SE102:Multivariable Calculus

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> Lecture 07 Stokes Theorem

From now on, we will assume that every function is differentiable and is of class \mathcal{C}^{∞} . (We call such functions as smooth functions.)

Definition

Let $\varphi(x,y)$ be a function defined on a region $D \subset \mathbf{R}^2$. The vector field $\nabla \varphi$ is called the **gradient vector field** of φ . Conversely, let $\mathbf{F}: D \to \mathbf{R}^2$ be a vector field defined on D. A function $\varphi(x,y)$ satisfying

$$\nabla \varphi = (\varphi_x, \varphi_y) = \mathbf{F}$$

is called the **potential function** of **F**.

Let $\mathbf{F}(x,y) = (P(x,y), Q(x,y))$. If $Q_x - P_y = 0$, then \mathbf{F} is called a **closed** vector field.

Theorem

If a vector field **F** admits a potential function, then it is closed.

Proof.

Suppose that $\mathbf{F} = (P, Q) = \nabla \varphi$. Then

$$Q_x - P_y = \varphi_{yx} - \varphi_{xy} = 0.$$

A vector field \mathbf{F} defined on $D \subset \mathbf{R}^2$ is called **conservative** if the value of line integral $\int_C \mathbf{F} \cdot d\mathbf{s}$ only depends on the start and end point of a parametrization of the curve $C \subset D$. Equivalently, a vector field is conservative if

$$\oint_C \mathbf{F} \cdot d\mathbf{s} = 0$$

for any closed curve $C \subset D$.

Theorem

If a vector field ${\bf F}$ admits a potential function, then it is conservative.

Proof.

Let $c(t) = (x(t), y(t)), a \le t \le b$, be a parametrization of C from $p_0 = c(a)$ to $p_1 = c(b)$. Note that

$$\int_{C} \mathbf{F} \cdot d\mathbf{s} = \int_{C} \varphi_{x} dx + \varphi_{y} dy = \int_{a}^{b} \frac{\partial \varphi}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial \varphi}{\partial y} \frac{\partial y}{\partial t} dt$$

By the Chain rule, we get

$$\int_{a}^{b} \frac{\partial \varphi}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial \varphi}{\partial y} \frac{\partial y}{\partial t} dt = \int_{a}^{b} \frac{d}{dt} \varphi(x(t), y(t)) dt = \varphi(p_{1}) - \varphi(p_{0}).$$



Let $D = \{(x, y) | x, y > 0\}$ be the first quadrant on \mathbb{R}^2 . The function

$$\theta(x,y) = \tan^{-1}\left(\frac{y}{x}\right)$$

is a potential function of the vector field

$$\mathbf{A} = \left(-\frac{y}{x^2 + y^2}, \frac{x}{x^2 + y^2}\right)$$

on D. Does A admits a potential function on $\mathbb{R}^2 - \{(0,0)\}$?

A curve $C \subset \mathbf{R}^2$ is said to be **simple** if it has no self-intersection. We say a simple closed curve $C \subset \mathbf{R}^2$ is **positively oriented** if it is parametrized by c(t) where the region by C always lies on the *left* side of the tangent vector c'(t).

Theorem (Green)

Let D be a connected region in \mathbb{R}^2 bounded by piecewise differentiable simple closed curve C. Let $\mathbf{F}(x,y) = (P(x,y),Q(x,y))$ be a vector field defined on D. Then

$$\oint_C \mathbf{F} \cdot d\mathbf{s} = \iint_D Q_x - P_y dA$$

where the curve C is positively oriented.

Proof.

Suppose that the region D is given by

$$D = \{(x, y) \mid a \le x \le b, g_1(x) \le y \le g_2(x)\}$$

Then

$$\oint_C Pdx = \int_a^b P(x, g_1(x)) dx + \int_b^a P(x, g_2(x)) dx
= \int_a^b P(x, g_1(x)) - P(x, g_2(x)) dx = -\iint_D P_y dA$$

Similarly, we can show that
$$\int_C Qdy = \iint_D Q_x dA$$
.

A region $D \subset \mathbf{R}^2$ is said to be **connected** if every pair of points in D can be connected by a path in D. The set D is said to be **simply connected** if every *loop* can be continuously *shrink* to a point.

Corollary

A vector field **F** defined on a simply connected region is conservative if it is a closed vector field.

Theorem (Poincare lemma)

Let \mathbf{F} a vector field defined on a simply connected region $D \subset \mathbf{R}^2$. If \mathbf{F} is closed, then \mathbf{F} admits a potential function. Furthermore, if D is connected, then the potential function is unique up to constant multiple.

Proof.

