SMART IRRIGATION SYSTEM

PROJECT REPORT

Submitted for CAL in B.Tech Internet of Things (CSE3009)

By

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CERTIFICATE

This is to certify that the Project work entitled "Smart Irrigation System" that is

being submitted by Piyush Bamel, Kaustubh Nagar and Kunal Dilip

Chandiramani for CAL in B.Tech. Internet of Things (CSE3009) is a record of

bonafide work done under my supervision. The contents of this Project work, in

full or in parts, have neither been taken from any other source nor have been

submitted for any other CAL course.

Place: VIT University, Chennai Campus

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Signature of Faculty:

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INTRODUCTION

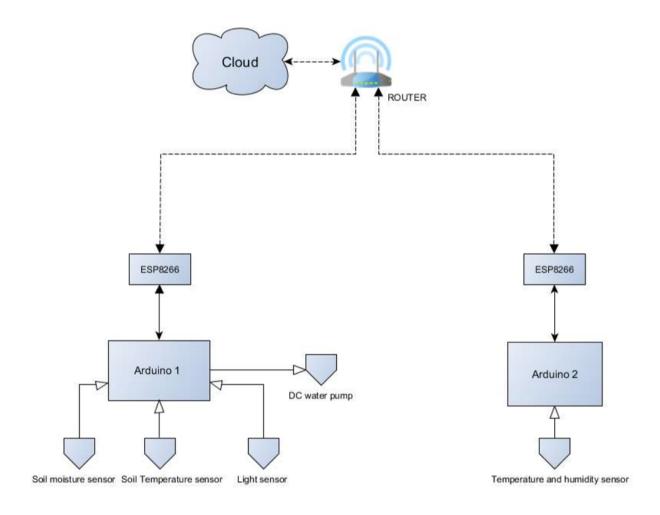
India is the country of village and agriculture plays an important role for development of country. In our country, agriculture depends on the monsoons which has insufficient source of water. So the irrigation is used in agriculture field. In Irrigation system, depending upon the soil type, water is provided to plant. In agriculture, two things are very important, first to get information of about the fertility of soil and second to measure moisture content in soil. Nowadays, for irrigation, different techniques are available which are used to reduce the dependency of rain. And mostly this technique is driven by electrical power and on/off scheduling. In this technique, water level indicator placed in water reservoir and soil moisture sensors are placed root zone of plant and near the module and gateway unit handles the sensor information and transmit data to the controller which in turns the control the flow of water through the valves.

Smart Irrigation System can be used for controlling the watering or irrigation of plants. It controls the irrigation of plants where the need of human intervention can be reduced. This mainly focused on wastage of water, which is a major concern of modern era. It also aids time saving, cost effectiveness, environmental protection, low maintenance and operating cost and efficient irrigation service. Arduino is used in the design of the prototype model in making the system compact and sustainable. The system has sensor which measures the moisture of the soil and switches on watering pump according to the requirement.

LEVEL OF DEPLOYMENT

Level 4: Data storage and Analysis on cloud with multiple nodes.

A level-4 IoT system has multiple nodes that perform local analysis. Data is stored in the cloud and application is cloud-based. Smart Irrigation System consists of multiple node placed in different locations for monitoring weather and plant in an area. Node 1 consists of temperature, humidity and dew point sensor which constantly monitors surrounding and sent data to cloud for further processing. Processing done over it in cloud is prediction of rainfall using minimum,maximum and average of temperature, humidity and dew point to predict category of rainfall. Node 2 consists of plant monitoring system with records and updates soil moisture as well status of motor. If a certain condition is met, it actuates the motor to water the plants.



IMPLEMENTATION AND WORKING

The system is realized using multiple components that work in synchronization. It consists of 2 Arduino Uno, one for calculating rain prediction and other for measuring the soil moisture in the soil and accordingly supplying water to the soil using water pump connected to it. To store the data and make rainfall prediction using machine learning algorithm the system uses Thingspeak cloud which is connected to the arduino using ESP8266 module. A dashboard was also developed for monitoring and controlling the system.

