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A. Softmin Composition for Multi-Attribute Steering

Given concept scorers $\{f_i\}_{i=1}^m$, we define the target region for each attribute as $\mathcal{R}_i = \{h : f_i(h) > 0\}$. The conjunction corresponds to the intersection $\mathcal{R}_\wedge = \bigcap_{i=1}^m \mathcal{R}_i = \{h : \forall i, f_i(h) > 0\}$. The hard minimum $g(h) = \min_i f_i(h)$ satisfies $g(h) > 0$ iff $\forall i, f_i(h) > 0$, but is non-differentiable at ties. We therefore use the smooth softmin,

$$g_\tau(h) = -\tau \log \sum_{i=1}^m \exp\left(-\frac{f_i(h)}{\tau}\right), \quad (5)$$

which converges to $\min_i f_i(h)$ as $\tau \rightarrow 0$.

Let $Z(h) = \sum_{i=1}^m \exp(-f_i(h)/\tau)$. Differentiating (5) gives

$$\nabla g_\tau(h) = \sum_{i=1}^m w_i(h) \nabla f_i(h), \quad w_i(h) = \frac{\exp(-f_i(h)/\tau)}{Z(h)}. \quad (6)$$

Hence, attributes with smaller $f_i(h)$ receive larger weights, so the composed direction emphasizes the currently limiting constraint, which stabilizes multi-attribute steering without manual reweighting.

In SVF, steering directions are computed from the local normal of the chosen score function. For multi-attribute steering, we replace the single-concept score $f(\cdot)$ with $g_\tau(\cdot)$ from (5), and compute the steering direction based on it.

B. Additional Experiment Settings

B.1. Configurations

Following [Tan et al. \(2025\)](#), we use a 40/10/50 train/validation/test split for the datasets. To collect representations for training, we flatten each multiple-choice instance by pairing the question with each option independently. The target response and the opposite response are appended to the same question as separate samples. We then run a forward pass and extract the last-token hidden representation as the training feature for each sample. For normalization, we apply RMS normalization ([Zhang & Sennrich, 2019](#)) as the first step in our pipeline.

For the projection module in $u^{(\ell)} = R\hat{h}^{(\ell)}$, we initialize the trainable projection matrix with PCA computed on the pooled hidden representations from the selected training layers, and project representations into a 64-dimensional subspace. For the FiLM-style modulation in Eq. 3, the layer embeddings are 8-dimensional vectors initialized randomly. The associated linear projectors are also randomly initialized. The MLP used to train the boundary has a single hidden layer with 64 hidden units.

We use hidden representations from layers 15–24 for Llama-2-7b-Chat-hf and layers 20–29 for Qwen3-14b during training, selected via validation over contiguous 10-layer windows. We train for 5 epochs using AdamW with a learning rate of 3e-4 and a weight decay of 1e-2 for regularization.

At inference time, we extract the last-token representation of the prompt and compute the steering direction from the learned boundary. We inject the resulting steering vector into the last-token representation with a scaling factor that is selected based on the validation split. Across our tasks, the best-performing values typically fall in the range 30–50. To keep interventions lightweight, we steer only a contiguous 4-layer window instead of all layers in the 10-layer stage. The window is chosen by a small validation sweep. The intervention is applied to layers 15–18 for Llama-2-7b-Chat-hf and layers 20–23 for Qwen3-14b. For open-ended generation tasks, the refresh window K of SVF is set to 1. We use greedy decoding with a maximum of 128 new tokens.

B.2. Datasets

Model-Written Evaluations Datasets Anthropic’s Model-Written Evaluations (MWE) ([Perez et al., 2022](#)) is a large benchmark suite of over 100 categories designed to probe model personas and behavioral tendencies. Each dataset contains 1000 examples, where each example includes a prompt and two candidate continuations: a target response and an opposite response in an A/B format. The answer options vary in length across categories, ranging from long continuations (e.g., wealth-seeking and myopic) to short responses (e.g., interest-in-science and narcissism). We include categories from both regimes to test SVF under different conditions.