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Chapter 1

Decomposition of graphs

1.1 Problem 3.7

(a) We use DFS as follows:

```
boolean bipartite = true
check_bipartite:
  for all v in V:
    v.visited = false
    v.color = 0
  for all v in V:
    if v.visited == false:
      explore(v)
  return bipartite

explore(v):
  v.visited = true
  for all u adjacent to v:
    if u.visited == false:
      u.color = !v.color
      explore(u)
    else if u.color == v.color:
      bipartite = false
```

- (b) If the undirected graph $G = (V, E)$ is bipartite then all vertices in V belong to one of the two sets V_1 or V_2 . Every edge leads from one set to the other. So if we have a cycle that starts and ends in V_1 , its length must be an even number. Therefore if G is bipartite it has no odd cycle. Now suppose G has no odd cycle. For each connected component C of G , let v_0 be a random vertex in C . For any vertex v in C , color v red if the shortest path from v_0 to v has even length, and black if the shortest path from v_0 to v has odd length. If there is an edge between two vertices with the same color, say u and v , then G has an odd cycle ($v_0 \rightarrow v \rightarrow u \rightarrow v_0$). Therefore if G has no odd cycle then there is no edge connecting any two vertices with the same color. The set of vertices with red color and the set of those with blue colors are two disjoint sets that make G bipartite.
- (c) 3 colors. Use DFS and color the vertices in red or blue like part a. When an edge connecting two vertices of the same color is encountered (there is exactly one such edge), change the color of either of the two to yellow.

1.2 Problem 3.8

Create a directed graph G as follows:

- Each vertex stores a tuple (a, b, c) , where a, b, c are the amount of water currently in the 10-pint, 7-pint and 4-pint containers respectively.
- There is an edge from u to v iff we can pour water from one container to another in u to get v .

We start with the root vertex $r = (0, 7, 4)$, and keep creating new child nodes to represent all possible states of the 3 containers. If a vertex whose value has the form $(x, y, 2)$ or $(x, 2, y)$ is encountered, return true. Else return false.

1.3 Problem 3.9

```

for all v in V:
    v.degree = 0
for all v in V:
    for all u adjacent to v:
        v.degree ++
for all v in V:
    twodegree[v] = 0
    for all u adjacent to v:
        twodegree[v] += u.degree

```

1.4 Problem 3.11

Let $e = (u, v)$. Remove e from the graph and run DFS on u . If v is marked as visited, then there is a cycle containing e . Otherwise there isn't.

1.5 Problem 3.12

False. $\{u, v\}$ can be a cross edge.

1.6 Problem 3.13

- (a) We prove that a tree always has a leaf. Let the vertices in the tree be v_1, v_2, \dots, v_n and let $d(i)$ be the degree of vertex i . Then we have

$$\sum_{i=1}^n d(i) = 2|E| = 2(n-1).$$

If there is no leaf then $d(i) \geq 2 \forall i \Rightarrow 2(n-1) = \sum_{i=1}^n d(i) \geq 2n$. This is a contradiction.

Now we consider the DFS tree of the graph. The node to remove is one of its leaves.

- (b) Consider $\triangle ABC$ with edges $\overrightarrow{AB}, \overrightarrow{BC}, \overrightarrow{CA}$.
- (c) Graph consists of vertex A and B with no edge.

1.7 Problem 3.15

- (a) Consider a graph where each intersection in the city is a vertex and there is an edge from u to v if one can go along some one-way streets from u to reach v . Break down the graph into its SCCs and check if the number of SCCs is 1. If it is, the claim is true; otherwise it's false.
- (b) We want to see if given a specific vertex T , is it true that for every other vertex v , if v is reachable from t then t is reachable from v . Break down the graph into its SCCs. Check that there is no outgoing edge from the SCC that contains T .

1.8 Problem 3.16

Each vertex has a property `sem`, which indicates the minimum number of semester required to reach it and finish it. First linearize the dag so we get the course order $c[1], c[2], \dots, c[n]$. Then traverse the edges according to this order:

```
for i = 1 to n:
    for v adjacent to c[i]:
        v.sem = max {v.sem, c[i].sem + 1}
```

The max `sem` among all vertices is the minimum number of semesters required.

