Slot-queue - An optimized wait-free distributed MPSC

1. Motivation

A good example of a wait-free MPSC has been presented in [1]. In this paper, the authors propose a novel tree-structure and a min-timestamp scheme that allow both enqueue and dequeue to be wait-free and always complete in $\Theta(\log n)$ where n is the number of enqueuers.

We have tried to port this algorithm to distributed context using MPI. The most problematic issue was that the original algorithm uses load-link/ store-conditional (LL/SC). To adapt to MPI, we have to propose some modification to the original algorithm to make it use only compare-and-swap (CAS). Even though the resulting algorithm pretty much preserve the original algorithm's characteristic, that is wait-freedom and time complexity of $\Theta(\log n)$, we have to be aware that this is $\Theta(\log n)$ remote operations, which is very expensive. We have estimated that for an enqueue or a dequeue operation in our initial LTQueue version, there are about $2 * \log n$ to $10 * \log n$ remote operations, depending on data placements and the current state of the LTQueue.

Therefore, to be more suitable for distributed context, we propose a new algorithm that's inspired by LTQueue, in which both enqueue and dequeue only perform a constant number of remote operations, at the cost of dequeue having to perform $\Theta(n)$ local operations, where n is the number of enqueuers. Because remote operations are much more expensive, this might be a worthy tradeoff.

2. Structure

Each enqueue will have a local SPSC as in LTQueue [1] that supports dequeue, enqueue and readFront. There's a global queue whose entries store the minimum timestamp of the corresponding enqueuer's local SPSC.

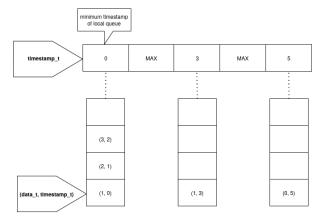


Figure 1: Basic structure of slot queue

3. Pseudocode

3.1. **SPSC**

The SPSC of [1] is kept in tact, except that we change it into a circular buffer implementation.

Types

```
data_t = The type of data stored
spsc_t = The type of the local SPSC
    record
    First: int
    Last: int
    Capacity: int
    Data: an array of data_t of capacity
    Capacity
    end
```

Shared variables

First: index of the first undequeued entry Last: index of the first unenqueued entry

Initialization

```
First = Last = 0
Set Capacity and allocate array.
```

The procedures are given as follows.

Procedure 1: spsc_enqueue(v: data_t) returns bool

- 1 if (Last + 1 == First)
 2 | return false
- 3 Data[Last] = v
- 4 Last = (Last + 1) % Capacity
- 5 return true

Procedure 2: spsc_dequeue() returns data_t

- 6 **if** (First == Last) **return** \perp
- 7 res = Data[First]
- 8 First = (First + 1) % Capacity
- 9 return res

Procedure 3: spsc readFront returns data t

- 10 if (First == Last)
- 11 | return \perp
- 12 return Data[First]

3.2. Slot-queue

The slot-queue types and structures are given as follows:

Types

data_t = The type of data stored
timestamp_t = uint64_t
spsc_t = The type of the local SPSC

Shared variables

slots: An array of timestamp_t with the number of entries equal the number of enqueuers spscs: An array of spsc_t with the number of entries equal the number of enqueuers counter: uint64_t

Initialization

| Initialize all local SPSCs.

Initialize slots entries to MAX.

The enqueue operations are given as follows:

Procedure 4: enqueue(rank: int, v: data_t)
returns bool

- 1 timestamp = FAA(counter)
- 2 value = (v, timestamp)
- 3 res = spsc_enqueue(spscs[rank], value)
- 4 if (!res) return false
- 5 if (!refreshEnqueue(rank, timestamp))
- 6 | refreshEnqueue(rank, timestamp)
- 7 return res

Procedure 5: refreshEnqueue(rank: int, ts:
timestamp_t) returns bool

- 8 old-timestamp = slots[rank]
- 9 front = spsc readFront(spscs[rank])
- new-timestamp = front == \(\perp \) ? MAX :
 front.timestamp
- 11 if (new-timestamp != ts)
- 12 | return true
- return CAS(&slots[rank], old-timestamp,
 new-timestamp)

The dequeue operations are given as follows:

Procedure 6: dequeue() returns data_t

- 14 rank = readMinimumRank()
- 15 if (rank == DUMMY || slots[rank] == MAX)
- 16 | return ⊥
- 17 res = spsc_dequeue(spscs[rank])
- 18 **if** (res == \perp) **return** \perp
- 19 if (!refreshDequeue(rank))
- 20 | refreshDequeue(rank)
- 21 return res

Procedure 7: readMinimumRank() returns int

```
22 rank = length(slots)
23 min-timestamp = MAX
24 for index in 0..length(slots)
     timestamp = slots[index]
25
     if (min-timestamp < timestamp)</pre>
26
       rank = index
2.7
28
       min-timestamp = timestamp
29 \text{ old-rank} = \text{rank}
30 for index in 0..old-rank
     timestamp = slots[index]
31
32
     \mathbf{if} (min-timestamp < timestamp)
        rank = index
33
       min-timestamp = timestamp
  return rank == length(slots) ? DUMMY :
35
   rank
```

Procedure 8: refreshDequeue(rank: int) returns bool

36 old-timestamp = slots[rank]

4. Linearizability of the local SPSC

In this section, we prove that the local SPSC is linearizable.

Lemma 4.1 (*Linearizability of spsc_enqueue*) The linearization point of spsc_enqueue is right after line 2 or right after line 4.