Let p_0 be a point in D. For p = (x, y) in D, let us define a function $\varphi(x, y)$ as follows.

$$\varphi(x,y) = \int_{p_0}^{p} \mathbf{F} \cdot d\mathbf{s} = \int_{p_0}^{p} P dx + Q dy$$

The function $\varphi(x,y)$ is well-defined. Suppose that the path in the integral near p is given by $c(t)=(x+t,y), \ \epsilon\in(-\epsilon,0]$. Then

$$\varphi_x = \frac{\partial}{\partial x} \int_{(x-\Delta x,y)}^{(x,y)} P dx = P.$$

We can show $\varphi_y = Q$ in a similar way.

Let C be the semicircular arc from (0,2) to (0,-2) oriented counter-clockwise. Evaluate

$$\int_C xy^2 dx - xy dy$$

Example

Let C be the circle $(x-2)^2 + (y-3)^2 = 1$ oriented counter-clockwise. Evaluate

$$\int_C (y - \log(x^2 + y^2)) dx + (2 \tan^{-1}(y/x)) dy$$

Let (a_1, b_1) , (a_2, b_2) , \cdots , (a_n, b_n) be the successive vertices of a *convex n*-polygon. Show that the area inside the polygon is

$$\frac{1}{2} \left(\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix} + \begin{vmatrix} a_2 & b_2 \\ a_3 & b_3 \end{vmatrix} + \dots + \begin{vmatrix} a_{n-1} & b_{n-1} \\ a_n & b_n \end{vmatrix} + \begin{vmatrix} a_n & b_n \\ a_1 & b_1 \end{vmatrix} \right)$$

Suppose that a simple closed curve C in \mathbb{R}^3 bounds a orientable surface S with a fixed orientation \mathbf{n} . We say C is **positively** oriented with respect to S if it is parametrized by $\mathbf{c}(t)$ where the surface S is on the *left* side of the tangent vector $\mathbf{c}'(t)$ when the *upward* direction is \mathbf{n} .

Theorem (Stokes)

Let S be an oriented surface with a piecewise continuous boundary C. For \mathbf{F} be a continuous vector field defined on S. Then

$$\oint_C \mathbf{F} \cdot d\mathbf{s} = \iint_S \nabla \times \mathbf{F} \cdot d\mathbf{S}$$

where C is positively orientated with respect to S.

Proof.

Let $\mathbf{F} = (P, Q, R)$ be a 3-dimensional vector field. Suppose that the surface S is given by the graph of z = f(x, y) over a region $D \subset \mathbf{R}^2$. Let X(x, y) = (x, y, f(x, y)) be the parametrization of S. Then

$$\iint_{S} \nabla \times \mathbf{F} d\mathbf{S} = \iint_{D} -(R_{y} - Q_{z}) f_{x} - (P_{z} - R_{x}) f_{y} + (Q_{x} - P_{y}) dA$$
$$= \iint_{D} \frac{\partial}{\partial x} (Q + R f_{y}) - \frac{\partial}{\partial y} (P + R f_{x}) dA$$

Let C' be a planar curve which bounds that area D. By Green's theorem, the last integral becomes

$$\oint_{C'} (P + Rf_x) dx + (Q + Rf_y) dy = \oint_{C} P dx + Q dy + R dz = \oint_{C} \mathbf{F} \cdot d\mathbf{s}$$



Remark

Stokes' theorem provides the meaning of curl $\nabla \times \mathbf{F}$ of a vector field \mathbf{F} . Suppose that the surface S is planar disk with sufficiently small radius r centered at (x_0, y_0, z_0) . Then

$$\oint_C \mathbf{F} \cdot d\mathbf{s} \approx \text{area} S \cdot (\nabla \times \mathbf{F})(x_0, y_0) \circ \mathbf{n}$$

When \mathbf{n} is the orientation of S, we can say

$$(\nabla \times \mathbf{F})(x_0, y_0) \circ \mathbf{n} \approx \frac{1}{\text{area}S} \oint_C \mathbf{F} \cdot d\mathbf{s}$$

Let S be the surface bounded by $z = 1 - x^2 - y^2$, $z \ge 0$ with upward orientation $(\mathbf{n} \cdot \mathbf{k} \ge 0)$. Confirm that Stokes' theorem holds for $\mathbf{F} = (y, -x, 0)$.

A surface S in \mathbb{R}^3 is said to be **closed** it it has no boundary.

Theorem (Divergence Theorem)

Let V be a region in \mathbf{R}^3 whose boundary $S = \partial V$ is a closed orientable surface. For a vector field \mathbf{F} defined on V,

$$\iint_{S} \mathbf{F} \cdot d\mathbf{S} = \iiint_{V} \nabla \cdot \mathbf{F} dV$$

where the orientation of S is set to be the outward direction.