1.9 Problem 3.17

Use DFS on the root node to update the preorder and postorder of all vertices. u is an ancestor of v if and only if

$$pre(u) < pre(v) < post(v) < post(u).$$

1.10 Problem 3.19

We use DFS as follows:

```
dfs:
    for all v in V:
        v.visited = false
        z[v] = x[v]
        explore(root)

explore(v):
    v.visited = true
    for all u adjacent to v:
        if u.visited == false:
            explore(u)
            z[v] = max{ x[v], z[u]}
```

1.11 Problem 3.21

A graph G has an odd-length directed cycle if and only if one (or more) of its SCCs is nonbipartite (when treated as an undirected graph):

- An odd-length directed cycle must belong to a SCC C . When it is treated as an undirected graph, the cycle becomes an odd-length undirected cycle. Therefore C is nonbipartite in undirected mode.

- Suppose a SCC C is nonbipartite (when treated as undirected). So there is an odd-length, undirected cycle in C . Now if this is also a directed cycle, we are done. Otherwise, if edge connecting v and w is pointing in the wrong direction (i.e. we have $\overrightarrow{(w,v)}$ while we want $\overrightarrow{(v,w)}$), we can replace it with an odd-length path pointing in the opposite direction. Note that there exists a directed path P from v to w because v and w belong to the same SCC. If P has odd length, replace the edge $\overrightarrow{(w,v)}$ with P . If P has even length, then P combined with $\overrightarrow{(w,v)}$ is an odd cycle.

Chapter 2

Distance in graph

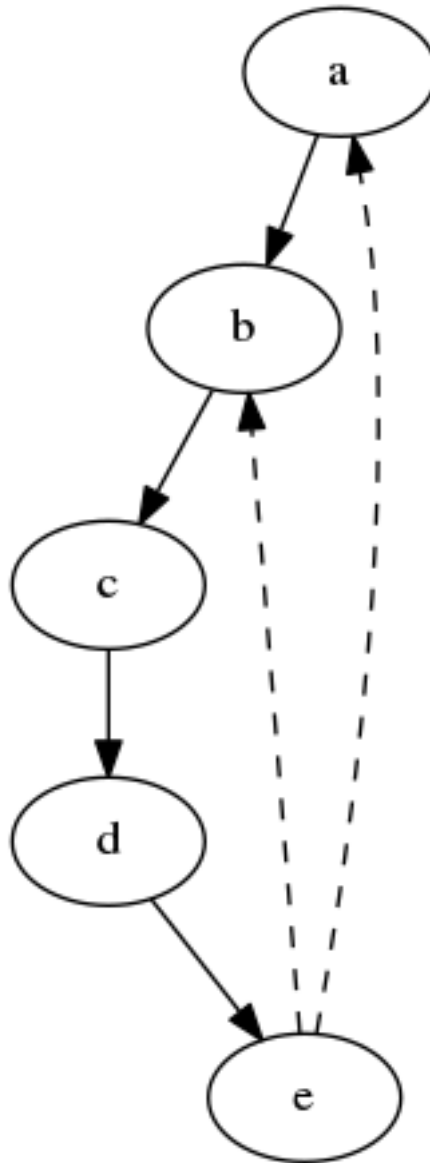
2.1 Problem 4.3

Modify the breadth first search algorithm as follows. Here each node has a property `dist`, the length of the shortest path from the source node to it, and a property `n`, the number of shortest paths from the source node to it. We update both as we visit each node. If we find a node whose `dist = n = 2` then there exists a cycle of length 4.

```
bfsModified(Node u):
    For all node v:
        v.dist = INFINITY
        v.n = 0
    u.dist = 0
    H = makeQueue(u)
    while H is not empty:
        Node s = h.poll()
        for all node v adjacent to s:
            if v.dist == INFINITY:
                v.n ++
                v.dist = s.dist + 1
                H.add(v)
            else:
                if s.dist + 1 == v.dist:
                    // found another shortest path from u to v
                    v.n ++
                if v.n == 2 && v.dist == 2:
                    // found a simple cycle of four
                    return TRUE
    return FALSE
```

We call `bfsModified` on all vertices in the graph. The complexity is therefore $O(|V|(|E| + |V|)) = O(|V|^3)$ because $|E| = O(|V|^2)$.

