EECS 545: Machine Learning
Lecture 4. Classification

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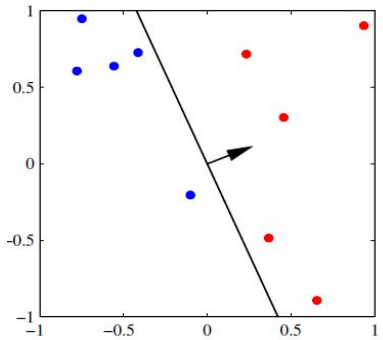
Outline

- Logistic regression (for binary classification)
  - Gradient Descent
  - Newton's method
- Softmax regression (for multi-class classification)
- K-nearest neighbors (KNN)

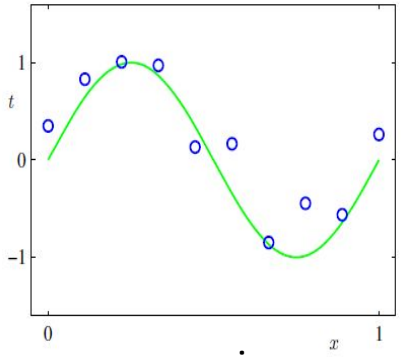
Supervised learning: classification

Supervised learning

- Goal:
  - Given data X in feature space and labels Y
  - Learn to predict Y from X
- Labels could be discrete or continuous
  - Discrete-valued labels: classification (today's topic)
  - Continuous-valued labels: regression



classification



regression

Classification problem

- The task of classification:
  - Given an input vector **x**, assign it to one of K distinct classes C_k where $k = 1, \ldots K$
- Representing the assignment:
  - For $K = 2$:
    - y = 1 means that **x** is in C_1
    - y = 0 means that **x** is in C_2.
      - (Sometimes, y = -1 can be used depending on algorithms)
- For $K > 2$:
  - Use 1-of-K coding
  - e.g., $\mathbf{y} = (0, 1, 0, 0, 0)^T$ means that **x** is in C_2.
    - (This works for $K = 2$ as well)

Classification problem

- Training: train a classifier $h(\mathbf{x})$ from training data
  - Training data $\left\{\left(x^{(1)}, y^{(1)}\right), \left(x^{(2)}, y^{(2)}\right), \ \ldots \ , \left(x^{(N)}, y^{(N)}\right)\right\}$

- Testing (evaluation):
  - testing data: $h\left(x_{\text{test}}^{(1)}\right), h\left(x_{\text{test}}^{(2)}\right), \ldots, h\left(x_{\text{test}}^{(N')}\right)$
  - The learning algorithm produces predictions
  - 0-1 loss: $\text{Classification error} = \frac{1}{N'} \sum_{j=1}^{N'} \mathbb{I}\left[h\left(x_{\text{test}}^{(j)}\right) \neq y_{\text{test}}^{(j)}\right]$

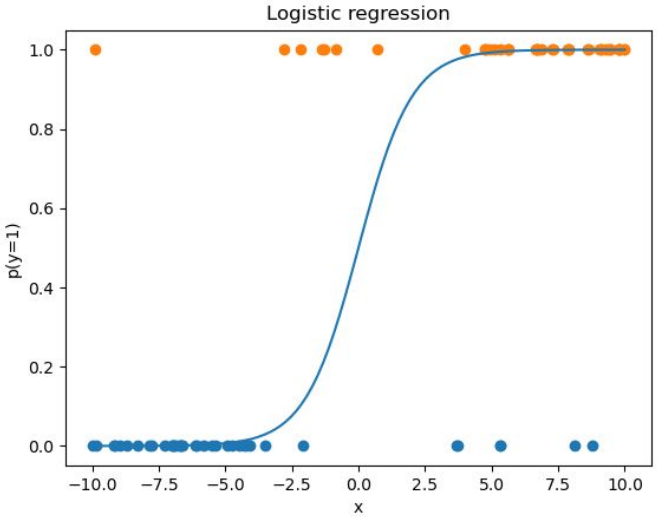
Logistic regression

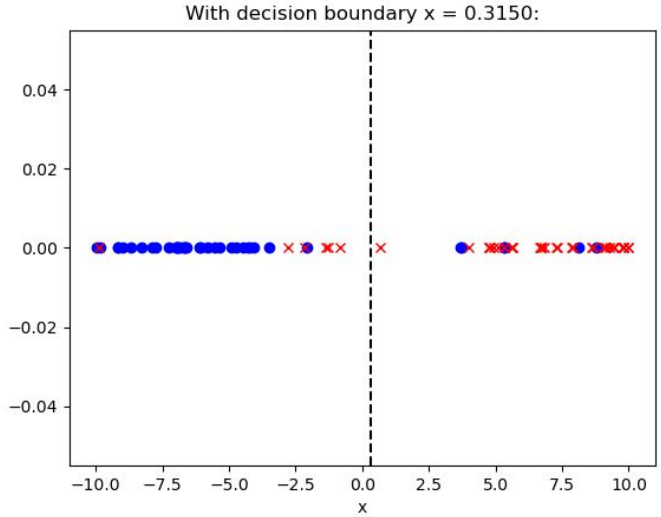
Probabilistic discriminative models

- Model decision boundary as a function of input **x**
  - Learn $P(C_k|\mathbf{x})$ over data (e.g., maximum likelihood)
  - Directly predict class labels from inputs

