

# Lecture 11 – Multiple Linear Regression and Feature Engineering



**DSC 40A, Fall 2022 @ UC San Diego**

Dr. Truong Son Hy, with help from **many others**

# Announcements

- ▶ Look at the readings linked on the course website!
- ▶ Groupwork Release Day: Thursday afternoon  
Groupwork Submission Day: Monday midnight  
Homework Release Day: Friday after lecture  
Homework Submission Day: Friday before lecture
- ▶ See [dsc40a.com/calendar](https://dsc40a.com/calendar) for the Office Hours schedule.

# Midterm study strategy

- ▶ Review the solutions to previous homeworks and groupworks.
- ▶ Re-watch lecture, post on Campuswire, come to office hours.
- ▶ Look at the past exams at <https://dsc40a.com/resources>.
- ▶ Study in groups.
- ▶ **Remember:** it's just an exam.

# Agenda

- ▶ Many demo.
- ▶ Recap of linear regression and linear algebra.
- ▶ Using multiple features.

**Many demo**

# Regression and linear algebra

- Last time, we used linear algebra to fit a prediction rule of the form

$$H(x) = w_0 + w_1 x$$

- To do so, we first defined a **design matrix**  $X$ , **parameter vector**  $\vec{w}$ , and **observation vector**  $\vec{y}$  as follows:

$$X = \begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \dots & \dots \\ 1 & x_n \end{bmatrix}, \quad \vec{w} = \begin{bmatrix} w_0 \\ w_1 \end{bmatrix}, \quad \vec{y} = \begin{bmatrix} y_1 \\ y_2 \\ \dots \\ y_n \end{bmatrix}$$

- We also re-wrote our prediction rule as a matrix-vector multiplication, defining the **hypothesis vector**  $\vec{h}$  as

$$\vec{h} = X\vec{w}$$

# Minimizing mean squared error

- ▶ With our new linear algebra formulation of regression, our mean squared error now looks like:

$$R_{sq}(\vec{w}) = ||\vec{y} - X\vec{w}||^2$$

- ▶ To find  $\vec{w}^*$ , the optimal parameter vector, we took the gradient of  $R_{sq}(\vec{w})$  with respect to  $\vec{w}$ , set it equal to 0, and solved.
- ▶ The result is the **normal equations**:

$$X^T X \vec{w}^* = X^T y$$

- ▶ When  $X^T X$  is invertible, an equivalent form is

$$\vec{w}^* = (X^T X)^{-1} X^T y$$

## Using multiple features



# Using multiple features

- ▶ How do we predict salary given **multiple** features?
- ▶ We believe salary is a function of experience *and* GPA.
- ▶ In other words, we believe there is a function  $H$  so that:

$$\text{salary} \approx H(\text{years of experience, GPA})$$

- ▶ Recall:  $H$  is a **prediction rule**.
- ▶ **Our goal:** find a good prediction rule,  $H$ .

## Example prediction rules

$$H_1(\text{experience, GPA}) = \$2,000 \times (\text{experience}) + \$40,000 \times \frac{\text{GPA}}{4.0}$$

$$H_2(\text{experience, GPA}) = \$60,000 \times 1.05^{(\text{experience} + \text{GPA})}$$

$$H_3(\text{experience, GPA}) = \cos(\text{experience}) + \sin(\text{GPA})$$

# Linear prediction rules

- ▶ We'll restrict ourselves to **linear** prediction rules:

$$H(\text{experience}, \text{GPA}) = w_0 + w_1(\text{experience}) + w_2(\text{GPA})$$

- ▶ This is called **multiple linear regression**.
- ▶ Note that  $H$  is **linear in the parameters**  $w_0, w_1, w_2$ .
  - ▶  $H$  is a linear combination of features (1, experience, GPA) with  $w$ s as the coefficients ( $w_0, w_1$ , and  $w_2$ ).
- ▶ As a result, we can solve the **normal equations** to find  $w_0^*$ ,  $w_1^*$ , and  $w_2^*$ !
- ▶ Linear regression with multiple features is called **multiple linear regression**.

## Geometric interpretation

**Question:** The prediction rule

$$H(\text{experience}) = w_0 + w_1(\text{experience})$$

looks like a line in 2D.

1. How many dimensions do we need to graph

$$H(\text{experience, GPA}) = w_0 + w_1(\text{experience}) + w_2(\text{GPA})$$

2. What is the shape of the prediction rule?

## Example dataset

- For each of  $n$  people, collect each feature, plus salary:

Person #	Experience	GPA	Salary
1	3	3.7	85,000
2	6	3.3	95,000
3	10	3.1	105,000

- We represent each person with a **feature vector**:

$$\vec{x}_1 = \begin{bmatrix} 3 \\ 3.7 \end{bmatrix}, \quad \vec{x}_2 = \begin{bmatrix} 6 \\ 3.3 \end{bmatrix}, \quad \vec{x}_3 = \begin{bmatrix} 10 \\ 3.1 \end{bmatrix}$$

