

## Lecture 8

### time reversal + reversibility

$X_n$  is a M.C. fix some  $N$

Let  $Y_n = X_{N-n}$

Thm: If  $X_n$  is a M.C.  
with stat. dist.  $\pi$  and  
 $X_0$  has dist.  $\pi$ , then  
 $Y$  is also a M.C. with  
trans. prob.  $Q_{ij} = \frac{P_{ji} \cdot \pi_j}{\pi_i}$ .

Proof: for any seq. of states

$x_0 x_1 \dots x_N$ , the

$$P(X_i = x_i \text{ for } i=0, \dots, N)$$

$$= \pi_{x_0} P_{x_0 x_1} P_{x_1 x_2} \dots P_{x_{N-1} x_N}$$

This is  $P(Y_i = x_{N-i} \text{ for all } i)$

Claim: This equals

$$\pi_{x_N} Q_{x_N x_{N-1}} Q_{x_{N-1} x_{N-2}} \dots Q_{x_1 x_0}$$

need:

$$\pi_{x_0} \prod P_{x_i x_{i+1}} = \pi_{x_N} \prod Q_{x_{i+1} x_i}$$

If plug in  $Q_{ij} = \frac{P_{ji} \pi_j}{\pi_i}$

$$\pi_{x_N} \prod Q_{x_{i+1} x_i} = \pi_{x_N} \prod \frac{P_{x_i x_{i+1}} \pi_{x_i}}{\pi_{x_{i+1}}}$$

$$= \prod P_{x_i x_{i+1}} \cdot \frac{\pi_{x_0}}{\pi_{x_1}} \frac{\pi_{x_1}}{\pi_{x_2}} \dots \frac{\pi_{x_{N-1}}}{\pi_{x_N}} \pi_{x_N}$$

$$= \pi_{x_0} \prod P_{x_i x_{i+1}} \quad \square$$

Proposition:  $Q$  has same  
stat. dist. as  $P$ , namely  
 $\pi$ .

Proof: need  $\pi Q = \pi$ .

$$(\pi Q)_j = \sum_i \pi_i Q_{ij} = \sum_i \pi_i \frac{P_{ji}}{\pi_i} \pi_j$$

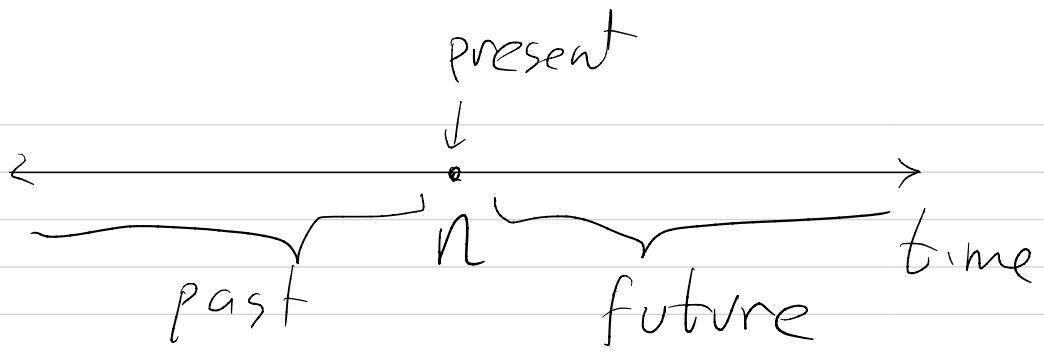
$$= \left( \sum_i P_{ji} \right) \cdot \pi_j = \pi_j \quad \square$$

Thm: If  $(X_i)_{i=0 \dots N}$  is any M.C.

then  $Y_n = X_{N-n}$  is also a  
M.C.

Note: If  $X$  is not stationary  
then  $Y$  might not be  
time homog.

Proof idea: Markov property,  
given present, future is  
indep. of past.



□

In general  $Q \neq P$ .

Def: A Markov chain  
is reversible if  $Q = P$   
i.e. for any  $i, j$   $P_{ij} = Q_{ij}$

$$\forall i, j \quad \pi_i \cdot P_{ij} = \pi_j \cdot P_{ji} \quad (*)$$

(\*) is called detailed  
balance equation

Thm: If  $P$  is an irreducible  
stoch. matrix and  $\pi$  has  
 $\sum \pi_i = 1$  and detailed balance  
then  $\pi$  is the stat. dist.  
for  $P$ .

Pf need  $\pi P = \pi$

$$(\pi P)_j = \sum_i \pi_i P_{ij}$$

$$= \sum_i \pi_j P_{ji} \quad (\text{def. bal.})$$

$$= \pi_j \sum_i P_{ji} = \pi_j$$

□