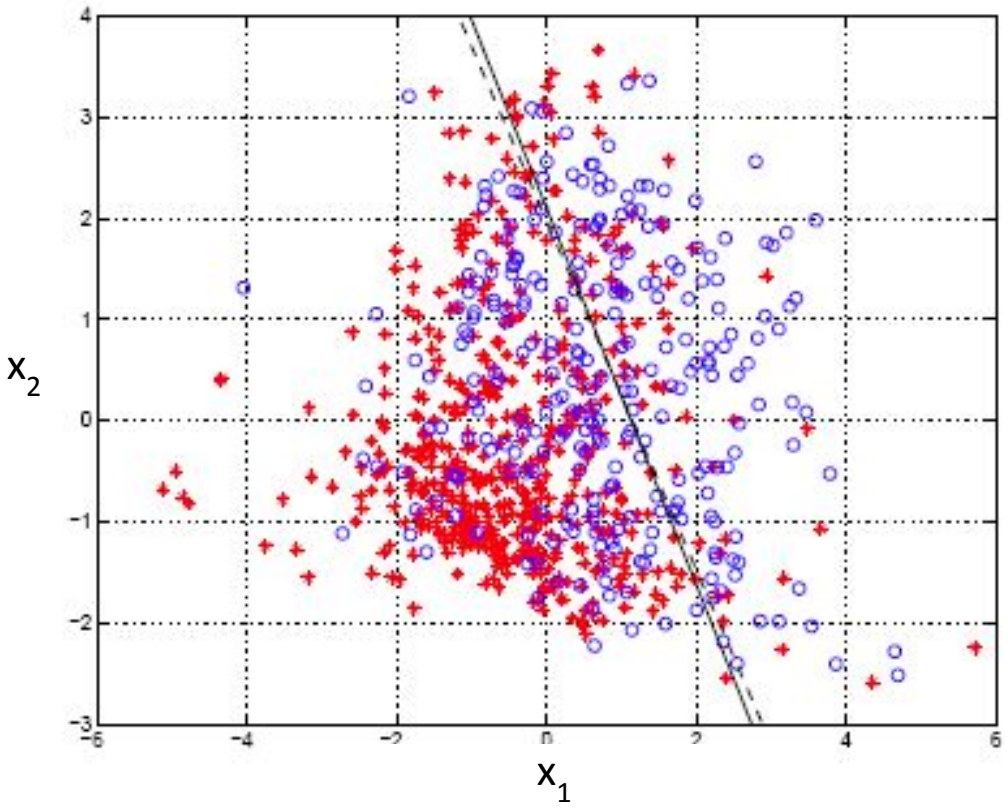
- Next class: we will cover probabilistic generative models
  - Learn $P(C_k, \mathbf{x})$ over data (maximum likelihood) and then use Bayes' rule to predict $P(C_k|\mathbf{x})$

Example (1-dim. case)





Example (2-dim. case)



note: we use $\phi(x) = x$ here for illustration. The decision boundary can be nonlinear when $\phi(x)$ is a nonlinear function of x.

Logistic regression

- Models the class posterior using a sigmoid applied to a linear function of the feature vector:

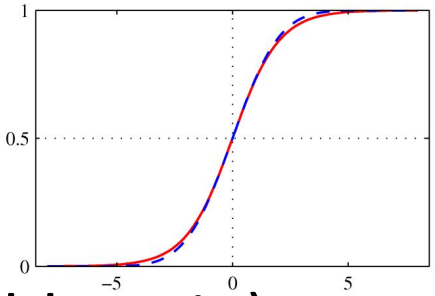
$$p(C_1|\phi) = h(\phi) = \sigma(\mathbf{w}^\top \phi(\mathbf{x}))$$

- We can solve the parameter **w** by maximizing the likelihood of the training data

Sigmoid and logit functions

- The *logistic sigmoid* function is:

$$\sigma(a) = \frac{1}{1+\exp(-a)} = \frac{\exp(a)}{1+\exp(a)}$$



- Its inverse is the *logit* function (aka log odds ratio):

$$a = \ln\left(\frac{\sigma}{1-\sigma}\right)$$

- Generalizes to *normalized exponential*, or *softmax*

$$p_i = \frac{\exp(q_i)}{\sum_j \exp(q_j)}$$

Class-conditional probability (for a single example)

- Depending on the label *y*, the conditional probability of y given **x** is defined as:

$$P(y = 1|\mathbf{x}, \mathbf{w}) = \sigma(\mathbf{w}^\top \phi(\mathbf{x}))$$

$$P(y = 0|\mathbf{x}, \mathbf{w}) = 1 - \sigma(\mathbf{w}^\top \phi(\mathbf{x}))$$

- Therefore we can write both cases compactly as:

$$P(y|\mathbf{x}, \mathbf{w}) = \sigma(\mathbf{w}^\top \phi(\mathbf{x}))^y (1 - \sigma(\mathbf{w}^\top \phi(\mathbf{x})))^{1-y}$$

Likelihood function (of logistic regression)

- The likelihood of Data $\{(\phi(\mathbf{x}^{(n)}), y^{(n)})\}$, where $y^{(n)} \in \{0, 1\}$

$$P(D|\mathbf{w}) = \prod_{i=1}^{N} P(\mathbf{x}^{(i)}, y^{(i)}|\mathbf{w})$$

IID (Independent Identical Distribution)

Definition of conditional probability

$$= \prod_{i=1}^{N} P(y^{(i)}|\mathbf{x}^{(i)}, \mathbf{w}) \underbrace{P(\mathbf{x}^{(i)}|\mathbf{w})}_{=P(\mathbf{x}^{(i)})}$$

P(x) does not depend on w

$$\propto \prod_{i=1}^{N} P(y^{(i)}|\mathbf{x}^{(i)}, \mathbf{w}) \longrightarrow P(\mathbf{y}|\mathbf{X}, \mathbf{w})$$

Compact notation: Technically speaking, this is (conditional) likelihood of y given X