2.2 Problem 4.4



In the above tree, the cycle edges are EB and EA . EB will give $\text{level}[E] - \text{level}[B] + 1 = 4 - 1 + 1 = 4$, while EA will give $\text{level}[E] - \text{level}[A] + 1 = 4 - 0 + 1 = 5$. The shortest cycle, however, is ABE with length 3.

The reason is that dfs can only detect all back edges but not all cycles; a back edge might belong to more than one cycle.

2.3 Problem 4.5

Use the `bfsModified` algorithm from 4.3:

```
bfs_modified(Node u, Node target):  
    For all node v:  
        v.dist = INFINITY  
        v.n = 0  
    u.dist = 0  
    H = makeQueue(u)  
    while H is not empty:  
        Node s = h.poll()  
        for all node v adjacent to s:
```



```

if v.dist = INFINITY:
    // first time v is discovered, set number of shortest path to 1
    v.n ++
    v.dist = s.dist + 1
    H.add(v)
else:
    if s.dist + 1 == v.dist:
        // found another shortest path from u to v
        v.n ++
return target.n

```

2.4 Problem 4.6

Consider the directed graph G' formed by taking all the edges $\overrightarrow{(u, \text{prev}[u])}$. We note that the `prev` array is set in Dijkstra when

```

s = H.remove()
for v adjacent to s:
    if v.dist > s.dist + l(v,s):
        v.dist = s.dist + l(v,s)
        prev[v] = s

```

In other words, if we have an edge $\overrightarrow{(a, b)}$ in G , then $b = \text{prev}[a]$ so $b.\text{dist} > a.\text{dist}$. So if there is a path from a node a to a node c then $c.\text{dist} > a.\text{dist}$. If there is a cycle then there is an edge from a node c to a node a while there is also a path from a to c . The former implies $a.\text{dist} > c.\text{dist}$ while the latter implies $c.\text{dist} > a.\text{dist}$, so we have a contradiction.

2.5 Problem 4.7

First get the shortest path distance of all vertices using only the edges in E' . Now remove all the edges in E' . We are left with the graph $G'(V, E - E')$. Run `update` on all edges in E' :

```

update(e = (u,v)){
    v.dist = min { v.dist, u.dist + w(e) }
}

```

If any vertex has its `dist` changed, then the `dist` we obtained from T is not correct, so T is not the shortest path tree and we return false. Otherwise, all `dist`s are correct so we return true.

2.6 Problem 4.8

Dijkstra's algorithm only cares about the weight of the paths, not their lengths. Adding a constant to the weight of each edge will change the graph, because two paths that previously had same weights but different lengths will not have different weights.

Example: Consider $\triangle ABC$ where $AB = -2, BC = 2, CA = 1$. The shortest path from A to C is $A \rightarrow B \rightarrow C$. If we add 2 to each edge weight, $AB = 0, BC = 4, CA = 3$ so the shortest path from A to C is now AC .

2.7 Problem 4.9

Let U be the set of edges connecting to S . Add a large constant to all edges in U so that they all become positive. Since any shortest path from S to any vertex includes exactly one edge in U , the relative weight of the shortest paths remain the same, so Dijkstra's algorithm still works.

2.8 Problem 4.10

Run a modified version of Bellman-ford. Because we know no path can have more than k edges, the loop only needs to execute k times, not $|V| - 1$ times. The runtime is therefore $O(k|E|)$.

2.9 Problem 4.11

Use Dijkstra's algorithm to find the shortest cycle going through a given node n : After we get the `dist` of all nodes from n , find

$$\min_{u:n \in u.\text{adj}} \{u.\text{dist} + w(u, s)\}.$$

Call the method on all nodes and find the min of the return values. Dijkstra takes $O(|V|^2)$ and is called $|V|$ times, so the runtime is $O(|V|^3)$.

2.10 Problem 4.12

The length of the shortest cycle containing $e = (u, v)$ is the sum of $w(e)$ and the shortest path from u to v .

Remove the edge $e = (u, v)$ from the graph and call Dijkstra's on u . The result is $v.\text{dist} + w(e)$.

