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A Appendix

A.1 Experimental setup

A.1.1 BigToM

BigToM (Gandhi et al., 2023) is constructed using GPT-4 (Achiam et al., 2023) to populate causal templates and combine elements from these templates. Each causal template is set up with a *context* and a description of the *protagonist* (e.g. “Noor is working as a barista [...]”), a *desire* (“Noor wants to make a cappuccino”), a *percept* (“Noor grabs a milk pitcher and fills it with oat milk”), and a *belief* (“Noor believes that the pitcher contains oat milk”). The state of the world is changed by a *causal event* (“A coworker swaps the oat milk in the pitcher with almond milk”). The dataset constructs different conditions by changing the percepts of the protagonist after the causal event, which will result in different beliefs – true or false. Gandhi et al. (2023) generated 200 templates and extracted 25 conditions from each template, resulting in 5,000 test samples. In this work, following Zhu et al. (2024) and Gandhi et al. (2023) we focused on the 6 most important conditions, corresponding to true and false beliefs on the following three tasks:

- *Forward Belief*: given the protagonist’s percepts of the causal event, infer their belief: $P(\text{belief}|\text{percept})$.
- *Forward Action*: infer the protagonist’s action given their desire and percepts of the causal event. Before inferring the action, one would need to first implicitly infer the protagonist’s belief: $\sum_{\text{belief}} P(\text{action}|\text{percept}, \text{belief}, \text{desire})$.
- *Backward Belief*: infer the protagonist’s belief from observed actions. This requires to first implicitly infer the protagonist’s percepts: $\sum_{\text{percepts}} P(\text{belief}|\text{action}, \text{percept}, \text{desire})$.