Logistic regression

- For a data set $\{(\phi(\mathbf{x}^{(n)}), y^{(n)})\}, \text{where } y^{(n)} \in \{0, 1\}$ the likelihood function is

$$p(\mathbf{y}|\mathbf{X}, \mathbf{w}) = \prod_{n=1}^{N} (h^{(n)})^{y^{(n)}} (1 - h^{(n)})^{1-y^{(n)}}$$

where

$$h^{(n)} = p(C_1|\phi(\mathbf{x}^{(n)})) = \sigma(\mathbf{w}^\top \phi(\mathbf{x}^{(n)}))$$

note: *h*(**x**) is the hypothesis function, σ(**x**) is the specific hypothesis for logistic regression

- Define a loss function $E(\mathbf{w}) = -\log p(\mathbf{y}|\mathbf{X}, \mathbf{w})$
  - Minimizing *E*(**w**) maximizes likelihood

Derivation

- $$\log P(\mathbf{y}|\mathbf{X}, \mathbf{w}) = \sum_{n=1}^{N} y^{(n)} \log h^{(n)} + (1 - y^{(n)}) \log(1 - h^{(n)})$$
- Gradient (matrix calculus)

$$\nabla_{\mathbf{w}} \log P(\mathbf{y}|\mathbf{x}^{(1)}, \ \ldots \ , \mathbf{x}^{(N)}, \mathbf{w})$$
$$= \sum_{n=1}^{N} \nabla_{\mathbf{w}} \left(y^{(n)} \log h(\mathbf{x}^{(n)}, \mathbf{w}) + (1 - y^{(n)}) \log(1 - h(\mathbf{x}^{(n)}, \mathbf{w})) \right)$$

Derivation

- $$\log P(\mathbf{y}|\mathbf{X}, \mathbf{w}) = \sum_{n=1}^{N} y^{(n)} \log h^{(n)} + (1 - y^{(n)}) \log(1 - h^{(n)})$$
- Gradient (matrix calculus)

$$h(\mathbf{x}^{(n)}, \mathbf{w}) \triangleq \sigma\left(\mathbf{w}^\top \phi(\mathbf{x}^{(n)})\right) \triangleq \sigma^{(n)}$$

$$\nabla_{\mathbf{w}} \log P(\mathbf{y}|\mathbf{x}^{(1)}, \ \ldots\ , \mathbf{x}^{(N)}, \mathbf{w})$$

$$= \sum_{n=1}^{N} \nabla_{\mathbf{w}} \left(y^{(n)} \log h(\mathbf{x}^{(n)}, \mathbf{w}) + (1 - y^{(n)}) \log(1 - h(\mathbf{x}^{(n)}, \mathbf{w})) \right)$$

Derivation

- $\log P(\mathbf{y}|\mathbf{X}, \mathbf{w}) = \sum_{n=1}^{N} y^{(n)} \log h^{(n)} + (1 - y^{(n)}) \log(1 - h^{(n)})$
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$$\nabla_{\mathbf{w}} \log P(\mathbf{y}|\mathbf{x}^{(1)}, \ \ldots \ , \mathbf{x}^{(N)}, \mathbf{w})$$

$$= \sum_{n=1}^{N} \nabla_{\mathbf{w}} \left(y^{(n)} \log h(\mathbf{x}^{(n)}, \mathbf{w}) + (1 - y^{(n)}) \log(1 - h(\mathbf{x}^{(n)}, \mathbf{w})) \right)$$

$$= \sum_{n=1}^{N} \left(y^{(n)} \frac{\sigma^{(n)}(1 - \sigma^{(n)})}{\sigma^{(n)}} - (1 - y^{(n)}) \frac{\sigma^{(n)}(1 - \sigma^{(n)})}{1 - \sigma^{(n)}} \right) \nabla_{\mathbf{w}} (\mathbf{w}^\top \phi(\mathbf{x}^{(n)}))$$

$$\frac{\partial}{\partial s}\sigma(s) = \frac{\partial}{\partial s}\left(\frac{1}{1 + \exp(-s)}\right) = \sigma(s)(1 - \sigma(s))$$

Derivation

- $\log P(\mathbf{y}|\mathbf{X}, \mathbf{w}) = \sum_{n=1}^{N} y^{(n)} \log h^{(n)} + (1 - y^{(n)}) \log(1 - h^{(n)})$
- Gradient (matrix calculus)

$$h(\mathbf{x}^{(n)}, \mathbf{w}) \triangleq \sigma\left(\mathbf{w}^\top \phi(\mathbf{x}^{(n)})\right) \triangleq \sigma^{(n)}$$

$$\begin{aligned}
&\nabla_{\mathbf{w}} \log P(\mathbf{y}|\mathbf{x}^{(1)}, \ \ldots\ , \mathbf{x}^{(N)}, \mathbf{w}) \\
&= \sum_{n=1}^{N} \nabla_{\mathbf{w}} \left(y^{(n)} \log h(\mathbf{x}^{(n)}, \mathbf{w}) + (1 - y^{(n)}) \log(1 - h(\mathbf{x}^{(n)}, \mathbf{w})) \right) \\
&= \sum_{n=1}^{N} \left(y^{(n)} \frac{\sigma^{(n)}(1 - \sigma^{(n)})}{\sigma^{(n)}} - (1 - y^{(n)}) \frac{\sigma^{(n)}(1 - \sigma^{(n)})}{1 - \sigma^{(n)}} \right) \nabla_{\mathbf{w}} (\mathbf{w}^\top \phi(\mathbf{x}^{(n)})) \\
&= \sum_{n=1}^{N} \left(y^{(n)}(1 - \sigma^{(n)}) - (1 - y^{(n)}) \sigma^{(n)} \right) \nabla_{\mathbf{w}} (\mathbf{w}^\top \phi(\mathbf{x}^{(n)}))
\end{aligned}$$

