2.1 Savings from Improving Individual Driving Profiles

2.1.1 Drive Profile Subsample from Real-World Travel Survey

The interim report (Gonder et al. 2010) included results from detailed analyses on five cycles selected from a large set of real-world global positioning system (GPS) travel data collected in 2006 as part of a study by the Texas Transportation Institute and the Texas Department of Transportation (Ojah and Pearson 2008). The cycles were selected to reflect a range of kinetic intensity (KI) values. (KI represents a ratio of characteristic acceleration to aerodynamic speed and has been shown to be a useful drive cycle classification parameter [O'Keefe et al. 2007].) To determine the maximum possible cycle improvement fuel savings, the real-world cycles were converted into equivalent "ideal" cycles using the following steps:

- 1. Calculate the trip distance of each sample trip.
- 2. Eliminate stop-and-go and idling within each trip.
- 3. Set the acceleration rate to 3 mph/s.
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- 5. Continue cruising at 40 mph until the trip distance is reached.

To compare vehicle simulations over each real-world cycle and its corresponding ideal cycle, a midsize conventional vehicle model from a previous NREL study was used (Earleywine et al. 2010). The results indicated a fuel savings potential of roughly 60% for the drive profiles with either very high or very low KI and of 30%–40% for the cycles with moderate KI values.

Table 2-1. Simulated fuel savings from isolated cycle improvements

Cycle	KI	Distance	Percent Fuel Savings				
Name (1/km)	(mi)	Improved Speed	Decreased Accel	Eliminate Stops	Decreased Idle		
2012_2	3.30	1.3	5.9%	9.5%	29.2%	17.4%	
2145_1	0.68	11.2	2.4%	0.1%	9.5%	2.7%	
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