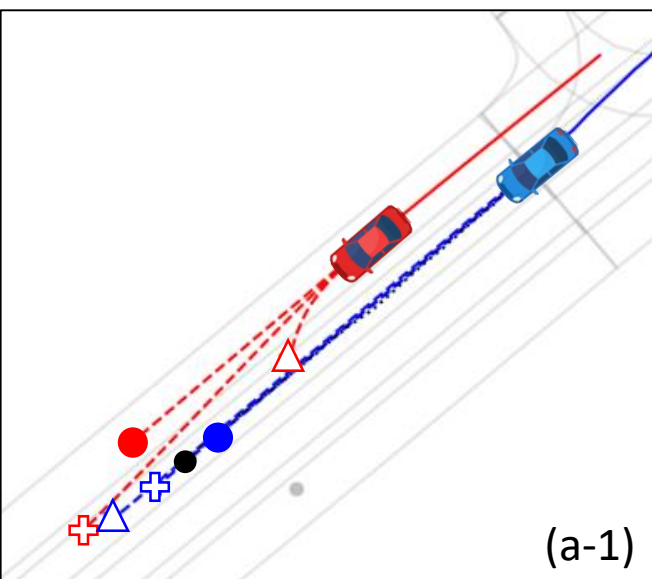
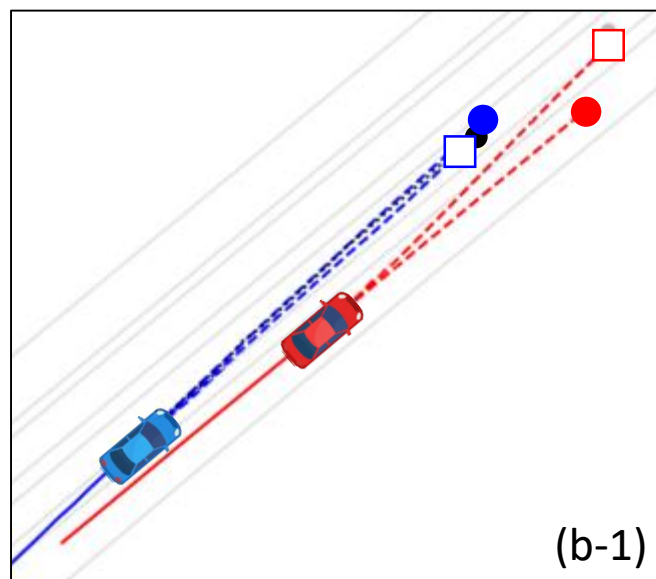