REQUIRED HARDWARE COMPONENTS:

- FOR SOIL MONITORING
- 1. Evana soil moisture/ humidity sensor
- 2. Arduino uno
- 3. REES52 serial wireless transceiver module for IOT ESP8266
- 4. Electomanai Micro DC 3-6V Micro submersible mini water pump
- 5. 9V Battery
- 6. Jumper wires

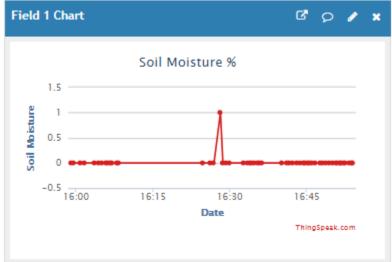
ESTIMATED COST: Rs 1577

- FOR WEATHER STATION
- 1. Robodo electronics DHT11 temperature and humidity sensor
- 2. Arduino uno
- 3. REES52 serial wireless transceiver module for IOT ESP8266
- 4. 9v battery
- 5. Jumper wires

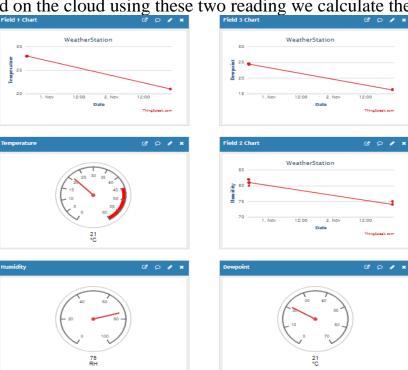
ESTIMATED COST: Rs 996

The working and steps involved in smart irrigation system are as follows:

- Initially node 1 (Soil monitoring node) checks for soil moisture using enava soil moisture and humidity sensor connected to it. If the soil moisture reading is less than 20 percent than it checks for rain prediction category.



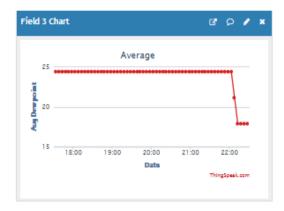
- Parallely node 2 (weather station node) takes the humidity and temperature reading from the environment and stores the data into the thingspeak cloud using ESP8266 module. Once humidity and temperature readings are uploaded on the cloud using these two reading we calculate the dew point.



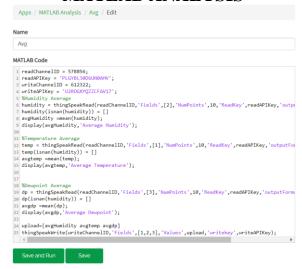
- In the cloud using the temperature, humidity and dew point readings, we also calculate the average temperature, average humidity and average dew point taking the last 10 readings. Which will be used as a feature for rainfall prediction. These are calculated with help of MATLAB Analysis with TimeControl (features provided by Thingspeak)







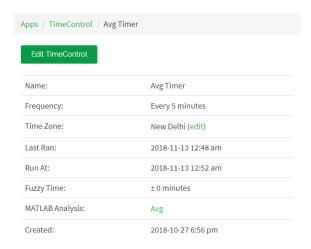
MATLAB ANALYSIS



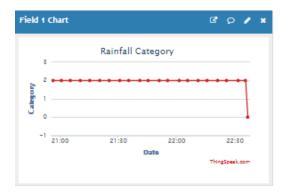
Code

```
readChannelID =;
      readAPIKey = ;
      writeChannelID =;
      writeAPIKey =;
      %Humidity Average
      humidity =
thingSpeakRead(readChannelID,'Fields',[2],'NumPoints',10,'ReadKey',readAPIKey
,'outputFormat','matrix');
      humidity(isnan(humidity)) = []
      avgHumidity = mean(humidity);
      display(avgHumidity,'Average Humidity');
      %Temperature Average
      temp =
thingSpeakRead(readChannelID,'Fields',[1],'NumPoints',10,'ReadKey',readAPIKey
,'outputFormat','matrix');
      temp(isnan(humidity)) = []
      avgtemp =mean(temp);
      display(avgtemp, 'Average Temperature');
      %Dewpoint Average
      dp =
thingSpeakRead(readChannelID,'Fields',[3],'NumPoints',10,'ReadKey',readAPIKey
,'outputFormat','matrix');
      dp(isnan(humidity)) = []
      avgdp =mean(dp);
      display(avgdp,'Average Dewpoint');
      upload=[avgHumidity avgtemp avgdp]
      thingSpeakWrite(writeChannelID, 'Fields', [1,2,3], 'Values', upload, 'writekey',
writeAPIKey);
```

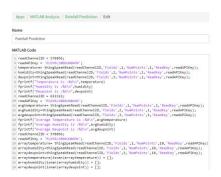
TimeControl



- Using year, month, day, max humidity, minimum humidity, average humidity, max temperature, minimum temperature, average temperature, max dew point, minimum dew point, average dew point as features we apply linear regression with gradient descent to predict the rainfall category. We have divided rainfall into four categories, the representation of these categories is 0 - no rainfall, 1 - light rainfall, 2 - medium rainfall, 3 - heavy rainfall. These are calculated with help of MATLAB Analysis with TimeControl (features provided by Thingspeak)



