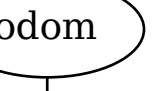


Broadcaster: /amcl  
Average rate: 49.798 Hz  
Most recent transform: 1613.270 ( -0.380 sec old)  
Buffer length: 4.960 sec



Broadcaster: /laser\_odometry  
Average rate: 10.288 Hz  
Most recent transform: 1612.770 ( 0.120 sec old)  
Buffer length: 4.860 sec



Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1612.890 sec old)  
Buffer length: 0.000 sec



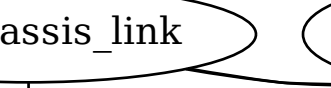
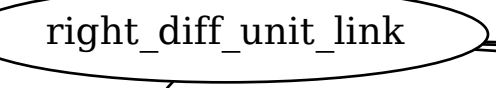
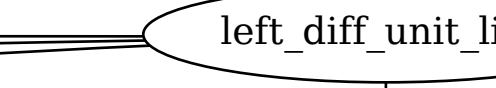
Broadcaster: /robot\_state\_publisher  
Average rate: 10.204 Hz  
Most recent transform: 1612.850 ( 0.040 sec old)  
Buffer length: 4.900 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10.204 Hz  
Most recent transform: 1612.850 ( 0.040 sec old)  
Buffer length: 4.900 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1612.890 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1612.890 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1612.890 sec old)  
Buffer length: 0.000 sec



Broadcaster: /robot\_state\_publisher  
Average rate: 30.346 Hz  
Most recent transform: 1612.850 ( 0.040 sec old)  
Buffer length: 4.910 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 30.346 Hz  
Most recent transform: 1612.850 ( 0.040 sec old)  
Buffer length: 4.910 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1612.890 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1612.890 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1612.890 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1612.890 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1612.890 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1612.890 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1612.890 sec old)  
Buffer length: 0.000 sec