2.11 Problem 4.13

- (a) Iterate through E and remove all edges whose lengths are larger than L . Then call bfs on s and see if t can be reached.
- (b) We use a modified version of Dijkstra's algorithm. Here `u.dist` is the maximum edge weight on the path from s to u .

```
dijkstra(s):
  for all v in V:
    v.prev = null
    v.dist = INFINITY
  s.dist = 0
  H = makeQueue(V)
  while H is not empty:
    u = H.remove()
    for all v adjacent to u:
      if v.dist > max{u.dist, w(u,v)}:
        v.dist = max{u.dist, w(u,v)}
        v.prev = u
```

2.12 Problem 4.14

For all $u, v \in V$ we need to find $d(u, v_0) + d(v_0, v)$.

Run Dijkstra's algorithm on v_0 we can find $d(v_0, v)$ for all $v \in V$.

Consider the reverse graph $G'(V, E')$ such that there is an edge from u to v in G if and only if there is an edge from v to u in G' . Run Dijkstra's algorithm on v_0 in G' we get $d'(v_0, u)$ for all $u \in V$, which is also $d(u, v_0)$ in the original graph.

2.13 Problem 4.15

Keep a property `count` in each node u , which indicates the number of shortest paths from s to u . We modify Dijkstra's algorithm as follows:

```
dijkstra(s):
    for all v in V:
        v.prev = null
        v.dist = INFINITY
        v.count = 0
    s.dist = 0
    s.count = 1
    H = makeQueue(V)
    while H is not empty:
        u = H.remove()
        for all v adjacent to u:
            if v.count == 0:
                // first time v is visited
                v.count ++
            if v.dist > u.dist + w(u,v):
                v.dist = u.dist + w(u,v)
                v.prev = u
            else if v.dist == u.dist + w(u,v):
                // found another shortest path
                v.count ++
```

Then, for all $u \in V$, `usp[u] = (u.count == 1)`.

2.14 Problem 4.17

[See link](#)

2.15 Problem 4.18

Keep a property `count` in each node u , which indicates the minimum number of edges in any shortest path from s to u . We modify Dijkstra's algorithm as follows:

```
dijkstra(s):
    for all v in V:
        v.prev = null
        v.dist = INFINITY
    s.dist = 0
    s.count = 0
    H = makeQueue(V)
    while H is not empty:
        u = H.remove()
        for all v adjacent to u:
            if v.dist > u.dist + w(u,v):
                v.dist = u.dist + w(u,v)
```

```

v.prev = u
v.count = u.count + 1
else if v.dist == u.dist + w(u,v):
    // found another shortest path
    if v.count > u.count + 1:
        v.count = u.count + 1
        v.prev = u

```

2.16 Problem 4.19

Update the weight of all edges as follows:

- For all edge e coming from s : $w(e) = w(e) + cost[s]$.
- For all edge $e = \overrightarrow{(u, v)}$: $w(e) = w(e) + cost[v]$.

Then disregard the costs of the vertices (because we have moved them to the edges) and run Dijkstra's algorithm on s .

2.17 Problem 4.20

The algorithm is as follows:

- Run Dijkstra's algorithm on s and t . Because the graph is undirected, we get

$$d(s, u), d(u, s), d(t, u), d(u, t)$$

for all $t \in V$. Let $d(s, t) = M$.

- For each edge $e = (u, v) \in E'$, calculate the length of the shortest path from s to t that includes e . This number is

$$f(e) = \min\{d(s, u) + w(e) + d(v, t), d(s, v) + w(e) + d(u, t)\}.$$

- Compare $f(e)$ to M and update $M = \min\{M, f(e)\}$.

2.18 Problem 4.21

(a) Create a currency trading graph $G(V, E)$:

- For each currency i there is a node $v_i \in V$.
- For all $u, v \in V (u \neq v)$ there is an edge from u to v .
- For all $v_i, v_j \in V$: $w(v_i, v_j) = \log \frac{1}{r_{i,j}} = -\log r_{i,j}$.

Therefore if $d = w(i, j)$ then one unit of c_i can be converted into 2^d units of c_j . The best way to convert from s to t is the shortest path from node v_s to v_t in G , which can be found by Bellman-Ford's algorithm.