MATLAB ANALYSIS



Code

```
readChannelID =;
readAPIKey =;
temperature=
thingSpeakRead(readChannelID,'Fields',1,'NumPoints',1,'ReadKey',readAPIKey);
humidity=thingSpeakRead(readChannelID,'Fields',2,'NumPoints',1,'ReadKey',read
APIKey);
dewpoint=thingSpeakRead(readChannelID,'Fields',3,'NumPoints',1,'ReadKey',read
APIKey);
fprintf("Temperature is :%d\n",temperature)
fprintf("Humidity is :%d\n",humidity)
fprintf("Dewpoint is :%d\n",dewpoint)
readChannelID =;
readAPIKey =;
avgtemperature=
thingSpeakRead(readChannelID,'Fields',1,'NumPoints',1,'ReadKey',readAPIKey);
avghumidity=thingSpeakRead(readChannelID,'Fields',2,'NumPoints',1,'ReadKey',r
eadAPIKey);
avgdewpoint=thingSpeakRead(readChannelID,'Fields',3,'NumPoints',1,'ReadKey',r
eadAPIKey);
fprintf("Average Temperature is :%d\n",avgtemperature)
fprintf("Average Humidity is :%d\n",avghumidity)
fprintf("Average Dewpoint is :%d\n",avgdewpoint)
readChannelID =:
readAPIKey =;
arraytemperature=
thingSpeakRead(readChannelID,'Fields',1,'NumPoints',10,'ReadKey',readAPIKey);
arrayhumidity=thingSpeakRead(readChannelID,'Fields',2,'NumPoints',10,'ReadKe
y',readAPIKey);
arraydewpoint=thingSpeakRead(readChannelID,'Fields',3,'NumPoints',10,'ReadKe
y',readAPIKey);
arraytemperature(isnan(arraytemperature)) = [];
```

```
arrayhumidity(isnan(arrayhumidity)) = [];
arraydewpoint(isnan(arraydewpoint)) = [];
maxtemperature=max(arraytemperature);
maxhumidity=max(arrayhumidity);
maxdewpoint=max(arraydewpoint);
mintemperature=min(arraytemperature);
minhumidity=min(arrayhumidity);
mindewpoint=min(arraydewpoint);
d = datetime('today');
[year,month,date] = ymd(d);
theta = [0.122021\ 0.042260\ -0.013015\ -0.041535\ 0.146186\ -0.071218\ -0.052697\ -
0.034748 0.074159 0.128699]
X=[1 maxtemperature avgtemperature mintemperature maxdewpoint avgdewpoint
mindewpoint maxhumidity avghumidity minhumidity]
%use test set for prediction - using mean & stdev of entire set
v hat = X*theta';
fprintf("y hat is %d\n",y hat);
if y_hat<=1
y hat = 0;
elseif y_hat>1 && y_hat<=5
y_hat = 1;
elseif y_hat>5 && y_hat<10
y hat = 2;
else
y_hat = 3;
end
fprintf(' y = \%.3f \n',y_hat);
writeChannelID =:
writeAPIKey =;
thingSpeakWrite(writeChannelID,'Fields',1,'Values',y_hat,'writekey',writeAPIKey)
```

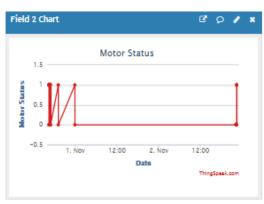
TimeControl

| Apps / TimeControl / Category | |
|-------------------------------|---------------------|
| Edit TimeControl | |
| Name: | Category |
| Frequency: | Every 5 minutes |
| Time Zone: | New Delhi (edit) |
| Last Ran: | 2018-11-13 12:55 am |
| Run At: | 2018-11-13 1:00 am |
| Fuzzy Time: | ± 0 minutes |
| MATLAB Analysis: | Rainfall Prediction |
| Created: | 2018-10-29 10:50 pm |

Once the rainfall category is predicted it send the back the category of rainfall predicted by the machine learning algorithm to node 1 (Soil Monitoring node) which depending on the rainfall category switches ON the motor (that pumps water). Like in our case if rainfall category is 0 - motor is switched ON for 10 seconds, 1 - motor is switched ON for 6 seconds, 2 - motor is switched ON for 3 seconds and for 3 - motor is switched On for

only 1 second.

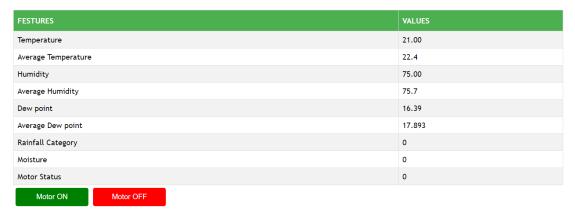




Also we have developed a dashboard for the user using which user can monitor the status at any point of time, also dashboard can be used to manually switch ON/OFF the motor according to the use of user. The link for dashboard is http://go-together.000webhostapp.com. System operates in 2 modes manual and automatic. When manually switched off from dashboard is goes to automatic mode.