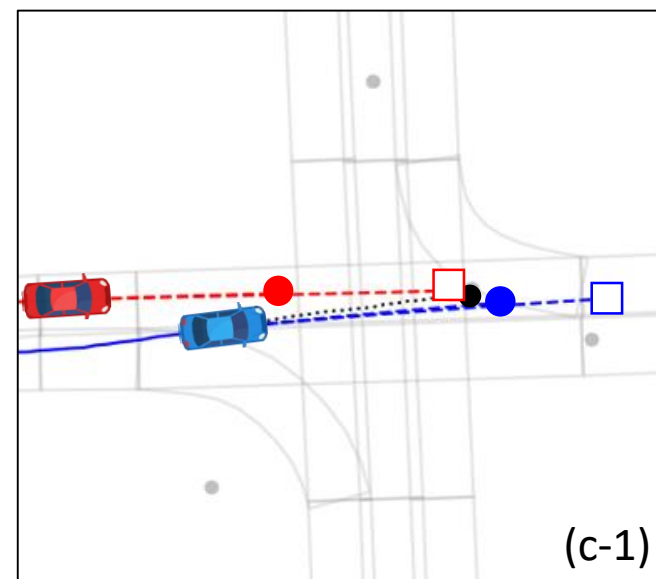
Scenario 1



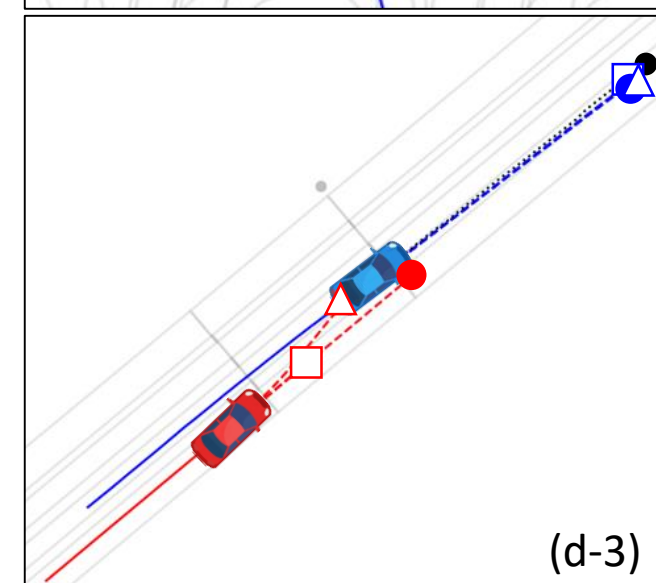
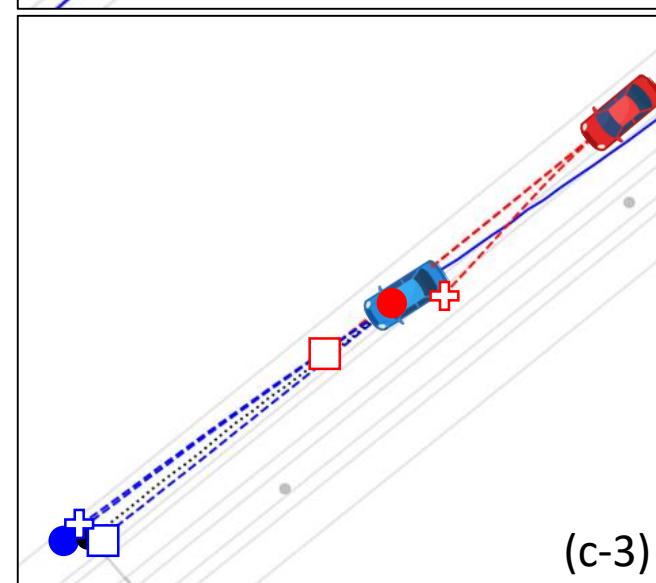
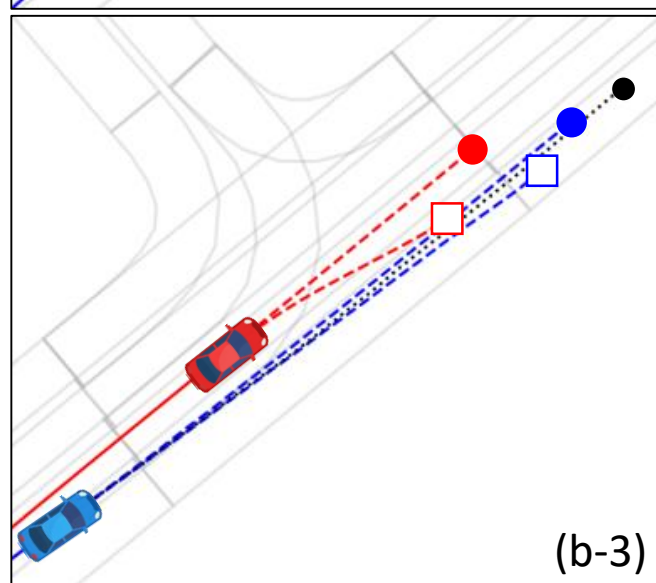
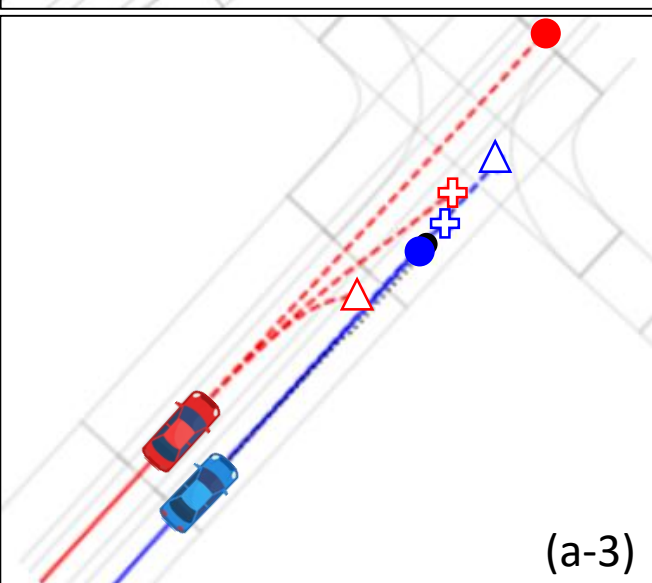
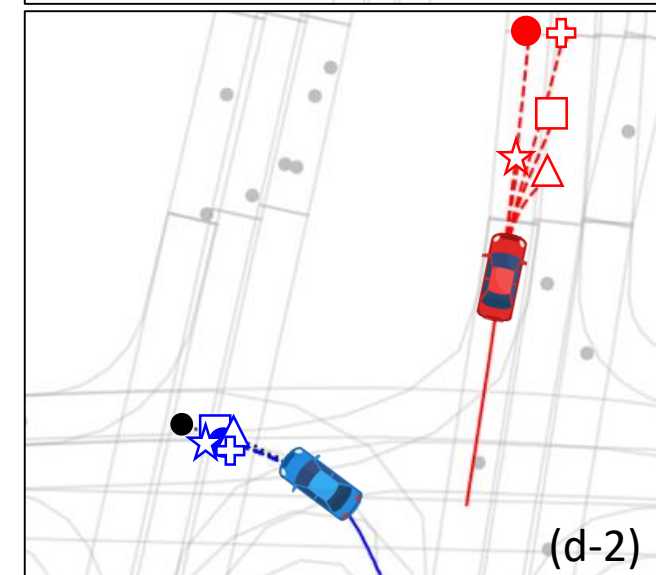
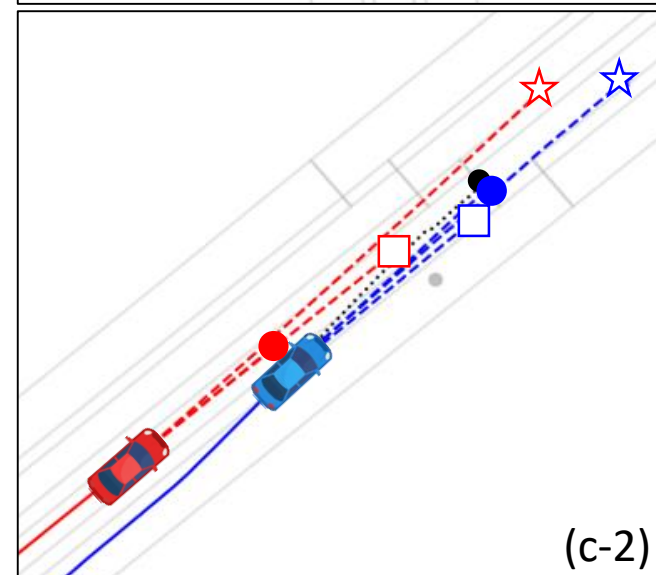
