# Minhyeok Lee

Computer Vision Engineer, ML/DL Researcher

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# RESEARCH INTERESTS

### **Segmentation**

- Salient Object Detection
- Video Object Segmentation
- Camouflaged Object Detection

#### **Autonomous Driving**

- Lane Detection
- Monocular Depth Estimation
- LiDAR Point Cloud

#### **Detection & Recognition**

- Video Anomaly Detection
- Skeleton based Action Recognition

#### **Novel View Synthesis**

Neural Radiance Field

# **EDUCATION**

Yonsei University | College of Engineering

Integrated M.S./Ph.D. in Electrical and Electronic Engineering Image and Video Pattern Recognition Lab. (M.S/Ph.D 4th)

Yonsei University | College of Engineering

B.S. in Electrical and Electronic Engineering

Hansung Science High School

Seoul, Korea Mar. 2021-Present

Seoul, Korea Mar.2017-Feb.2021

Seoul, Korea Mar.2014-Feb.2017

# **PUBLICATIONS**

Unsupervised Video Object Segmentation via Prototype Memory Network, WACV'23

- Minhyeok Lee, Suhwan Cho, Seunghoon Lee, Chaewon Park, Sangyoun Lee

Treating Motion as Option to Reduce Motion Dependency in Unsupervised Video Object Segmentation WACV'23

- Suhwan Cho, Minhyeok Lee, Seunghoon Lee, Chaewon Park, Donghyeong Kim, Sangyoun Lee

Global-Local Aggregation with Deformable Point Sampling for Camouflaged Object Detection, arXiv'22

-Minhyeok Lee, Suhwan Cho, Chaewon Park, Dogyoon Lee, Jungho Lee, Sangyoun Lee

Domain Alignment and Temporal Aggregation for Unsupervised Video Object Segmentation, arXiv'22

-Suhwan Cho\*, Minhyeok Lee\*, Seunghoon Lee, Sangyoun Lee

Deblurred Neural Radiance Field with Physical Scene Priors, arXiv'22

-Dogyoon Lee, Minhyeok Lee, Chajin Shin, Sangyoun Lee

Hierarchically Decomposed Graph Convolutional Networks for Skeleton-Based Action Recognition, arXiv'22

- Jungho Lee, Minhyeok Lee, Dogyoon Lee, Sangyoon Lee

Pixel-Level Equalized Matching for Video Object Segmentation, arXiv'22

- Suhwan Cho, Woo Jin Kim, MyeongAh Cho, Seunghoon Lee, Minhyeok Lee, Chaewon Park, Sangyoun Lee

SPSN: Superpixel Prototype Sampling Network for RGB-D Salient Object Detection, ECCV'22

- Minhyeok Lee\*, Chaewon Park\*, Suhwan Cho, Sangyoun Lee

Tackling Background Distraction in Video Object Segmentation, ECCV'22

- Suhwan Cho, Heansung Lee, Minhyeok Lee, Chaewon Park, Sungjun Jang, Minjung Kim, Sangyoun Lee

Saliency Detection via Global Context Enhanced Feature Fusion and Edge Weighted Loss, ICIP'22

- Chaewon Park\*, Minhyeok Lee\*, MyeongAh Cho, Sangyoun Lee

#### Robust Lane Detection via Expanded Self Attention, WACV'22

- Minhyeok Lee, Junhyeop Lee, Dogyoon Lee, Woojin Kim, Sangwon Hwang, Sangyoun Lee

#### EdgeConv with Attention Module for Monocular Depth Estimation, WACV'22

- Minhyeok Lee, Sangwon Hwang, Chaewon Park, Sangyoun Lee

#### FastAno: Fast Anomaly Detection via Spatio-temporal Patch Transformation, WACV'22

- Chaewon Park, MyeongAh Cho, Minhyeok Lee, Sangyoun Lee

#### Multi-level Feature maps Attention for Monocular Depth Estimation, ICCE-Asia '21

- Seunghoon Lee, Minhyeok Lee, Sangyoun Lee

#### Regularization Strategy for Point Cloud via Rigidly Mixed Sample, CVPR'21

- Dogyoon Lee, Jaeha Lee, Junhyeop Lee, Hyeongmin Lee, Minhyeok Lee, Sungmin Woo, Sangyoun Lee

# **PROJECTS**

#### Development of degradation removal and video enhancement using artificial intelligence

Yonsei University

• Funded by Tech Incubator Program for startup Korea (TIPS)

Nov.2022-Present

- Deep learning researcher
- Video Enhancement, Video Super Resolution
- Development of an efficient intelligent image processing algorithm that is robust on complex degradation

# Development of learning technology to improve classification performance based on LiDAR point cloud Yonsei University

• Funded by Hyundai Motor Company

Apr.2021-Mar.2022

- Deep learning researcher
- Development of unsupervised and semi-supervised learning algorithms
- Development of lightweight models for point cloud classification

#### Road conditions and autonomous bus AI data

Yonsei University Sep.2020-Jun.2021

- Funded by National Information society Agency (NIA)
- Deep learning researcher
- Crack and Obstacle Segmentation
- Development of Road anomaly detection algorithms and models