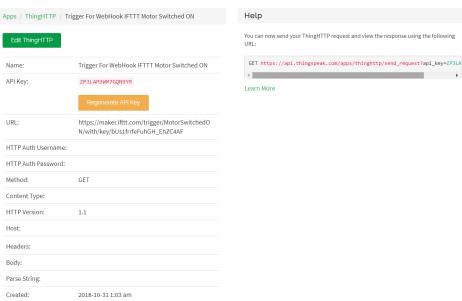
SMART IRRIGATION SYSTEM



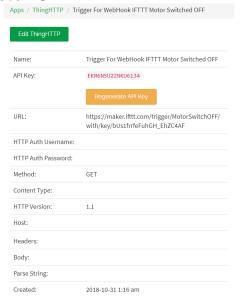
- Using webhooks in IFTTT platform http requests are called whenever the motor status changes. ThingHTTP is run with the help of React feature provided by Thingspeak. User gets notified on his/her mobile phone every time the motor switches ON/OFF.

ThingHTTP

• Motor ON



Motor OFF



React

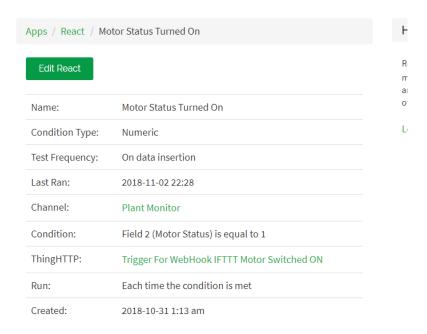
Help

Learn More

You can now send your ThingHTTP request and view the response using the following URL:

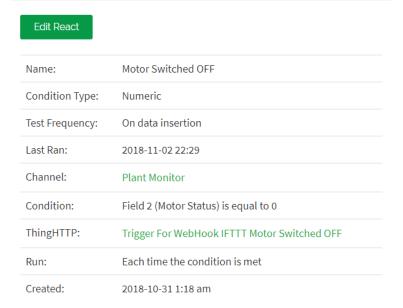
GET https://api.thingspeak.com/apps/thinghttp/send_request?api_key=EKM6N

• Motor ON

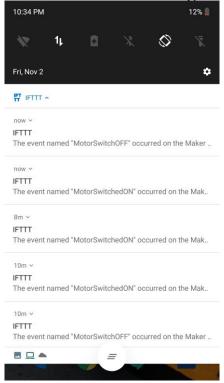


Motor OFF

Apps / React / Motor Switched OFF



Notification Generated on configured device



Widgets for Smartphone for easier monitoring



PROTOCOL STACK

As Arduino Uno doesn't have communication capabilities to internet, we require a ESP8266 module with provides it with TCP/IP stack.

COMMUNICATION PROTOCOL USED BY ARDUINO UNO ON PHYSICAL LAYER:

UART (Universal Asynchronous Receiver/Transmitter): UART is a form of serial communication because data is transmitted as sequential bits (we'll get to this in a bit). The wiring involved with setting up UART communication is very simple: one line for transmitting data (TX) and one line for receiving data (RX).

SPI (Serial Peripheral Interface): SPI is different from UART in several key ways: Synchronous. Follows a master-slave model, where there is one master device and multiple slave devices. More than two lines required for implementation

PROTOCOL STACK FOR COMMUNICATION BETWEEN ESP8266 AND CLOUD

| Layer | Protocols |
|-------------|-------------|
| Application | НТТР |
| Transport | TCP |
| Network | IPV4/IPV6 |
| Data Link | WIFI 802.11 |
| Physical | UART,SPI |

REST API is used for this constraint environment with uses HTTP over TCP. It works with client-server model. It is used as we only require latest message according when we have necessity of a service. Also for making operations energy efficient, arduino frequently goes in sleep state to save energy.