Derivation

- $$\log P(\mathbf{y}|\mathbf{X}, \mathbf{w}) = \sum_{n=1}^{N} y^{(n)} \log h^{(n)} + (1 - y^{(n)}) \log(1 - h^{(n)})$$
- Gradient (matrix calculus)

$$h(\mathbf{x}^{(n)}, \mathbf{w}) \triangleq \sigma\left(\mathbf{w}^\top \phi(\mathbf{x}^{(n)})\right) \triangleq \sigma^{(n)}$$

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&\nabla_{\mathbf{w}} \log P(\mathbf{y}|\mathbf{x}^{(1)}, \ \ldots\ , \mathbf{x}^{(N)}, \mathbf{w}) \\
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&= \sum_{n=1}^{N} \left(y^{(n)} \frac{\sigma^{(n)}(1 - \sigma^{(n)})}{\sigma^{(n)}} - (1 - y^{(n)}) \frac{\sigma^{(n)}(1 - \sigma^{(n)})}{1 - \sigma^{(n)}} \right) \nabla_{\mathbf{w}} (\mathbf{w}^\top \phi(\mathbf{x}^{(n)})) \\
&= \sum_{n=1}^{N} \left(y^{(n)}(1 - \sigma^{(n)}) - (1 - y^{(n)}) \sigma^{(n)} \right) \nabla_{\mathbf{w}} (\mathbf{w}^\top \phi(\mathbf{x}^{(n)})) \\
&= \sum_{n=1}^{N} \left(y^{(n)} - \sigma^{(n)} \right) \phi(\mathbf{x}^{(n)}))
\end{aligned}$$

Logistic regression: gradient descent

Note: Vectorized form

$$\nabla E(\mathbf{w}) = \mathbf{\Phi}^T(\mathbf{h} - \mathbf{y})$$

- Taking the gradient of *E*(w) gives us

$$\nabla_{\mathbf{w}} E(\mathbf{w}) = -\nabla_{\mathbf{w}} \log P(\mathbf{y}|\mathbf{X}, \mathbf{w}) = \sum_{n=1}^{N} (h^{(n)} - y^{(n)}) \phi(\mathbf{x}^{(n)})$$

- Recall $h^{(n)} = p(C_1|\phi(\mathbf{x}^{(n)}) = \sigma(\mathbf{w}^\top \phi(\mathbf{x}^{(n)}))$
- This is essentially the same gradient expression that appeared in linear regression with least-squares.
- Note the error term between model prediction and target value:
  - Logistic regression: $h^{(n)} - y^{(n)} = \sigma(\mathbf{w}^\top \phi(\mathbf{x}^{(n)})) - y^{(n)}$
  - Cf. Linear regression: $h^{(n)} - y^{(n)} = \mathbf{w}^\top \phi(\mathbf{x}^{(n)}) - y^{(n)}$

Note: Gradient Descent vs Ascent

The following optimization problems are equivalent:

Minimizing the negative log-likelihood

→ gradient descent with $E(\mathbf{w}) = -\log P(\mathbf{y}|\mathbf{X},\mathbf{w})$ as an objective

$$w := w - \eta \nabla_{\mathbf{w}} E(\mathbf{w}) = w - \eta \sum_{n=1}^{N} (h^{(n)} - y^{(n)}) \phi(\mathbf{x}^{(n)})$$

Maximizing the log-likelihood

→ gradient ascent with $\log P(\mathbf{y}|\mathbf{X},\mathbf{w})$ as an objective

$$w := w + \eta \nabla_{\mathbf{w}} \log P(\mathbf{y}|\mathbf{X},\mathbf{w}) = w + \eta \sum_{n=1}^{N} (y^{(n)} - h^{(n)}) \phi(\mathbf{x}^{(n)})$$

Newton's method

- Goal: Minimizing a general function $E(\mathbf{w})$ (one-dimensional case)
  - Approach: solve for

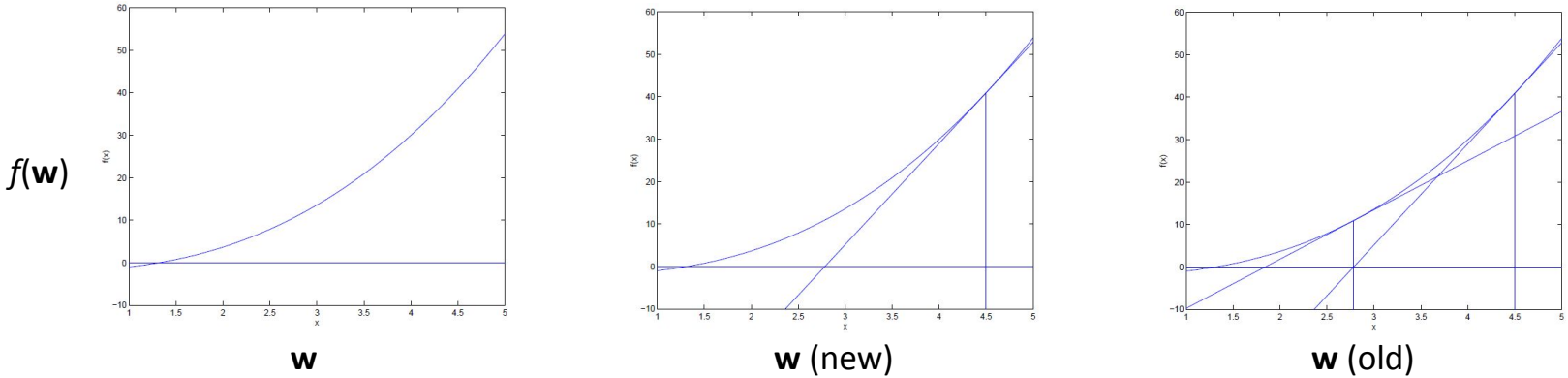
$$f(\mathbf{w}) = \frac{\partial E(\mathbf{w})}{\partial \mathbf{w}} = 0$$

  - So, how to solve this problem?
- Newton's method (aka Newton-Raphson method)
  - Repeat until convergence:

$$\mathbf{w} := \mathbf{w} - \frac{f(\mathbf{w})}{f'(\mathbf{w})}$$

Newton's method

- Interactively solve until we get f(w) = 0.