# The hypothesis vector

- When our prediction rule is

$$H(\text{experience}, \text{GPA}) = w_0 + w_1(\text{experience}) + w_2(\text{GPA}),$$

the hypothesis vector  $\vec{h} \in \mathbb{R}^n$  can be written

$$\vec{h} = \begin{bmatrix} H(\text{experience}_1, \text{GPA}_1) \\ H(\text{experience}_2, \text{GPA}_2) \\ \dots \\ H(\text{experience}_n, \text{GPA}_n) \end{bmatrix} = \begin{bmatrix} 1 & \text{experience}_1 & \text{GPA}_1 \\ 1 & \text{experience}_2 & \text{GPA}_2 \\ \dots & \dots & \dots \\ 1 & \text{experience}_n & \text{GPA}_n \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ w_2 \end{bmatrix}$$

## How do we find $\vec{w}^*$ ?

- To find the best parameter vector,  $\vec{w}^*$ , we can use the design matrix and observation vector

$$X = \begin{bmatrix} 1 & \text{experience}_1 & \text{GPA}_1 \\ 1 & \text{experience}_2 & \text{GPA}_2 \\ \dots & \dots & \dots \\ 1 & \text{experience}_n & \text{GPA}_n \end{bmatrix}, \vec{y} = \begin{bmatrix} y_1 \\ y_2 \\ \dots \\ y_n \end{bmatrix}$$

and solve the **normal equations**

$$X^T X \vec{w}^* = X^T \vec{y}$$

- Notice that the rows of the design matrix are the (transposed) feature vectors, with an additional 1 in front.

# Notation for multiple linear regression

- ▶ We will need to keep track of multiple<sup>1</sup> features for every individual in our data set.
- ▶ As before, subscripts distinguish between individuals in our data set. We have  $n$  individuals (or **training examples**).
- ▶ Superscripts distinguish between features.<sup>2</sup> We have  $d$  features.
  - ▶ experience =  $x^{(1)}$
  - ▶ GPA =  $x^{(2)}$

---

<sup>1</sup>In practice, we might use hundreds or even thousands of features.

<sup>2</sup>Think of them as new variable names, such as new letters.



## Augmented feature vectors

- The **augmented feature vector**  $\text{Aug}(\vec{x})$  is the vector obtained by adding a 1 to the front of feature vector  $\vec{x}$ :

$$\vec{x} = \begin{bmatrix} x^{(1)} \\ x^{(2)} \\ \vdots \\ x^{(d)} \end{bmatrix} \quad \text{Aug}(\vec{x}) = \begin{bmatrix} 1 \\ x^{(1)} \\ x^{(2)} \\ \vdots \\ x^{(d)} \end{bmatrix} \quad \vec{w} = \begin{bmatrix} w_0 \\ w_1 \\ w_2 \\ \vdots \\ w_d \end{bmatrix}$$

- Then, our prediction rule is

$$\begin{aligned} H(\vec{x}) &= w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \dots + w_d x^{(d)} \\ &= \vec{w} \cdot \text{Aug}(\vec{x}) \end{aligned}$$

# The general problem

- ▶ We have  $n$  data points (or **training examples**):  
 $(\vec{x}_1, y_1), \dots, (\vec{x}_n, y_n)$  where each  $\vec{x}_i$  is a feature vector of  $d$  features:

$$\vec{x}_i = \begin{bmatrix} x_i^{(1)} \\ x_i^{(2)} \\ \dots \\ x_i^{(d)} \end{bmatrix}$$

- ▶ We want to find a good linear prediction rule:

$$\begin{aligned} H(\vec{x}) &= w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \dots + w_d x^{(d)} \\ &= \vec{w} \cdot \text{Aug}(\vec{x}) \end{aligned}$$

# The general solution

- Use design matrix

$$X = \begin{bmatrix} 1 & x_1^{(1)} & x_1^{(2)} & \dots & x_1^{(d)} \\ 1 & x_2^{(1)} & x_2^{(2)} & \dots & x_2^{(d)} \\ \dots & \dots & \dots & \dots & \dots \\ 1 & x_n^{(1)} & x_n^{(2)} & \dots & x_n^{(d)} \end{bmatrix} = \begin{bmatrix} \text{Aug}(\vec{x}_1)^T \\ \text{Aug}(\vec{x}_2)^T \\ \dots \\ \text{Aug}(\vec{x}_n)^T \end{bmatrix}$$

and observation vector to solve the **normal equations**

$$X^T X \vec{w}^* = X^T \vec{y}$$

to find the optimal parameter vector.

## Interpreting the parameters

- ▶ With  $d$  features,  $\vec{w}$  has  $d + 1$  entries.
- ▶  $w_0$  is the **bias**, also known as the **intercept**.
- ▶  $w_1, \dots, w_d$  each give the **weight**, i.e. **coefficient**, of a feature.

$$H(\vec{x}) = w_0 + w_1 x^{(1)} + \dots + w_d x^{(d)}$$

- ▶ The sign of  $w_i$  tells us about the relationship between  $i$ th feature and the output of our prediction rule.