Lemma 4.2 (*Linearizability of spsc_dequeue*) The linearization point of spsc_dequeue is right after line 6 or right after line 8.

Lemma 4.3 (*Linearizability of spsc_readFront*) The linearization point spsc_readFront is right after line 11 or right after line 12.

Theorem 4.4 (*Linearizability of local SPSC*) The local SPSC is linearizable.

Proof This directly follows from Lemma 4.1, Lemma 4.2, Lemma 4.3. □

5. ABA problem

Noticeably, we use no scheme to avoid ABA problem in Slot-queue. In actuality, ABA problem does not adversely affect our algorithm's correctness, except in the extreme case that the 64-bit global counter overflows, which is unlikely.

5.1. ABA-safety

Not every ABA problem is unsafe. We formalize in this section which ABA problem is safe and which is not.

Definition 5.1.1 A **CAS-sequence** on a variable v is a sequence of instructions that:

- Starts with a load $v_0 = load(v)$.
- Ends with a CAS (& v_0 , v_0 , v_1).

Definition 5.1.2 A **successful CAS-sequence** on a variable v is a **CAS-sequence** on v that ends with a successful CAS.

Definition 5.1.3 A **modification instruction** on a variable v is an atomic instruction that may change the value of v e.g. a store or a CAS.

Definition 5.1.4 A successful modification instruction on a variable v is an atomic instruction that changes the value of v e.g. a store or a successful CAS.

Definition 5.1.5 A **history** of successful **CAS**-sequences and **modification instructions** is a timeline of when any **CAS**-sequences start/end and when any modification instructions end.

We can define a strict partial order < on the set of **CAS-sequences** and **modification instructions** such that:

- A < B if A and B are both CAS-sequences and A ends before B starts.
- A < B if A and B are modification instructions and A ends before B ends.
- A < B if A is a modification instruction, B is a CAS-sequence and A ends before B starts.
- B < A if A is a modification instruction, B is a CAS-sequence and A ends after B ends.

Definition 5.1.6 Consider a history of successful **CAS-sequences** and **modification instructions** on the same variable v. **ABA problem** is said to have occurred with v if there exists a **successful CAS-sequence** on v, during which there's some **successful modification instruction** on v.

CAS-sequences and **modification instructions** on the same variable v. A history is said to be **ABA-safe** with v if and only if:

- **ABA problem** does not occur with v in the history.
- We can reorder the successful CAS-sequences and modification instructions in the history such that:
 - ► No two successful CAS-sequences overlap with each other.
 - No modification instruction lies within another successful CAS-sequence.
 - ► The resulting history after reordering produces the same output as the original history.

5.2. Proof of ABA-safety

Notice that we only use CAS on:

- Line 13 of refreshEnqueue (Procedure 5), or an enqueue in general (Procedure 4).
- Line 42 of refreshDequeue (Procedure 8) or a dequeue in general (Procedure 6).

Both CAS target some slot in the slots array.

We apply some domain knowledge of our algorithm to the above formalism.

Definition 5.2.1 A **CAS-sequence** of an enqueue is the sequence of instructions from line 8 to line 13 of its refreshEngueue.

Definition 5.2.2 A **slot-modification instruction** of an enqueue is line 13 of refreshEnqueue.

Definition 5.2.3 A **CAS-sequence** of a dequeue is the sequence of instructions from line 36 to line 42 of its refreshDequeue.

Definition 5.2.4 A **CAS-sequence** is said to **observes a slot value s** if it loads s at line 8 of refreshEnqueue or line 36 of refreshDequeue.

Definition 5.2.5 A **slot-modification instruction** of a dequeue is line 40 or line 42 of refreshDequeue.

We can now turn to our interested problem in this section.

Lemma 5.2.1 (Concurrent accesses on a local SPSC and a slot) Only one dequeuer and one enqueuer can concurrently modify a local SPSC and a slot in the slots array.

Proof This is trivial to prove based on the algorithm's definition. \Box

Lemma 5.2.2 (Monotonicity of local SPSC timestamps) Each local SPSC in Slot-queue contains elements with increasing timestamps.

Proof Each enqueue would FAA the global counter (line 1 in Procedure 4) and enqueue into the local SPSC an item with the timestamp obtained from the counter. Applying Lemma 5.2.1, we know that items are enqueued one at a time into the SPSC. Therefore, later items are enqueued by later enqueues, which obtain increasing values by FAA-ing the shared counter. The theorem holds.

Lemma 5.2.3 A refreshEnqueue (Procedure 5) can only changes a slot to a value other than MAX.

Proof For refreshEnqueue to change the slot's value, the condition on line 11 must be false. Then new-timestamp must equal to ts, which is not MAX.

It's obvious that the CAS on line 13 changes the sl	ot
to a value other than MAX.	
Theorem 5.2.4 (No ABA problem in dequeue)	
Proof	
Theorem 5.2.5 (No ABA problem in enqueue)	
Proof	
Theorem 5.2.6 (No ABA problem) Assume the 64-bit global counter never overflows, there no ABA problem in Slot-queue.	
Proof This follows from Theorem 5.2.5 ar Theorem 5.2.4.	ıd

6. Linearizability of Slot-queue

7. Wait-freedom

8. Memory-safety

References

[1] P. Jayanti and S. Petrovic, "Logarithmic-time single deleter, multiple inserter wait-free queues and stacks," 2005, *Springer-Verlag*. doi: 10.1007/11590156_33.