COMPSCI361: Machine Learning Introduction to Bayesian Learning

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Motivation and Introduction
Bayes' Theorem
Maximum A Posteriori Hypothesis
Bayes Optimal Classifier
Maximum Likelihood and Least-Squared Error
Minimum Description Length
Naive Bayes Classifier
Naive Bayes for Document Classification
Bayesian Networks

Partly based on Mitchel's book, lecture slides from Stanford's NLP lecture and The University of Utah

Motivation and Introduction

Spam Filtering



- Spam filters analyze the text of emails and classify them into Spam and Ham
 - SpamAssassin Features:
 - Mentions Generic Viagra
 - Online Pharmacy
 - Mentions millions of (dollar) ((dollar) NN,NNN,NNN.NN)
 - Phrase: impress ... girl
 - From: starts with many numbers
 - Subject is all capitals
 - HTML has a low ratio of text to image area
 - One hundred percent guaranteed
 - Claims you can be removed from the list
 - 'Prestigious Non-Accredited Universities'

Spam Filtering



- We want to build a system that detects e-mails
- Can we formulate this as a supervised learning task?
 Dear Home Owner.

Your credit doesn't matter to us! If you own real estate and want IMMEDIATE cash to spend ANY way you like, or simply wish to LOWER your monthly payments by one third or more, here are the deals we have today:

```
$488.000,00 at 3.67% fixed rate
$372.000,00 at 3.90% variable-rate
$492.000,00 at 3.21% interest-only
$248.000,00 at 3.36% fixed rate
$198.000,00 at 3.55% variable rate
```

Hurry, when these deals are gone, they're gone! Simple fill out the 1 minute form.

Don't worry about approval, credit is not a matter!

CLICK HERE AND FILL THE 60 SECS FORM!





■ Collect a large number of e-mails, get users to label them

\$	Hi	CS	762	Vicodin	Offer	 Spam?	
1	1	0	0	1	0	 1	
0	0	0	0	1	1	 1	
0	1	1	1	0	0	 0	

- We can use $(y_i = 1)$ if e-mail i is spam, $(y_i = 0)$ if e-mail is not spam
- Extract features of each e-mail (bag of words)
 - $(x_{ij} = 1)$ if word/phrase j is in e-mail i, $(x_{ij} = 0)$ if it is not





- Are there better features than bag of words?
 - We can add bigrams (sets of two words)
 - "CS 762", "Computer Science"
 - Or trigrams (sets of three words)
 - "University of Auckland", "Limited time offer"
 - We might include the sender domain
 - <sender domain == "mail.com" >
 - We might include regular expressions

Probabilistic Classifiers



- For years, best spam filtering methods used naive Bayes
 - A probabilistic classifier based on Bayes rule
 - It tends to work well with bag of words
- Probabilistic classifiers model the conditional probability, $p(y_i|x_i)$
 - "If a message has word x_i , what is the probability that message is spam?"
- Classify it as spam if conditional probability of spam is higher than that of not spam
 - If $p(y_i = 1|x_i) > p(y_i = 0|x_i)$ return "spam" else return "not spam"





- So far, learning as a search or based on rules
- For Bayesians: Learning is just another application of the Bayes' Theorem

$$P(Y|X) = \frac{P(X|Y)P(Y)}{P(X)}$$

Search the most likely hypothesis



Basic assumption



- Quantities of interest are governed by probability distributions
- Optimal decisions can be made by reasoning about these probabilities together with observed training data

Relevance



- Bayesian Learning is relevant for two reasons
 - 1. Explicit manipulation of probabilities
 - Among the most practical approaches to certain types of learning problems
 - E.g. Bayes classifier is competitive with decision tree and ANNs
 - Useful framework for understanding learning methods that do not explicitly manipulate probabilities
 - Determine conditions under which algorithms output the most probable hypothesis
 - E.g. justification of the least square error function
 - E.g. justification of the why smaller decision trees are preferred (Occam's razor)

Practical difficulties



- Initial knowledge of many probabilities is required
- Significant computational costs required

Bayes' Theorem

Bayes' Theorem



- \blacksquare Machine Learning is interested in the best hypothesis h from some space H, given observed training data D
- lacksquare best hypothesis pprox most probable hypothesis
- Bayes' Theorem provides a direct method of calculating the probability of such a hypothesis based on
 - its prior probability,
 - the probabilities of observing various data given the hypothesis, and
 - the observed data itself

Bayes' Theorem



$$P(Y|X) = \frac{P(X|Y)P(Y)}{P(X)}$$

which is short for $\forall x, y$:

$$P(Y = y | X = x) = \frac{P(X = x | Y = y)P(Y = y)}{P(X = x)}$$

Random events with outcome Ω

- Coins $\rightarrow \Omega = \{\text{"head", "tail"}\}\$
- Weather $\rightarrow \Omega = \{\text{"sunny", "rainy", ...}\}$

Random variable $X \rightarrow$ a function $\Omega \rightarrow E$

- Coins \rightarrow X = {"head" \rightarrow 0, "tail" \rightarrow 1}
- Weather \rightarrow X = {"sunny" \rightarrow 0, "rainy" \rightarrow 1, ...}

Bayesian Learning



- Given data set *D*, we want to find the *best* hypothesis *h*
- What does "best" mean?
- Bayesian learning uses P(h|D), the conditional probability of a hypothesis given the data, to define *best*

Bayesian Learning



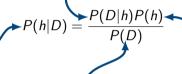
$$P(h|D) = \frac{P(D|h)P(h)}{P(D)}$$

- Key insights: Both h and D are events
 - D: The event that we observed this particular data set
 - *h*: The event that the hypothesis *h* is the true hypothesis
- \blacksquare \Rightarrow Hypothesis h and observed data set D to substitute X and Y in Bayes' Theorem

Bayesian Learning

Posterior probability: What is the probability that *h* is the hypothesis, given that the data *D* is observed?