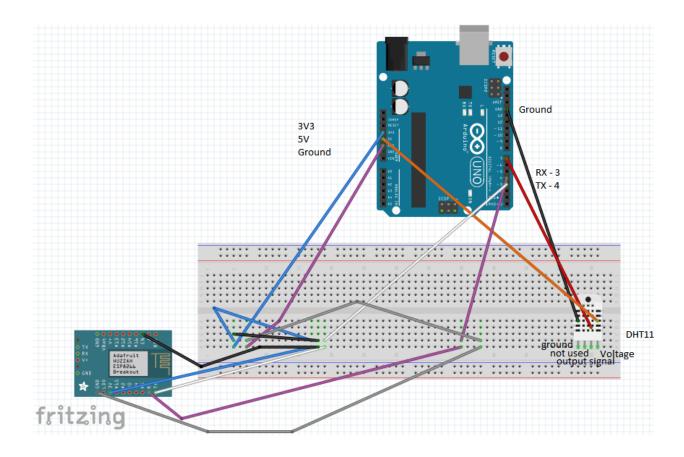
CHALLENGES/CONSTRAINTS

- ➤ To get better predictions more features are required like Sunlight intensity, cloud cover and wind speeds. If these features are used with pre-existing once, we would certainly see jump in accuracy of algorithm.
- ➤ Area specific meteorological data is required to make prediction more personalised and accurate.
- ➤ Keeping the equipment compact is also a challenge, as it constitutes in better usability and portability.
- ➤ Keeping cost low at prototyping is also a challenge. Mass production can drive the cost down significantly so it can be affordable to consumers.
- ➤ Plant specific information can also be useful for better usability of the product. It can be manually calibrated with ease during set-up time.

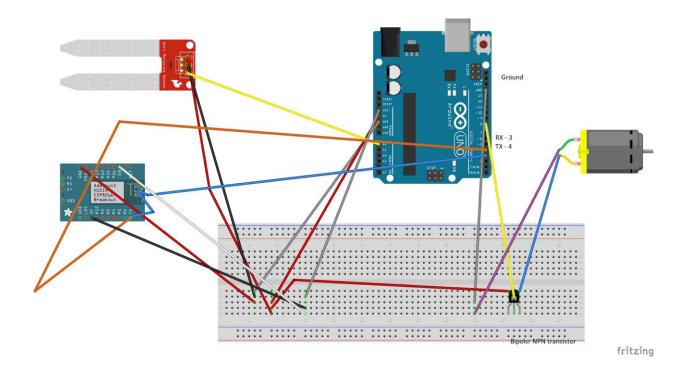
CIRCUIT DIAGRAMS

Circuits diagrams with pin configuration are made using a free software called fritzing http://fritzing.org/home/. Fritzing is an open-source hardware initiative that make electronics accessible as a creative material for anyone.

Weather Station



• Plant Monitoring



ARDUINO CODE

1. Weather_Station.ino

```
#include<SoftwareSerial.h> //to interface esp8266 with arduino through serial
communication
#include <dht.h>
dht DHT; //DHT sensor object
#define DHT11_PIN 7
SoftwareSerial esp8266(3,4);//set the software serial pins RX=3,TX=4
#define SID"piyush"
#define PASS"okaytry12"
void sendAT(String command,const int timeout){
 String response="";
 esp8266.print(command);
 long int time=millis();
 while((time+timeout)>millis()){
  while(esp8266.available()){
   char c = esp8266.read();
   response +=c;
 Serial.println(command);
void connectwifi(){
 delay(1000);
 sendAT("AT\r\n",2000);
 sendAT("AT+CWMODE=1\r\n",2000);//call sendAT function to set esp8266 to
station mode
 sendAT("AT+CWJAP=\""SID"\",\""PASS"\"\r\n",2000);//AT command to
connect with wifi network
 while(!esp8266.find("OK")){
  //wait for connection
 Serial.println("WIFI CONNECTED");
 sendAT("AT+CIFSR\r\n",2000);//AT command to print IP address on serial
monitor
 sendAT("AT+CIPMUX=0\r\n",2000);//AT command to set esp8266 to single
connection
```

```
void setup() {
 Serial.begin(115200);
 esp8266.begin(115200);//begin the software serial communication with baud rate
115200
 sendAT("AT+RST\r\n",2000);//call sendAT function to send reset AT command
 connectwifi();
void loop() {
 int chk = DHT.read11(DHT11_PIN);
 double gamma = log(DHT.humidity / 100) + ((17.62 * DHT.temperature) / (243.5)
+ DHT.temperature));
 double dp = 243.5 * gamma / (17.62 - gamma);
 //int converted to string so that values can be passed to cloud
 String Temperature=String(DHT.temperature);//convert integer to string data type
 String Humidity=String(DHT.humidity);
 String Dewpoint=String(dp);
 Serial.print("Temperature: ");
 Serial.println(Temperature);
 Serial.print("Humidity: ");
 Serial.println(Humidity);
 Serial.print("Dewpoint: ");
 Serial.println(Dewpoint);
 updateThinkspeak(Temperature,Humidity,Dewpoint);//call the function to update
Thingspeak channel
 delay(10000);
void updateThinkspeak(String Temperature,String Humidity,String Dewpoint){
 sendAT("AT+CIPSTART=\"TCP\",\"api.thingspeak.com\",80\r\n",2000);//tcp
connection with domain name and port no.
 delay(2000);
 String cmdlen;
 String cmd = "GET
/update?api_key=&field1="+Temperature+"&field2="+Humidity+"&field3="+De
wpoint+"\r\n";//update the temperature, humidity and dewpoint values to
thingspeak channel
 cmdlen=cmd.length();
 sendAT("AT+CIPSEND="+cmdlen+"\r\n",2000);
 esp8266.print(cmd);
 sendAT("AT+CIPCLOSE\r\n",2000);
 delay(1000);
```