Proof.

For $\mathbf{F} = (P, Q, R)$, we have

$$\iint_{S} \mathbf{F} \cdot d\mathbf{S} = \iint_{S} P\mathbf{i} \cdot \mathbf{n} dS + \iint_{S} Q\mathbf{j} \cdot \mathbf{n} dS + \iint_{S} R\mathbf{k} \cdot \mathbf{n} dS$$

Suppose that the volume V is given by

$$V = \{(x, y, z) \mid h_1(x, y) \le z \le h_2(x, y), (x, y) \in D\}.$$

Then

$$\iint_{S} R\mathbf{k} \cdot \mathbf{n} dS = \iint_{S_{1}} R\mathbf{k} \cdot \mathbf{n} dS + \iint_{S_{2}} R\mathbf{k} \cdot \mathbf{n} dS$$
$$= \iint_{D} R(x, y, h_{2}(x, y)) - R(x, y, h_{1}(x, y)) dx dy$$
$$= \iiint_{V} R_{z} dV$$

Compute the surface integral $\iint_S \mathbf{F} \cdot d\mathbf{S}$ where

$$\mathbf{F} = (z^2, \frac{1}{3}x^3 + \tan z, z + y^2)$$
 and S is the closed surface $x^2 + y^2 + z^2 = 1$.

Let S be a parabola $x^2 + y^2 + z = 2$ above the plane z = 1. Find the flux of $\mathbf{F} = (z \tan^{-1}(y^2), z^3 \ln(x^2 + 1), z)$ to the upward direction of S.

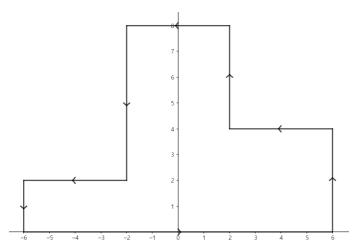
Let $\mathbf{F} = \frac{(x,y,z)}{(x^2+y^2+z^2)^{3/2}}$ and S be the surface $z=4-x^2-y^2$, $z \geq 0$ with upward orientation $\mathbf{n} \cdot \mathbf{k} \geq 0$. Use divergence theorem to compute the flux $\iint_S \mathbf{F} \cdot d\mathbf{S}$. (How should we choose the volume V?)

Let $\mathbf{F} = \langle 3y, -4x \rangle$. Find $\oint_{\partial D} \mathbf{F} \cdot d\mathbf{s}$ oriented counter-clockwise for the following region.

- 1. $D = \{(x, y) \mid x^2 + y^2 \le 4\}$
- 2. $D = \{(x,y) \mid x^2 + 2y^2 \le 4\}$

Problem Evaluate $\oint_C 5ydx - 3xdy$ where C is the cardioid $r=1-\sin\theta$ oriented counter-clockwise.

Evaluate $\oint_C (x^4y^5 - 2y)dx + (3x + x^5y^4)dy$ where C is as shown below.



Determine the value of

$$\oint_C \frac{xdx + ydy}{x^2 + y^2}$$

where C is a simple closed curve enclosing the origin oriented counter-clockwise.

Let

$$\mathbf{A} = \frac{(x, y, z)}{(x^2 + y^2 + z^2)^{3/2}}$$

Let S be a surface bounded by $z=4-x^2-y^2,\,z\geq 0,$ orieted upward. Find

$$\iint_{S} \mathbf{A} \cdot d\mathbf{S}$$

.

Let S be the surface bounded by $z = e^{-x^2 - y^2}$ and $z \ge 1/e$. Let **n** be the orientation of S satisfying $\mathbf{n} \cdot \mathbf{k} \ge 0$. Find the flux of

$$\mathbf{F} = (e^{x+y} - xe^{y+z}, e^{y+z} - e^{x+y}, 2)$$

on S to the direction of \mathbf{n} .

Let C be the intersection of $z = 1 - 2(x^2 + y^2)$ and $z = x^2 - y^2$ oriented counter-clockwise. Find $\oint_C \mathbf{F} \cdot d\mathbf{s}$ where

$$\mathbf{F} = (y\cos(x) - yz, \sin x, e^z)$$

Let $S = \partial V$ be a closed surface. Prove the following statements.

1. For any constant vector field **C**,

$$\iint_{S} \mathbf{C} \cdot d\mathbf{S} = 0$$

2. For any vector field \mathbf{F} ,

$$\iint_{S} \nabla \times \mathbf{F} \cdot d\mathbf{S} = 0$$

Explain geometric meanings of curl $(\nabla \times \mathbf{F})$ and divergence $(\nabla \cdot \mathbf{F})$ for 2 or 3-dimensional vector fields.