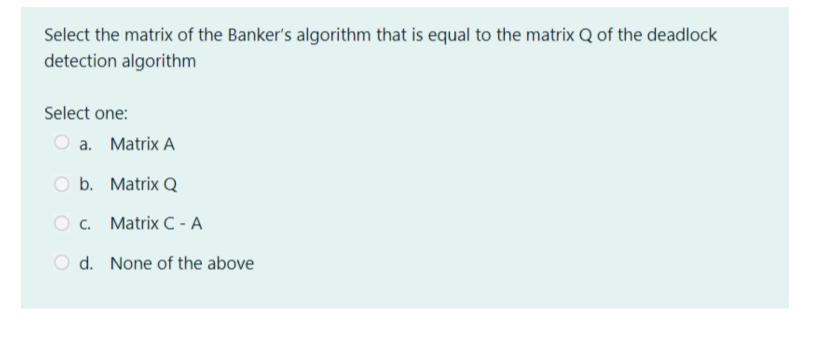
After the theory part, two additional questions will be presented.

True or False questions (2 points each question)

A deadlock avoidance mechanism requires knowledge of future process requests
Select one:
O True
O False
When a thread calls a signal over a condition variable, if there is no waiting thread on the signaled condition variable, this signal is lost.
Select one:
○ True
○ False
In message passing, a solution based on mailboxes uses direct addressing
Select one:
○ True
○ False

A disadvantage of the deadlock detection algorithm is that frequent checks consume considerable processor time
Select one:
○ True
○ False
In deadlock avoidance, the solution is executed after assigning the resources to a process.
Select one:
O True
○ False
Peterson's algorithm is a hardware-based solution to guarantee mutual exclusion.
Select one:
O True
○ False

Simple Choice questions (4 points each question)



Select the concurrency mechanism that is a hardware solution

Select one:

- oa. Semaphores
- b. Exchange Instruction
- oc. Peterson's Algorithm
- Od. None of the above

Select o	one:
○ a.	Requesting all resources at once
O b.	Banker's algorithm
○ c.	Detection algorithm
O d.	Ostrich Algorithm
О е.	None of the above
Select t	he option that is not a requirement for mutual exclusion
Select o	one:
○ a.	No deadlock or starvation
O b.	Using the relative process speeds or the number of processes as parameters to guarantee mutual exclusion.
O c.	A process remains inside its critical section for a finite time only.
O d.	A process that halts must do so without interfering with other processes.
О е.	None of the above
In the c	deadlock detection algorithm, if all processes are marked, then:
Select o	one:
○ a.	All processes are deadlocked
○ b.	No deadlock was detected
O c.	The algorithm has not started its execution
○ d.	None of the above

Select the option that is a deadlock prevention approach

Select the option that is not a recovery strategy of the deadlock detection algorithm

Select one:

- a. Abort all deadlocked processes
- Ob. Successively abort deadlocked processes until deadlock no longer exists
- o. Successively preempt resources until deadlock no longer exists
- d. None of the above

Given the following code, determine a) the number of critical sections; and b) the shared resource(s) protected by the critical section(s) in the following code. (14 points)

```
static int tunnelStatus=0;
static pthread_mutex_t mu;
pthread mutex init(&mu, NULL);
void* tunnel(void* arg)
    int status;
    while (1)
        sleep(5);
        pthread_mutex_lock(&mu);
        status = tunnelStatus;
        tunnelStatus = 0;
        pthread_mutex_unlock(&mu);
        sleep(5);
        pthread_mutex_lock(&mu);
        tunnelStatus = -1*status;
        pthread mutex unlock(&mu);
}
```

Number of critical sections				
Answer:				
Shared Resource(s) controlled by the critical section: (this is an all-or-nothing question)				
Select one or more:				
a. tunnelStatus				
a. turrierstatus				
b. mu				
b. mu				