2. Plant_Monitor.ino

```
#include<SoftwareSerial.h> //to interface esp8266 with arduino through serial
communication
SoftwareSerial esp8266(3,4);//set the software serial pins RX=3,TX=4
#define SID"piyush"
#define PASS"okaytry12"
String response="":
int sensor_pin = A0;
int output_value;
int a:
void sendAT(String command,const int timeout){
 response="";
 int copy=0;
 esp8266.print(command);
 long int time=millis();
 while((time+timeout)>millis()){
  while(esp8266.available()){
   char c = esp8266.read();
   if(isAlpha(c))
    copy=0;
   if(copy)
    response +=c;
   if(c==':')
    copy=1;
 Serial.println(command);
void connectwifi(){
 delay(1000);
 sendAT("AT\r\n",2000);
 sendAT("AT+CWMODE=1\r\n",2000);//call sendAT function to set esp8266 to
station mode
 sendAT("AT+CWJAP=\""SID"\",\""PASS"\"\r\n",2000);//AT command to
connect with wifi network
 while(!esp8266.find("OK")){
  //wait for connection
 Serial.println("WIFI Connected");
```

```
sendAT("AT+CIFSR\r\n",2000);//AT command to print IP address on serial
monitor
 sendAT("AT+CIPMUX=0\r\n",2000);//AT command to set esp8266 to single
connection
void setup() {
 Serial.begin(115200);
 pinMode(8, OUTPUT);
 int a=0;
 esp8266.begin(115200);//begin the software serial communication with baud rate
115200
 sendAT("AT+RST\r\n",2000);//call sendAT function to send reset AT command
 connectwifi();
 delay(2000);
  }
void loop() {
 output_value= analogRead(sensor_pin);
 output_value = map(output_value,1023,73,0,100);
 Serial.print("Mositure : ");
 Serial.println(output_value);
 String moisture=String(output_value);
 String motor;
   a=0:
   int auth=getData2();
   if(auth==1)
    Serial.println("Admin forced motor to start");
    a=1:
    motor=String(a);
    updateThinkspeak(moisture,motor);
    digitalWrite(8, HIGH);
   else{
    if(output_value<20)
       digitalWrite(8, LOW);
```

```
int category=getData();
 if(category==0)
  a=1:
  motor=String(a);
  updateThinkspeak(moisture,motor);
  Serial.println("Start Motor for 10 secs");
  digitalWrite(8, HIGH);
  delay(10000);
  digitalWrite(8,LOW);
  Serial.println("Motor Off");
  output_value= analogRead(sensor_pin);
  output_value = map(output_value,1023,73,0,100);
  String moisture=String(output_value);
  a=0;
if(category==1)
 a=1;
 motor=String(a);
 updateThinkspeak(moisture,motor);
 Serial.println("Start Motor for 6 secs");
 digitalWrite(8, HIGH);
 delay(6000);
 digitalWrite(8,LOW);
 Serial.println("Motor Off");
 output_value= analogRead(sensor_pin);
 output_value = map(output_value, 1023, 73, 0, 100);
 String moisture=String(output_value);
 a=0;
if(category==2)
 a=1:
 motor=String(a);
 updateThinkspeak(moisture,motor);
 Serial.println("Start Motor for 2 secs");
 digitalWrite(8, HIGH);
 delay(2000);
 digitalWrite(8,LOW);
 Serial.println("Motor Off");
 output_value= analogRead(sensor_pin);
 output value = map(output value, 1023, 73, 0, 100);
 String moisture=String(output_value);
```

```
a=0;
   if(category==3)
    a=1;
    motor=String(a);
    updateThinkspeak(moisture,motor);
    Serial.println("Start Motor for 1 sec for maintain threshold moisture");
    digitalWrite(8, HIGH);
    delay(1000);
    digitalWrite(8,LOW);
    Serial.println("Motor Off");
    output_value= analogRead(sensor_pin);
    output value = map(output value, 1023, 73, 0, 100);
    String moisture=String(output_value);
    a=0;
    Serial.println("Heavy Rainfall Prediction");
   a=0;
   motor=String(a);
   updateThinkspeak(moisture,motor);
else
   Serial.println("Enough moisture");
   a=0;
   motor=String(a);
   updateThinkspeak(moisture,motor);
}
delay(4000);
```

```
void updateThinkspeak(String Moisture,String Motor){
 sendAT("AT+CIPSTART=\"TCP\",\"api.thingspeak.com\",80\r\n",2000);//tcp
connection with domain name and port no.
 delay(2000);
 String cmdlen;
 String cmd = "GET /update?api_key=
&field1="+Moisture+"&field2="+Motor+"\r\n";//update the temperature,humidity
and dewpoint values to thingspeak channel
 cmdlen=cmd.length();
 Serial.println(cmd);
 sendAT("AT+CIPSEND="+cmdlen+"\r\n",2000);
 esp8266.print(cmd);
 sendAT("AT+CIPCLOSE\r\n",2000);
 delay(1000);
int getData(){
sendAT("AT+CIPSTART=\"TCP\",\"api.thingspeak.com\",80\r\n",2000);
 delay(2000);
 String cmdlen;
 String fieldname="field1":
String cmd="GET /channels/channel id/field/"+fieldname+"/last"+"\r\n";
///channels/channel_id/fields/1.csv?api_key="+API+"&results=1"+"\r\n"
 cmdlen=cmd.length();
sendAT("AT+CIPSEND="+cmdlen+"\r\n",2000);
 esp8266.print(cmd);
sendAT("AT+CIPCLOSE\r\n",2000);
 Serial.print("Rainfall Category Predicted: ");
 int category = response.toInt();
 Serial.println(category);
 return(category);
int getData2(){
 sendAT("AT+CIPSTART=\"TCP\",\"api.thingspeak.com\",80\r\n",2000);
 delay(2000);
 String cmdlen:
 String fieldname="field1";
 String cmd="GET /channels/channel id/field/"+fieldname+"/last"+"\r\n";
 cmdlen=cmd.length();
 sendAT("AT+CIPSEND="+cmdlen+"\r\n",2000);
 esp8266.print(cmd);
 sendAT("AT+CIPCLOSE\r\n",2000);
 Serial.print("Admin Mode: ");
```

```
int category = response.toInt();
Serial.println(category);
return(category);
delay(5000);
}
```