(b) The existence of an anomaly implies that

$$r_{i_1, i_2} \cdot r_{i_2, i_3} \cdot \dots \cdot r_{i_k, i_1} > 1,$$

which is equivalent to

$$\log \frac{1}{r_{i_1, i_2}} + \log \frac{1}{r_{i_2, i_3}} + \dots + \log \frac{1}{r_{i_k, i_1}} < 0.$$

In other words,

$$w(v_{i_1}, v_{i_2}) + w(v_{i_2}, v_{i_3}) + \dots + w(v_{i_k}, v_{i_1}) < 0,$$

So we have a negative cycle $i_1 \rightarrow i_2 \rightarrow i_3 \rightarrow \dots \rightarrow i_k \rightarrow i_1$.

To detect if a negative cycle exists, use Bellman-Ford's algorithm. If it returns YES, there is an anomaly. Otherwise, there isn't.

Chapter 3

Greedy algorithm

3.1 Problem 5.3

Run DFS on the graph to detect a cycle edge. Return YES as soon as a cycle edge is found. Else, if there is no cycle edge, return NO.

This algorithm has $O(|V|)$ runtime because we note that G is either a tree (in which case $|E| = |V| - 1$) or it is not (in which case $|E| > |V| - 1$).

- If G is a tree then we will not be able to detect any back edge. DFS will traverse the entire graph, which takes $O(|V| + |E|)$, but because $|E| = |V| - 1$, this is $O(|V|)$.
- If G is not a tree then we can find a back edge after traversing at most $|V|$ edges because the edges picked by DFS form a tree, and any tree in the original graph can have at most $|V|$ vertices.

3.2 Problem 5.4

We note that a connected component with m vertices must have at least $m - 1$ edges¹.

Let the number of vertices in component i be m_i , $i = 1, 2, \dots, k$. We have $\sum_{i=1}^k m_i = n$.

The number of edges in the graph is the total number of edges in all components, which is at least

$$\sum_{i=1}^k (m_i - 1) = n - k.$$

3.3 Problem 5.5

- (a) We follow Kruskal's algorithm to build the minimum spanning tree: at each step, pick the edge with the least weight that does not create a cycle. Because all edge weights are increased by 1, the weight of any edge relative to all other edges is the same, so Kruskal's will produce the same result.
- (b) The shortest path will change. Consider the quadrilateral $ABCD$ with

$$AB = BC = CD = 2, AD = 7.$$

Currently the shortest path from A to D is $A \rightarrow B \rightarrow C \rightarrow D$. If we increase the weight of all edges by 1 then $AB = BC = CD = 3, DA = 8$, so the shortest path from A to D is $A \rightarrow D$.

¹since the component is connected, we can build a minimum spanning tree in it; this tree has m vertices and $m - 1$ edges, so the number of edges in the component must be at least $m - 1$.

3.4 Problem 5.6

Sort the edge by their weights

$$e_1 < e_2 < \dots < e_n.$$

Kruskal's algorithm will iterate n times and, at time i , pick edge e_i , or the i -th smallest edge in the graph. Because the edge weights are distinct, the i -th smallest edge in the graph is distinct for all $1 \leq i \leq n$. Therefore the minimum spanning tree is unique.

3.5 Problem 5.7

Negate all the edge weights in the input graph and use Kruskal's algorithm to find the minimum spanning tree in the new graph. This tree is the maximum spanning tree in the original graph.

3.6 Problem 5.8

We use Prim's algorithm to build a minimum spanning tree in G .

Start building the MST from a vertex that is not S . Now assume we have reached the step where we have the tree current tree T and we are about to add S to $T(V)$. In other words, the next edge to be added to $T(E)$ is the edge SA connecting S to a vertex $A \in T(V)$, which means SA is the lightest edge that connects T a vertex outside of T . (*)

We prove that SA is also the shortest path from S to A and therefore T and the tree of shortest paths from S share the same edge SA .

Assume otherwise, the shortest path from S to A is not SA . Then there exists a vertex $B \neq A$ such that the shortest path from S to A consists of the shortest path from S to B and BA . So

$$d(S, B) + BA < SA.$$

We consider two cases:

- If $B \notin T(V)$ then because $BA < SA$, SA is not the lightest edge that connects T to a vertex outside of it.
- If $B \in T(V)$, call I and K two vertices on the path from S to B such that $I \in T(V)$, $K \notin T(V)$ (I can be B and K can be S). Then $SA > d(S, B) = d(S, K) + IK + d(I, B) \geq IK$, so again SA is not the lightest edge.