- Geometric intuition:

$$\mathbf{w} := \mathbf{w} - \frac{f(\mathbf{w})}{f'(\mathbf{w})}$$

Current value

"Slope"

Newton's method

- Now we want to minimize $E(\mathbf{w})$
  - Convert $E'(\mathbf{w}) = f(\mathbf{w})$
  - Repeat until convergence

$$\mathbf{w} := \mathbf{w} - \frac{E'(\mathbf{w})}{E''(\mathbf{w})}$$

Newton update when w is a scalar

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Newton's method

- Now we want to minimize $E(\mathbf{w})$
  - Convert $E'(\mathbf{w}) = f(\mathbf{w})$
  - Repeat until convergence

$$\mathbf{w} := \mathbf{w} - \frac{E'(\mathbf{w})}{E''(\mathbf{w})}$$

Newton update when w is a scalar

- This method can be extended to the multivariate case:

$$\mathbf{w} := \mathbf{w} - H^{-1}\nabla_{\mathbf{w}} E$$

Newton update when w is a vector

where **H** is a Hessian matrix evaluated at **w**

$$H_{ij}(\mathbf{w}) = \frac{\partial^2 E(\mathbf{w})}{\partial \mathbf{w}_i \partial \mathbf{w}_j}$$

- Note: for linear regression, the Hessian is $\Phi^\top \Phi$

Derivation of Newton's method

Taylor expansion of E(**w**) at $\mathbf{w}_0$ up to 2nd order:

$$E(\mathbf{w}) \approx E(\mathbf{w}_0) + \nabla E(\mathbf{w}_0)^T (\mathbf{w} - \mathbf{w}_0) + \frac{1}{2} (\mathbf{w} - \mathbf{w}_0)^T H(\mathbf{w}_0) (\mathbf{w} - \mathbf{w}_0)$$

Find a closed-form solution that optimizes the quadratic approximation above

$$\nabla \left[E(\mathbf{w}_0) + \nabla E(\mathbf{w}_0)^T (\mathbf{w} - \mathbf{w}_0) + \frac{1}{2} (\mathbf{w} - \mathbf{w}_0)^T H(\mathbf{w}_0) (\mathbf{w} - \mathbf{w}_0) \right] = \mathbf{0}$$

Using matrix calculus trick similar to Linear regression, we get

$$\mathbf{w} = \mathbf{w}_0 - H(\mathbf{w}_0)^{-1} \nabla E(\mathbf{w}_0)$$

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Iteratively Reweighted Least Squares (IRLS)

- Recall: for linear regression, least-squares has a closed-form solution:

$$\mathbf{w}_{\mathrm{ML}} = (\Phi^\top \Phi)^{-1} \Phi^\top y$$

- This generalizes to weighted-least-squares with an NxN diagonal weight matrix **R**.

$$\mathbf{w}_{\mathrm{WLS}} = (\Phi^\top \mathbf{R} \Phi)^{-1} \Phi^\top \mathbf{R} y$$

- For logistic regression, however, $h(\mathbf{x}, \mathbf{w})$ is non-linear, and there is no closed-form solution. So **we need to iterate (i.e. repeatedly apply Newton steps) to get the optimal solution, which is called IRLS.**

Iterative solution

- Apply Newton-Raphson method to iterate to a solution **w** for $\nabla E(\mathbf{w}) = 0$
- This involves least-squares with weights **R**:

$$R_{\mathrm{nn}} = h^{(n)}(1 - h^{(n)})$$

- Since **R** depends on **w** (and vice versa), we get *iterative reweighted least squares* (IRLS)

  where $\mathbf{w}^{(\mathrm{new})} = (\Phi^{\top}\mathbf{R}\Phi)^{-1}\Phi^{\top}\mathbf{R}\mathbf{z}$

$$\mathbf{z} = \Phi\mathbf{w}^{(\mathrm{old})} - \mathbf{R}^{-1}(\mathbf{h} - \mathbf{y})$$

Iterative solution: Derivation

Applying Newton's method:

$$\mathbf{w}^{(\text{new})} = \mathbf{w}^{(\text{old})} - H(\mathbf{w}^{(\text{old})})^{-1} \nabla E(\mathbf{w}^{(\text{old})})$$

Gradient and Hessians from Logistic Regression loss function:

$$\nabla E(\mathbf{w}) = \Phi^T (\mathbf{h} - \mathbf{y}) \quad \text{and} \quad H(\mathbf{w}) = \nabla^2 E(\mathbf{w}) = \Phi^T R \Phi$$

where $R_{nn} = h^{(n)} \left(1 - h^{(n)}\right)$

Putting together: $\mathbf{w}^{(\text{new})} = \mathbf{w}^{(\text{old})} - \left[\Phi^T R \Phi\right]^{-1} \Phi^T (\mathbf{h} - \mathbf{y})$

If we define z as $\mathbf{z} = \Phi \mathbf{w}^{(\text{old})} - R^{-1} (\mathbf{h} - \mathbf{y})$