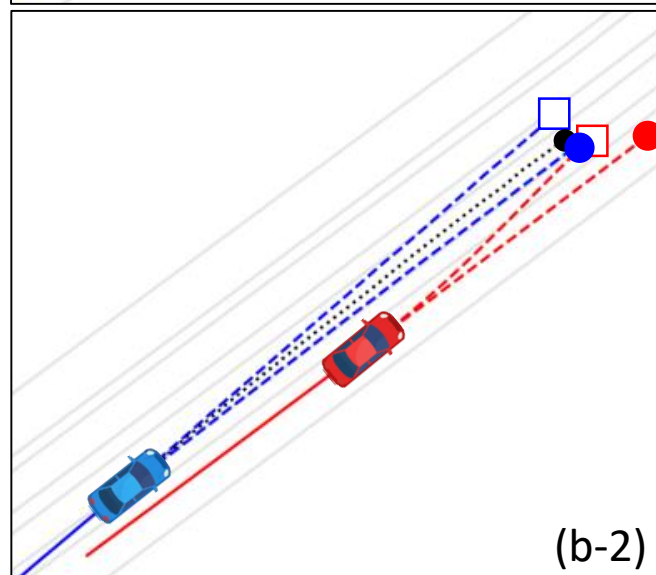
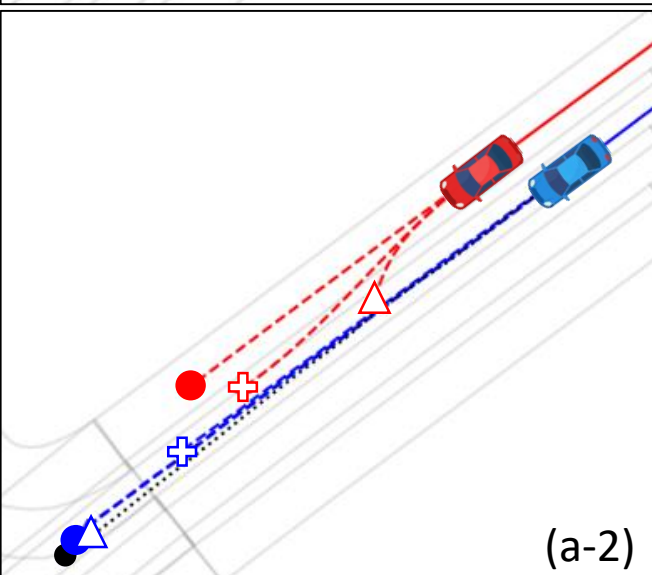
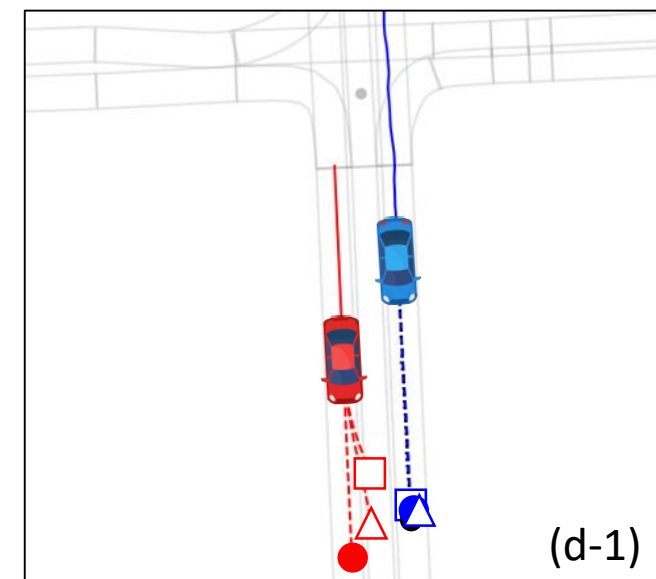
Scenario 2



Scenario 3



Scenario 4



: Ego vehicle

: Historical trajectory

: Final position of the ego given in the dataset

: Final position of the manually generated ego action plan

: Target vehicle

: Future action candidates

: Predicted trajectory

: Final position of the predicted trajectory correspond to , respectively

: Ground truth trajectory and final position in the dataset

: Current position of the other vehicles