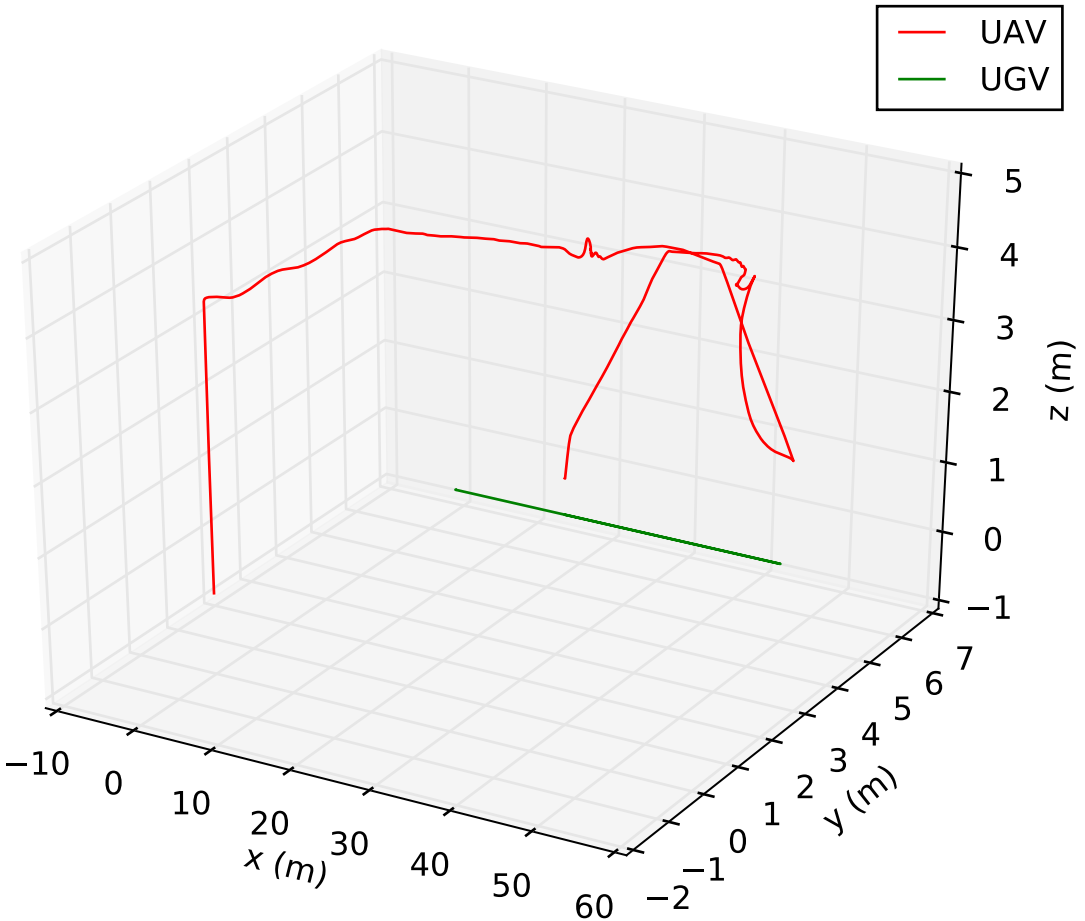
UAV
UGV
z (m)
5
4
3
2
1
0
−1
x (m)
−10
0
10
20
30
40
50
60
y (m)
−2
−1
0
1
2
3
4
5
6
7