We can also write the solution as: $\mathbf{w}^{(\text{new})} = (\Phi^T R \Phi)^{-1} \Phi^T R \mathbf{z}$

Multi-class Classification

Softmax regression for multiclass classification

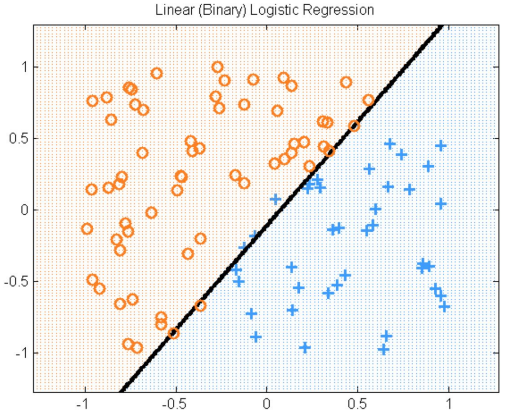
- For multiclass case, we can use softmax regression.
  - Softmax regression can be viewed as a generalization of logistic regression
- Recall that, logistic regression (binary classification) models class conditional probability as:

$$p(y=1 \mid \mathbf{x}; \mathbf{w}) = \frac{\exp\left(\mathbf{w}^\top \phi(\mathbf{x})\right)}{1+\exp\left(\mathbf{w}^\top \phi(\mathbf{x})\right)}$$

$$p(y=0 \mid \mathbf{x}; \mathbf{w}) = \frac{1}{1+\exp\left(\mathbf{w}^\top \phi(\mathbf{x})\right)}$$

  - Note that these probability sum to 1.

note: we use $\phi(x) = x$ here for illustration. The decision boundary can be nonlinear when $\phi(x)$ is a nonlinear function of x.

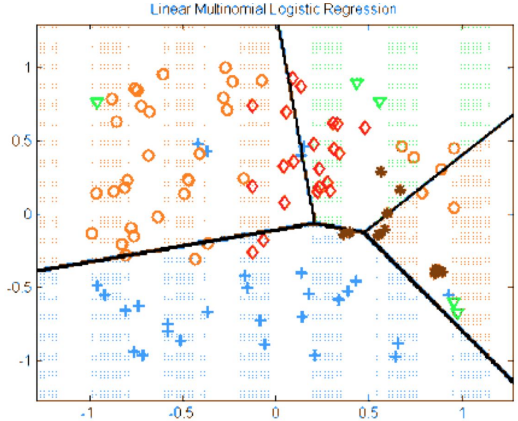


- For multiclass classification (with K classes), we use the following model

$$p(y=k \mid \mathbf{x}; \mathbf{w}) = \frac{\exp\left(\mathbf{w}_k^\top \phi(\mathbf{x})\right)}{1+\sum_{j=1}^{K-1}\exp\left(\mathbf{w}_j^\top \phi(\mathbf{x})\right)} \quad \text{for } k=\{1,\ldots,K-1\}$$

$$p(y=K \mid \mathbf{x}; \mathbf{w}) = \frac{1}{1+\sum_{j=1}^{K-1}\exp\left(\mathbf{w}_j^\top \phi(\mathbf{x})\right)} \quad \text{equivalent to setting } \mathbf{w}_K = 0$$

  - Note that these probability sum to 1.



Softmax regression: Log-likelihood (objective function) and learning

- Defining $\mathbf{w}_K = 0$, we can write as:

$$p(y = k \mid \mathbf{x}; \mathbf{w}) = \frac{\exp\left(\mathbf{w}_k^\top \phi(\mathbf{x})\right)}{\sum_{j=1}^{K} \exp\left(\mathbf{w}_j^\top \phi(\mathbf{x})\right)}$$

$$p(y \mid \mathbf{x}; \mathbf{w}) = \prod_{k=1}^{K} \left[\frac{\exp\left(\mathbf{w}_k^\top \phi(\mathbf{x})\right)}{\sum_{j=1}^{K} \exp\left(\mathbf{w}_j^\top \phi(\mathbf{x})\right)} \right]^{\mathbb{I}(y=k)}$$

- Log-Likelihood $\log p(D|\mathbf{w}) = \sum_i \log p(y^{(i)}|\mathbf{x}^{(i)}, \mathbf{w})$

$$= \sum_i \log \prod_{k=1}^{K} \left[\frac{\exp\left(\mathbf{w}_k^\top \phi(\mathbf{x}^{(i)})\right)}{\sum_{j=1}^{K} \exp\left(\mathbf{w}_j^\top \phi(\mathbf{x}^{(i)})\right)} \right]^{\mathbb{I}(y^{(i)}=k)}$$

- We can learn $\mathbf{w}$ by gradient ascent for maximizing the log-likelihood or iterative Newton's method (IRLS).

K-nearest neighbor classification

K-nearest neighbors

- Training method:
  - Save the training examples (no sophisticated learning)
- At prediction (testing) time:
  - Given a test (query) example **x**, find the *K* training examples that are *closest* to **x**.

$$\mathrm{KNN}(\mathbf{x}) = \left\{ \left(\mathbf{x}^{(1)\prime}, y^{(1)\prime}\right), \left(\mathbf{x}^{(2)\prime}, y^{(2)\prime}\right), ..., \left(\mathbf{x}^{(K)\prime}, y^{(K)\prime}\right) \right\}$$

- Predict the most frequent class among all *y'*s from *KNN*(**x**).

