\theta \frac{u(x_{j+1}, t_{n+1}) - 2u(x_j, t_{n+1}) + u(x_{j-1}, t_{n+1})}{\Delta x^2} \right]$$

$\underbrace{\qquad\qquad\qquad}_{A_{n+1}}$

$$+ (1-\theta) \frac{u(x_{j+1}, t_n) - 2u(x_j, t_n) + u(x_{j-1}, t_n)}{\Delta x^2}$$

$\underbrace{\qquad\qquad\qquad}_{A_n}$

$$+ \ell_j^n$$

Rewrite Θ -scheme:

$$\frac{u(x_j, t_{n+1}) - u(x_j, t_n)}{\Delta t} = \theta A_{n+1} +$$

$\underbrace{\qquad\qquad\qquad}_{LHS}$

$$(1-\theta) A_n + \frac{\ell_j^n}{\Delta t}$$

Taylor expand u around x_j and t_n to obtain precise form of \hat{d}_j^n

1. LHS: (T.E. w.r.t time)

$$u(x_j, t_{n+1}) = u(x_j, t_n) + \Delta t u_t(x_j, t_n)$$

$$+ \frac{\Delta t^2}{2} u_{tt}(x_j, t_n) + \Theta(\Delta t^3)$$

So

$$\frac{u(x_j, t_{n+1}) - u(x_j, t_n)}{\Delta t} = u_t(x_j, t_n)$$

$$+ \frac{\Delta t}{2} u_{tt} + \Theta(\Delta t^2)$$

2. A_n : (T.E w.r.t x)

$$u(x_{j \pm 1}, t_n) = u(x_j, t_n) \pm \Delta x u_x$$

$$+ \frac{\Delta x^2}{2} u_{xx} \pm \frac{\Delta x^3}{6} u_{xxx} + \frac{\Delta x^4}{24} u_{xxxx}$$

$$A_n = u_{xx}(x_j, t_n) + \underbrace{\frac{\Delta x^2}{12} u_{xxxx}(\xi, t_n)}_{\Theta(\Delta x^2)}$$

$$x_{j-1} < \xi < x_{j+1}$$

3. A_{n+1} : (T.E w.r.t x)

$$A_{n+1} = u_{xx}(x_j, t_{n+1}) + \Theta(\Delta x^2)$$

(T.E w.r.t t)

$$A_{n+1} = u_{xx}(x_j, t_n) + \Delta t \underbrace{u_{xxt}(x_j, t_n)}_{= u_{ttt}(x_j, t_n)} + \mathcal{O}(\Delta x^2 + \Delta t^2)$$

Since $u_t = u_{xx}$

we have $u_{tt} = u_{xxt}$

Combine 1, 2, 3 :

At $x = x_j$, $t = t_n$:

$$\underline{u_t} + \frac{\Delta t}{2} u_{tt} + \mathcal{O}(\Delta t^2)$$

$$= \underline{\theta u_{xx}} + \underline{\theta \Delta t u_{tt}}$$

$$+ \underline{(1-\theta)u_{xx}} + \mathcal{O}(\Delta x^2 + \Delta t^2)$$

$$+ \frac{d_j^n}{\Delta t}$$

$$u_e = u_{xx} \quad \text{so}$$

$$\frac{u_j^n}{\Delta t} = \Delta t \left(\frac{1}{2} - \theta \right) u_{tt}$$

$$+ O(\Delta x^2 + \Delta t^2)$$

$$u_j^n = \begin{cases} O(\Delta t \cdot (\Delta x^2 + \Delta t^2)), & \theta = \frac{1}{2} \\ O(\Delta t \cdot (\Delta x^2 + \Delta t)), & \theta \neq \frac{1}{2} \end{cases}$$

FEM for parabolic PDEs

Ansatz:

$$u_h(x,t) = \sum_{k=1}^{N-1} u_k(t) \phi_k(x)$$

Galerkin principle for
fixed t :

Find $\{u_k(t)\}$ such that

$$(*) \int_a^b r_h(x,t) \phi_\ell(x) dx = 0$$

$$\ell = 1, \dots, N-1$$

Insert $r_h(x,t) = \frac{\partial}{\partial t} u_h(x,t)$

$$-\partial_{xx} u_h(x,t) - f(x,t)$$

and ansatz $u_n(x, t)$ in (*)

$$\int_a^b \left(\sum_{k=1}^{N-1} u_k'(t) \phi_k(x) - \sum_{k=1}^{N-1} u_k(t) \phi_k''(x) \right.$$

$$- f(x, t) \left. \phi_\ell(x) \right) dx =$$

$$\sum_{k=1}^{N-1} u_k'(t) \int_a^b \phi_k(x) \phi_\ell(x) dx$$

$$- \sum_{k=1}^{N-1} u_k(t) \int_a^b \phi_k''(x) \phi_\ell(x) dx$$

Integration by
parts, boundary

terms vanish

because $\phi_k(a) =$

$$- \int_a^b f(x, t) \phi_\ell(x) dx$$

$$= \sum_{k=1}^{N-1} u_k(t) \int_a^b \phi_k(x) \phi_\ell(x) dx$$

$\phi_\ell(b) = 0$

$m_{\ell, k}$ - elements
in mass matrix

$$+ \sum_{k=1}^{N-1} u_k(t) \int_a^b \phi'_k(x) \phi'_\ell(x) dx$$

$- a_{\ell, k}$ - elements
in stiffness matrix

$$- \int_a^b f(x, t) \phi_\ell(x) dx$$

$f_\ell(t)$

$$\sum_{k=1}^{N-1} u_k^l m_{l,k} = u_1^l m_{l,1} + u_2^l m_{l,2}$$

$$+ \dots u_{N-1}^l m_{l,N-1}$$

row l in M
multiplied
with $\frac{du}{dt}$

$$M \frac{d\bar{u}}{dt} = \begin{bmatrix} m_{11} & m_{12} & m_{13} & \dots & m_{1,N-1} \\ m_{21} & m_{22} & - & - & - \\ m_{N-1,1} & - & - & - & - \end{bmatrix} \begin{bmatrix} u_1^l \\ u_2^l \\ \vdots \\ u_{N-1}^l \end{bmatrix}$$

Wave equation

$$\underbrace{\begin{pmatrix} u_{tt} \\ u_{xt} \end{pmatrix}}_{\bar{U}_t} - \begin{pmatrix} 0 & c^2 \\ 1 & 0 \end{pmatrix} \underbrace{\begin{pmatrix} u_{xt} \\ u_{xx} \end{pmatrix}}_{\bar{U}_x} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\bar{U} = \begin{pmatrix} u_t \\ u_x \end{pmatrix}$$

Eigenvalues:

$$\det(2I - A) = \begin{vmatrix} \lambda - c^2 & \\ -1 & \lambda \end{vmatrix}$$

$$= \lambda^2 - c^2 = 0, \lambda_{1,2} = \pm c$$