Both cases contradict (*). Thus we have proven that the minimum spanning tree and the tree of shortest paths from a vertex S always share an edge.

3.7 Problem 5.10

Start with a MST $T_H \in MST_H$ and $T_G \in MST_G$.

While there is an edge $e \in T_G \cap H$ such that $e \notin T_H$ do:

1. Add e to T_H to create a cycle C .
2. We see that for all $e' \in C$, $e' \neq e$ we have $w(e') \leq w(e)$. Otherwise if $w(e') > w(e)$ we should have picked e , not e' when building the MST T_H , according to Kruskal's algorithm.
3. Let $e = (u, v)$, so $u, v \in H$. We see that $e \in T_G$ so it connects two previously separate connected components, which we call U and V , and assume that $u \in U$, $v \in V$. Because u and v are in H and T_H is the MST of H , there exists an edge $e'' \in C \cap T_H$ that connects U and V .

4. From Step 2 we get $w(e'') \leq w(e)$. If $w(e'') < w(e)$ then when we built T_G we should have picked e'' instead of e to connect U and V . Therefore $w(e'') = w(e)$.
5. Let $T'_H = T_H \cup \{e\} - \{e''\}$ then T'_H is also a MST in H .
6. Rename $T'_H \rightarrow T_H$ and check the loop condition.

After the loop we have $T_G \cap H \subset T_H$.

3.8 Problem 5.16

[See link](#)

3.9 Problem 5.20

Perfect matching.

Let $G(V, E)$ be the input graph, S be the queue that contains all leaf nodes and M be the perfect matching.

The algorithm is as follows:

```

all leaf nodes to S.
while S is not empty:
    u = S.pop()
    v = u.adjacent
    M.add((u,v))
    Remove u, v from V and all edges connected to v from E
    Add new leaf nodes to S
return |V| = 0

```

Feedback edge set.

Let F be the feedback edge set. Negate all the edges in G to get a graph G' . Use Kruskal's algorithm to build a minimum spanning tree T in G' . At each step, after we pop an edge e , if adding e to T does not form a cycle, then add e to T , else add e to F . As we go back to the original graph, T is the maximum spanning tree and F is the feedback set edge with minimum weight.

3.10 Problem 5.21

- (a) If no MST contain e , we are done. If **there is a MST T that contains e** , removing e from T will separate it into two connected components M and N . Since e is part of a cycle, there exists another edge e' that connects M and N . Then $T \cup \{e'\} - \{e\}$ is also a MST with $w(T') \leq w(T)$.
 - If $w(T') < w(T)$ then we have a contradiction because T is a MST, so no MST can contain e .
 - If $w(T') = w(T)$ then e and e' are both the heaviest edges in the cycle. T contains e and not e' , while T' contains e' and not e . In other words, there is a MST that does not contain the heaviest edge in a cycle.
- (b) If we get an edge e that is part of a cycle, then because the edges are ordered in decreasing weights, e is the heaviest edge in that cycle. By the property in (a), e cannot belong a MST. Therefore we can remove it.
- (c) To check if an edge e belongs to a cycle:
 - Let $e = (u, v)$.

- Remove e from the graph and DFS on u .
 - If v can be reached, return YES. Else, return NO.
- (d) The loop executes $E - (|V| - 1)$ times because that is the number of edges we need to remove to get a MST with $|V|$ vertices and $|V| - 1$ edges. Each iteration takes $O(|V| + |E|)$ times because of DFS. Therefore the total runtime is

$$O((|V| + |E|) \cdot (|E| - |V| + 1)).$$

3.11 Problem 5.23

The algorithm can be described as follows:

- Let E' be the set of all edges that touch a vertex in U .
- Build a MST T in $G'(V - U, E - E')$.
- For each node u in U , add the lightest edge that connects u and T to T .
- Return T .