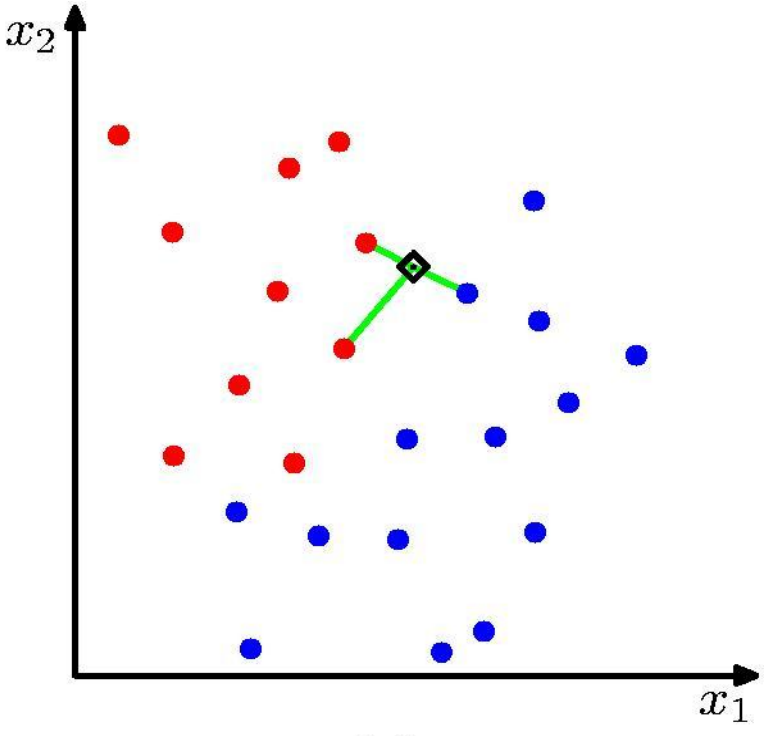
$$h(\mathbf{x}) = \arg\max_{y} \sum_{(\mathbf{x}', y') \in \mathrm{kNN}(\mathbf{x})} \mathbb{I}[y' = y]$$

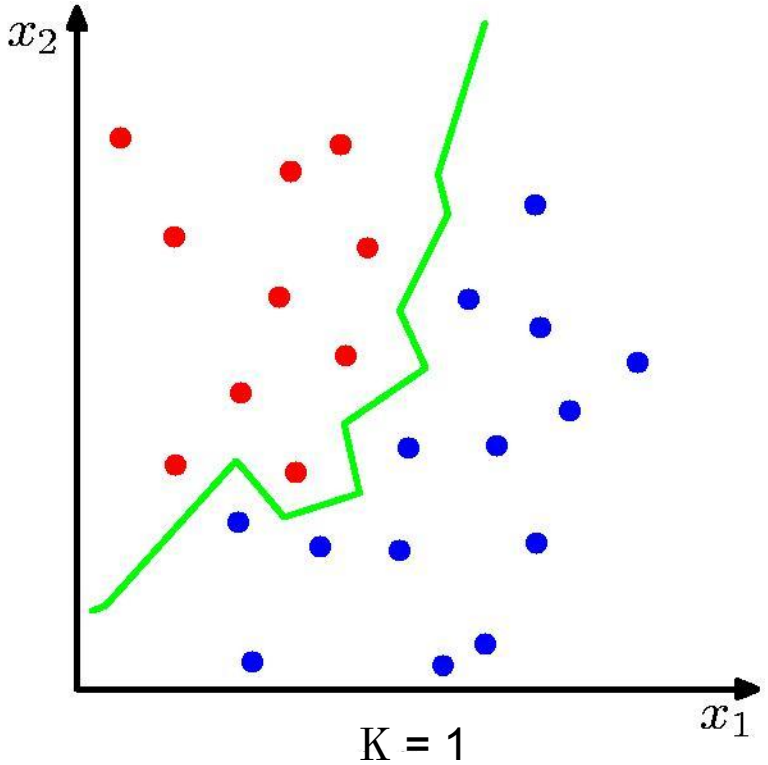
"majority vote"

- <u>Note: this function can be applied to regression!</u>

Slide credit: William Cohen

K-nearest neighbors for classification

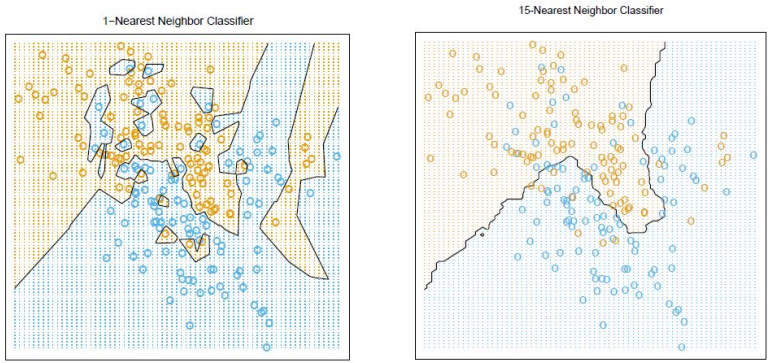




K = 1

Slide credit: Ben Kuipers

K-nearest neighbors for classification



- Larger *K* leads to a smoother decision boundary (bias-variance trade-off)
- Classification performance generally improves as *N* (training set size) increases
- For $N \Rightarrow \infty$, the error rate of the 1-nearest-neighbor classifier is never more than twice the optimal error (obtained from the true conditional class distributions). See ESL CH 13.3.

Slide credit: Ben Kuipers

Factors (hyperparameters) affecting KNN

- Distance metric $D(\mathbf{x}, \mathbf{x'})$
  - How to define distance between two examples **x** and **x'**?