MACHINE LEARNING ALGORITHM

In the algorithm we have used linear regression with gradient descent to predict the rainfall. We have used gradient descent for error optimization with learning rate of 0.01 and make it loop for 4000 iterations. Initially before training the algorithm we have applied regularization for better results . Also we have divided our dataset into train and test, so that we can test our model and check its mean square error. We see that our model has performed very well with training error of 0.082 and testing error of 0.015.

CODE:

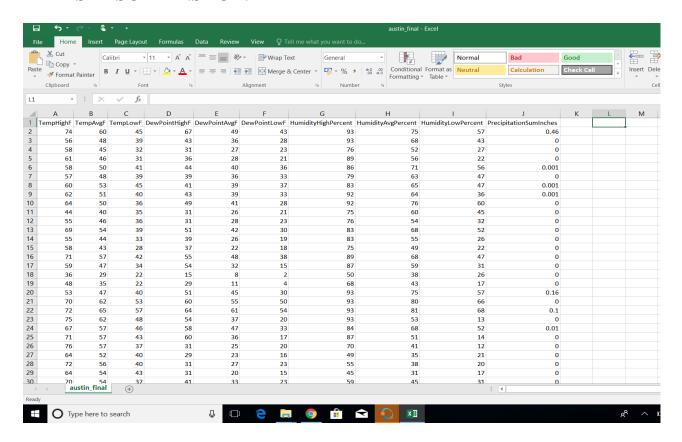
%Linear Regression with Gradient Descent

```
%% Clear and Close Figures
clear; close all; clc
%Input must contain feature columns followed by dependent variable column at
end
data = csvread('austin_final.csv');
%Gradient Descent parameters
alpha = 0.01; num_iters = 4000;
% percentage of data to use for training
train_perc = .95;
%extract columns to use
X = data(:,1:end-1);
X_{orig} = X;
y = data(:,end);
% Print out some data points
fprintf('First 3 examples from the dataset: \n');
%.0f %.0f %.0f %.0f %.0f , y = \text{%.0f } / n', [X(1:3,:) y(1:3,:)]';
fprintf('Program paused. Press enter to continue.\n');
pause;
%split into training and test sets:
test\_rows = round(size(X,1)*(1-train\_perc)); % number of rows to use in test set
X_{\text{test}} = X(1:\text{test\_rows,:}); y_{\text{test}} = y(1:\text{test\_rows,:}); \% \text{ this is the test set}
X = X(\text{test\_rows}+1:\text{end},:); y = y(\text{test\_rows}+1:\text{end},:); \% \text{this is the training set}
```