3.12 Problem 5.29

[See link](#)

Chapter 4

Dynamic programming

4.1 Problem 6.2

Let $b[i]$ be the minimum total penalty for stopping at hotel a_i , $1 \leq i \leq n$. We have

$$b[i] = \min_{1 \leq j < i} \{b[j] + (200 - (a[i] - a[j]))^2\}.$$

Also record the value j which yields $\min_{1 \leq j < i} \{b[j] + (200 - (a[i] - a[j]))^2\}$ and set $b[i].prev = b[j]$. Backtrack from $b[n]$ to get the sequence of hotels to stop by.

4.2 Problem 6.3

Let $S[i]$ be the maximum total profit we get from building some restaurants in $\{m_1, m_2, \dots, m_i\}$. Consider 2 cases:

- (1) If restaurant m_i should not be built, then $S[i] = S[i - 1]$.
- (2) If restaurant m_i should be built, then let c_i be the maximum index j which yields $m_i - m_j \geq k$. We then have $S[i] = p_i + S[c_i]$.

Therefore in general,

$$S[i] = \max\{S[i - 1], p_i + S[c_i]\}.$$

To get the sequence of restaurants, keep an array $R[n]$ such that $R[i] = 1$ if restaurant i is built in the optimal solution, and $R[i] = 0$ otherwise. When we calculate $S[i]$, if the max falls to case (1), $R[i] = 0$. Else, $R[i] = 1$. Output all the $R[i]$ s that are 1.

4.3 Problem 6.4

Consider an array $S[n]$ where $S[i] = \text{true}$ if the substring $s_1s_2 \dots s_i$ is a valid string, and false otherwise. We have $S[1] = \text{dict}(s[1])$ and

$$\begin{aligned} S[i] = & (S[1] \ \&\& \ \text{dict}(s[2 \dots i]) \\ & || (S[2] \ \&\& \ \text{dict}(s[3 \dots i]) \\ & || \dots \\ & || (S[i - 1] \ \&\& \ \text{dict}(s[i \dots i]))), \end{aligned}$$

where $s[j \dots i]$ is $s_js_{j+1} \dots s_i$.

4.4 Problem 6.5

- (a) Consider a column of 4 squares. There can be either 0 pebble, or 1 pebble (4 ways to place it), or 2 pebbles (either place it on square 1 and 3 or 2 and 4). Therefore there are a total of 7 patterns on a column.
- (b) Let $T[i, j]$ be the max sum we get from putting pebbles on the table from column 1 to i using the pattern j . Let $C(i, j)$ be the value we get when putting a pebble on square (i, j) . We have

$$T[i, j] = C(i, j) + \max\{T[i-1, j']\},$$

where $j' \in \{0, 1, \dots, 6\}$ and pattern j' is compatible with pattern j .

4.5 Problem 6.6

Let the input string be $x_1x_2\dots x_n$.

Let $Z = \{a, b, c\}$ and let $T[i, j] \subset Z$ be the set of the possible values that the product $x_i x_{i+1} \dots x_j$ can yield with all possible parenthesizations.

We see that $T[i, i] = x_i$ for all $1 \leq i \leq n$. We need to compute $T[1, n]$.

Define $A \times B$ as $\{a \cdot b \mid a \in A, b \in B\}$.

We note that

$$T[i, i+1] = T[i, i] \times T[i+1, i+1]$$

and

$$T[i, i+2] = (T[i, i] \times T[i+1, i+2]) \cup (T[i, i+1] \times T[i+2, i+2]).$$

(to put it another way, xyz can be written as $(x)(yz)$ or $(xy)(z)$)

We therefore see that we already have

$$T[1, 1], T[2, 2], T[3, 3], \dots,$$

from which we can calculate

$$T[1, 2], T[2, 3], T[3, 4], \dots,$$

from which we can calculate

$$T[1, 3], T[2, 4], T[3, 5], \dots$$

and eventually we can expand to $T[1, n]$, which is what we need to find.