Likelihood: What is the probability that this data point (an example or an entire data set) is observed, given that the hypothesis is *h*?



Prior Probability: What is the probability that the data D is observed (independent of any knowledge about the hypothesis)?



Prior Probability of *h*: Background knowledge. What do we expect the hypothesis to be even before we see any data? For example, in the absence of any information, maybe the uniform distribution.

Maximum A Posteriori Hypothesis





- In many learning scenarios, the learner considers some set of candidate hypotheses H and is interested in finding the most probable hypothesis $h \in H$ given the observed training data D
- Any maximally probable hypothesis is called maximum a posteriori (MAP) hypothesis h_{MAP}

$$h_{MAP} = \underset{h \in H}{\operatorname{arg \, max}} \, P(h|D)$$

$$= \underset{h \in H}{\operatorname{arg \, max}} \, \frac{P(D|h)P(h)}{P(D)} \, \text{by Bayes' Theorem}$$

$$= \underset{h \in H}{\operatorname{arg \, max}} \, P(D|h)P(h)$$

Note that we can drop P(D) because it is a constant independent of h

Choosing a Hypothesis



- Sometimes it is assumed that every hypothesis is equally probable apriori
- In this case, the equation above can be simplified
- Because P(D|H) is often called the likelihood of D given h, any hypothesis that maximizes P(D|h) is called maximum likelihood (ML) hypothesis

$$h_{ML} = \underset{h \in H}{\operatorname{arg\,max}} P(D|h)$$

Note that in this case P(h) can be dropped, because it is constant for each $h \in H$

Example



- Consider a medical diagnosis problem in which there are two alternative hypotheses
 - The patient has a particular form of cancer (denoted by *cancer*)
 - The patient does not have a cancer (denoted by $\neg cancer$)
- The available data is from a particular laboratory with two possible outcomes: ⊕ (positive) and ⊖(negative)

$$P(cancer) = 0.008$$
 $P(\neg cancer) = 0.992$ $P(\oplus | cancer) = 0.98$ $P(\ominus | cancer) = 0.02$ $P(\ominus | \neg cancer) = 0.97$

■ Suppose a new patient is observed for whom the lab test returns a positive (⊕) result. Should we diagnose the patient as having cancer or not?

$$P(cancer|\oplus) \sim P(\oplus|cancer)P(cancer)$$
 = 0.98 * 0.008 = 0.0078
 $P(\neg cancer|\oplus) \sim P(\oplus|\neg cancer)P(\neg cancer)$ = 0.03 * 0.992 = 0.0298
 $\Rightarrow h_{MAP} = \neg cancer$

Example (cont.)



■ The exact posterior probabilities can be determined by ?normalizing the above probabilities to sum up to 1

$$P(cancer|\oplus) = rac{0.0078}{0.0078 + 0.0298} = 0.21$$

 $P(\neg cancer|\oplus) = rac{0.0298}{0.0078 + 0.0298} = 0.79$

The probability of cancer increases when we observe a positive test result!

Bayes Optimal Classifier

Bayes Optimal Classifier



- Question: What is the most probable classification of the new instance given the training data?
- **Simply applying** h_{MAP} is not the best solution (as one could wrongly think of)
- Example
 - $H = \{h_1, h_2, h_3\}, \text{ where } P(h_1|D) = 0.4, P(h_2|D) = P(h_3|D) = 0.3$
 - \bullet $h_{MAP} = h_1$
 - Consider a new instance x encountered, which is classified positive by h_1 and negative by h_2 , h_3
 - Taking all hypotheses into account
 - The probability that x is positive is 0.4
 - The probability that x is negative is 0.6
 - \Rightarrow most probable classification \neq classification of h_{MAP}





■ The most probable classification is obtained by combining the predictions of all hypotheses, weighted by their posterior probabilities

$$P(v_j|D) = \sum_{h_i \in H} P(v_j|h_i)P(h_i|D)$$

where $P(v_j|D)$ is the probability that the correct classification is v_j

Bayes optimal classifier

$$\argmax_{v_j \in V} P(v_j|D) = \argmax_{v_j \in V} \sum_{h_i \in H} P(v_j|h_i) P(h_i|D)$$

Example



$$V = \{\oplus, \ominus\}$$

$$P(h_1|D) = 0.4, P(\ominus|h_1) = 0, P(\ominus|h_1) = 1$$

 $P(h_2|D) = 0.3, P(\ominus|h_2) = 1, P(\ominus|h_2) = 0$
 $P(h_3|D) = 0.3, P(\ominus|h_3) = 1, P(\ominus|h_3) = 0$

therefore

$$P(\oplus|D) = \sum_{h_i \in H} P(\oplus|h_i)P(h_i|D) = 0.4$$

$$P(\ominus|D) = \sum_{h_i \in H} P(\ominus|h_i)P(h_i|D) = 0.6$$

and

$$\argmax_{v_j \in \{\oplus,\ominus\}} \sum_{h_i \in H} P(v_j|h_i)P(h_i|D) = \ominus$$

Literature



- Chapter 6 of Mitchell's *Machine Learning*
- Chapter 8 of Bishop's Pattern Recognition and Machine Learning



Thank you for your attention!

https://ml.auckland.ac.nz