- The value of *K*
  - *K* determines how much we "smooth out" the prediction

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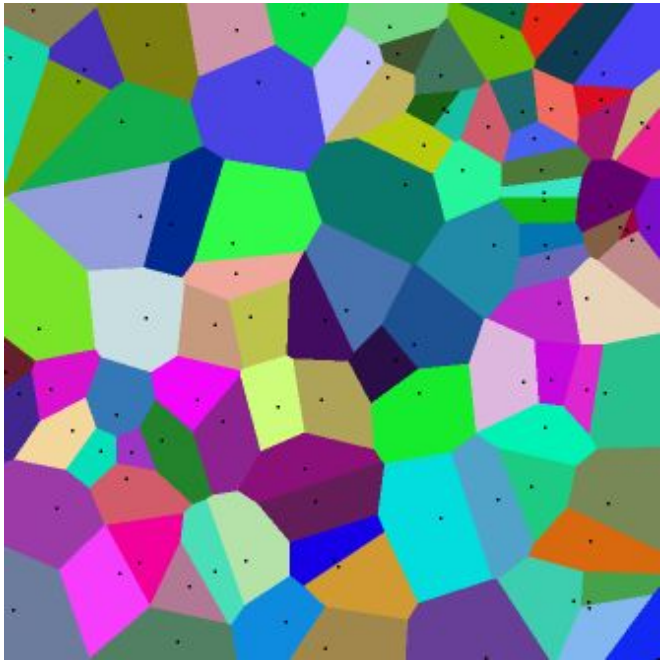
What is the decision boundary?

Voronoi diagram: Euclidean (L_2) distance



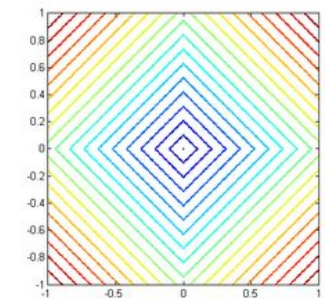
Note: Each region corresponds kNN's prediction when K=1

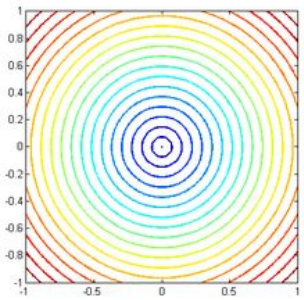
i.e. prediction is the same as the corresponding training sample's label in each region (training sample is visualized as dot).

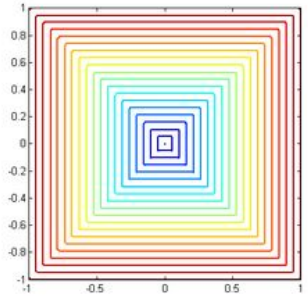
Slide credit: William Cohen

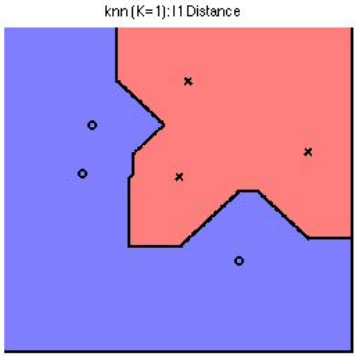
Dependence on distance metric (L^q norm)

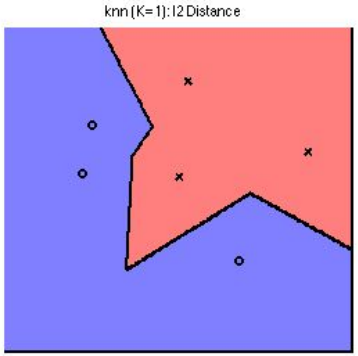
Distance between i-th and j-th example: $\sqrt[q]{\sum_l \left(x_l^{(i)} - x_l^{(j)}\right)^q}$

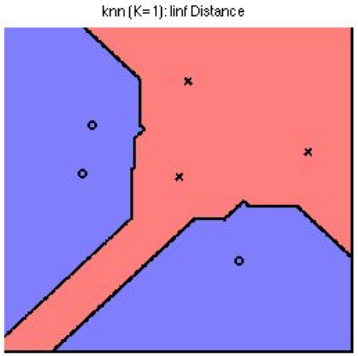












Slide credit: Ben Taskar

KNN: classification vs regression

- We can formulate KNN into regression/classification
- For classification, where the label *y* is categorical, we take the "majority vote" over target labels.

$$h(\mathbf{x}) = \arg\max_{y} \sum_{(\mathbf{x}',y')\in \mathrm{KNN}(\mathbf{x})} \mathbb{I}[y' = y]$$

- For regression, where the label *y* is real-valued numbers, we take "average" over target labels.

$$h(\mathbf{x}) = \frac{1}{k} \sum_{(\mathbf{x}',y')\in \mathrm{KNN}(\mathbf{x})} y'$$

Advantage/disadvantages of KNN methods

- Advantage:
  - Very simple and flexible (no assumption on distribution)
  - Effective (e.g. for low dimensional inputs)
- Disadvantages:
  - Expensive: need to remember (store) and search through all the training data for every prediction
  - Curse of dimensionality: in high dimensions, all points are far
  - Not robust to irrelevant features: if **x** has irrelevant/noisy features, then distance function does not reflect similarity between examples

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Concept check

- How are labels represented in multiclass classification problems?
- What is the motivation for using Newton's method for optimization in logistic regression?
- What does increasing K do for the results from KNN?

Any feedback (about lecture, slide, homework, project, etc.)?

(via **anonymous** google form: https://forms.gle/fpYmiBtG9Me5qbP37)

Change Log of lecture slides:
https://docs.google.com/document/d/e/2PACX-1vSSIHJjkIypK7rKFSR1-5GYXyBCEW8UPtpSfCR9AR6M1l7K9ZQEmxfFwaWaW7kLDxusthsF8WlCyZJ-/pub