In other words,

$$T[i, i+s] = \bigcup_{i \leq k < i+s} (T[i, k] \times T[k+1, i+s]).$$

The algorithm is as follows:

```

for i = 1 to n:
    T[i, i] = x[i].
for s = 1 to n-1:
    for i = 1 to n - s:
        T[i, i + s] = empty
        for k = 1 to i + s - 1:
            T[i, i + s] = T[i, i + s] UNION (T[i, k] * T[k+1, s])
If a is in T[1, n] return true. Else, return false.
```

4.6 Problem 6.7

Let the input string be $x_1x_2 \dots x_n$. Let $T[i, j]$ be the length of the longest palindromic subsequence in $x[i..j]$. We have

$$\begin{cases} T[i, i] = 1 \\ T[i, i+1] = 2 \text{ if } x[i] = x[i+1] \text{ and } 0 \text{ if } x[i] \neq x[i+1] \\ T[i, j] = T[i+1, j-1] + 2 \text{ if } x[i] = x[j] \text{ and } \max\{T[i+1, j], T[i, j-1]\} \text{ else} \end{cases}$$

4.7 Problem 6.8

Let $E[i, j]$ be the length of the largest common substring of $x_1x_2 \dots x_i$ and $y_1y_2 \dots y_j$ such that $x_i = y_j$. We see that $E[1, j] = 1$ if $x_1 = y_j$ and 0 otherwise. Similarly, $E[j, 1] = 1$ if $y_1 = x_j$ and 0 otherwise. In general, we have

$$E[i, j] = \begin{cases} E[i-1, j-1] + 1 \text{ if } x_i = y_j \\ 0 \text{ if } x_i \neq y_j \end{cases}$$

4.8 Problem 6.9

Let the input string be $x[0..n-1]$ and the input breakpoint array be $y[1..m]$. Convert y to $y[0..m+1]$ and let $y[0] = -1, y[m+1] = n-1$.

Let $M(i, j)$ be

$$\begin{cases} M(i, i) = 0, \forall i : 0 \leq i \leq m+1 \\ M(i, i+1) = 0, \forall i : 0 \leq i \leq m+1 \\ M(i, j) = (y[j] - y[i]) + \min_{l:i < l < j} \{M(i, l) + M(l, j)\} \end{cases}$$

4.9 Problem 6.10

Let $E[i, j]$ be the probability of obtaining exactly i heads when j coins c_1, c_2, \dots, c_j with head-probability p_1, p_2, \dots, p_j are tossed. We have

$$\begin{cases} E[0, 0] = 1 \\ E[0, j] = E[0, j-1] \cdot (1 - p_j) \quad \forall 1 \leq j \leq n \\ E[i, 0] = 0 \quad \forall 1 \leq i \leq k \\ E[i, j] = p_j \cdot E[i-1, j-1] + (1 - p_j) \cdot E[i, j-1] \end{cases}$$

4.10 Problem 6.11

Let $E[i, j]$ be the longest common subsequence of $x_1x_2 \dots x_j$ and $y_1y_2 \dots y_j$.

We have $E[1, j] = 1$ if $x_1 = y_j$, for all $1 \leq j \leq m$. Similarly, $E[j, 1] = 1$ if $x_j = y_1$, for all $1 \leq j \leq n$.

In general we have

$$E[i, j] = \begin{cases} E[i-1, j-1] + 1 \text{ if } x_i = y_j \\ \max\{E[i-1, j] + E[i, j-1]\} \text{ if } x_i \neq y_j. \end{cases}$$

4.11 Problem 6.12

Let $d[i, j]$ be the distance between point i and j . We have

$$\begin{cases} A[i, i] = 0 \\ A[i, i + 1] = 0 \\ A[i, i + 2] = 0 \\ A[i, j] = \min_{i < k < j} \{A[i, k] + A[k, j] + d[i, k] + d[k, j]\} \end{cases}$$

4.12 Problem 6.13

A sequence where a greedy approach would fail is

$$1000 \quad 2000 \quad 500 \quad 1.$$

Let $E[i, j]$ be the maximum value the first player can have by picking cards from the set of cards s_i, s_{i+1}, \dots, s_j .

We see that $E[i, j] = 0$ if $i \leq j$. In general,

$$E[i, j] = \max\{v_i + \min\{E[i + 2, j] - v_{i+1}, E[i + 1, j - 1] - v_j\}, \\ v_j + \min\{E[i + 1, j - 2] - v_{j-1}, E[i + 2, j - 1] - v_{i+1}\}\}.$$