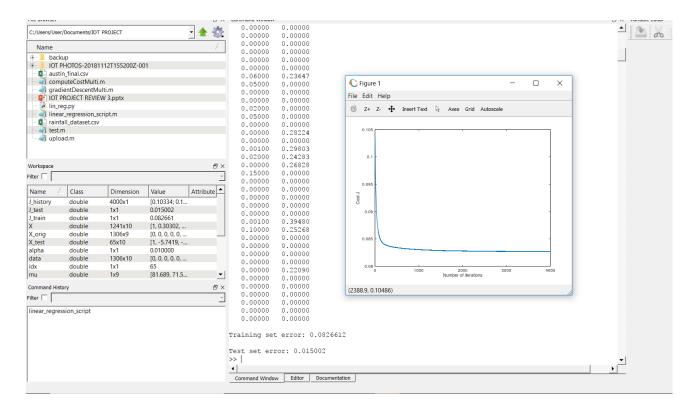
```
%Compute mean and standard deviation, normalize X
mu = mean(X); sigma = std(X);
X = (X-repmat(mu, size(X,1) 1))./repmat(sigma, size(X,1) 1);
X_{test} = (X_{test-repmat}(mu, size(X_{test,1}) 1))./repmat(sigma, size(X_{test,1}) 1));
% Add intercept term to X
X = [ones(size(X,1), 1) X];
X_{\text{test}} = [ones(size(X_{\text{test}}, 1), 1) X_{\text{test}}];
% Init Theta and Run Gradient Descent
theta = zeros(size(X,2), 1);
[theta, J history] = gradientDescentMulti(X, y, theta, alpha, num iters);
% Plot the convergence graph
figure; plot(1:numel(J_history), J_history);
xlabel('Number of iterations'); ylabel('Cost J');
% Display gradient descent result
fprintf('Theta computed from gradient descent: \n');
fprintf('\%f \n', theta);
% Display cost function start and end values
fprintf('Cost function start: %g\n',J_history(1));
fprintf('Cost function end: %g\n',J_history(end));
%use test set for prediction - using mean & stdev of entire set
y_hat = X_test*theta;
%Compute training set error
J train = computeCostMulti(X, y, theta);
%Compute test set error
J_test = computeCostMulti(X_test,y_test,theta);
fprintf('Program paused. Press enter to continue.\n');
pause;
for idx = 1:numel(y_hat)
 if y_hat(idx) < 0.2
  y_hat(idx) = 0;
 endif
end
```

%print test set variable - actual and prediction fprintf('\nLinear fit:\n\n') fprintf('\ty\t\ty_hat\n'); disp([y_test,y_hat]); fprintf('\nTraining set error: %g\n',J_train); fprintf('\nTest set error: %g\n',J_test); %EOF

DATASET SCREENSHOT:

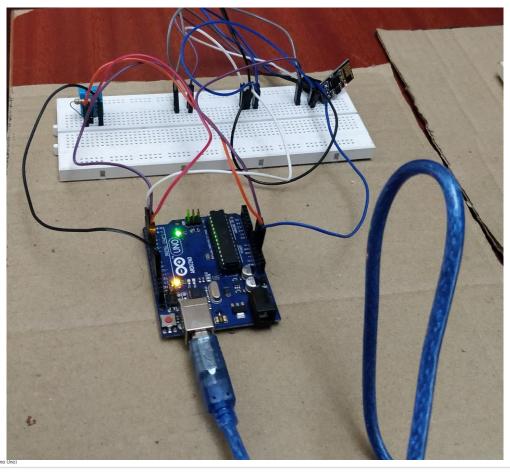


OUTPUT:



IMPLEMENTATION IMAGES

• Weather Station



```
COMS (Arduino/Genuino Uno)

- D X

RAT+RST

AT

AT+CWMODE=1

AT+CWJAP="piyush","okaytry12"

WIFI CONNECTED

AT+CIFER

AT+CIFERUX=0

Temperature: 21.00

Humidity: 74.00

Dewpoint: 16.18

AT+CIPSTART="TCP","api.thingspeak.com",80

AT+CIPSEND=77

AT+CIPSEND=77

AT+CIPCLOSE
```

• Plant Monitoring



No watering required as minimum moisture % condition met:



Admin controlling motor:



Automatic turning on of motor according to prediction

